# Feed separators HPV





#### Feed separators HPV

#### Key features

#### Separation of workpieces in the feed process Previously

- At least 2 drives, 2 valves and 4 proximity sensors
- Extensive programming



High functionality



#### **Operating principle**

Plunger A is retracted. The locking mechanism locks plunger B.

Plunger A advances.



The locking mechanism prevents plunger A from retracting until plunger B is fully advanced.



#### Now

- One unit (1 drive, 1 valve and 2 proximity sensors)
- Cheaper
- Reliable
- No programming required



- [1] Corrosion-resistant thanks to stainless steel plungers
- [2] Optimum and precise adaptation options using centring sleeves
- [3] Supply ports optionally at top or rear
- [4] Proximity sensors suitable for integration in the housing can be used (type SME/SMT-8)

The locking mechanism prevents plunger B from retracting until plunger A is fully advanced.



- Note

An integrated mechanical interlock between the two plungers ensures that one plunger cannot retract until the other has advanced. Both plungers are briefly extended during switching and the part to be separated is enclosed.

Plunger B advances.



# Peripherals overview and type codes

#### Peripherals overview



#### Accessories

		Description	→ Page/Internet
[1]	Centring sleeve, connecting sleeve	For centring when mounting	9
[2]	Proximity sensor	For position sensing, integrated in sensor slot	9
[3]	QS push-in fitting	For connecting compressed air tubing with standard O.D.	qs

#### Type codes

001	Series
HPV	Separator, double-acting
002	Size
10	10
14	14
22	22

003	Stroke
10	10
20	20
30	30
40	40
60	60
004	Position sensing
Α	For proximity sensor

#### Feed separators HPV

#### Data sheet





Stroke length 20 ... 60 mm

# -

#### General technical data

Size	10	14	22		
Pneumatic connection	M5/M3	M5/M5			
Mode of operation	Double-acting	L.			
Operating medium	Compressed air to ISO 8573-1:2010	[7:4:4]			
Note on the operating/pilot medium	Lubricated operation possible (in whi	ich case lubricated operatio	n will always be required)		
Design	Double piston				
	Piston rod				
	Locking mechanism				
	Non-rotating				
Protection against rotation/guide	Square				
Max. interchangeability [mm]	0.3				
Cushioning	None				
Position sensing	Via proximity sensor				
Type of mounting	With through-hole				
	Via female thread				
Mounting position	Any				

#### Operating and environmental conditions

Operating and environmental conditions				
Operating pressure	[bar]	38		
Ambient temperature	[°C]	+5+60		
Degree of protection		IP40		
Corrosion resistance class CRC <sup>1)</sup>		2		

1) Corrosion resistance class CRC 2 to Festo standard FN 940070

Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment.

Forces [N]			
Size	10	14	22
Theoretical force at 6 bar Advancing	45	90	225
Theoretical force at 6 bar Retracting	35	75	180

Weight [g]					
Size	10	14		22	
Stroke	10	20	40	30	60
Product weight	135	290	460	950	1 500

#### Materials

Sectional view



#### Feed separator

1000		
[1]	Plunger	High-alloy steel
[2]	Housing	Wrought aluminium alloy (with CompCoat)
[3]	Locking mechanism	Case-hardened steel
[4]	Piston rod	High-alloy steel
[5]	End cap	High-alloy steel
-	Seals	Nitrile rubber
	Note on materials	Copper/PTFE-free
		RoHS-compliant

#### - 📲 - Note

The plunger slideways in the housing are determined by choosing the appropriate fit, and cannot be adjusted. The necessary basic lubrication is applied during assembly. We recommend that the feed separator be re-lubricated after 2 million cycles.

#### Cycle times [ms] without add-on plunger separators at 6 bar (unrestricted)



1) If the max. permissible weights of the add-on plunger separators are exceeded, the retracting and advancing times must be adapted in accordance with the table below using one-way flow control valves. Failure to do so may result in components of the feed separator being damaged.

#### Retracting and advancing times [s] with add-on plunger separators as a function of the mass [g] of the plunger separators

Retracting and advancing times [s] with add-on plunger separators as a function of the mass [g] of the plunger separators							
Size		10	14 22		22		
Stroke		10	20	40	30	60	
Weight force	100 g	0.03	-	-	-	-	
	200 g	0.04	0.03	0.05	-	-	
	300 g	0.05	0.04	0.08	-	-	
	400 g	0.06	0.05	0.11	0.24	0.48	
	500 g	-	0.07	0.13	0.3	0.6	
	600 g	-	-	-	0.36	0.72	
	700 g	-	-	-	0.42	0.84	
	800 g	-	-	-	0.48	0.96	

#### Permissible characteristic static load values at the plungers



Size		10	14	22	
Force F	[N]	75	100	180	
Torque Mx	[Nm]	3	5	9	
Torque My	[Nm]	3	5	9	
Torque Mr	[Nm]	3	5	9	

#### Plunger backlash



Size		10	14		22	
Stroke		10	20	40	30	60
S <sub>x</sub>	[mm]	0.05	0.05	0.05	0.05	0.05
Sz	[mm]	0.03	0.03	0.03	0.03	0.03
α <sub>x</sub>	[°]	0.12	0.12	0.07	0.06	0.04
α <sub>y</sub>	[°]	0.2	0.2	0.12	0.11	0.07
α	[°]	0.262	0.175	0.175	0.12	0.12

#### Minimum clearances

To prevent malfunctioning of the proximity sensors, the feed separators must comply with the minimum clearances specified in the table.



Size		10	14	22
For SME-8	[mm]	60	59	73
For SMT-8B	[mm]	60	54	69

#### Projection of proximity sensors



Size		10	14	22	
For SME-8	[mm]	max. 14 <sup>1)</sup>			
For SMT-8	[mm]	max. 22 <sup>1)</sup>			

1) Depending on mounting position

#### Mounting options

Only the underside (opposite the supply ports) may be used as a mounting surface.



#### Surface finish and positional accuracy of bearing surface



#### Dimensions



[1] Sensor slot for proximity sensor

[2] Choice of supply port

[3] Centring sleeves (2 included in scope of delivery)

[4] Stroke

Туре	B1	B2	B3	B4	B5	D1	D2	D3 H8/h7	D4 H13	D5 H13	D6 H13	EE	EE1	H1
			±0.02	±0.05		ø		п8/11/ Ø	Ø	Ø	Ø			
HPV-10-10-A	47	6	7	20	7	5.3	M4	7	6	-	3.2	M5	M3	78
HPV-14-20-A	60	12	10	30	10	5.3	M5	7	7.4	-	4.2	M5	M5	119
HPV-14-40-A	60	12	10	30	10	5.3	M5	7	7.4	-	4.2	M5	M5	189
HPV-22-30-A	78	13	14	38	11	8.4	M8	12	10.4	6.2	6.2	M5	M5	175
HPV-22-60-A	78	13	14	38	11	8.4	M8	12	10.4	6.2	6.2	M5	M5	280
							1							
Туре	H2	H3	H4	H5 <sup>1)</sup>	H6	H7	H8	H9	L1	L2	T1	T2	T3	T5
			±0.1		±0.2	±0.1	±0.5				+0.1		min.	-0.3
HPV-10-10-A	53	24.5	16	30	7	4	10	7.5	18	9	1.6	3.1	4	1.4
HPV-14-20-A	79	36	20	30	10	5	20	36	19	7	1.6	4.6	5	1.4
HPV-14-40-A	129	56	20	60	10	5	40	56	19	7	1.6	4.6	5	1.4
HPV-22-30-A	115	48	40	60	14	8	30	48	32	16	2.6	6.1	5	2.4
	190	78	40	120	1	8	60	78	32	16	2.6	6.1	5	2.4

1) Tolerance for centring hole ±0.02

Tolerance for thread and through-hole ±0.1

#### Ordering data

Ordering data			
Size	Stroke		
	[mm]	Part no.	Туре
10	10	550908	HPV-10-10-A
14	20	529351	HPV-14-20-A
	40	529352	HPV-14-40-A
22	30	529353	HPV-22-30-A
	60	529354	HPV-22-60-A

Download CAD data → <u>www.festo.com</u>

# Accessories

Orde	ring data			Data sheets → Inter	net: zbh
		For size	Part no.	Туре	PU <sup>1)</sup>
Centr	ring sleeve Z	3H			
	\ \	10, 14	8146544	ZBH-7-B	10
		22	189653	ZBH-12	10

1) Packaging unit

Ordering data	a – Proximity sensor for T-slot, magneto-resist Type of mounting	<b>ve</b> Switching output	Electrical connection	Cable length [m]	Part no.	Data sheets → Internet: smt Type	
N/O contact							
E BERN	Inserted in the slot from above, flush with t cylinder profile, short design	ne PNP	Cable, 3-wire Plug M8x1, 3-pin	2.5 0.3	574335 574334	SMT-8M-A-PS-24V-E-2.5-OE SMT-8M-A-PS-24V-E-0.3-M8D	
Ordering data	a – Proximity sensor for T-slot, magnetic reed					Data sheets $\rightarrow$ Internet: smoothed by the state of the s	
	Type of mounting	Switching output	Electrical connection	Cable length [m]	Part no.	Туре	
N/O contact							
<b>6.</b> 87	Inserted in the slot lengthwise, flush with the cylinder profile	e Contacting	Cable, 3-wire Plug M8x1, 3-pin	2.5 0.3			
)rdering data	a – Connecting cables Electrical connection, left	Electrical co	nnection, right	Cable length [m]	Part no.	Data sheets → Internet: neb	
$\sim$	Straight socket, M8x1, 3-pin	Cable, open	end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3	
1 June				5	541334	NEBU-M8G3-K-5-LE3	
g	Straight socket, M12x1, 5-pin	Cable, open	Cable, open end, 3-wire		541363	NEBU-M12G5-K-2.5-LE3	
					541364	NEBU-M12G5-K-5-LE3	
	Angled socket, M8x1, 3-pin	Cable, open	end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3	
SE I		Cable and		5	541341	NEBU-M8W3-K-5-LE3	
	Angled socket, M12x1, 5-pin	Cable, open	end, 3-wire	2.5 5	541367 541370	NEBU-M12W5-K-2.5-LE3 NEBU-M12W5-K-5-LE3	
Ordering data	a – Slot cover						
_	Mounting	Length [m]				Туре	
	Inserted from above	2 x 0.5	2 x 0.5			ABP-5-S	
)rdering data	a – One-way flow control valves					Data sheets → Internet: grla-m5-q	
	Connection		Material			Type	
		ubing O.D.			Part no.		
) (O)	M5 3		Metal design	Metal design		GRLA-M5-QS-3-D	
5	4				193137 193138	GRLA-M5-QS-4-D	
OWNER	6			193139		GRLA-M5-QS-6-D	