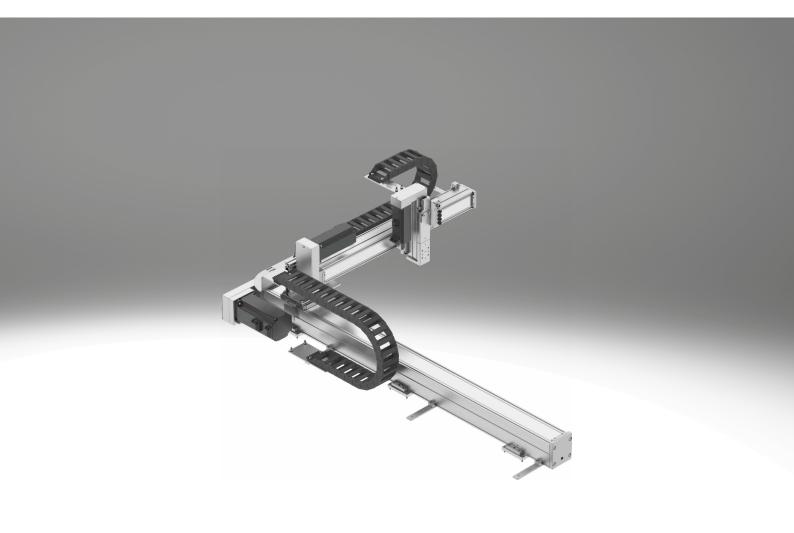
FESTO



At a glance

The cantilever system facilitates movement in 3D space.

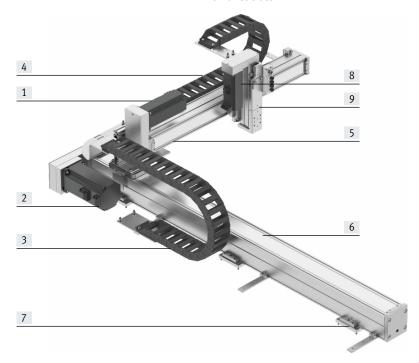
The cantilever system is composed of several axis modules depending on the requirements.

These are all tried-and-tested components from Festo.

- Can be used universally for handling light to medium-weight workpieces or payloads
- Optimum ratio of installation space to working space
- Working space with minimal interfering contours – freely accessible from three sides
- Pneumatic and electric components are freely combinable
- As an electrical solution it is freely positionable/any intermediate positions

Range of applications:

- For any movements in 3D space
- Ideal for line assembly processes
- Cost-effective handling unit in a compact format for small parts handling and simple tasks (YXCR-B)
- [1] Servo motor for the Y-module
- [2] Servo motor for the X-module
- [3] Energy chain for the X-module
- [4] Energy chain for the Y-module
- [5] Y-axis
- [6] X-axis
- [7] Profile mounting/adjusting kit
- [8] Servo motor for the Z-module
- [9] Z-axis



Description of the modules

X-module

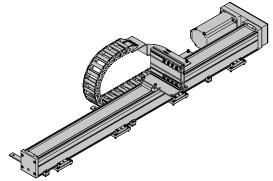
Design:

The X-module EHMX-AS comprises a linear axis which is powered by a servo or stepper motor.

Adapters are mounted on the slide of the X-axis to connect the Y-module. The position of the motor and energy chain can be selected using the configurator. The following components are located on the motor side:

- Energy chain (optional)
- Multi-pin plug distributor for proximity switch (if a sensor package has been selected)





Description of the modules

Y-module

Design:

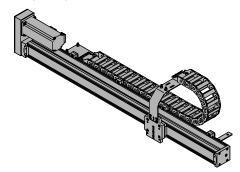
The Y-module EHMY comprises a linear axis which is powered by a servo or stepper motor.

Adapters are mounted on the slide of the Y-axis to connect the Z-module. The position of the motor and energy chain is dependent on the position of the motor on the X-module.

The following components are located on the motor side:

- Energy chain (optional)
- Multi-pin plug distributor for proximity switch (if a sensor package has been selected)

Sample image:



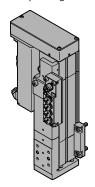
Z-module

Design:

The Z-module EHMZ comprises an electric drive, the DHMZ comprises a pneumatic drive. Based on the configuration, an energy chain is optionally installed as a cable guide depending on the axis type and stroke.

The Z-module can be selected using the configurator, depending on the application.

Sample image:



Key features

Dispatch options

Fully assembled:

The cantilever system is fully assembled. All cables and tubing are installed and connected. The system is already set up on delivery, but must be adapted to the particular mounting surface during installation.

Note flatness → table below.

Partially assembled:

The cantilever system is delivered partially assembled. This means that all three axis modules (X-/Y-/Z-axis) are assembled, each with the optional motors. The partially assembled system must be completed by the customer. Help can be found in the assembly instructions provided.

Optional accessories (→ page 9) are enclosed.

Note flatness → table below.

System overview ¹⁾		
Size	YXCA-1-B	YXCA-2-B
Max. working stroke	X: 800 mm	X: 1000 mm
	Y: 300 mm	Y: 400 mm
	Z: 150 mm	Z: 200 mm
Max. payload	Dependent on the selected dynamic response	
Required flatness of the mounting surface	≤ 0.1 mm/m	
Mounting position	Horizontal	

 $^{1) \}quad \hbox{ Drive package depends on the configuration selected.}$

Configurator: Handling Guide Online (HGO)

Selecting a handling system

Planning complex handling systems takes a lot of time. You can use the configurator "Handling Guide Online" (HGO) to design a customised handling system for your application in just a few steps.

You can choose from the following systems:

- Single-axis system
- 2D linear gantry
- 2D planar surface gantry
- Three-dimensional gantry
- 3D cantilever system

Selecting the handling solution Select your handling system Single-axis movement: Single-axis module as a complete system. Easy to connect to your own front unit. Animation Animation O 2D linear garntry Movements in 2D in the vertical working space: Linear garntres as complete systems. Electric and pneumatic axes can be combined



Movements in 2D in the horizontal working space Planar surface gantries as complete systems. Combining electric axes. Easy to connect to your own Z unit.

Movements in 3D:

■ Animation

*

Three-dimensional gantries as complete systems Electric and pneumatic axes can be combined Animation

O 3D cantilever system

Movements in 3D: Cantilever system as complete system. Electric and pneumatic axes can be combined

Advantages:

- Automatic selection of all relevant components
- Automatic design and calculation of the workload
- Quote created automatically
- CAD model available immediately
- Configuration-specific parameters for servo drives available immediately
- Complete Eplan project can be ordered according to the individual configuration
- Fully automated processing
- You can order fully or partially assembled systems through the Online Shop
- Lots of possible options

Entering the application data

- Payload
- · Drive system of the axis
- Distance from the centre of the load
- Working stroke
- Reference cycle

Axis definition and payload Axis definition Drive system of the axis X Electric: several positions Y Electric: several positions Z Electric: several positions V I 120 mm i Y 120 mm Working stroke in Z direction i Z 50 mm Take the stroke reserve into account in your specification Payload Payload Distance from the centre of the load i X mm i Y mm i Z mm Electric: several positions V Elec

Configurator: Handling Guide Online (HGO)

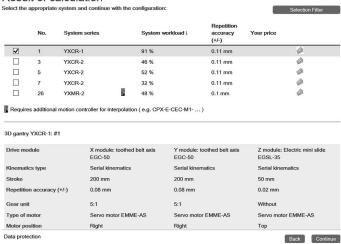
Result of the calculation

You will be offered a selection of systems that have been calculated based on the application data you entered.

The following are available immediately:

- CAD model
- Datasheet of the selected system
- Price information

Result of calculation



System overview

You will be given an overview of the complete system.

You will also have the following options:

- Show price
- · Send request
- Add to basket

Your handling solution







Back

Standard components within the handling system

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. The single axes installed will be displayed in the configurator HGO on the "Result of calculation" page.

Drives/axes

X-axis

Ball screw axis ELGC-BS



- Electrical
- Optimal installation space to working space ratio
- Protected against external influences by internal guide
- · Various spindle pitches

Y-axis

Ball screw axis ELGC-BS



- Electrical
- Optimal installation space to working space ratio
- Protected against external influences by internal guide
- Various spindle pitches

Z-axis

Mini slide EGSC



• Electrical

- Compact design
- High load capacity
- Precision guide and ball screw
- Easy adjustment of end positions

Mini slide DGST



Pneumatic

electric: EGSC-45

- Precise and resilient roller bearing guide
- Slide and yoke plate as a single component
- High dynamic response

Possible axis o	Possible axis combinations 1)					
Size	X-module Y-module		Z-module			
YXCA-1-B	Ball screw axis ELGC-60-BS	Ball screw axis ELGC-45-BS	Mini slide pneumatic: DGST-8/12 electric: EGSC-32			
YXCA-2-B	Ball screw axis ELGC-80-BS	Ball screw axis ELGC-60-BS	Mini slide pneumatic: DGST-12/16			

¹⁾ Drive package depends on the configuration selected.

Standard components within the handling system

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. You can alter the scope and design of the drive package in the configurator HGO on the "System configuration" page.

Motors and controllers

Servo motors EMMB-AS





- Dynamic, brushless, permanently excited servo motor
- Digital absolute displacement encoder in single-turn or multi-turn version
- With optional brake
- Two-phase hybrid technology
- Digital absolute displacement encoder in single-turn or multi-turn version
- Simple connection technology (OCP: one cable plug) – hybrid cable: motor cable and connecting cable for supply and encoder in one
- Plug can be rotated 310°
- · With optional brake

Stepper motors EMMB-ST



- Two-phase hybrid technology
- Digital absolute displacement encoder in single-turn or multi-turn version
- Simple connection technology (OCP: one cable plug) – hybrid cable: motor cable and connecting cable for supply and encoder in one
- Can be positioned to the front or the rear
- · With optional brake

Servo drive CMMT-AS, for servo motor



- Universal servo drive
- For synchronous servo motors
- Integrated EMC filters
- Integrated brake chopper
- · Integrated braking resistor
- Position controller
- Speed controller
- Force controller
- Range of control functions

Options:

- Safety function: safe torque off (STO)/ category 4, Performance Level e
- Safe stop 1 (SS1)
- Safe brake control (SBC) up to SIL3/ category 3, Performance Level e
- Bus protocols
 - EtherCAT[®]
 - PROFINET RT/IRT
 - EtherNet/IP
 - Modbus TCP

Servo drive CMMT-ST, for stepper motor



- Servo drive for operating stepper motors and brushless direct current motors
- Options for point-to-point and interpolating motion and for precise positioning
- Primary voltage from 24 ... 48 V DC
- Position controller
- Speed controller
- Force controller
- · Range of control functions

Options:

- Safety function: safe torque off (STO)/ category 3, Performance Level e
- Safe stop 1 time controlled (SS1-t)
- · Bus protocols
- EtherCAT®
- PROFINET RT/IRT
- EtherNet/IP
- Modbus TCP

Module/motor combinations

We recommend that the three-dimensional gantry is operated with the proposed motors from Festo. These precisely match the mechanical system. When using third-party motors, it is essential that the technical limits are observed.

Module	Motor		
	Servo motor	Stepper motor	
X-module			
EHMX-ELGC-60-BS	EMMB-AS-80-07	EMMT-ST-57-L	EMMB-ST-57-L
EHMX-ELGC-80-BS	EMMB-AS-80-07	EMMT-ST-87-M	EMMB-ST-87-M
Y-module			
EHMY-RP-ELGC-45-BS	EMMB-AS-40-01	EMMT-ST-42-L	EMMB-ST-42-L
EHMY-RP-ELGC-60-BS	EMMB-AS-60-04	EMMT-ST-57-L	EMMB-ST-57-L
Z-module			
EHMZ-EGSC-32	EMMB-AS-40-01	EMMT-ST-42-L	EMMB-ST-42-L
EHMZ-EGSC-45	EMMB-AS-40-01	EMMT-ST-42-L	EMMB-ST-42-L

Ordering data – Accessories

Ordering data				
		Cable length [m]	Part no.	Туре
For servo motor EMMB-AS				
Motor cable				
	For EMMB-AS-40/60/80 with CMMT-AS	2.5	5219197	NEBM-H6G4-E-2.5-Q13N-LE4
		5	5219198	NEBM-H6G4-E-5-Q13N-LE4
		7.5	5219199	NEBM-H6G4-E-7.5-Q13N-LE4
		10	5219200	NEBM-H6G4-E-10-Q13N-LE4
		15	8097203	NEBM-H6G4-E-15-Q13N-LE4
Encoder cable				
	For EMMB-AS-40/60/80 with CMMT-AS	2.5	5219213	NEBM-REG6-E-2.5-Q14N-REG6
		5	5219214	NEBM-REG6-E-5-Q14N-REG6
		7.5	5219215	NEBM-REG6-E-7.5-Q14N-REG6
		10	5219216	NEBM-REG6-E-10-Q14N-REG6
		15	8097200	NEBM-REG6-E-15-Q14N-REG6
Connecting cable for brake				
Connecting capie for brake	For EMMB-AS-40/60/80 with CMMT-AS	2.5	5219205	NEBM-H7G2-E-2.5-Q14N-LE2
	Tot Emmo 7.5 40/00/00 with emmi 7.5	5	5219206	NEBM-H7G2-E-5-Q14N-LE2
		7.5	5219207	NEBM-H7G2-E-7.5-Q14N-LE2
		10	5219208	NEBM-H7G2-E-10-Q14N-LE2
		15	8097206	NEBM-H7G2-E-15-Q14N-LE2
A 1 4	Land to be a second to 0			,
Adapter for encoder cable (a		Familiant to	iish Cas	MTAC
	• For EMMB-AS-40/60/80 with CMMT-AS	0.5	version with CM 8097197	NEFM-REG6-K-0.5-R3G8
		0.5	809/19/	NEFM-REGO-R-U.3-R3G6
<u> </u>	For EMMB-AS-40/60/80 with CMMT-AS	For multi-turn v	version with CMN	NT-AS ¹⁾
		0.5	8097195	NEFM-REG6-K-0.5-B-R3G8
		For multi-turn v	ersion with CMA	MB-AS ¹⁾
		0.5	8097196	NEFM-REG6-K-0.5-B-REG6

¹⁾ The required battery is not included in the scope of delivery

Designation	Description	Cable length [m]	Part no.	Туре
For stepper motor EN	MMT-ST			
Motor cable				
	For EMMT-ST-42 with CMMT-ST	2.5	8181670	NEBM-M17G12-EH-2.5-Q6N-LE12
		5	8181668	NEBM-M17G12-EH-5-Q6N-LE12
	26	7	8190096	NEBM-M17G12-EH-7.5-Q6N-LE12
		10	8195457	NEBM-M17G12-EH-10-Q6N-LE12
		15	8214679	NEBM-M17G12-EH-15-Q7N-LE12
	For EMMT-ST-57 with CMMT-ST	2.5	8181670	NEBM-M17G12-EH-2.5-Q6N-LE12
		5	8181668	NEBM-M17G12-EH-5-Q6N-LE12
		7	8195460	NEBM-M17G12-EH-7.5-Q7N-LE12
		10	8195461	NEBM-M17G12-EH-10-Q7N-LE12
		15	8214683	NEBM-M17G12-EH-15-Q9N-LE12
	For EMMT-ST-87 with CMMT-ST	2.5	8195458	NEBM-M17G12-EH-2.5-Q7N-LE12
		5	8195459	NEBM-M17G12-EH-5-Q7N-LE12
		7	8214681	NEBM-M17G12-EH-7.5-Q9N-LE12
		10	8214682	NEBM-M17G12-EH-10-Q9N-LE12
		15	8214683	NEBM-M17G12-EH-15-Q9N-LE12
Designation	Description	Cable length [m]	Part no.	Туре
For stepper motor EA	MMB-ST			
Motor cable				I
	For EMMB-ST-42 with CMMT-ST	2.5	8181675	NEBM-L5G14-EH-2.5-Q6N-LE12
N. C.		5	8181664	NEBM-L5G14-EH-5-Q6N-LE12
		7	8181676	NEBM-L5G14-EH-7.5-Q6N-LE12
		10	8181672	NEBM-L5G14-EH-10-Q6N-LE12
		15	8214680	NEBM-L5G14-EH-15-Q6N-LE12
	• For EMMB-ST-57 with CMMT-ST	2.5	8181677	NEBM-L10G14-EH-2.5-Q6N-LE12
		5	8181667	NEBM-L10G14-EH-5-Q6N-LE12
			04044	
		7	8181674	NEBM-L10G14-EH-7.5-Q7N-LE12
		10	8181673	NEBM-L10G14-EH-10-Q7N-LE12
		10 15	8181673 8214689	NEBM-L10G14-EH-10-Q7N-LE12 NEBM-L10G14-EH-15-Q9N-LE12
	• For EMMB-ST-87 with CMMT-ST	10 15 2.5	8181673 8214689 8181666	NEBM-L10G14-EH-10-Q7N-LE12 NEBM-L10G14-EH-15-Q9N-LE12 NEBM-L10G14-EH-2.5-Q7N-LE12
	• For EMMB-ST-87 with CMMT-ST	10 15 2.5 5	8181673 8214689 8181666 8181671	NEBM-L10G14-EH-10-Q7N-LE12 NEBM-L10G14-EH-15-Q9N-LE12 NEBM-L10G14-EH-2.5-Q7N-LE12 NEBM-L10G14-EH-5-Q7N-LE12
	For EMMB-ST-87 with CMMT-ST	10 15 2.5 5 7	8181673 8214689 8181666 8181671 8214687	NEBM-L10G14-EH-10-Q7N-LE12 NEBM-L10G14-EH-15-Q9N-LE12 NEBM-L10G14-EH-2.5-Q7N-LE12 NEBM-L10G14-EH-5-Q7N-LE12 NEBM-L10G14-EH-7.5-Q9N-LE12
	For EMMB-ST-87 with CMMT-ST	10 15 2.5 5	8181673 8214689 8181666 8181671	NEBM-L10G14-EH-10-Q7N-LE12 NEBM-L10G14-EH-15-Q9N-LE12 NEBM-L10G14-EH-2.5-Q7N-LE12 NEBM-L10G14-EH-5-Q7N-LE12

Possible cable and tube lengths

- Cables and tubing are selected so that the length specified when ordering will be the minimum connection length from the energy chain output.
- Cables and tubing are only available in fixed lengths as stated in the table below. This can mean that the cable plugs of the different cables do not end at the same point.

Length	1 m	2 m	5 m	7 m	10 m
Motor cable	-	•	•	•	•
Encoder cable	-		•	•	•
Multi-pin plug connecting cable	-	•	•	•	•
Tubing (for DHMZ only)	•	•	•	_	-

Standard components within the handling system

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. You can alter the scope and design of the accessories in the configurator HGO on the "System configuration" page.

Designation	Description		Cable length	Part no.	Туре
Proximity switch (inc	luctive) for sensing the position of the slide on the X-/Y-/Z-a	axis			
	Cable with open end				
	For ball screw axis ELGC-BS	PNP, N/C contact	7.5 m	551391	SIES-8M-PO-24V-K-7.5-OE
	For mini slide EGSC	PNP, N/O contact	7.5 m	551386	SIES-8M-PS-24V-K-7.5-0E
	For DC voltage	NPN, N/C contact	7.5 m	551401	SIES-8M-NO-24V-K-7.5-OE
	Included if the "Festo sensor package" is selected:	NPN, N/O contact	7.5 m	551396	SIES-8M-NS-24V-K-7.5-OE
	For ELGC: 2 pieces				
	For EGSC: 1 piece				
Proximity switches (nagneto-resistive) for sensing the position of the slide on t	he Z-axis			
	For mini slide DGST-8/-12	PNP, N/O contact	2.5 m	551375	SMT-10M-PS-24V-E-0.3-L-M8D
	For DC voltage	NPN, N/O contact	2.5 m	551379	SMT-10M-NS-24V-E-0.3-L-M8D
	Included if the "Festo sensor package" is selected:				
	• 2 pieces				
	For mini slide DGST-16/-20	PNP, N/O contact	2.5 m	574334	SMT-8M-A-PS-24V-E-0.3-M8D
	For DC voltage	NPN, N/O contact	2.5 m	574339	SMT-8M-A-NS-24V-E-0.3-M8D
5	Included if the "Festo sensor package" is selected:		•		
ON THE STATE OF TH	• 2 pieces				
(1) I					

Designation	Description	Cable length	Part no.	Туре
Plug socket with cable				
	Connection between multi-pin plug distributor NEDU and control cabinet	5 m	525618	SIM-M12-8GD-5-PU
		10 m	570008	SIM-M12-8GD-10-PU
Plug				
	For connection to the multi-pin plug distributor NEDU / distributor NEDY	_	562024	NECU-S-M8G3-HX
Connecting cable				
	Connection between distributor NEDY and control cabinet	2.5	8078227	NEBA-M8G4-U-2.5-N-LE4
		5	8078228	NEBA-M8G4-U-5-N-LE4
		7.5	8215486	NEBA-M8G4-U-7.5-N-LE4
		10	8078229	NEBA-M8G4-U-10-N-LE4
		15	8215487	NEBA-M8G4-U-15-N-LE4

Designation	Description	Cable length	Part no.	Туре		
Multi-pin plug distributor	Aulti-pin plug distributor					
	With the help of the multi-pin plug distributor, all electrical signals such as for end-position sensing can be transferred 4 individual connections	_	574586	NEDU-L4R1-M8G3L-M12G8		
	With the help of the distributor, all electrical signals such as for end-position sensing can be transferred 2 individual connections	_	8005312	NEDY-L2R1-V1-M8G3-N-M8G4		

Designation Description

Motor controller/servo drive



The accessories for the relevant motor controllers/servo drives can be found at:

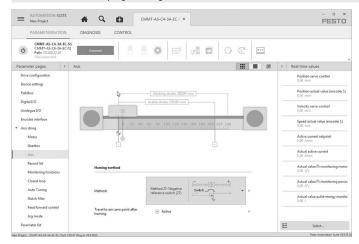
•	www.fes	to.com/	cata	logue/	cmm	
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Designation	Description		Part no.	Туре	
Adjusting kit					
a M.S.	Used to mount the handling system on the supporting	EHMXELGC-60-BS	8142650	EADC-E15-60-E22	
	surface	EHMXELGC-80-BS	8142651	EADC-E15-80-E22	
Can be used to easily compensate for any unevenness in the bearing surface					
Profile mounting	Used to mount the handling system on the supporting	EHMXELGC-60-BS	8142652	EAHM-E15-60-E22	
	surface	EHMXELGC-80-BS	8142653	EAHM-E15-80-E22	
	It is not height-adjustable				

Programming aid

Festo Automation Suite

Parameterisation and programming software for electronic devices from Festo



- Parameterisation, programming and commissioning in a clear and user-friendly interface
- Optimum support for complex processes thanks to guided wizards (e.g. for commissioning, drive configuration, etc.)
- Fast access to the required documents and additional information
- Easy integration of electric drives in the controller programming