

# Product range overview

Function	Туре	Description				
Drives	Rodless					
	DDLI	Without guide     With displacement encoder for contactless measurement     Based on linear drive DGC-K     Supply ports on end face     System product for handling and assembly technology				
	DGCI	With guide     With displacement encoder for contactless measurement     Based on linear drive DGC     Supply ports optionally on end face or front     System product for handling and assembly technology				
	With piston rod					
	DNCI	<ul> <li>With displacement encoder for contactless measurement</li> <li>Various piston rod variants</li> <li>Standards-based cylinder to ISO 15552</li> </ul>				
	DDPC	<ul> <li>With displacement encoder for contactless measurement</li> <li>Various piston rod variants</li> <li>Standards-based cylinder to ISO 15552</li> </ul>				
	DNC/DSBC	With attached potentiometer MLO-LWG     Various piston rod variants     Standards-based cylinder to ISO 15552				
Swivel modul	le   Swivel module					
		<ul> <li>Based on swivel module DSM</li> <li>Integrated rotary potentiometer</li> <li>Compact design</li> <li>Wide range of mounting options</li> </ul>				

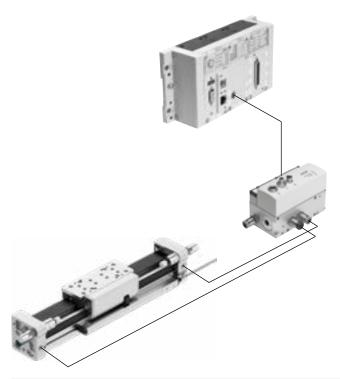
# Product range overview

Piston	Stroke/swivel angle	Suitable				
diameter		for positioning with	for end-position controll	ler	for use as a measuring	
	[mm/°]	CPX-CMAX	CPX-CMPX	SPC11	cylinder	
Rodless						
25, 32, 40, 63	100, 160, 225, 300, 360, 450, 500, 600, 750, 850, 1000, 1250, 1500, 1750, 2000	•	-	•	•	
18, 25, 32, 40, 63	100, 160, 225, 300, 360, 450, 500, 600, 750, 850, 1000, 1250, 1500, 1750, 2000	•	•	•	•	
With piston rod					I	
32, 40, 50, 63	10 2000	-	-	-	•	
	100 750	-				
80, 100	10 2000	-	-	-	•	
	100 750	•	-	•	_	
32, 40, 50, 63, 80	100, 150, 225, 300, 360, 450, 600, 750	•	•	•	•	
Swivel module						
25, 40, 63	270	•	•	•	•	

## Key features

#### Servo-pneumatic drive technology

Positioning and Soft Stop applications as an integral component of the valve terminal CPX – the modular peripheral system for decentralised automation tasks. The modular design means that valves, digital inputs and outputs, positioning modules and end-position controllers, as appropriate to the application, can be combined in almost any way on the CPX terminal.



#### Advantages:

- Pneumatics and electrics control and positioning on one platform
- Innovative positioning technology piston rod drives, rodless drives, rotary drives
- Actuation via fieldbus
- Remote maintenance, remote diagnostics, web server, SMS and e-mail alerts are all possible via TCP/IP
- · Modules can be quickly exchanged and expanded without altering the wiring

#### Axis controller CPX-CMAX



### Free choice:

Position and force control, directly actuated or selected from one of 128 configurable position sets. If you are looking for something more: The configurable record sequencing function enables simple functional sequences to be realised in the axis controller CPX-CMAX.

Everything is recognisable: The auto-identification function identifies each participant with its device data on the controller CPX-CMAX.

### Also included:

Actuation of a brake or clamping unit via the proportional directional control valve VPWP is also part of the scope of performance of the controller CPX-CMAX.

Up to 8 modules (max. 8 axes) can be operated in parallel and independently of each other.

Commissioning via FCT (Festo configuration software) or via fieldbus: no programming, only configuration.

- Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
- You program the system in your PLC environment

# Key features

#### End-position controllers CPX-CMPX



Fast travel between the mechanical end stops of the cylinder, stopping gently and without impact in the end position.

Fast commissioning via control panel, fieldbus or handheld unit.
Improved standstill control.
Actuation of a brake or clamping unit via the proportional directional control valve VPWP is an integral part of the controller CMPX.

Depending on the fieldbus chosen, up to 9 end-position controllers can be actuated on the CPX terminal.

All system data can be read and written via the fieldbus, including, for example, the mid-positions.

#### Data sheets → Internet: cpx-cmpx

#### Advantages:

- · Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
  - Up to 30% faster cycle rates
  - Significantly reduced system vibration
- Improved work ergonomics thanks to significantly reduced noise level
- The extended diagnostics help to reduce the service time of the machine

### Proportional directional control valve VPWP



The 5/3-way proportional directional control valve for applications with Soft Stop and pneumatic positioning. Fully digitalised – with integrated pressure sensors, with new diagnostic functions.

In sizes 4, 6, 8 and 10. Flow rates of 350, 700, 1400 and 2000 l/min. With switching output for controlling a brake.

Colour-coded supply ports.

Pre-assembled cables guarantee
faultless and fast connection with the
controllers CPX-CMPX and CPX-CMAX.

# Data sheets → Internet: vpwp

#### Advantages:

- Easy installation and fast commissioning
- Reduction of system downtimes thanks to the new diagnostic options
- With switching output for controlling a brake/clamping unit

### Measuring module CPX-CMIX



Fully digital data acquisition and transmission means that pneumatic cylinders can be used as sensors. With very high repetition accuracy and incorporating both analogue and digital measuring sensors.

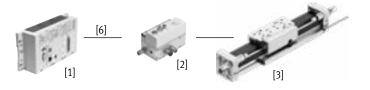
Suitable for the linear drive DGCI with displacement encoder for measuring absolute values, for the piston rod drive DNCI/DDPC with incremental displacement encoder or alternatively for a potentiometer of the type MLO.

# Data sheets → Internet: cpx-cmix

- All process steps can be documented, which improves quality
- An adjustable contact force (via pressure regulator) increases the precision of the "displacement sensor"
- With displacement encoders for measuring absolute values, the actual position is immediately available after the system is switched on

## **Drive options**

#### System with linear drive DDLI, DGCI



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [3] Linear drive DDLI, DGCI with displacement encoder
- [6] Connecting cable KVI-CP-3-...

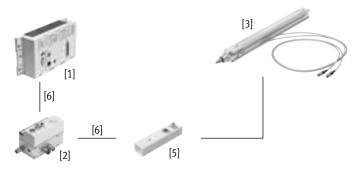
- Pneumatic rodless linear drive with displacement encoder, with or without recirculating ball bearing guide
- Displacement encoder with absolute and contactless measurement
- · Diameter:
  - With DGCI: 18 ... 63 mm
  - With DDLI: 25 ... 63 mm
- Stroke: 100 ... 2000 mm in fixed lengths
- Range of applications: Soft Stop and pneumatic positioning
- Loads from 1 ... 180 kg
- No sensor interface required

### Data sheets → Internet: ddli or dgci

#### Advantages:

- · Complete drive unit
- DDLI for easy connection to the customer's guide system
- Excellent running characteristics
- For fast and accurate positioning up to ±0.2 mm (only with axis controller CPX-CMAX)

### System with standards-based cylinder DNCI, DDPC



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [3] Standards-based cylinder DNCI, DDPC with displacement encoder
- [5] Sensor interface CASM-S-D3-R7
- [6] Connecting cable KVI-CP-3-...

## Standards-based cylinder with integrated displacement encoder, conforms to DIN ISO 6432, VDMA 24 562, NF E 49 003.1 and Uni 10 290

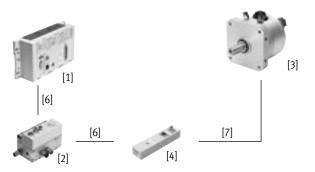
- Displacement encoder with contactless and incremental measurement
- Diameter: 32 ... 100 mm
- Stroke: 100 ... 750 mm
- Range of applications: Soft Stop and pneumatic positioning
- Loads from 3 ... 450 kg and the corresponding sensor interface CASM-S-D3-R7
- Pre-assembled cables guarantee faultless and fast electrical connection

### Data sheets → Internet: dnci

- Compact drive unit
- Can be used universally
- Also with guide unit
- For fast and accurate positioning up to ±0.5 mm (only with axis controller CPX-CMAX)

# Drive options

#### System with swivel module DSMI



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [3] Swivel module DSMI with displacement encoder
- [4] Sensor interface CASM-S-D2-R3
- [6] Connecting cable KVI-CP-3-...
- [7] Connecting cable NEBC-P1W4-K-0.3-N-M12G5

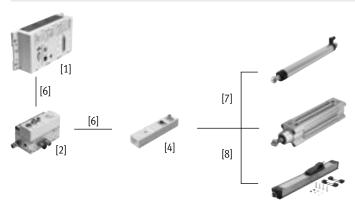
- Swivel module DSMI with integrated displacement encoder
- Identical design to pneumatic swivel module DSM
- Absolute displacement encoder based on a potentiometer
- Swivel range from 0 ... 270°
- Size: 25, 40, 63
- Max. torque: 5 ... 40 Nm
- Range of applications: Soft Stop and pneumatic positioning
- Mass moments of inertia of 15 ... 6000 kgcm<sup>2</sup> and the corresponding sensor interface CASM-S-D2-R3
- Pre-assembled cables guarantee faultless and fast connection to the proportional directional control valve VPWP

#### Data sheets → Internet: dsmi

#### Advantages:

- Complete drive unit, compact, can be used immediately
- High angular acceleration
- With adjustable fixed stops
- For fast and accurate positioning down to ±0.2° (only with axis controller CPX-CMAX)

#### System with potentiometer



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [4] Sensor interface CASM-S-D2-R3
- [6] Connecting cable KVI-CP-3-...
- [7] Connecting cable NEBC-P1W4-K-0.3-N-M12G5
- 8] Connecting cable NEBC-A1W3-K-0.4-N-M12G5

### Attachable potentiometers with absolute measurement, with high degree of protection

- With connecting rod or moment compensator
- Measuring range:
   Connecting rod: 100 ... 750 mm
   Moment compensator:
   225 ... 2000 mm
- Pre-assembled cables guarantee faultless and fast connection with the sensor interface CASM
- Range of applications: Soft Stop and pneumatic positioning with cylinder diameters of 25 ... 80 mm
- Loads from 1 ... 300 kg

#### Data sheets → Internet: casm

- Easy installation and fast commissioning
- Cost-effective
- Can also be used in harsh ambient conditions
- Variety of drives: CPX-CMPX and CPX-CMAX also support cylinders with external displacement encoder

# Drive options

	Linear drive	Standards-based cylinder	Swivel module	Displacement encoder		→ Page/ Internet
	DDLI/DGCI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	Internet
End-position controller CPX-CMPX	•	•	•	•	-	cmpx
Proportional directional control valve VPWP	-	•	•	•	-	vpwp
Sensor interface CASM-S-D2-R3	_	-	•	•	-	casm
Sensor interface CASM-S-D3-R7	_	•	-	-	-	casm
Connecting cable KVI-CP-3	-	•	•	•	-	kvi
Connecting cable NEBC-P1W4	-	-	•	■/-	-	nebc
Connecting cable NEBC-A1W3	_	-	-	-/■	-	nebc
Connecting cable NEBP-M16W6	_	-	-	-	•	vpwp

System components for pneumatic p	ositioning systems with	h axis controller CPX-CMA	X			
	Linear drive	Standards-based cylinder	Swivel module	Displacement encoder		→ Page/ Internet
	DDLI/DGCI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	
Axis controller CPX-CMAX	•	•	•	•	•	cmax
Proportional directional control valve VPWP	•	•	•	•	•	vpwp
Sensor interface CASM-S-D2-R3	-	-	•	•	_	casm
Sensor interface CASM-S-D3-R7	-	•	-	-	_	casm
Connecting cable KVI-CP-3	•	•	•	•	•	kvi
Connecting cable NEBC-P1W4	-	-	•	■/-	_	nebc
Connecting cable NEBC-A1W3	-	-	-	<b>-/■</b>	_	nebc
Connecting cable NEBP-M16W6	-	-	-	-	•	vpwp

System components for measuring c	Linear drive	Standards-based cylinder	Swivel module	Displacement encoder		→ Page/ Internet
	DDLI/DGCI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	
Measuring module CPX-CMIX-M1-1	•	•	•	•	•	cmix
Sensor interface CASM-S-D2-R3	_	-	•	•	-	casm
Sensor interface CASM-S-D3-R7	_	•	_	_	_	casm
Connecting cable KVI-CP-3	(■)¹)			-	(■)	kvi
Connecting cable NEBC-P1W4	_	-	•	■ / -	_	nebc
Connecting cable NEBC-A1W3	-	-	_	<b>-/■</b>	-	nebc
Connecting cable NEBP-M16W6	_	-	_	_	•	vpwp

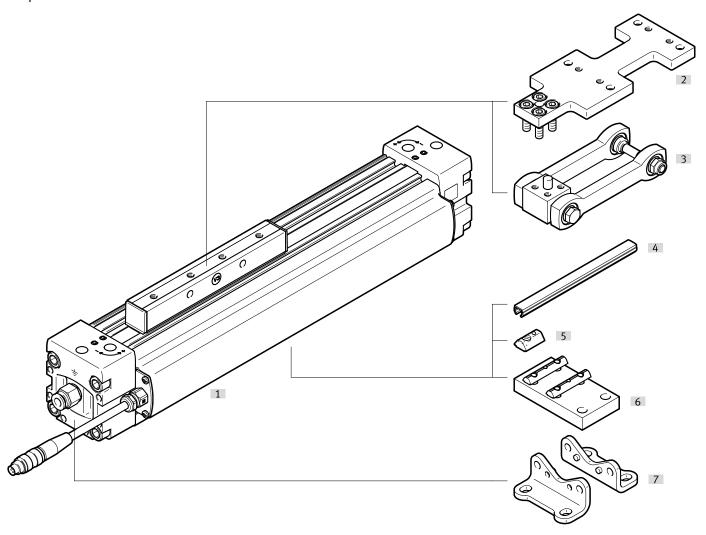
<sup>1)</sup> As an extension

# Type codes

001	Series
DDLI	Linear drive, integrated displacement encoder
002	Piston diameter
25	25
32	32
40	40
63	63
003	Stroke
	100 2000
004	Cushioning
P	Elastic cushioning rings/plates on both sides
	0 0.71
005	Lubrication
005	
005 H1	Lubrication
	Lubrication Standard
H1	Lubrication Standard Food-safe lubrication
H1	Lubrication  Standard  Food-safe lubrication  Foot mounting
<b>H1</b>	Lubrication  Standard Food-safe lubrication  Foot mounting None
H1 006 MF	Lubrication  Standard Food-safe lubrication  Foot mounting None 1 record

800	Cover, sensor slot
	None
NS	1 record
009	Cover, mounting slot
	None
NC	1 record
010	Slot nut for mounting slot
	None
NM	1 50 units
011	Moment compensator
	None
T	Moment compensator coupling DARD
012	Adapter plate
	None
AP	FKP interface
013	Operating instructions
	With operating instructions
DN	Without operating instructions

# Peripherals overview



# Peripherals overview

Acce	ssories		
	Туре	Description	→ Page/Internet
[1]	Linear drive DDLI	With integrated displacement encoder	12
[2]	Adapter plate DAMF	Has the same interface as the moment compensator FKP for the linear drive DGP	23
[3]	Moment compensator DARD	For compensating misalignments when using external guides	22
[4]	Slot cover ABP	For protection against contamination	24
[5]	Slot nut ABAN, NST	For mounting attachments	24
[6]	Central support MUP	For mounting the axis, particularly for long stroke lengths	21
[7]	Foot mounting HP	For mounting the axis. The foot mounting cannot be used when the bottom mounting position is used for the displacement encoder	21



## Note

Allocation table of drives and associated proportional directional control valves

→ page 24

# Data sheet





- **D** - Diameter 25 ... 63 mm





General technical data						
Piston diameter		25	32	40	63	
Design	Rodless linear drive with slide	e and displacement encoder				
Mode of operation		Double-acting				
Moment compensator principle	Slotted cylinder, mechanicall	y coupled				
Mounting position	Any		·			
Type of mounting		Central support				
		Foot mounting				
		Direct mounting				
Cushioning	·	Elastic cushioning rings/pads at both ends				
Position sensing		Via integrated displacement	encoder			
Measuring principle (displacement encoder)		Digital, magnetostrictive, contactless and absolute measurement				
Pneumatic connection <sup>1)</sup>		G1/8		G1/4	G3/8	
Stroke <sup>2)</sup>	[mm]	100, 160, 225, 300, 360, 450, 500, 600, 750, 850, 1000, 1250, 1500, 1750, 2000				
Max. speed	[m/s]	3				

- 1) For pre-assembled push-in fittings, the tubing fittings → page 15 apply
- 2) Note stroke reduction in combination with CPX-CMAX

Operating and environmental conditions						
Piston diameter		25	32	40	63	
Operating pressure	[MPa]	0.2 0.8			0.15 0.8	
	[bar]	2 8			1.5 8	
	[psi]	29 116			21.75 116	
Operating pressure <sup>1)</sup>	[MPa]	0.4 0.8				
	[bar]	48				
	[psi]	58 116				
Operating medium <sup>2)</sup>		Compressed air to ISO 8573-1:2010 [6:4:4]				
Note on the operating/pilot medium		Operation with lubricated medium not possible				
		Pressure dew point 10°C belo	ow ambient temperature/temp	erature of medium		
Ambient temperature	[°C]	-10 +60				
Vibration resistance to DIN/IEC 68 Part 2-6		At 1060 Hz: 0.15 mm				
		At 60150 Hz: 2G				
Continuous shock resistance to DIN/IEC 68, Part 2-27	,	Half sine 15 g, 11 ms				
CE marking (see declaration of conformity) <sup>3)</sup>	To EU EMC Directive					
Certification	RCM trademark					
Corrosion resistance class CRC <sup>4)</sup>		1				

- 1) Only applies to applications with end-position controller CPX-CMPX, SPC11 and axis controller CPX-CMAX
- $2) \quad \text{The proportional directional control valve VPWP, MPYE used requires these characteristic values} \\$
- 3) For information about the area of use, see the EC declaration of conformity: www.festo.com/sp → Certificates.

  If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.
- 4) Corrosion resistance class CRC 1 to Festo standard FN 940070

 $Low corrosion stress.\ Dry\ indoor\ application\ or\ transport\ and\ storage\ protection.\ Also\ applies\ to\ parts\ behind\ coverings,\ in\ the\ non-visible\ interior\ area,\ and\ parts\ which\ are\ covered\ in\ the\ application\ (e.g.\ drive\ trunnions).$ 

Forces [N] and impact energy [Nm]						
Piston diameter	25	32	40	63		
Theoretical force at 0.6 MPa (6 bar, 87 psi)	295	483	754	1870		
Impact energy at the end positions	0.05	0.12	0.25	0.5		

Positioning characteristics with axis controlle	er CPX-CMAX				
Piston diameter		25	32	40	63
Mounting position		Any			
Resolution	[mm]	0.01			
Repetition accuracy		→ Page 15			
Minimum load, horizontal <sup>1)</sup>	[kg]	2	3	5	12
Maximum load, horizontal <sup>1)</sup>	[kg]	30	50	75	180
Minimum load, vertical <sup>1)</sup>	[kg]	2	3	5	12
Maximum load, vertical <sup>1)</sup>	[kg]	10	15	25	60
Min. travel speed	[m/s]	0.05	•		·
Max. travel speed	[m/s]	3			
Typical positioning time, long stroke <sup>2)</sup>	[s]	0.6 5/1.00	0.6 5/1.05	0.7 0/1.05	1.0 5/1.2
Typical positioning time, short stroke <sup>3)</sup>	[s]	0.3 8/0.60	0.3 8/0.60	0.3 8/0.60	0.6 5/0.65
Minimum positioning stroke <sup>4)</sup>	[%]	≤ 3	·		
Stroke reduction <sup>5)</sup>	[mm]	25	25	35	35
Recommended proportional directional contr	ol valve				
For CPX-CMAX		→ Page 24			

- 1) Load = payload + load of all moving parts on the drive
- $2) \hspace{0.5cm} \textbf{At 0.6 MPa (6 bar, 87 psi), horizontal mounting position, DDLI-XX-1000, 800 \, mm positioning travel at min./max. load} \\$
- 3) At 0.6 MPa (6 bar, 87 psi), horizontal mounting position, DDLI-XX-1000, 100 mm positioning travel at min./max. load
- 4) In relation to the maximum stroke of the drive, but never more than 20 mm.
- 5) The stroke reduction must be maintained on each side of the drive, the max. positionable stroke is thus: stroke 2x stroke reduction

Force control characteristics with axis controller CPX-CMAX						
Piston diameter		25	32	40	63	
Mounting position		Any				
Maximum controllable force <sup>1)</sup>	[N]	266	435	679	1683	
Typical friction forces <sup>2)</sup>	[N]	20	30	40	50	
Repetition accuracy of pressure control <sup>3)4)</sup>	[%]	< ±2				

- 1) Advancing/retracting at 0.6 MPa (6 bar, 87 psi)
- 2) These values can fluctuate greatly from cylinder to cylinder and are not guaranteed.
- These friction forces must also be taken into consideration when using an external guide or when the cylinder is moving other components subject to friction
- 3) This value defines the repetition accuracy with which the internal differential pressure in the cylinder, which corresponds to the prescribed force setpoint value, is controlled and refers to the maximum controllable force
- 4) The effective force at the workpiece and its accuracy depend largely on the friction in the system as well as the repetition accuracy of the internal control system. Note that friction forces always work against the direction of movement of the piston. The following formula can be used as a rule of thumb to approximate the force F at the workpiece:

 $F = F_{setpoint} \pm F_{friction\;forces} \pm repetition\;accuracy\;of\;pressure\;control$ 

# Data sheet

Positioning characteristics with Soft Stop end-position controller CPX-CMPX, SPC11						
Piston diameter		25	32	40	63	
Mounting position		Any				
Repetition accuracy <sup>1)</sup>	[mm]	±2				
Minimum load, horizontal <sup>2)</sup>	[kg]	2	3	5	12	
Maximum load, horizontal <sup>2)</sup>	[kg]	30	50	75	180	
Minimum load, vertical <sup>2)</sup>	[kg]	2	3	5	12	
Maximum load, vertical <sup>2)</sup>	[kg]	10	15	25	60	
Travel time		→ SoftStop enginee	→ SoftStop engineering software: → www.festo.com			
Recommended proportional directional of	Recommended proportional directional control valve					
For CPX-CMPX	→ Page 25	→ Page 25				
For SPC11		→ Page 26				

- 1) One intermediate position. The accuracy in the end positions depends solely on the design of the end stops
- 2) Load = payload + load of all moving parts on the drive

Electrical data – Displacement encoder	Electrical data – Displacement encoder				
Output signal	•	Digital			
Linearity error <sup>1)</sup>	[%]	< ±0.02, min. ±50 μm			
Max. travel speed	[m/s]	3			
Degree of protection		IP67			
CE marking (see declaration of conformity)		To EU EMC Directive <sup>2)</sup>			
Power supply	[V DC]	24 (±25%)			
Current consumption	[mA]	Typically 100			
Max. temperature coefficient	[ppm/°K]	15			
Electrical connection		Cable with 5-pin plug, round type, M9			
Cable length	[m]	1.5			
Cable quality		Suitable for use with energy chains			

- 1) Always refers to max. stroke.
- For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp → Certificates.
   If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

### Pin allocation

Plugs

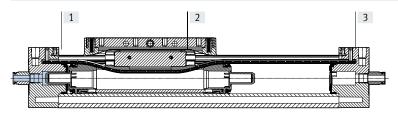


Pin	Function
1	+24 V
2	-
3	0 V
4	CAN_H
5	CAN_L
Housing	Cable shielding

Weight [g]				
Piston diameter	25	32	40	63
Basic weight with 0 mm stroke	1103	1716	2580	8730
Additional weight per 10 mm stroke	34	43	58	139
Moving mass	130	227	350	1669

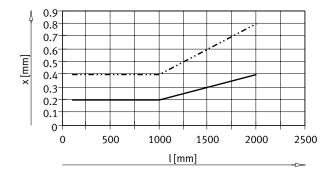
### Materials

Sectional view



Linea	Linear actuators				
[1]	Cylinder profile, housing	Anodised aluminium			
[2]	Slide	Anodised aluminium			
[3]	End cap	Painted aluminium			
-	Seals	NBR, TPE-U(PU)			
-	Cable	PUR			
-	Note on materials	RoHS-compliant			
	PWIS conformity	VDMA24364-B2-L			

### Repetition accuracy x as a function of stroke l



 Horizontal
 Vertical

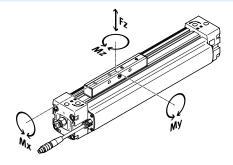
Tubing O.D. of pre-assembled push-in fittings							
Size	Stroke	Ø in [mm]	øin [mm]				
	[mm]	6	8	10	12		
DDLI-25	100 160	•	_	-	_		
	225 2000	_		-	-		
DDLI-32	100		-	-	-		
	160 2000	-	•	-	-		
DDLI-40	100 750	_		_	-		
	850 2000	_	-		-		
DDLI-63	100 300	_	•	-	-		
	360 450	_	_	•	_		
	500 2000	_	_	_	•		

# Data sheet

### **Characteristic load values**

The indicated forces and torques refer to the surface of the slide.

These values must not be exceeded during dynamic operation. Special attention must be paid to the deceleration phase.



If the drive is subjected to two or more of the indicated forces and torques simultaneously, the following equation must be satisfied in addition to the indicated maximum loads:

$$0.4 \cdot \frac{F_{z1}}{F_{z2}} + \frac{M_{x1}}{M_{x2}} + \frac{M_{y1}}{M_{y2}} + 0.2 \cdot \frac{M_{z1}}{M_{z2}} \leq 1$$

$$\frac{F_{z1}}{F_{z2}} \le 1 \qquad \qquad \frac{M_{z1}}{M_{z2}} \le 1$$

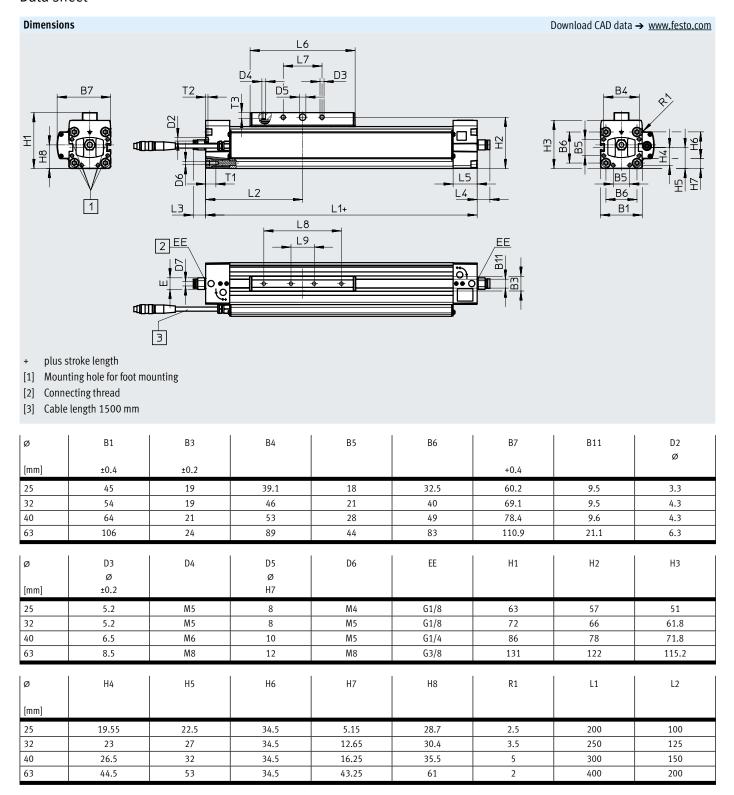
F1/M1 = dynamic value F2/M2 = maximum value

Permissible forces and torques						
Piston diameter		25	32	40	63	
Fz <sub>max.</sub>	[N]	330	480	800	1600	
Mx <sub>max</sub> .	[Nm]	1.2	1.9	3.8	5.7	
My <sub>max.</sub>	[Nm]	20	40	60	150	
Mz <sub>max.</sub>	[Nm]	3	5	8	24	

## Number of central supports MUP as a function of overall length

Excessive distances between the central supports can reduce the positioning accuracy. The following table shows the required minimum number of central supports and foot mountings.

Stroke [mm]	Number of mounting components	Number of mounting components						
	Order code MA	Order code MF	Order code MF					
	Central support	Foot mounting + central support						
	<b>\$</b> =	\$	<b>1</b>					
100 400	2	2	0					
401 600	2	2	1					
601 1200	3	2	1					
1201 1400	3	2	2					
1401 2000	4	2	2					

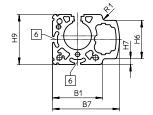


Ø	L5	L6	L7	L8	L9	T1	T2	T3
[mm]			±0.1	±0.1	±0.1			
25	25	109	30	50	-	13	2	7.5
32	31	135	50	100	30	13.2	3	7.5
40	31	171	70	130	40	13.2	3	7.5
63	34	234	110	190	70	21.2	6	12.5

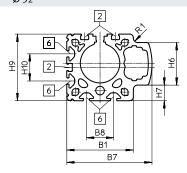
ø	Stroke	D7	E	L3	L4
[mm]	[mm]				
25	100 160	6	15	15.9	16.4
	225 2000	8	16	21.1	21.6
32	100	6	15	15.9	16.4
	160 2000	8	16	21.1	21.6
40	100 750	8	19	16.6	17.2
	850 2000	10	19	23.6	24.3
63	100 300	8	22	15.8	16.3
	360 500	10	22	19.6	20.2
	600 2000	12	24	25.7	26.3

## Profile barrel

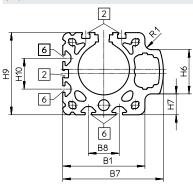
Ø 25



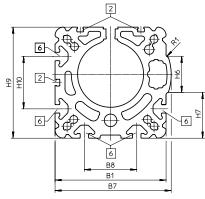
Ø 32



Ø 40



ø 63



ø	B1	B7	B8	Н6	H7	H9	H10	R1
[mm]	+0.4	+0.4				+0.4		
25	45	60.2	-	34.5	5.15	45	-	2.5
32	54	69.1	22	34.5	12.65	54	22	3.5
40	64	78.4	24	34.5	16.25	64	24	5
63	106	110.9	50	34.5	43.3	106	50	2

# Ordering data – Modular product system

<b>Ordering table</b> Piston diameter		25	32	40	63	Condi- tions	Code	Enter code
Module no.		1315779	1344778	1463452	1572299			
Function		Linear drive with integrated displacement encoder					DDLI	DDLI
Piston diameter	[mm]	25	32	40	63			
Stroke	[mm]	100, 160, 225, 3	00, 360, 450, 500, 600	, 750, 850, 1000, 1250	), 1500, 1750, 2000			
Cushioning		Elastic cushionin	g rings/pads at both end	ds			-P	-P
Lubrication		Standard						
		Food-safe lubrica	tion				-H1	
Foot mounting		None						
		1 set					-MF	
Profile mounting		None						
		1 10					MA	
Sensor slot cover		None						
		-	1 set (for the ent	ire drive length and all s	lots)		NS	
Mounting slot cover		None						
		1 set (for the enti	re drive length and all s	lots)			NC	
Slot nut for the mounting slot		None						
		1 50				[1]	NM	
Moment compensator		None						
		Moment compens	sator coupling				T	
Adapter plate		None						
		FKP interface				[2]	AP	
Operating instructions		With operating in	structions					
		Without operating					DN	

<sup>[1]</sup> NM For size 25: Entry "1NM" = delivery quantity 4 pieces

<sup>[2]</sup> AP Only with moment compensator T

# Foot mounting HP (Order code: MF)

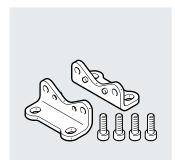
Material: Galvanised steel

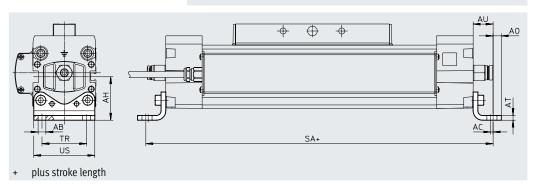
# · 🖢 - Note

Central supports MUP are additionally required for strokes above 400 mm

→ page 17

The foot mounting cannot be used when the bottom mounting position is used for the displacement encoder.





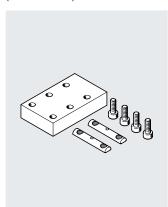
Dimensions and ordering data												
Forø	AB	AC	AH	AO	AT	AU	SA	TR	US	Weight	Part no.	Туре
	ø											
[mm]										[g]		
25	5.5	2	29.5	6	3	13	226	32.5	44	61	150731	HP-25
25 32	5.5 6.6	2	29.5 37	6 7	3	13 17	226 284	32.5 38	44 52	61 117	150731 150732	HP-25 HP-32
		2 2 2		6 7 8.5	3							

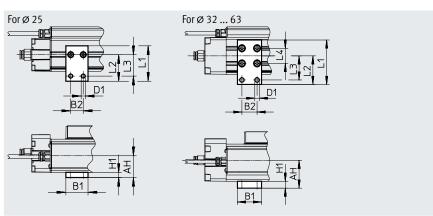
### Central support MUP

(Order code: MA)

### Material:

Anodised aluminium





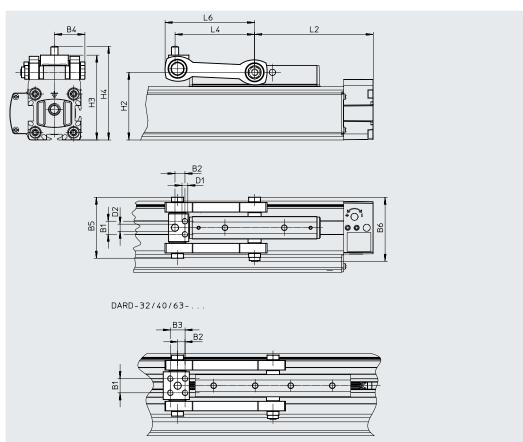
Dimensions and	ordering d	ata										
Forø	AH	B1	B2	D1	H1	L1	L2	L3	L4	Weight	Part no.	Туре
				ø								
[mm]										[g]		
25	29.5	30	17	5.5	7	48	36	29	_	33	1711704	MUP-18/25-P
25 32	29.5 37	30 35	17 22	5.5 6.6	7 10	48 64.5	36 41.5	29 35	- 22	33 89	1711704 150737	MUP-18/25-P MUP-32
	_				7 10 14	-	_					· · · · · · · · · · · · · · · · · · ·

### Moment compensator DARD

(Order code: T)

Material: Galvanised steel





Dimensions and ordering data								
Forø	Max. offset between linear drive and external guide <sup>1)</sup>	Max. permissible load in direction of force	Ambient temperature	Weight				
[mm]	[mm]	[N]	[°C]	[g]				
25	±2.5	800	-10 +60	240				
32	±2.5	1300	-10 +60	275				
40	±2.5	2000	-10 +60	580				
63	±4	5000	-10 +60	1000				

1) Laterally and vertically.

For Ø	B1	B2	В3	B4	B5	В6	D1 Ø	D2 Ø	H2
[mm]									
25	11	8.4	-	25.7±2.5	51.4	54	M5x17	6	57
32	12	6.2	12.4	25.7±2.5	51.4	54	M5x13	6	66
40	18	11	17	36±2.5	72	75.3	M6x16	8	78
63	26	12.6	19	44±4	88	96.4	M8x18	10	122

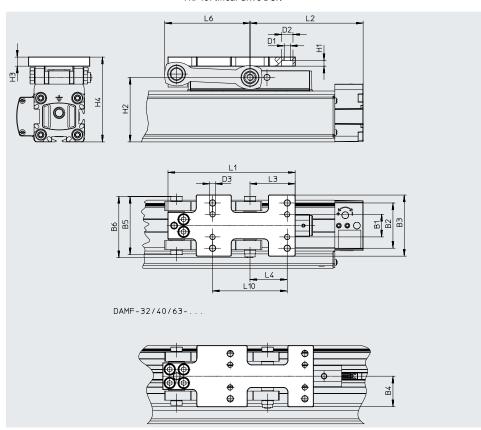
For Ø	Н3	H4	L2	L4	L6	Part no.	Туре
[mm]					max.		
25	71.5±2.5	79±2.5	100	67.1	75.5	2349275	DARD-L1-25-M
32	80.5±2.5	88±2.5	125	80.3	91	2349276	DARD-L1-32-M
40	94.5±2.5	104.5±2.5	150	104	117	2349277	DARD-L1-40-M
63	142±4	152±4	200	138	153	2349279	DARD-L1-63-M

# Adapter plate DAMF

(Order code: AP)

Material: Galvanised steel The adapter plate DAMF has the same interface as the moment compensator FKP for linear drive DGP.





Dimensions and	d ordering data	1										
For Ø	B1	B2	В3	B4	B5	B6	D1	D2	D3	H1	H2	Н3
							Ø	ø				
[mm]												
25	20	40	54	27±2.5	51.4	54	5.5	10	M5	5	57	8
32	20	40	54	27±2.5	51.4	54	5.5	10	M5	5	66	8
40	24	44	58	29±2.5	72	75.3	6.6	11	M6	6	78	10

Forø	H4	L1	L2	L3	L4	L6	L10	Weight	Part no.	Туре
[mm]						max.				
25	75±2.5	112.4	100	40	33	75.5	66	265	2349282	DAMF-25-FKP
32	84±2.5	133	125	40.5	33	91	66	308	2349283	DAMF-32-FKP
40	99±2.5	162	150	45	38	117	76	593	2349284	DAMF-40-FKP
63	146±4	214	200	61	51	153	102	1042	2349286	DAMF-63-FKP

# Accessories

Ordering data						
	Forø	Description	Order code	Part no.	Туре	PU <sup>1)</sup>
Slot nut ABAN, NST					Data sheets →	Internet: hmbn
<b>P</b>	25	For mounting slot	NM	8003032	ABAN-1M4-5	4
	32, 40			150914	NST-5-M5	1
	63			150915	NST-8-M6	
Slot cover ABP					Data sheets =	Internet: abp
	25	For mounting slot	NC	563360	ABP-5-S1	2
	32, 40	Each 0.5 m		151681	ABP-5	
	63			151682	ABP-8	
	25, 32, 40, 63	For sensor slot	NS	563360	ABP-5-S1	2
		Each 0.5 m				

<sup>1)</sup> Packaging unit

Ordering data – Proportional direct	tional control valv	es							
	Forø	Stroke		directional control valve → Internet: vpwp					
	[mm]	[mm]	Part no.	Туре					
	For applications with axis controller CPX-CMAX								
33	25	100 160	550170	VPWP-4-L-5-Q6-10-E					
		225 600	550170	VPWP-4-L-5-Q8-10-E					
الوزي المراجعة		750 2000	550171	VPWP-6-L-5-Q8-10-E					
0000000	32	100	550170	VPWP-4-L-5-Q6-10-E					
		160 360	550170	VPWP-4-L-5-Q8-10-E					
		450 2000	550171	VPWP-6-L-5-Q8-10-E					
	40	100 300	550170	VPWP-4-L-5-Q8-10-E					
		360 750	550171	VPWP-6-L-5-Q8-10-E					
		850 2000	550172	VPWP-8-L-5-Q10-10-E					
	63	100 300	550171	VPWP-6-L-5-Q8-10-E					
		360 450	550172	VPWP-8-L-5-Q10-10-E					
		500 750	550172	VPWP-8-L-5-Q-10-E <sup>1)</sup>					
		850 2000	1552544	VPWP-10-L-5-Q-10-E-G-EX1 1)					

<sup>1)</sup> Push-in fittings for a tubing O.D. of 12 mm must be used for these stroke ranges.

Ordering data – Proportional directi	onal control valves								
	For Ø	Stroke		directional control valve → Internet: vpwp					
	[mm]	[mm]	Part no.	Туре					
	For applications with Soft Stop end-position controller CPX-CMPX, horizontal								
	25	100 160	550170	VPWP-4-L-5-Q6-10-E					
		225 300	550170	VPWP-4-L-5-Q8-10-E					
الوه في أ		360 2000	550171	VPWP-6-L-5-Q8-10-E					
0000000	32	100	550170	VPWP-4-L-5-Q6-10-E					
		160 1000	550171	VPWP-6-L-5-Q8-10-E					
		1250 2000	550172	VPWP-8-L-5-Q-10-E 1)					
	40	100 500	550171	VPWP-6-L-5-Q8-10-E					
		600 750	550172	VPWP-8-L-5-Q-10-E 1)					
		850 2000	550172	VPWP-8-L-5-Q10-10-E					
	63	100 300	550171	VPWP-6-L-5-Q8-10-E					
		360 400	550172	VPWP-8-L-5-Q10-10-E					
		450	1552544	VPWP-10-L-5-Q-10-E-G-EX1 <sup>2)</sup>					
		500 2000	1552544	VPWP-10-L-5-Q-10-E-G-EX1 3)					

- 1) Push-in fittings for a tubing O.D. of 8 mm must be used for these stroke ranges.
- 2) Push-in fittings for a tubing 0.D. of 10 mm must be used for this stroke range.
- 3) Push-in fittings for a tubing 0.D. of 12 mm must be used for these stroke ranges.

Ordering data – Proportional dir	ectional control va	ves					
	For Ø	Stroke	· ·	Proportional directional control valve  Data sheets → Internet: vpwp			
	[mm]	[mm]	Part no.	Туре			
a de la companya de l	For applicati	For applications with Soft Stop end-position controller CPX-CMPX, vertical					
	25	100 160	550170	VPWP-4-L-5-Q6-10-E			
		225 750	550170	VPWP-4-L-5-Q8-10-E			
		850 2000	550171	VPWP-6-L-5-Q8-10-E			
	32	100	550170	VPWP-4-L-5-Q6-10-E			
		160 300	550170	VPWP-4-L-5-Q8-10-E			
		360 1750	550171	VPWP-6-L-5-Q8-10-E			
		2000	550172	VPWP-8-L-5-Q-10-E 1)			
	40	100 225	550170	VPWP-4-L-5-Q8-10-E			
		300 750	550171	VPWP-6-L-5-Q8-10-E			
		850 1000	550171	VPWP-6-L-5-Q-10-E <sup>2)</sup>			
		1250 2000	550172	VPWP-8-L-5-Q10-10-E			
	63	100 225	550170	VPWP-4-L-5-Q8-10-E			
		300	550171	VPWP-6-L-5-Q8-10-E			
		360 450	550172	VPWP-8-L-5-Q10-10-E			
		500 2000	1552544	VPWP-10-L-5-Q-10-E-G-EX1 <sup>3)</sup>			

- 1) Push-in fittings for a tubing 0.D. of 8 mm must be used for these stroke ranges.
- 2) Push-in fittings for a tubing 0.D. of 10 mm must be used for these stroke ranges.
- 3) Push-in fittings for a tubing O.D. of 12 mm must be used for these stroke ranges.

	rectional control val	Stroke		Droportions	l directional control valve		
	FOLD	Sticke			in directional control valve  i→ Internet: mpye		
	[mm]	[mm]		Part no.	Type		
$\wedge$	For applications with Soft Stop end-position controller SPC11-MTS-AIF-2, horizontal						
2	25	100 160		151692	MPYE-5-1/8-LF-010-B		
		225 300		151692	MPYE-5-1/8-LF-010-B		
		360 2000		151693	MPYE-5-1/8-HF-010-B		
	32	100		151692	MPYE-5-1/8-LF-010-B		
		160 1000		151693	MPYE-5-1/8-HF-010-B		
		1250 2000		151694	MPYE-5-1/4-010-B		
	40	100 500		151693	MPYE-5-1/8-HF-010-B		
		600 750		151694	MPYE-5-1/4-010-B		
		850 2000		151694	MPYE-5-1/4-010-B		
	63	100 300		151693	MPYE-5-1/8-HF-010-B		
		360 400		151694	MPYE-5-1/4-010-B		
		450 2000		151695	MPYE-5-3/8-010-B		
rdering data – Proportional di	rectional control val	VPS					
.ac.m5 aata Troportionat ui	For Ø	1			l directional control valve		
				Data sheets	Data sheets → Internet: mpye		
	[mm]	[mm]		Part no.	Туре		
	For applicati	ons with Soft Stop end-position contr	oller SPC11-MTS-AIF-2, verti	ical			
00	25	100 160		151692	MPYE-5-1/8-LF-010-B		
		225 750	225 750		MPYE-5-1/8-LF-010-B		
		850 2000		151693	MPYE-5-1/8-HF-010-B		
	32	100		151692	MPYE-5-1/8-LF-010-B		
*		160 300		151692	MPYE-5-1/8-LF-010-B		
		360 1750		151693	MPYE-5-1/8-HF-010-B		
		2000		151694	MPYE-5-1/8-010-B		
	40	100 225		151692	MPYE-5-1/8-LF-010-B		
		300 750		151693	MPYE-5-1/8-HF-010-B		
		850 1000		151693	MPYE-5-1/8-HF-010-B		
		1250 2000		151694	MPYE-5-1/4-010-B		
	63	100 225		151692	MPYE-5-1/8-LF-010-B		
		300		151693	MPYE-5-1/8-HF-010-B		
		360 450		151694	MPYE-5-1/4-010-B		
		500 2000		151695	MPYE-5-3/8-010-B		
rdering data – Connecting cab	Noc						
rucing data connecting can	Description		Cable length	Part no.	Туре		
			[m]		7,75		
onnection between axis contr	oller CPX-CMAX/end	-position controller CPX-CMPX and pro	portional directional contro	l valve VPWP			
	Angled plug	Angled plug and angled socket 0.25			KVI-CP-3-WS-WD-0.25		
				540328	KVI-CP-3-WS-WD-0.5		
				540329	KVI-CP-3-WS-WD-2		
•			5	540330	KVI-CP-3-WS-WD-5		
			8	540331	KVI-CP-3-WS-WD-8		
	Straight plug and straight socket		2	540332	KVI-CP-3-GS-GD-2		
			5	540333	KVI-CP-3-GS-GD-5		
			8	540334	KVI-CP-3-GS-GD-8		