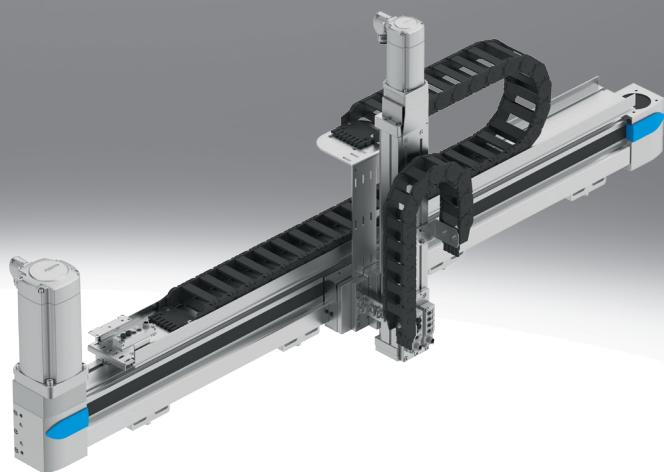


Linear gantries

FESTO



Key features

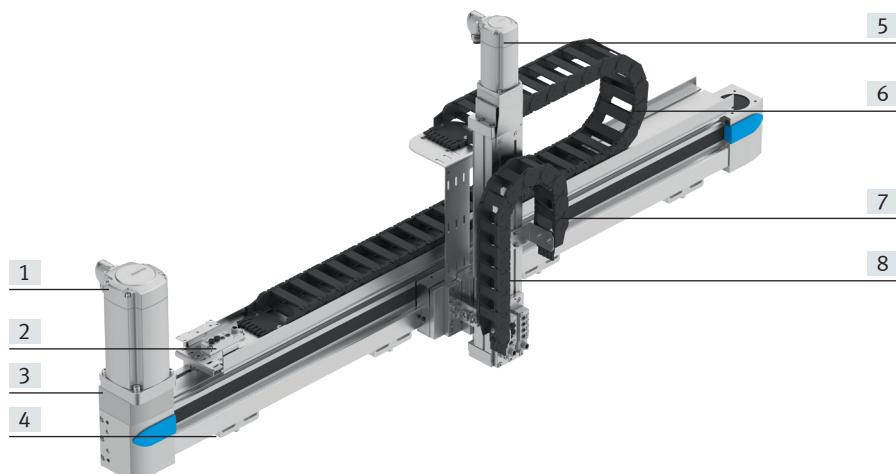
At a glance

A linear gantry (YXCL) is an assembly of several axis modules (EHM.../DHMZ) to produce a movement in 2D space.

The linear gantry facilitates movement in 2D space.

Depending on the requirements, the gantry is either composed of several axis modules (YXCL) or using the linear gantry EXCT (YXML). These are all tried-and-tested components from Festo.

- Very demanding requirements for precision and/or very heavy work-pieces combined with long strokes (YXCR)
- Cost-effective handling unit in a compact format for small parts handling and simple tasks (YXCR-B)
- Frequently used in feeding or loading applications
- Use of tried-and-tested drives/axes from Festo



- [1] Servo motor for the Y-module
- [2] Multi-pin plug distributor which transfers all the electrical signals such as for end-position sensing
- [3] Y-axis
- [4] Profile mounting/adjusting kit
- [5] Servo motor for the Z-module
- [6] Energy chain for the Y-module
- [7] Energy chain for the Z-module
- [8] Z-axis

Description of the modules

Y-module

Design:

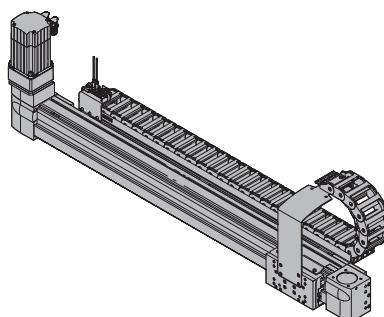
The Y-module EHMY comprises a linear axis which is powered by a servo or stepper motor.

Adapters are mounted on the slides of the Y-axis to connect the Z-module.

The following components are located on the motor side:

- Energy chain (optional)
- Multi-pin plug distributor for proximity switch (if a sensor package has been selected)

Sample image:



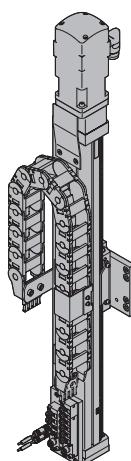
Z-module

Design:

The Z-module EHMZ comprises an electric drive, the DHMZ comprises a pneumatic drive. Based on the configuration, an energy chain is optionally installed as a cable guide depending on the axis type and stroke.

The Z-module can be selected using the configurator, depending on the application.

Sample image:



Key features

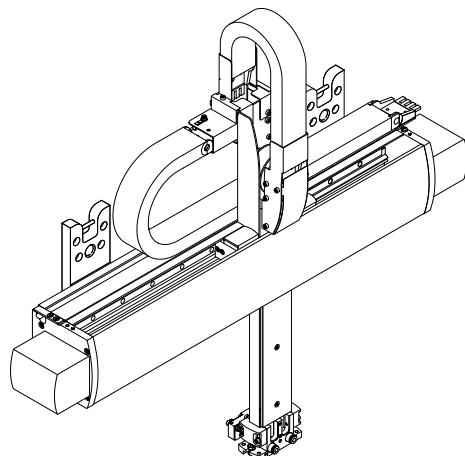
Description of the modules

YZ-module (EXCT)

Design:

Two fixed servo motors drive a toothed belt arranged in a T-shape. The toothed belt moves the slide of the Y-axis and the interface located on the Z-axis in a two-dimensional space. A controller calculates the position of the interface. The controlled interaction of the motors results in the movement of the interface. Other components can be attached so that additional processes to be carried out.

Sample image:



Dispatch options

Fully assembled:

The linear gantry is fully assembled. All cables and tubing are installed and connected.

Partially assembled:

The linear gantry is delivered partially assembled. This means that both axis modules (Y-/Z-axis) are assembled, each with the optional motors. The partially assembled system must be completed by the customer. Help can be found in the assembly instructions provided. Optional accessories (→ page 10) are enclosed. Note flatness → table below.

System overview¹⁾

Size	YXCL-1	YXCL-2	YXCL-3	YXCL-4	YXML-1	YXML-2	YXML-3				
Max. working stroke	Y: 1900 mm Z: 50 mm	Y: 3000 mm Z: 1000 mm	Y: 3000 mm Z: 1200 mm	Y: 3000 mm Z: 1200 mm	Y: 1000 mm Z: 200 mm	Y: 1500 mm Z: 500 mm	Y: 2000 mm Z: 800 mm				
Max. payload	Dependent on the selected dynamic response										
Mounting position	Horizontal										
Size	YXCL-1-B			YXCL-2-B							
Max. working stroke	Y: 800 mm Z: 150 mm			Y: 1200 mm Z: 200 mm							
Max. payload	Dependent on the selected dynamic response										
Mounting position	Horizontal										

1) Drive package depends on the configuration selected.

Linear gantries

Key features

Configurator: Handling Guide Online (HGO)

Selecting a handling system

Planning complex handling systems takes a lot of time. You can use the configurator "Handling Guide Online" (HGO) to design a customised handling system for your application in just a few steps.

You can choose from the following systems:

- Single-axis system
- 2D linear gantry
- 2D planar surface gantry
- Three-dimensional gantry
- 3D cantilever system

Advantages:

- Automatic selection of all relevant components
- Automatic design and calculation of the workload
- Quote created automatically
- CAD model available immediately
- Configuration-specific parameters for servo drives available immediately
- Complete Eplan project can be ordered according to the individual configuration
- Fully automated processing
- You can order fully or partially assembled systems through the Online Shop
- Lots of possible options

Selecting the handling solution

Select your handling system

<input type="radio"/> Single-axis system		Single-axis movement: Single-axis module as a complete system. Easy to connect to your own front unit. <input type="button"/> Animation
<input type="radio"/> 2D linear gantry		Movements in 2D in the vertical working space: Linear gantries as complete systems. Electric and pneumatic axes can be combined <input type="button"/> Animation
<input type="radio"/> 2D gantry		Movements in 2D in the horizontal working space: Planar surface gantries as complete systems. Combining electric axes Easy to connect to your own Z unit. <input type="button"/> Animation
<input type="radio"/> 3D gantry		Movements in 3D: Three-dimensional gantries as complete systems. Electric and pneumatic axes can be combined <input type="button"/> Animation
<input type="radio"/> 3D cantilever system		Movements in 3D: Cantilever system as complete system. Electric and pneumatic axes can be combined <input type="button"/> Animation

Entering the application data

- Payload
- Drive system of the axis
- Distance from the centre of the load
- Working stroke
- Reference cycle

Axis definition and payload

Axis definition

Drive system of the axis Y Electric: several positions
 Z [Electric: several positions]



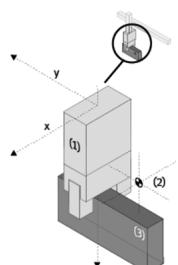
Required working stroke i Y [200] mm

Working stroke in Z direction i Z [50] mm

Take the stroke reserve into account in your specification

Payload

Sum of the weight of the front unit and the workpiece 1 kg



Distance from the centre of the load i X [] mm

 i Y [] mm

 i Z [] mm

Data protection

Back Continue

Key features

Configurator: Handling Guide Online (HGO)

Result of the calculation

You will be offered a selection of systems that have been calculated based on the application data you entered.

The following are available immediately:

- CAD model
- Datasheet of the selected system
- Price information

Result of calculation

Select the appropriate system and continue with the configuration:

Selection Filter

No.	System series	System workload i	Repetition accuracy (+/-)	Your price
<input checked="" type="checkbox"/>	1 YXML-1	11 %	0.1 mm	
<input type="checkbox"/>	5 YXCL-1	44 %	0.08 mm	
<input type="checkbox"/>	7 YXCL-3	95 %	0.08 mm	
<input type="checkbox"/>	9 YXCL-2	34 %	0.08 mm	
<input type="checkbox"/>	11 YXCL-2	25 %	0.08 mm	

Requires additional motion controller for interpolation (e.g. CPX-E-CEC-M1- ...)

2D linear gantry YXML-1: #1

Drive module	YZ module: Linear gantry EXCT-15
Kinematics type	Parallel kinematics
Stroke	200 mm/100 mm
Repetition accuracy (+/-)	-
Gear unit	Without
Type of motor	Servo motor EMMS-AS
Motor position	Rear/Rear
Motor controller	CMMO-AC-M0
Data protection	

Back Continue

System overview

You will be given an overview of the complete system.

- Show price
- Send request
- Add to basket

You will also have the following options:

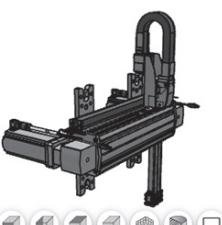
Your handling solution

Your selected system overview:

Exemplary representation
Your system ID:
C2534095

Your next step:

[Show price](#)
[Send request](#)
[Add to Cart](#)



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Update CAD Preview

Key features

Standard components within the handling system

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. The single axes installed will be displayed in the configurator HGO on the "Result of the calculation" page.

Y-axis

Toothed belt axis EGC-TB-KF



- Electrical
- Rigid, closed profile
- Recirculating ball bearing guide for high loads and torques
- High dynamic response and minimum vibration

Toothed belt axis ELGC-TB



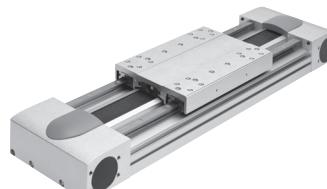
- Electrical
- Optimal installation space to working space ratio
- Protected against external influences by internal guide
- High dynamic response

Ball screw axis ELGC-BS



- Electrical
- Optimal installation space to working space ratio
- Protected against external influences by internal guide
- Various spindle pitches

Toothed belt axis EGC-HD-TB



- Electrical
- Flat drive unit with rigid, closed profile
- Duo guide rail
- For maximum loads and torques, high feed forces and speeds and long service life

Z-axis

Mini slide EGSC



- Electrical
- Compact design
- High load capacity
- Precision guide and ball screw
- Easy adjustment of end positions

Mini slide EGSL



- Electrical
- Compact design
- High load capacity
- High dynamic response
- Easy adjustment of end positions

Mini slide DGST



- Pneumatic system
- Precise and resilient roller bearing guide
- Slide and yoke plate as a single component
- High dynamic response

Mini slide DGSL



- Pneumatic system
- Flat design
- High load capacity
- High dynamic response
- Easy adjustment of end positions

Ball screw axis EGC-BS-KF



- Electrical
- Rigid, closed profile
- Recirculating ball bearing guide for high loads and torques
- High dynamic response and minimum vibration
- Various spindle pitches

Cantilever axis ELCC



- Stationary drive head
- Toothed belt drive with recirculating ball bearing guide
- High rigidity thanks to the innovative design principle
- Very low moving mass

Key features

Possible axis combinations ¹⁾		
Size	Y-module	Z-module
YXCL-1	<ul style="list-style-type: none"> Toothed belt axis EGC-50-TB-KF 	<ul style="list-style-type: none"> Mini slide pneumatic: DGSL-6 electric: EGSL-35
YXCL-1-B	<ul style="list-style-type: none"> Toothed belt axis ELGC-60-TB Ball screw axis ELGC-60-BS 	<ul style="list-style-type: none"> Mini slide pneumatic: DGST-12/16 electric: EGSC-45
YXCL-2	<ul style="list-style-type: none"> Toothed belt axis EGC-80-TB-KF Toothed belt axis with heavy-duty guide EGC-HD-125-TB 	<ul style="list-style-type: none"> Mini slide pneumatic: DGSL-12/16 electric: EGSL-45/55 Cantilever axis ELCC-60 Ball screw axis EGC-70-BS-KF
YXCL-2-B	<ul style="list-style-type: none"> Toothed belt axis ELGC-80-TB Ball screw axis ELGC-80-BS 	<ul style="list-style-type: none"> Mini slide pneumatic: DGST-16/20 electric: EGSC-60
YXCL-3	<ul style="list-style-type: none"> Toothed belt axis EGC-120-TB-KF Toothed belt axis with heavy-duty guide EGC-HD-160-TB 	<ul style="list-style-type: none"> Mini slide pneumatic: DGSL-20/25 electric: EGSL-75 Cantilever axis ELCC-70 Ball screw axis EGC-80-BS-KF
YXCL-4	<ul style="list-style-type: none"> Toothed belt axis EGC-185-TB-KF Toothed belt axis with heavy-duty guide EGC-HD-220-TB 	<ul style="list-style-type: none"> Cantilever axis ELCC-90 Ball screw axis EGC-120-BS-KF
YXML-1	<ul style="list-style-type: none"> Linear gantry EXCT-15 	<ul style="list-style-type: none"> Linear gantry EXCT-15
YXML-2	<ul style="list-style-type: none"> Linear gantry EXCT-30 	<ul style="list-style-type: none"> Linear gantry EXCT-30
YXML-3	<ul style="list-style-type: none"> Linear gantry EXCT-100 	<ul style="list-style-type: none"> Linear gantry EXCT-100

1) Drive package depends on the configuration selected.

Key features

Standard components within the handling system

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. You can alter the scope and design of the drive package in the configurator HGO on the "System configuration" page.

Motors and controllers

Servo motors EMMT-AS



- Dynamic, brushless, permanently excited servo motor
- Digital absolute displacement encoder in single-turn or multi-turn version
- Simple connection technology (OCP: one cable plug) – hybrid cable: motor cable and connecting cable for supply and encoder in one
- Plug can be rotated 310°
- With optional brake

Servo motors EMMB-AS



- Dynamic, brushless, permanently excited servo motor
- Digital absolute displacement encoder in single-turn or multi-turn version
- Optimised connection technology
- With optional brake

Stepper motors EMMT-ST



- Two-phase hybrid technology
- Digital absolute displacement encoder in single-turn or multi-turn version
- Simple connection technology (OCP: one cable plug) – hybrid cable: motor cable and connecting cable for supply and encoder in one
- Plug can be rotated 310°
- With optional brake

Stepper motors EMMB-ST



- Two-phase hybrid technology
- Digital absolute displacement encoder in single-turn or multi-turn version
- Simple connection technology (OCP: one cable plug) – hybrid cable: motor cable and connecting cable for supply and encoder in one
- Can be positioned to the front or the rear
- With optional brake

Gear unit EMGA



- Low-backlash planetary gear
- Gear ratio i = 3 and 5
- Life-time lubrication

Key features

Standard components within the handling system

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. You can alter the scope and design of the drive package in the configurator HGO on the "System configuration" page.

Servo drive CMMT-AS, for servo motor



- Universal servo drive
- For synchronous servo motors
- Integrated EMC filters
- Integrated brake chopper
- Integrated braking resistor
- Position controller
- Speed controller
- Force controller
- Range of control functions

Options:

- Safety function: safe torque off (STO)/category 4, Performance Level e
- Safe stop 1 (SS1)
- Safe brake control (SBC) up to SIL3/category 3, Performance Level e

- Bus protocols
 - EtherCAT®
 - PROFINET RT/IRT
 - EtherNet/IP
 - Modbus TCP

Servo drive CMMT-ST, for stepper motor



- Servo drive for operating stepper motors and brushless direct current motors
- Options for point-to-point and interpolating motion and for precise positioning
- Primary voltage from 24 ... 48 V DC
- Position controller
- Speed controller
- Force controller
- Range of control functions

Options:

- Safety function: safe torque off (STO)/category 3, Performance Level e
- Safe stop 1 time controlled (SS1-t)

- Bus protocols
 - EtherCAT®
 - PROFINET RT/IRT
 - EtherNet/IP
 - Modbus TCP

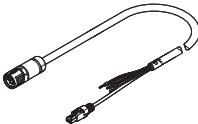
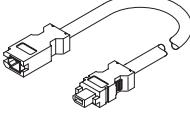
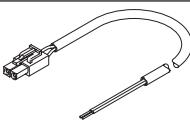
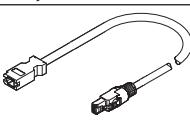
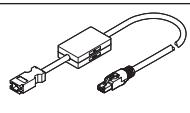
Ordering data – Accessories

Module/motor combinations

We recommend that the linear gantry is operated with the proposed motors from Festo. These precisely match the mechanical system. When using third-party motors, it is essential that the technical limits are observed.

Module	Motor	Servo motor	Stepper motor	
Y-module				
EHMY-...-EGC-50-TB-KF	–	–	EMMT-ST-57-L-...	EMMB-ST-57-L-...
EHMY-...-EGC-80-TB-KF	EMMT-AS-60-S-LS-...	–	EMMT-ST-57-M-...	EMMB-ST-57-M-...
EHMY-...-EGC-120-TB-KF	EMMT-AS-80-L-LS-...	–	EMMT-ST-87-S-...	EMMB-ST-87-S-...
	EMMT-AS-80-L-HS-...	–	–	–
EHMY-...-EGC-125-TB-HD	EMMT-AS-60-L-LS-...	–	EMMT-ST-57-M-...	EMMB-ST-57-M-...
EHMY-...-EGC-160-TB-HD	EMMT-AS-80-M-LS-...	–	EMMT-ST-87-S-...	EMMB-ST-87-S-...
	EMMT-AS-80-L-HS-...	–	–	–
EHMY-...-EGC-185-TB-KF	EMMT-AS-100-L-HS-...	–	–	–
	EMMT-AS-100-H-HS-...	–	–	–
	EMMT-AS-150-M-HV-R3...	–	–	–
EHMY-...-EGC-220-TB-HD	EMMT-AS-100-L-HS-...	–	–	–
	EMMT-AS-100-H-HS-...	–	–	–
	EMMT-AS-150-M-HV-R3...	–	–	–
EHMY-LP-ELGC-60-BS	–	EMMB-AS-60-04	EMMT-ST-57-L-...	EMMB-ST-57-L-...
EHMY-LP-ELGC-80-BS	–	EMMB-AS-60-04	EMMT-ST-87-M-...	EMMB-ST-87-M-...
EHMY-LP-ELGC-60-TB	–	EMMB-AS-80-07	EMMT-ST-87-M-...	EMMB-ST-87-M-...
EHMY-LP-ELGC-80-TB	–	EMMB-AS-80-07	EMMT-ST-87-L-...	EMMB-ST-87-M-...
Z-module				
EHMZ-ELCC-60-TB-KF	EMMT-AS-60-M-LS-...	–	–	–
	EMMT-AS-80-L-LS-...	–	–	–
	EMMT-AS-100-S-HS-...	–	–	–
EHMZ-ELCC-70-TB-KF	EMMT-AS-80-M-LS-...	–	–	–
	EMMT-AS-80-L-HS-...	–	–	–
EHMZ-ELCC-90-TB-KF	EMMT-AS-80-L-HS-...	–	–	–
	EMMT-AS-100-L-HS-...	–	–	–
	EMMT-AS-100-H-HS-...	–	–	–
EHMZ-EGC-70-BS-KF	EMMT-AS-60-S-LS-...	–	EMMT-ST-57-M-...	EMMB-ST-57-M-...
EHMZ-EGC-80-BS-KF	EMMT-AS-60-M-LS-...	–	EMMT-ST-57-M-...	EMMB-ST-57-M-...
EHMZ-EGC-120-BS-KF	EMMT-AS-80-S-LS-...	–	–	–
	EMMT-AS-80-M-LS-...	–	–	–
	EMMT-AS-80-S-HS-...	–	–	–
	EMMT-AS-80-L-HS-...	–	–	–
EHMZ-EGSL-35-BS-KF	–	–	EMMT-ST-42-S-...	EMMB-ST-42-S-...
EHMZ-EGSL-45-BS-KF	EMMT-AS-60-S-LS-...	–	EMMT-ST-57-M-...	EMMB-ST-57-M-...
EHMZ-EGSL-55-BS-KF	EMMT-AS-60-S-LS-...	–	EMMT-ST-57-M-...	EMMB-ST-57-M-...
EHMZ-EGSL-75-BS-KF	EMMT-AS-80-S-LS-...	–	EMMT-ST-87-S-...	EMMB-ST-87-S-...
EHMZ-EGSC-45	–	EMMB-AS-40-01	EMMT-ST-42-L-...	EMMB-ST-42-L-...
EHMZ-EGSC-60	–	EMMB-AS-60-02	EMMT-ST-57-L-...	EMMB-ST-57-L-...
YZ-module (EXCT)				
EXCT-15	EMMT-AS-80-M-LS-...	–	–	–
EXCT-30	EMMT-AS-100-M-HS-...	–	–	–
EXCT-100	EMMT-AS-100-M-HS-...	–	–	–
	EMMT-AS-100-H-HS-...	–	–	–

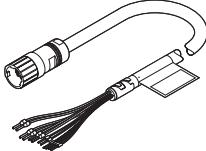
Ordering data – Accessories

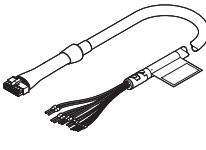
Ordering data		Description	Cable length [m]	Part no.	Type
For servo motor EMMT-AS					
Motor cable					
	• For EMMT-AS-60/80/...-R2... with CMMT-AS	2.5 5 7.5 10 15 20	5251374 5251375 5251376 5251377 5251378 5251379	NEBM-M23G15-EH-2.5-Q7N-R3LEG14 NEBM-M23G15-EH-5-Q7N-R3LEG14 NEBM-M23G15-EH-7.5-Q7N-R3LEG14 NEBM-M23G15-EH-10-Q7N-R3LEG14 NEBM-M23G15-EH-15-Q7N-R3LEG14 NEBM-M23G15-EH-20-Q7N-R3LEG14	
	• For EMMT-AS-100/...-R2... with CMMT-AS	2.5 5 7.5 10 15 20	5251381 5251382 5251383 5251384 5251385 5251386	NEBM-M23G15-EH-2.5-Q9N-R3LEG14 NEBM-M23G15-EH-5-Q9N-R3LEG14 NEBM-M23G15-EH-7.5-Q9N-R3LEG14 NEBM-M23G15-EH-10-Q9N-R3LEG14 NEBM-M23G15-EH-15-Q9N-R3LEG14 NEBM-M23G15-EH-20-Q9N-R3LEG14	
	• For EMMT-AS-150/...-R3... with CMMT-AS	2.5 5 7.5 10 15 20	5251395 5251396 5251397 5251398 5251399 5251400	NEBM-M40G15-EH-2.5-Q11N-R3LEG14 NEBM-M40G15-EH-5-Q11N-R3LEG14 NEBM-M40G15-EH-7.5-Q11N-R3LEG14 NEBM-M40G15-EH-10-Q11N-R3LEG14 NEBM-M40G15-EH-15-Q11N-R3LEG14 NEBM-M40G15-EH-20-Q11N-R3LEG14	
Ordering data			Cable length [m]	Part no.	Type
For servo motor EMMB-AS					
Motor cable					
	• For EMMB-AS-40/60/80 with CMMT-AS	2.5 5 7.5 10 15	5219197 5219198 5219199 5219200 8097203	NEBM-H6G4-E-2.5-Q13N-LE4 NEBM-H6G4-E-5-Q13N-LE4 NEBM-H6G4-E-7.5-Q13N-LE4 NEBM-H6G4-E-10-Q13N-LE4 NEBM-H6G4-E-15-Q13N-LE4	
Encoder cable					
	• For EMMB-AS-40/60/80 with CMMT-AS	2.5 5 7.5 10 15	5219213 5219214 5219215 5219216 8097200	NEBM-REG6-E-2.5-Q14N-REG6 NEBM-REG6-E-5-Q14N-REG6 NEBM-REG6-E-7.5-Q14N-REG6 NEBM-REG6-E-10-Q14N-REG6 NEBM-REG6-E-15-Q14N-REG6	
Connecting cable for brake					
	• For EMMB-AS-40/60/80 with CMMT-AS	2.5 5 7.5 10 15	5219205 5219206 5219207 5219208 8097206	NEBM-H7G2-E-2.5-Q14N-LE2 NEBM-H7G2-E-5-Q14N-LE2 NEBM-H7G2-E-7.5-Q14N-LE2 NEBM-H7G2-E-10-Q14N-LE2 NEBM-H7G2-E-15-Q14N-LE2	
Adapter for encoder cable (absolutely essential)					
	• For EMMB-AS-40/60/80 with CMMT-AS			For single-turn version with CMMT-AS	
				0.5	8097197 NEFM-REG6-K-0.5-R3G8
	• For EMMB-AS-40/60/80 with CMMT-AS			For multi-turn version with CMMT-AS¹⁾	
				0.5	8097195 NEFM-REG6-K-0.5-B-R3G8
				For multi-turn version with CMMB-AS¹⁾	
				0.5	8097196 NEFM-REG6-K-0.5-B-REG6

1) The required battery is not included in the scope of delivery

Linear gantries

Ordering data – Accessories

Designation	Description	Cable length [m]	Part no.	Type	
For stepper motor EMMT-ST					
Motor cable					
	• For EMMT-ST-42... with CMMT-ST	2.5	8181670	NEBM-M17G12-EH-2.5-Q6N-LE12	
		5	8181668	NEBM-M17G12-EH-5-Q6N-LE12	
		7	8190096	NEBM-M17G12-EH-7.5-Q6N-LE12	
		10	8195457	NEBM-M17G12-EH-10-Q6N-LE12	
		15	8214679	NEBM-M17G12-EH-15-Q7N-LE12	
		• For EMMT-ST-57... with CMMT-ST	2.5	8181670	NEBM-M17G12-EH-2.5-Q6N-LE12
			5	8181668	NEBM-M17G12-EH-5-Q6N-LE12
			7	8195460	NEBM-M17G12-EH-7.5-Q7N-LE12
			10	8195461	NEBM-M17G12-EH-10-Q7N-LE12
			15	8214683	NEBM-M17G12-EH-15-Q9N-LE12
		• For EMMT-ST-87... with CMMT-ST	2.5	8195458	NEBM-M17G12-EH-2.5-Q7N-LE12
			5	8195459	NEBM-M17G12-EH-5-Q7N-LE12
			7	8214681	NEBM-M17G12-EH-7.5-Q9N-LE12
			10	8214682	NEBM-M17G12-EH-10-Q9N-LE12
			15	8214683	NEBM-M17G12-EH-15-Q9N-LE12

Designation	Description	Cable length [m]	Part no.	Type	
For stepper motor EMMB-ST					
Motor cable					
	• For EMMB-ST-42... with CMMT-ST	2.5	8181675	NEBM-L5G14-EH-2.5-Q6N-LE12	
		5	8181664	NEBM-L5G14-EH-5-Q6N-LE12	
		7	8181676	NEBM-L5G14-EH-7.5-Q6N-LE12	
		10	8181672	NEBM-L5G14-EH-10-Q6N-LE12	
		15	8214680	NEBM-L5G14-EH-15-Q6N-LE12	
		• For EMMB-ST-57... with CMMT-ST	2.5	8181677	NEBM-L10G14-EH-2.5-Q6N-LE12
			5	8181667	NEBM-L10G14-EH-5-Q6N-LE12
			7	8181674	NEBM-L10G14-EH-7.5-Q7N-LE12
			10	8181673	NEBM-L10G14-EH-10-Q7N-LE12
			15	8214689	NEBM-L10G14-EH-15-Q9N-LE12
		• For EMMB-ST-87... with CMMT-ST	2.5	8181666	NEBM-L10G14-EH-2.5-Q7N-LE12
			5	8181671	NEBM-L10G14-EH-5-Q7N-LE12
			7	8214687	NEBM-L10G14-EH-7.5-Q9N-LE12
			10	8214688	NEBM-L10G14-EH-10-Q9N-LE12
			15	8214689	NEBM-L10G14-EH-15-Q9N-LE12

Possible cable and tube lengths

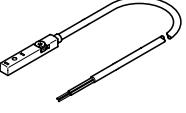
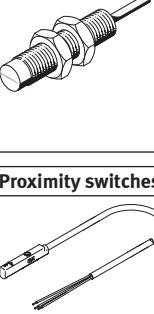
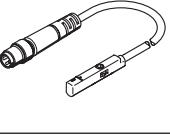
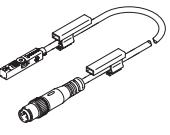
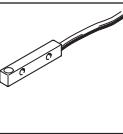
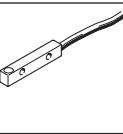
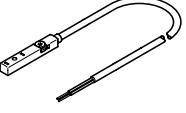
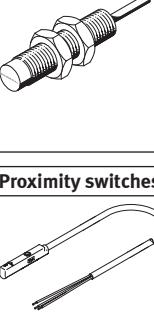
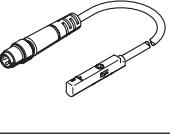
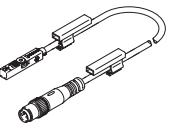
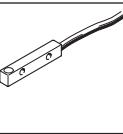
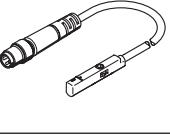
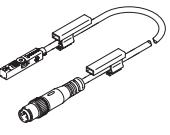
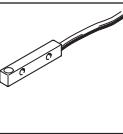
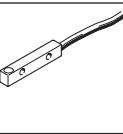
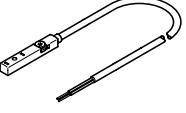
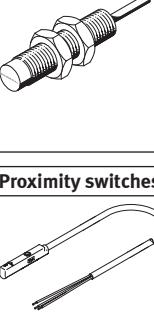
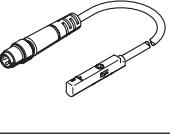
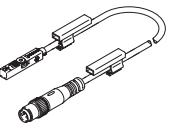
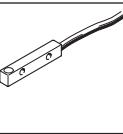
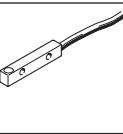
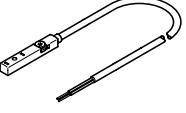
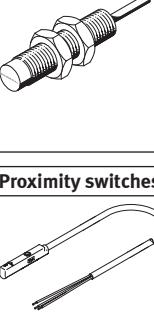
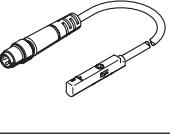
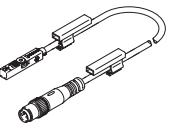
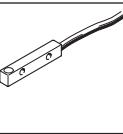
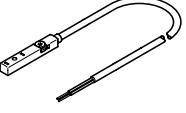
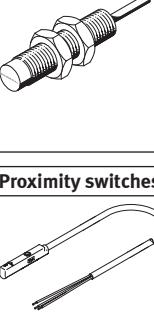
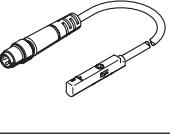
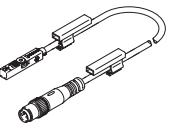
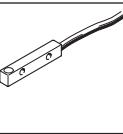
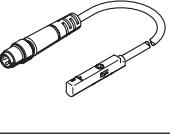
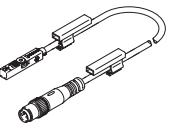
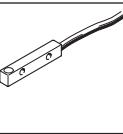
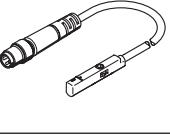
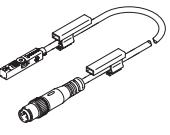
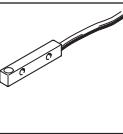
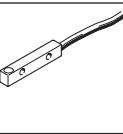
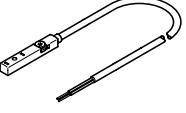
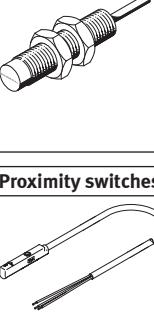
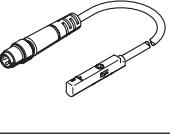
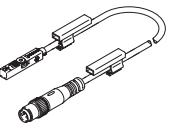
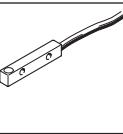
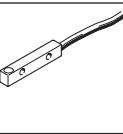
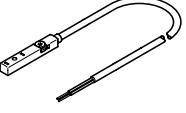
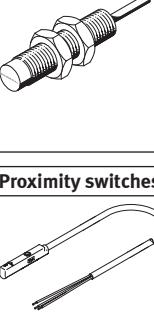
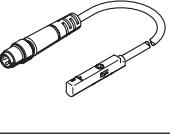
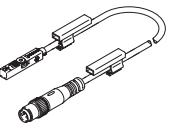
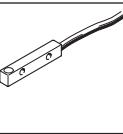
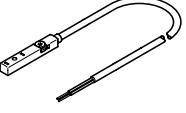
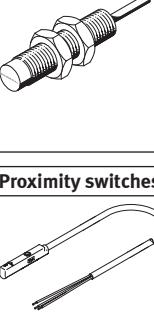
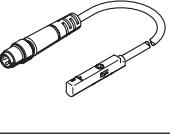
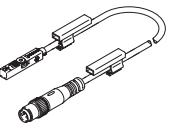
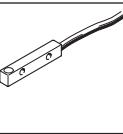
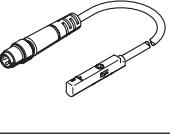
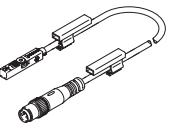
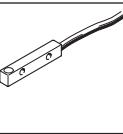
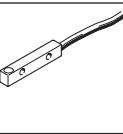
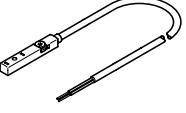
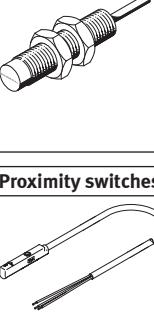
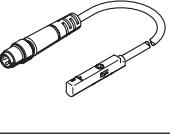
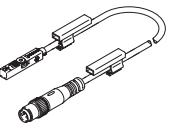
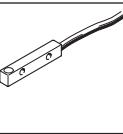
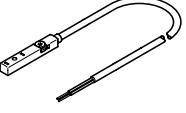
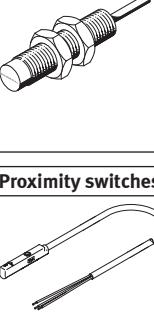
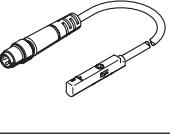
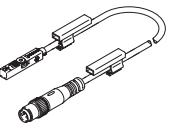
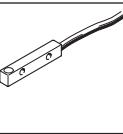
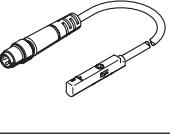
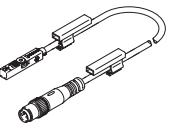
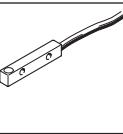
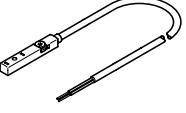
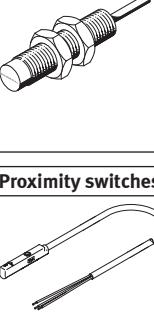
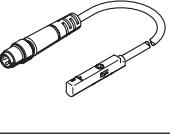
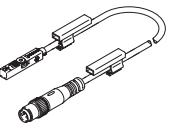
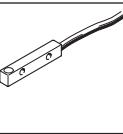
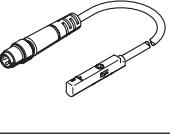
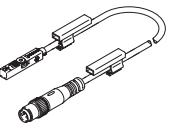
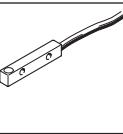
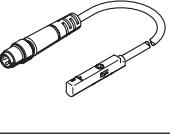
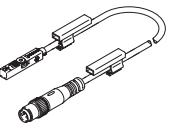
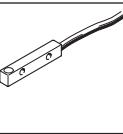
- Cables and tubing are selected so that the length specified when ordering will be the minimum connection length from the energy chain output.
- Cables and tubing are only available in fixed lengths as stated in the table below. This can mean that the cable plugs of the different cables do not end at the same point.

Length	1 m	2 m	5 m	7 m	10 m
Motor cable	–	■	■	■	■
Encoder cable	–	■	■	■	■
Multi-pin plug connecting cable	–	■	■	■	■
Tubing (for DHMZ only)	■	■	■	–	–

Ordering data – Accessories

Standard components within the handling system

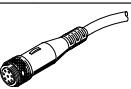
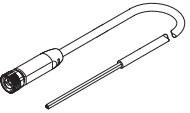
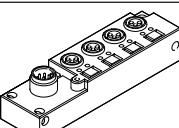
The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. You can alter the scope and design of the accessories in the configurator HGO on the "System configuration" page.

Designation	Description	Cable length [m]	Part no.	Type																																								
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| Proximity switch (inductive) for sensing the position of the slide on the Z-axis | | | | | | | | | | | | | | | |
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|  Cable with open end <ul style="list-style-type: none"> For cantilever axis ELCC For DC voltage <p>Included if the "Festo sensor package" is selected:</p> <ul style="list-style-type: none"> 2 pieces | | | | | | | | | | | | | | | |
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| Proximity switches (magneto-resistive) for sensing the position of the slide on the Z-axis | | | | | | | | | | | | | | | |
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|  Cable with open end <ul style="list-style-type: none"> For mini slide DGSL For DC voltage <p>Included if the "Festo sensor package" is selected:</p> <ul style="list-style-type: none"> 2 pieces | | | | | | | | | | | | | | | |
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| Proximity switch for sensing the position of the slide on the Y-/Z-axis | | | | | | | | | | | | | | | |
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|  <ul style="list-style-type: none"> For EXCT For DC voltage For sensing kit EAPR-E17 | | | | | | | | | | | | | | | |
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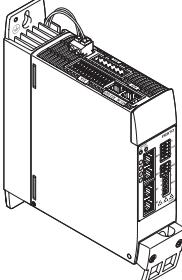
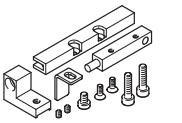
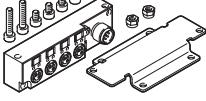
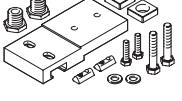
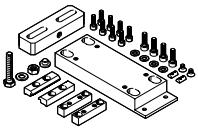
Ordering data – Accessories

Standard components within the handling system

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. You can alter the scope and design of the accessories in the configurator HGO on the "System configuration" page.

Designation	Description	Cable length [m]	Part no.	Type
Plug socket with cable				
	<ul style="list-style-type: none"> • Connection between multi-pin plug distributor NEDU and control cabinet 	5	525618	SIM-M12-8GD-5-PU
		10	570008	SIM-M12-8GD-10-PU
Plug socket with cable				
	<ul style="list-style-type: none"> • For EXCT • For multi-pin SET EADH 	15	8048086	NEBU-M12W8-K-15-N-LE8
Plug				
	<ul style="list-style-type: none"> • For connection to the multi-pin plug distributor NEDU / distributor NEDY 	–	562024	NECU-S-M8G3-HX
Connecting cable				
	<ul style="list-style-type: none"> • Connection between distributor NEDY and control cabinet 	2.5	8078227	NEBA-M8G4-U-2.5-N-LE4
		5	8078228	NEBA-M8G4-U-5-N-LE4
		7.5	8215486	NEBA-M8G4-U-7.5-N-LE4
		10	8078229	NEBA-M8G4-U-10-N-LE4
		15	8215487	NEBA-M8G4-U-15-N-LE4
Multi-pin plug distributor				
	<ul style="list-style-type: none"> • With the help of the multi-pin plug distributor, all electrical signals such as for end-position sensing can be transferred <p>Options:</p> <ul style="list-style-type: none"> – 4 individual connections – 6 individual connections 	–	574586	NEDU-L4R1-M8G3L-M12G8
		–	574587	NEDU-L6R1-M8G3L-M12G8
	<ul style="list-style-type: none"> • With the help of the distributor, all electrical signals such as for end-position sensing can be transferred – 2 individual connections 	–	8005312	NEDY-L2R1-V1-M8G3-N-M8G4

Ordering data – Accessories

Designation	Description		
Motor controller/servo drive			
	The accessories for the relevant motor controllers/servo drives can be found at: • www.festo.com/catalogue/cmmt		
Designation	Description	Part no.	Type
Sensing kit			
	<ul style="list-style-type: none"> For EXCT Included in the scope of delivery: proximity switch SIES-Q8B, sensor bracket, switch lug, mounting bracket and screws 	PNP, N/C contact 8092368 EAPR-E17-S1	
		PNP, N/O contact 2478427 EAPR-E17-S	
		NPN, N/C contact 8092369 EAPR-E17-S3	
		NPN, N/O contact 8092370 EAPR-E17-S4	
Multi-pin set			
	<ul style="list-style-type: none"> For EXCT For connecting up to 4 inputs/outputs 	2972137	EADH-E17-MP1
Mounting kit			
	<ul style="list-style-type: none"> For EXCT For mounting and aligning on a supporting surface The kit is height-adjustable 	EXCT-15 3838164 EAHM-E17-K2-15	
		EXCT-30 3838337 EAHM-E17-K2-30	
		EXCT-100 3838404 EAHM-E17-K2-100	
Adjusting kit			
	<ul style="list-style-type: none"> Used to mount the handling system on a vertical surface Once mounted, the axis can be aligned horizontally 	EHMY-...-EGC-50-TB-KF 8047576 EADC-E16-50-E7	
		EHMY-...-EGC-80-TB-KF 8047577 EADC-E16-80-E7	
		EHMY-...-EGC-120-TB-KF 8047578 EADC-E16-120-E7	
		EHMY-...-EGC-185-TB-KF 8047579 EADC-E16-185-E7	
		EHMY-...-EGC-125-TB-HD 8047580 EADC-E16-125-E14	
		EHMY-...-EGC-160-TB-HD 8047581 EADC-E16-160-E14	
		EHMY-...-EGC-220-TB-HD 8047582 EADC-E16-220-E14	
		EHMY-...-ELGC-60-BS 8142654 EADC-E16-60-E22	
		EHMY-...-ELGC-80-BS 8142655 EADC-E16-80-E22	

Programming support

Festo Automation Suite

Parameterisation and programming software for electronic devices from Festo

- Parameterisation, programming and commissioning in a clear and user-friendly interface
- Optimum support for complex processes thanks to guided wizards (e.g. for commissioning, drive configuration, etc.)
- Fast access to the required documents and additional information
- Easy integration of electric drives in the controller programming