



Linear modules HMP

Key features

At a glance

- O- New

- Sturdier
- Optimised end stop system
- Optimised intermediate position module
- Minimised susceptibility to wear
- One-way flow control valves that can be externally adjusted
- Integrated sensor strip

- Diameters of 16 ... 32 mm
- Stroke lengths of 50 ... 400 mm
- Extremely rigid basic profile
- Infinitely adjustable end stops
- Rotatable yoke plate
- Integrated clamping unit
- Precision backlash-free guide system
- Freely adjustable intermediate position
- Adjustable end-position cushioning

- Integrated sensors:
 - Sensor strip for proximity sensors for end-position sensing
 - Mounting slot for proximity sensors for position sensing
- Functional end cap:
 - Pneumatic interface
 - Electrical interface
- Highly flexible thanks to various mounting and assembly options:
 - Basic profile – Yoke plate
- Large selection of adapters for:
 - Drives
 - Grippers
- Innovative and user-friendly installation system



1 Yoke plate

Can be turned to any angle from 0 to 360°. The yoke plate cannot be turned if combined with the clamping unit. Drives and grippers can be mounted on the yoke plate by means of adapter kits (direct mounting or dovetail connections).

2 Guide system

Extremely high rigidity thanks to the hardened steel guide barrel which is supported in pre-loaded and backlash-free recirculating ball bearing guides guaranteeing the utmost precision.

3 Basic profile Drives and basic components can be attached to the rigid light

 alloy profile using adapter, connector and component kits.
End-position cushioning.
Extremely dynamic operation thanks to hydraulic shock absorbers which cushion the piston sleeve at the end positions.

5 End stop

Any desired intermediate position can be set between minimum and maximum stroke (plus the strokes of the shock absorbers).

Linear modules HMP

Key features

FESTO

Wide choice of variants

End stop

The optimised end stop system is practically wear-free. Rough adjustment is performed by moving the stop into the profile groove. Fine adjustment is performed using compressed air via a rotatable sleeve.

Clamping unit

The pneumatically-powered clamping unit can be used to hold loads at any end position and with the module installed at any angle. In the case of a pressure drop or pressure failure, the clamping unit acts like an EMERGENCY STOP device. The clamping unit can be released by means of the manual override.



End cap

Connections can be made on the top and bottom of the end cap. Pneumatic tubing and electrical cables can be bundled and routed through the end cap via conduits. Max. 6 proximity sensors can be connected to the integral terminal strip. The switching states of the proximity sensors are indicated via a display window in the end cap.



Intermediate position module

The intermediate position module permits advancing to an additional position between the two end positions. This is done by swivelling a lever into the traversing range of the moving stop on the guide tube. The intermediate position can be activated during the advancing stroke or retracting stroke, depending on the type of design. Multiple intermediate position modules can be installed on request.



Linear modules HMP

Key features

Mounting options			
	Dovetail mounting using connecting kit HAVB	Direct mounting using screws and slot nuts NST	Direct mounting using screws and centring sleeves ZBF
			ි පු
Mounting surfaces	×		
On the side	HMP-16/-20/-25/-32	HMP-16/-20/-25/-32	
of the basic profile			
On the underside	HMP-16/-20/-25/-32	HMP-25/-32	HMP-16/-20
of the basic profile			
On the yoke plate	HMP-16/-20/-25/-32	HMP-25/-32	HMP-16/-20/-25/-32

Linear modules HMP System example

System product for handling and assembly technology



Syste	em elements and accessories		
		Description	→ Page/Internet
1	Drives	Wide range of combination options within handling and assembly technology	drive
2	Grippers	Wide range of optional variants within handling and assembly technology	gripper
3	Adapters	For drive/drive combinations	29
		For drive/gripper combinations	gripper
4	Basic components	Profiles and profile combinations as well as profile/drive combinations	basic component
5	Installation components	For achieving a clear-cut, safe layout of electrical cables and tubing	installation component
-	Axes	Wide range of combination options within handling and assembly technology	axes
-	Motors	Servo and stepper motors, with or without gearing	motor

Linear modules HMP

Peripherals overview



Acce	ssories		
		Brief description	→ Page/Internet
1	Clamping unit	For holding loads in all mounting and end positions in the event of a drop in pressure	24
	KP		
2	End cap	The end cap (EL) houses an integrated electrical interface	24
	AD/EL		
3	Sensor strip	For mounting proximity sensors and flexible sensing of any desired end positions. Included in	24
	SL	the scope of delivery of the linear module.	
4	Centring sleeve	For centring loads and attachments on the yoke plate	26
	Z		
5	Shock absorber	Included in the scope of delivery of the linear module	26
6	Proximity sensor	For position sensing via the sensor strip	27
	A		
7	Housing cover	Included in the scope of delivery of the linear module	-
-	Cable with socket	For proximity sensor	27
	V		
-	Slot cover	For protecting the proximity sensor cable	26
	A		

Linear modules HMP

Peripherals overview



Acce	ssories		
		Description	→ Page/Internet
1	Intermediate position module	For approaching an intermediate position during the advance stroke. The intermediate position	18
	Z1A	module Z1E is used to approach an intermediate position during the return stroke.	
2	End cap AD/EL	The end cap (EL) houses an integrated electrical interface	24
3	Sensor strip SL	For mounting proximity sensors and flexible sensing of any desired end positions. Included in the scope of delivery of the linear module.	24
4	Centring sleeve Z	For centring loads and attachments on the yoke plate	26
5	Shock absorber	Included in the scope of delivery of the linear module	26
6	Proximity sensor A	For position sensing via the sensor strip	27
7	Housing cover	Included in the scope of delivery of the linear module	-
8	Proximity sensor A	For sensing the position of the lever at the intermediate position module (intermediate position active/not active)	28
_	Cable with socket V	For proximity sensor	27
-	Slot cover A	For protecting the proximity sensor cable	26

Linear modules HMP

Type codes

		HMP	- 16	- 150	— B	- SL	- 2G3	— КР	-	— EL	— A1	— E
1_												
Туре												
HMP	Linear module											
D'	a []											
Piston Ø	⊘ [mm]											
Stroke	[mm]											
Genera	tion											
В	B series					_						
Sensing	g											
SL	Sensor strip						1					
1												
	atic connection											
2G3	For 3 mm I.D. tubing											
2G4	For 4 mm I.D. tubing											
2G6	For 6 mm I.D. tubing											
Clampii	ng unit											
KP	Attached]			
M	Attuched											
Interme	ediate position module											
Z1A	For advance stroke									J		
Z1E	For return stroke											
1												
Interfac												
AD	End cap											
EL	End cap with electrical interfac	ce										
Proximi	ity sensor											
A1	With cable, 2.5 m											ļ
A2	Contactless with cable, 2.5 m,	NPN										
A3	Contactless with cable, 2.5 m,											
A4	With plug											
A5	Contactless with plug, NPN											
A6	Contactless with plug, PNP											
المرتبع ا	cumentation											
E	English											
S F	Spanish French											
T.	THEILUI											



Linear modules HMP

Type codes

→		+ ZUB] -]	A	Z
Access	sories				
ZUB	Accessories supplied loose		1		
Cable	with socket				
V	2.5 m			1	
Slot co	over				
А	Slot cover				
Centri	ng sleeve				
Z	For yoke plate				

Linear modules HMP

Technical data

Ę.

Function





FESTO

General technical data						
Piston Ø			16	20	25	32
System mode			Yoke			
Mode of operation			Double-acting			
Protection against torsion			Guide			
Connection type			Female thread			
Pneumatic connection, linear module	5		M5	G1/8	G1/8	G1/4
Pneumatic connection, intermediate	position module		M3			
Assembly position			Any			
Effective stroke		[mm]	16 320	24 400	24 400	40 400
Position sensing			For proximity sensing			
Max. repetition accuracy ¹⁾		[mm]	0.01			
Max. speed	advancing	[m/s]	0.8	1.1	1.1	1.2
	returning	[m/s]	0.8	1.1	1.1	1.1
Swivel time of lever at intermediate	advancing	[s]	0.04	0.04	0.04	0.072
position module	returning	[s]	0.04	0.036	0.034	0.065

1) Variation of end position and intermediate position for 100 successive strokes under constant operating conditions

Operating and environmental conditions

Piston Ø		16	20	25	32
Operating pressure	[bar]	4 8			
Operating medium		Compressed air in acc	ordance with ISO 8573	-1:2010 [7:4:4]	
Note on operating/pilot medium		Operation with lubrica	ted medium possible		
		(in which case lubricat	ed operation will alway	rs be required)	
Ambient temperature ¹⁾	[°C]	0 +60			
Protection class to EN 60 529		IP 40			
Noise level F _{LEQ}	[dB(A)]	62	65	68	69
Corrosion resistance class CRC ²⁾		2			±

1) Note operating range of proximity sensors

2)

Corrosion resistance class 2 according to Festo standard 940 070 Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Forces [N]				
Piston Ø	16	20	25	32
Theoretical force at 6 bar, advancing ¹⁾	121	188	295	483
Theoretical force at 6 bar, returning ¹⁾	104	158	247	415

1) Theoretical values, please note: Degree of efficiency: approx. 90%

→ Internet: www.festo.com/catalogue/...

0

Linear modules HMP

Technical data

1

Weight [g]					
Piston \varnothing		16	20	25	32
Product weight	with 0 mm stroke	2100	4700	6300	10900
	per 10 mm stroke	88	110	150	200
Moving load	with 0 mm stroke	900	1500	2300	4000
	per 10 mm stroke	28	37	55	74
End cap	HMPAD	180	270	300	400
	HMPEL	210	300	330	430
Clamping unit HMPKP	50 mm	109	114	-	-
for effective stroke	100 mm	120	125	-	-
	150 mm	131	136	-	-
	200 mm	142	147	-	-
	250 mm	153	158	-	-
	320 mm	168	173	-	-
	400 mm	-	191	-	-
Intermediate position module	HMPZ1A/Z1E	165	206	227	321

Materials Sectional view

Linear module

1 Housing cover	Anodised aluminium
2 Yoke plate	Anodised aluminium
3 Profile	Anodised aluminium
4 Guide barrel	Tool steel
– Seals	Nitrile rubber, polyurethane

Technical data

Permissible torque M as a function of the stroke length I (at the yoke plate)



M [Nm]

10

1+ 0

100

200 l [mm] зо́о

400





Linear modules HMP

Technical data







Linear modules HMP

Technical data

Max. permissible horizontal effective load at 6 bar

HMP-16: 10 kg HMP-20: 20 kg HMP-25: 30 kg HMP-32: 50 kg

Permissible horizontal advancing time t as a function of the stroke length and the effective load m with optimum shock absorber stroke













1) Further nominal strokes in preparation

Linear modules HMP

Technical data

FESTO

Max. permissible horizontal effective load at 6 bar HMP-16: 10 kg HMP-20: 20 kg HMP-25: 30 kg HMP-32: 50 kg

Permissible horizontal returning time t as a function of the stroke length and the effective load m with optimum shock absorber stroke





HMP-251) 1000 HMP-25-400 800 600 t [ms] 400 200 0 0 5 10 20 25 15 m [kg]



HMP-201)

600

500

400

200

100

t [ms] 300



HMP-20-400

HMP-20-250

HMP-20-200 /

HMP-20-50

20

. HMP-32-150 400 200 0 -0 10 20 30 40 50

m [kg]

1) Further nominal strokes in preparation

Linear modules HMP

Technical data

ad at 6 bar
with clamping cartridge
HMP-16: 4 kg
HMP-20: 7.5 kg

Permissible vertical advancing time t as a function of the stroke length and the effective load m with optimum shock absorber stroke HMP-16/-20/-25/-32¹)



Permissible vertical returning time t as a function of the stroke length and the effective load m with optimum shock absorber stroke HMP-16/-20/-25/-32¹⁾





1) Further nominal strokes in preparation

Linear modules HMP

Technical data

FESTO

Advancing/returning time t as a function of the optimum length L to which the shock absorber should be screwed out

In order to obtain the shortest possible travel time with a linear module HMP, it is essential to adjust the shock absorbers to match the advancing/returning time t.

The optimum length L to which the shock absorbers should be screwed out is shown in the adjacent graph.







As long as the centre of gravity of the effective load on the yoke plate lies within the outline of this plate, it is impossible to overload the linear module. Centre of gravity



When dovetail mounting components are used, the centre of gravity should be within this area.

4 4 5

L [mm]

5 5.5 6

Recommended position of centre of gravity for low-vibration operation.

Linear modules HMP

Technical data

FESTO

Intermediate position module Z1A/Z1E



Range for possible intermediate positions when advancing



- L1 = Rear non-operational zone
- L2 = Front non-operational zone
- L3 = Effective stroke
- X = Zone for possible
 - intermediate positions

X = L3 – L1 – L2

Non-operational zones [mm]

Non operational zones [mm]				
Piston Ø	16	20	25	32
L1	33	42	42	55.5
L2	66	68.5	54.5	56

Calculation example

Given: Linear module HMP-16-200-...-Z1A-...

To be found:

In which zone of the effective stroke are intermediate positions possible?

Calculation:

The piston \varnothing of the linear module (16 mm) determines the following non-operational zones which do not permit intermediate positions: L1 = 33 mm

- L2 = 66 mm
- X = L3 L1 L2 = 101 mm

This means:

The lower limit of the effective stroke range for permissible intermediate positions is: L1 = 33 mm

The upper limit of the effective stroke range for permissible intermediate positions is:

L1 + X = 134 mm

- 📲 - Note

Ordering data in the:

Modular products → 24

• Accessories → 26

Linear modules HMP

Technical data

FESTO





Range for possible intermediate positions when returning



- Rear non-operational zone L1 = Front non-operational zone L2 =
- Effective stroke L3 =
- Zone for possible X = intermediate positions L3 – L1 – L2 X =

Non-operational zones [mm]

Non-operational zones [inin]				
Piston Ø	16	20	25	32
L1	47.5	62	54.5	56
L2	33	42	42	55.5

Calculation example

Given: Linear module HMP-16-200-...-Z1E-...

To be found:

In which zone of the effective stroke are intermediate positions possible?

Calculation:

The piston \varnothing of the linear module (16 mm) determines the following non-operational zones which do not permit intermediate positions: L1 = 47.5 mm

33 mm L2 =

L3 – L1 – L2 = 119.5 mm Х =

This means:

The lower limit of the effective stroke range for permissible intermediate positions is: L1 = 47.5 mm

The upper limit of the effective stroke range for permissible intermediate positions is: L1 + X = 167 mm

Note

Ordering data in the:

• Modular products → page 24

Accessories → page 26

Linear modules HMP

Technical data

FESTO



1) Tolerance specification applies to countersink D1; tolerance for thread D2: ±0.2

Linear modules HMP

Technical data



1) Tolerance specification applies to countersink D1; tolerance for thread D2: ±0.2

Linear modules HMP

Technical data



Туре	B1	B2	H1	H2	H3	H4	L1	L2	=©1	=©2
HMP-162G3	17	11	33.6	19	5.5		20.6	15	7	9
HMP-162G4	1/	11	0.0	19	5.5	7	22.6	15	/	9
HMP-202G4	- 20			28.9			31.3			
HMP-202G6	20	16	48.7	27.5	8		31.4	22.2	13	14
HMP-252G4		10	40.7	28.9	0		31.3	22.2	1)	14
HMP-252G6	22			27.5		9	31.4			
HMP-322G4	22	20	61.8	37.9	10	2	35.8	28.2	17	17
HMP-322G6		20	01.0	38.2	10		35.9	20.2	1/	1/

Dimensions – Clamping unit

(code KP)





				l			
D1	00	D2	11	-7	Holding force	Effective load	

Туре	D1	D2	D3	L1	<u>ب</u>	Holding force	Effective load	
	Ø	1)	Ø				horizontal	vertical
						[N]	[kg]	[kg]
HMP-16	11.4	M3	6	5	F	100	10	4
HMP-20	11.4	WI S	0	3.8	J		20	7.5

1) Air connection is supplied ready-fitted with QS connector QSM-M3-4

- 📲 - Note

The clamping unit must only be operated when the rod is stationary (end position). Dynamic braking operations can result in severe damage to the clamping device. Precision positioning cannot be guaranteed with the clamping unit since slippage of approx. 1 – 2 mm can occur. When using the linear module HMP-20 together with the clamping unit, the max. possible stroke is reduced by 12.5 mm.

Download CAD data → www.festo.com

Linear modules HMP

Technical data

FESTO





Ŧ

HZ



Download CAD data → www.festo.com



Linear modules HMP

Ordering data – Modular products

M Mandato	ry data	Piston Ø	Stroke	Generation	Position sensing	Pneumatic connection
537940	НМР	16	50	В	SL	2G3
537941		20	100			2G4
537942		25	150			2G6
537943		32	200			
			250			
			320			
			400			
Ordering						
example						
537940	НМР	- 16	- 150	– B	– SL	- 2G3

Or	dering table								
Siz	e		16	20	25	32	Condi- tions	Code	Enter code
Μ	Module No.		537940	537941	537942	537943			
	Function		Linear module with ba	all bearing guide				HMP	HMP
	Piston Ø [[mm]	16	20	25	32			
	Stroke [[mm]	50	50	-	-		-50	
			100	100	100	100		-100	
			150	150	150	150		-150	
			200	200	200	200		-200	
			250	250	250	250		-250	
			320	320	320	320		-320	
			-	400	400	400		-400	
	Generation		B series	•		<u>.</u>		-В	-В
	Position sensing		Sensor strip					-SL	-SL
	Pneumatic connection		One-way flow control	-	-	-		-2G3	
			valve, 3 mm barbed						
			connector						
			One-way flow control	valve, 4 mm barbed co	onnector			-2G4	
r			-	One-way flow control	valve, 6 mm barbed	connector		-2G6	



Linear modules HMP

Ordering data – Modular products

Clamping unit	Intermedi- ate position	Interface	Proximity sensor set	User documentation	Acces- sories	Cable with socket	Slot cover	Centring sleeves
KP	Z1A	AD	A1	E	ZUB	V	A	Z
	Z1E	EL	A2	S				
			A3	F				
			A4	I				
			A5	V				
			A6	В				
	– Z1A	– EL	- A1	– B	ZUB	– 2V		1

Ordering table

Siz	e	16	20	25	32	Condi- tions	Code	Enter code
0	Clamping unit	Attached		-	-	1	-KP	
	Intermediate position	1 intermediate positi	on, advancing			2	-Z1A	
		1 intermediate positi	termediate position, returning					
	Interface	End cap	l cap					
		End cap with electrica	d cap with electrical interface					
	Proximity sensor, assembled	Proximity sensor with	pximity sensor with cable, 2.5 m					
		Proximity sensor, con	tactless, NPN with	n cable, 2.5 m			-A2	
		Proximity sensor, con	tactless, PNP with	n cable, 2.5 m			-A3	
		Proximity sensor with	plug M8			3	-A4	
		Proximity sensor, con	tactless, NPN with	n plug M8		3	-A5	
		Proximity sensor, con	tactless, PNP with	n plug M8		3	-A6	
	Alternative user documentation	User documentation,	English				-Е	
	(standard is German/English)	User documentation,	Spanish				-S	
		User documentation,	French				-F	
		User documentation,	Italian				-1	
		User documentation,	Swedish				-V	
		Express waiver - no m	anual to be inclue	ded (already availab	le)		-B	
	Accessories	Supplied separately					ZUB-	ZUB-
	Cable with socket, 2.5 m	1 10					V	
	Slot cover	Slot cover			Α			
	Centring sleeves (pack of 10)	10, 20, 30, 40, 50, 6	0, 70, 80, 90				Z	

Not with intermediate position Z1A, Z1E.

1 KP 2 Z1A, Z1E Min. stroke: 150 mm.

3 A4, A5, A6 Not with interface EL Max. stroke: Piston Ø 16, 20, 25 mm: 200 mm

Piston Ø 32 mm: 150 mm

Transfer order code

_

ZUB

_



Linear modules HMP

Accessories

Ordering data						
	For piston Ø [mm]	Remarks	Order code	Part No.	Туре	PU ¹
ntermediate position module B2	1-HMP					
	16	For advance movement	Z1A	538904	BZ1-HMP-16-B-Z1A	1
	20			538905	BZ1-HMP-20-B-Z1A	
	25			538906	BZ1-HMP-25-B-Z1A	
SA (33) (9)	32			538907	BZ1-HMP-32-B-Z1A	
	16	For return movement	Z1E	538908	BZ1-HMP-16-B-Z1E	
	20			539909	BZ1-HMP-20-B-Z1E	
¥	25			538910	BZ1-HMP-25-B-Z1E	
	32			538911	BZ1-HMP-32-B-Z1E	
Slot cover ABP	Т		I.	1		
	16 32	For sensor strip every 0.5 m	A	151681	ABP-5	2
Shock absorber YSRW					Technical data 🗲 In	ternet: ysr
~	16	-	-	191194	YSRW-8-14	1
	20			191196	YSRW-12-20	
- Sur -	25			191196	YSRW-12-20	
V	32			191197	YSRW-16-26	

1) Packaging unit quantity

Accessories

Ordering data	- Proximity sensors for T-slot, magneto-r	esistive				Technical data 🗲 Internet: smt
	Type of mounting	Switch output	Electrical connection	Cable length [m]	Part No.	Туре
N/O contact		υτιραί		[111]		
	Insertable in the slot from above, flush	PNP	Cable, 3-wire	2.5	574335	SMT-8M-A-PS-24V-E-2,5-0E
A B A	with cylinder profile, short design		Plug M8x1, 3-pin	0.3	574334	SMT-8M-A-PS-24V-E-0,3-M8D
Ţ.			Plug M12x1, 3-pin	0.3	574337	SMT-8M-A-PS-24V-E-0,3-M12
		NPN	Cable, 3-wire	2.5	574338	SMT-8M-A-NS-24V-E-2,5-OE
			Plug M8x1, 3-pin	0.3	574339	SMT-8M-A-NS-24V-E-0,3-M8D
N/C contact						
BE BE A	Insertable in the slot from above, flush with cylinder profile, short design	PNP	Cable, 3-wire	7.5	574340	SMT-8M-A-PO-24V-E-7,5-OE
*						
	Dravimity concern for T clot magnatic					Tashnisal data -> Internet am

Ordering data	- Proximity sensors for T-slot, magnetic re	eed				Technical data 🗲 Internet: sme
	Type of mounting	Switch	Electrical connection	Cable length	Part No.	Туре
		output		[m]		
N/O contact						
	Insertable in the slot from above, flush	Contacting	Cable, 3-wire	2.5	543862	SME-8M-DS-24V-K-2,5-OE
T B F	with cylinder profile			5.0	543863	SME-8M-DS-24V-K-5,0-OE
\$ <u></u>			Cable, 2-wire	2.5	543872	SME-8M-ZS-24V-K-2,5-0E
			Plug M8x1, 3-pin	0.3	543861	SME-8M-DS-24V-K-0,3-M8D
-	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	2.5	150855	SME-8-K-LED-24
	with the cylinder profile		Plug M8x1, 3-pin	0.3	150857	SME-8-S-LED-24
N/C contact						
	Insertable in the slot lengthwise, flush with the cylinder profile	Contacting	Cable, 3-wire	7.5	160251	SME-8-O-K-LED-24

Accessories

	ш.

Ordering data	- Proximity sensors for C-sl	ot, magneto-re	esistive			Technical data 🗲 Internet: smt
	Type of mounting	Switch output	Electrical connection, connection direction	Cable length [m]	Part No.	Туре
N/O contact						
A	Insertable in the slot from	PNP	Cable, 3-wire, in-line	2.5	551373	SMT-10M-PS-24V-E-2,5-L-OE
2 8 V	above		Plug M8x1, 3-pin, in-line	0.3	551375	SMT-10M-PS-24V-E-0,3-L-M8D
•			Plug M8x1, 3-pin, lateral	0.3	551376	SMT-10M-PS-24V-E-0,3-Q-M8D

Ordering data	- Proximity sensors for C-sl	ot, magnetic re	eed			Technical data 🗲 Internet: sme
	Type of mounting	Switch	Electrical connection,	Cable length	Part No.	Туре
		output	connection direction	[m]		
N/O contact						
T. Se	Insertable in the slot from	Contacting	Plug M8x1, 3-pin, in-line	0.3	551367	SME-10M-DS-24V-E-0,3-L-M8D
CT Ser	above		Cable, 3-wire, in-line	2.5	551365	SME-10M-DS-24V-E-2,5-L-OE
			Cable, 2-wire, in-line	2.5	551369	SME-10M-ZS-24V-E-2,5-L-OE
	Insertable in the slot	Contacting	Plug M8x1, 3-pin, in-line	0.3	173212	SME-10-SL-LED-24
	lengthwise		Cable, 3-wire, in-line	2.5	173210	SME-10-KL-LED-24

Ordering da	ata – Connecting cables				Technical data 🗲 Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3
and the second s			5	541334	NEBU-M8G3-K-5-LE3
	Straight socket, M12x1, 5-pin	Cable, open end, 3-wire	2.5	541363	NEBU-M12G5-K-2.5-LE3
			5	541364	NEBU-M12G5-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3
			5	541341	NEBU-M8W3-K-5-LE3
	Angled socket, M12x1, 5-pin	Cable, open end, 3-wire	2.5	541367	NEBU-M12W5-K-2.5-LE3
			5	541370	NEBU-M12W5-K-5-LE3

Accessories

Adapter kit
DHAA, HMAV, HMSV

Material: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant

Note -

The kit includes the individual mounting interface as well as the necessary mounting material.

FESTO

Permissible drive/drive combinati	ons with adapter kit				Download	CAD data → www.f	esto.com
Combination	1 Drive	2 Drive	Adapter	kit			
	Size	Size	CRC ¹⁾	Part No.	Туре	Required quantity	PU ²⁾
HMP/HMP	HMP	HMP	HMSV	÷			
	Direct mounting	g					
	16	16		-	M5x25 DIN 912 ³⁾	2	-
				150927	ZBH-9 ³⁾	2	10
	20	16, 20		-	M5x25 DIN 912 ³⁾	3	-
			2	150927	ZBH-9 ³⁾	3	10
	25, 32	16, 20	2	-	M5x30 DIN 912 ³⁾	3	-
				150927	ZBH-9 ³⁾	3	10
	25	25		177652	HMSV-6	-	-
	32	25, 32		177652	HMSV-6	-	-
	Dovetail mount			I			
	16, 20, 25	16		177647	HMSV-1	1	1
	20	20		177649	HMSV-3	1	1
	25	20, 25	2	177649	HMSV-3	1	1
	32	16		177649	HMSV-3	1	1
	32	20, 25, 32		177653	HMSV-7	1	1
	1	1					
DGC/HMP	DGC	HMP	DHAA, H	MAV			
	25	16, 20		176005	HMAV-DL25	1	1
	32	16, 20	2	562150	DHAA-D-L-32-H2	1	1
	40	20, 25, 32		562151	DHAA-D-L-40-H2	1	1
2							
DGP(I)L, DGE/HMP	DG	HMP	HMAV				
sek -	25	16, 20		176005	HMAV-DL25	1	1
1	32	16, 20, 25	2	176006	HMAV-DL32	1	1
	40	20, 25, 32		176007	HMAV-DL40	1	1
2							

Corrosion resistance class CRC 2 to Festo standard FN 940070
Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.

2) 3)

Packaging unit quantity The screws and centring sleeves listed are not included in the scope of delivery of the drives

Accessories

Adapter kit	N
DHAA, HMAV	W
	F

Material:
Wrought aluminium alloy
Free of copper and PTFE
RoHS-compliant

-- Note

The kit includes the individual mounting interface as well as the necessary mounting material.

	tions with adapter kit				Download	CAD data → www.f	esto.com
Combination	1 Drive	2 Drive	Adapter	kit			
	Size	Size	CRC ¹⁾	Part No.	Туре	Required	PU ²⁾
						quantity	
EGC/HMP	EGC	HMP	DHAA, H	MAV			
	80	16, 20	2	176005	HMAV-DL25	1	1
Se l	120	20, 25, 32	2	562151	DHAA-D-L-40-H2	1	1
2							

1) Corrosion resistance class CRC 2 to Festo standard FN 940070

Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.

2) Packaging unit quantity

FESTO