



★/☆	Festo core product range	$\star$ Generally ready for dispatch from the factory within 24 hours	
	Covers 80% of your automation tasks	In stock at 13 Service Centres worldwide	ok
		More than 2200 products for the	e
Worldwide:	Always in stock	$\star$ Generally ready for dispatch from the factory within 5 days $\star$	
Superb:	Festo quality at an attractive price	Assembled for you in 4 Service Centres worldwide	
Easy:	Simplified procurement and warehousing	Up to $6 \times 10^{12}$ variants per product family	

## Key features

### Features

#### Compact

- Extremely small dimensions
- Full integration of all components for the controller and power unit, including USB interface, Ethernet and CANopen interface
- Integrated brake chopper
- Integrated EMC filters
- Automatic actuation for a holding brake
- Compliance with the current CE and EN standards without additional external measures (→ page 6)

Ether**CAT** 

EtherNet/IP<sup>®</sup>

Profi

肉菌白

#### Bus protocols





## DeviceNet.

## Modbus

Integrated safety functions

- Depending on the variant or plug-in card, the motor controller supports the following safety functions:
  - Safe torque off (STO)
  - Safe stop 1 (SS1)
  - Safe brake control (SBC)
  - Safe operating stop (SOS)
  - Safe stop 2 (SS2)
  - Safely limited speed (SLS)
  - Safe speed range (SSR)
  - Safe speed monitor (SSM)

#### Motion control

- Evaluation of digital absolute encoders (EnDat/HIPERFACE) in single-turn or multi-turn versions
- Can be operated as a torque, rotational speed or position controller
- Integrated positioning control
- Time-optimised (trapezoidal) or jerk-free (S-shaped) positioning
- Absolute and relative movements
- · Point-to-point positioning with and without motion path smoothing
- Position synchronisation
- Electronic gear unit
- 255 position sets
- Wide range of homing methods

#### Input/output

- Freely programmable I/OsHigh-resolution 16-bit analogue input
- Jog/teach mode
- Easy connection to a higher-order controller via I/O or fieldbus
- Synchronous operation
- Master/slave mode
- Additional I/Os with the plug-in card CAMC-D-8E8A → page 18

#### Integrated sequence control

- Automatic sequence of position sets without a higher-level controller
- Linear and cyclical position sequences
- Adjustable delay times
- Branches and wait positions
- Overlapping restart possible during the movement

#### Interpolating multi-axis movement

 With a suitable controller, the CMMP-AS can perform path movements with interpolation via CANopen or EtherCAT. To do this, the controller specifies setpoint position values in a fixed time pattern. In between, the servo position controller independently interpolates the data values between two interpolation points.

PROFIBUS®, PROFINET®, DeviceNet®, CANopen®, EtherCat® and EtherNet/IP® are registered trademarks of their respective trademark holders in certain countries.

→ www.festo.com/eplan

### Key features

#### Motion program

- · Linking of any number of position sets into a motion program
- Step enabling conditions for the motion program possible via digital inputs, for example
- MC motion complete
- I/O digital inputs

#### Library for EPLAN



EPLAN macros for fast and reliable planning of electrical projects in combination with motor controllers, motors and cables. This enables a high level of planning reliability and standardisation of documentation without the need to create symbols, graphics and master data.

#### Cam disc functionality

The "electronic cam disc" application type creates optimised motion profiles that generate less vibration and lower acceleration forces at the machine. In addition, the movement of the motor is always synchronised with the position of a master axis so that overlapping, time-optimised motion sequences can be easily defined. To be able to use the cam disc function, you will need the Festo Configuration Tool (FCT) and also the cam editor  $\rightarrow$  Page 4.

#### Key features:

- High flexibility of the system. The mechanical system does not need to be modified if the requirements for the cam shapes change.
- User-friendly motion plan editor. All limits for position, speed and acceleration are immediately displayed in the editor. Up to 16 cam discs with a total of up to 2048 interpolation points can be managed. The interpolation points can be randomly distributed along the cam discs.
- There are four digital trip cams coupled with each cam disc.
- Each cam disc can be offset by a certain amount from the master axis.

## Key features

#### FCT software – Festo Configuration Tool

Software platform for electric drives from Festo



- All drives in a system can be managed and saved in a common project
- Project and data management for all supported types of equipment
- Easy to use thanks to graphically supported parameter entry

Universal mode of operation for all	
drives	

• Work offline at your desk or online at the machine

## FHPP – Festo Handling and Positioning Profile

Optimised data profile

Festo has developed an optimised data profile, the "Festo Handling and Positioning Profile (FHPP)", which is specifically tailored to handling and positioning applications.

With the FHPP data profile, Festo motor controllers can be controlled using a fieldbus interface via standardised control and status bytes.

## The following are defined, among others:

- Operating modes
- I/O data structure
- Parameter objects
- Sequence control

## Product range overview and type codes

Туре	CMMP-ASM0	CMMP-ASM3		
Bus protocols				
Integrated in the controller				
CANopen				
Modbus TCP	•			
Optional via plug-in card				
PROFIBUS DP	-			
DeviceNet	-			
EtherCAT	-			
EtherNet/IP	-	•		
PROFINET RT	-			
Safety functions				
Integrated in the controller	•	-		
Optional via plug-in card	-			

#### Type codes

001	Series	004	Nominal input voltage	
CMMP	Motor controller, premium	3A	230 V AC/50-60Hz	
		11A	400 V AC	
002	Motor type			
AS	AC synchronous	005	Number of phases	
			Single-phase	
003	Nominal current	P3	Three-phase	
C2	2 A			· ·
C5	5 A	006	Number of slots	
C10	10 A	МО	Without slots	
C15	15 A	M3	With 3 slots	

Bus protocols



DeviceNet.





Ether CAT.

EtherNet/IP<sup>\*</sup>

<u>prof</u> Nét

General technical data									
CMMP-AS-		C2-3A	C2-3A C5-3A C5-11A-P3 C10-11A-P3 C15-11A-P3						
Type of mounting		Screwed onto con	Screwed onto connection plate						
Display		Seven-segment di	splay						
Parameterisation interface		USB, Ethernet							
Active PFC		Yes		-					
DIP switch		Firmware downloa	d/fieldbus settings <sup>1</sup>	)/CAN terminating resisto	r				
SD card slot		Memory card → p	age 18						
Encoder interface input		Resolver							
		Incremental encod	ler with analogue or	digital tracking signals					
		Absolute encoder	with EnDat V2.1 seri	al/V2.2					
		Absolute encoder							
			Additional input for synchronous/cam disc operation						
Encoder interface output			Actual value feedback via encoder signals in rotational speed control mode						
		Setpoint specifica	Setpoint specification for downstream slave drive						
		Resolution up to 1	Resolution up to 16384 ppr						
Braking resistor, integrated	[Ω]	60		68					
Pulse power of braking resistor	[kVA]	2.8		8.5					
Braking resistor, external	[Ω]	≥ 50		≥ 40					
Impedance of setpoint input	[kΩ]	20							
Number of analogue outputs		2							
Operating range of analogue outputs	[V]	±10							
Resolution of analogue outputs		9 bit	9 bit						
Characteristics of analogue outputs		Short-circuit-proof	Short-circuit-proof						
Number of analogue inputs		3	3						
Operating range of analogue inputs	[V]	±10	±10						
Characteristics of analogue inputs		1x differential, res	1x differential, resolution 16 bit						
	<u> </u>	2x single-ended, resolution 10 bit							
		Configurable for ro	Configurable for rotational speed setpoint value/torque setpoint value/position setpoint value						
Mains filter		Integrated				External <sup>2)</sup>			
Max. motor cable length <sup>3)</sup>	[m]	25				-			
Product weight	[g]	2100	2200	3800		3450			

1) Not in combination with CMMP-AS-...-M0  $\,$ 

2) The mains filter is mandatory for compliance with the CE and EN standards  $\rightarrow$  page 20

3) Without external mains filter

#### | Function blocks for PLC programming

Function blocks for PLC pro	gramming						
Programming software	Controller manufacturer	Interfaces					
		CANopen	PROFIBUS DP	DeviceNet	EtherCAT	EtherNet/IP	PROFINET RT
CODESYS	Festo			•			
TwinCAT	Beckhoff						
	Other manufacturers						
RSLogix5000	Rockwell Automation	-	-	•	-		-
Step 7/TIA Portal	Siemens	-		-	-	-	

Interfaces		1/0	Additional I/O <sup>1)</sup>	CANopen	Modbus TCP	PROFIBUS DP	DeviceNet	EtherCAT	EtherNet/IP	PROFINE RT
Number of digital logic outputs		5	8	5						
Characteristics of digital logic output	ıts	Freely confi	gurable	•						
Number of digital logic inputs		10	8	10						
Characteristics of logic inputs		Freely confi	gurable							
Process interfacing		16 (127) position sets <sup>2)</sup>	255 posi- tion sets	250 positio	on sets					
Communication profile		-	-	DS301; FHPP+	FHPP+	DP-V0/ FHPP+	FHPP+	DS301; FHPP+	FHPP+	FHPP+
				DS301; DSP402	_			CoE: DS301; DSP402		
Max. fieldbus transmission rate	[Mbps]	-	-	1	100	12	0.5	100	100	100
Interface					_!				•	
CMMP-ASM0	Integrated	•	-			-	-	-	-	-
CMMP-ASM3	Integrated		-			-	-	-	-	-
	Optional <sup>3)</sup>			-	-					

With the plug-in card CAMC-D8E8A → page 18

2) Can be extended with configurable logic inputs up to max. 127 position sets

3) Plug-in cards can be ordered separately  $\rightarrow$  page 18

Electrical data						
CMMP-AS-		C2-3A	C5-3A	C5-11A-P3	C10-11A-P3	C15-11A-P3
Output connection data						
Output voltage range	[V AC]	3x 0 270		3x 0 360		
Nominal current	[A <sub>eff</sub> ]	2.5	5	5	10	15
Peak current	[A <sub>eff</sub> ]	5	10	10	20	30
at max. peak current duration	[s]	5				· · ·
	[A <sub>eff</sub> ]	10	20	20	40	45
	[s]	0.5				1
Max. DC link voltage	[V DC]	320/380 <sup>1)</sup>		560		
Output frequency	[Hz]	0 1000				
Load supply		·				
Nominal voltage phases		1		3		
Input voltage range	[V AC]	100 230 ±10%	)	3x 230 480 ±10%		
Max. nominal input current	[A]	3	6	5.5	11	13
Nominal power	[VA]	500	1000	3000	6000	9000
Peak power	[VA]	1000	2000	6000	12000	18000
Mains frequency	[Hz]	50 60				
Logic supply						
Nominal voltage	[V DC]	24 ±20%				
Nominal current	[A]	0.55/2.05 <sup>2)</sup>	0.65/2.15 <sup>2)</sup>	1/3.5 <sup>2)</sup>		
Max. current of digital logic outputs	[mA]	100	•			

1) Without PFC/with PFC

2) Max. current with brake and I/Os

#### Safety functions to EN 61800-5-2

Safety functions to EN 61800-5-2									
Motor controller	CMMP-AS-	CMMP-AS-							
	C2/C5/C10M0	C2/C5/C10/C15M3							
With plug-in card	-	CAMC-G-S1	CAMC-G-S3						
		→ Page 14	→ Page 15						
Safe torque off (STO)		•							
Safe stop 1 (SS1)	-	-	•						
Safe brake control (SBC)									
Safe operating stop (SOS)	-	-							
Safe stop 2 (SS2)	-	-							
Safely limited speed (SLS)	-	-							
Safe speed range (SSR)	-	-							
Safe speed monitor (SSM)	-	-	•						

#### Safety data

Safety data	
CMMP-AS-	C2/C5/C10M0
Safety function to EN 61800-5-2	Safe torque off (STO)
Performance Level (PL) to EN ISO 13849-1	Category 4, Performance Level e
Safety Integrity Level (SIL) to EN 61800-5-2, EN 62061,	SIL 3
EN 61508	
Certificate issuing authority	German Technical Control Board (TÜV) 01/205/5162.02/19
Proof test interval	20a
Diagnostic coverage [%]	97
Safe failure fraction (SFF) [%]	99.2
Hardware fault tolerance	1
CE marking (see declaration of conformity)	To EU EMC Directive <sup>1)</sup>
	To EU Machinery Directive

1) For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp  $\rightarrow$  Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

#### Technical data – Connection to the integrated safety module with CMMP-AS-...-MO

Control input STO-A/STO-B		
Nominal voltage	[V DC]	24 (related to 0V-A/B)
Operating range	[V]	19.2 28.8
Nominal current	[mA]	20 (typical; max. 30)
Starting current	[mA]	450 (typical, duration approx. 2 ms; max. 600 at 28.8 V)
Max. positive test pulse length with logic 0	[ms]	0.3 (related to nominal voltage 24 V and intervals > 2 s between pulses)
Max. allowable time for test pulses at 24 V	[ms]	< 2 6
signal		
Key features		Galvanically isolated
Monitoring contact C1, C2		
Nominal voltage	[V DC]	24
Max. voltage	[V DC]	< 30 (overvoltage-resistant up to 60 V)
Nominal current	[mA]	< 200 (not short-circuit-proof)
Design		Potential-free signal contact
Switching logic		Contact closes at STO

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## Data sheet

#### Operating and environmental conditions

Operating and environmental conditions	5	1	1	1	1	1					
CMMP-AS-		C2-3A	C5-3A	C5-11A-P3	C10-11A-P3	C15-11A-P3					
Digital logic outputs		Galvanically isola	Galvanically isolated								
Logic inputs		Galvanically isola	ited	·							
Degree of protection											
With plug at X6 and X9		IP20									
Without plug at X6 and X9		IP10									
Protective function		l <sup>2</sup> t monitoring									
		Intermediate circu	uit over/undervoltage	·							
		Output stage sho	rt circuit	·							
		Standstill monitoring									
		Temperature monitoring									
Ambient temperature	[°C]	0 +40		÷							
Storage temperature	[°C]	-25 +70									
Relative humidity	[%]	0 90 (non-cond	densing)								
CE marking (see declaration of conformity	i)	To EU Low Voltage Directive									
		To EU EMC Directive <sup>1)</sup>									
		To EU Machinery Directive									
UKCA marking (see declaration of conform	nity)	To UK instructions for EMC									
		To UK instructions for machines									
		To UK regulations for electrical equipment									
Certification		c UL us listed (OL)									
		RCM compliance mark									
PWIS conformity		VDMA24364 zone	e III								
Note on materials		RoHS-compliant			·						

1) For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp → Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

#### Installation clearance for motor controller



Туре	H1 <sup>1)</sup>	L1
CMMP-AS-C2-3A CMMP-AS-C5-3A	100	71
СММР-АS-C5-11А-Р3 СММР-АS-C10-11А-Р3 СММР-АS-C15-11А-Р3	100	85

1) An installation clearance of 150 mm is recommended for optimum wiring of the motor or encoder cable on the underside of the motor controller

### Data sheet

View of motor controller CMMP-AS-...-M0



## PE connection LEDs

- [3] Reset button
- [4] Seven-segment display
- [5] X19 USB interface
- [6] X18 Ethernet interface
- [7] X40 digital I/O interface for controlling the STO function
- [8] X4 CANopen interface
- [9] Activation of CANopen terminating resistor
- [10] SD/MMC card slot
- [11] Activation of firmware download
- [12] Shield connection

#### From above



- [1] PE connection
- [2] X9 power supply
- [3] X11 incremental encoder inter-
- face (output)
- [4] X10 incremental encoder interface (input)
- [5] X1 I/O interface



- [1] X2B encoder connection
- [2] X2A resolver connection
- [3] X6 motor connection





## - 🖡 - Note

One of the plug-in cards must be inserted in slot [7] in order to operate the motor controller.

#### From above



Possible plug-in cards: CAMC-DS-M1  $\rightarrow$  page 18 CAMC-G-S1  $\rightarrow$  page 14 CAMC-G-S3  $\rightarrow$  page 15

- [1] PE connection
- [2] X9 power supply
- [3] X11 incremental encoder interface (output)
- [4] X10 incremental encoder interface (input)
- [5] X1 I/O interface

#### [1] PE connection

- [2] LEDs
- [3] Reset button
- [4] Seven-segment display
- [5] X19 USB interface
- [6] X18 Ethernet interface
- [7] Slot for switch or safety module
- [8] X4 CANopen interface[9] Fieldbus settings
- [10] Activation of CANopen terminating resistor
- [11] Slots for extension modules
- [12] SD/MMC card slot
- [13] Activation of firmware download
- [14] Shield connection

#### From underneath



- [1] X2B encoder connection
- [2] X2A resolver connection
- [3] X6 motor connection

## Data sheet

### Dimensions

CMMP-AS-C2/C5-3A-M0, CMMP-AS-C5/C10-11A-P3-M0



Туре	B1	B2	B3	D1 Ø	D2 Ø	H1	L1	L2	L3	L4	L5	L6
CMMP-AS-C2-3A-M0	66	61	30.7	10	5.5	215	248	202	281	12.5	19.5	10.5
CMMP-AS-C5-3A-M0	1											
CMMP-AS-C5-11A-P3-M0	79	75	37.5	10	5.5	255	297	252	330	12.5	19.8	10.5
CMMP-AS-C10-11A-P3-M0												

CMMP-AS-C2/C5-3A-M3, CMMP-AS-C5/C10/-C15-11A-P3-M3



Туре	B1	B2	B3	D1 Ø	D2 Ø	H1	L1	L2	L3	L4	L5	L6
CMMP-AS-C2-3A-M3 CMMP-AS-C5-3A-M3	66	61	30.7	10	5.5	207	281	248	227	202	12.5	10.5
CMMP-AS-C5-11A-P3-M3 CMMP-AS-C10-11A-P3-M3 CMMP-AS-C15-11A-P3-M3	79	75	37.5	10	5.5	247	330	297	276	252	12.5	10.5

Download CAD data → <u>www.festo.com</u>

## ★ Core product range

#### Safety module CAMC-G-S1

Only for motor controller: CMMP-AS-...-M3

The safety module serves as an extension to achieve the safety function: • Safe torque off (STO)

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#### Safety data

Salety uata						
Safety function to EN 61800-5-2		Safe torque off (STO)				
Performance Level (PL) to EN ISO 13849-1		Category 4, Performance Level e				
Safety Integrity Level (SIL) to EN 61800-5-	2, EN 62061,	SIL 3				
EN 61508						
Certificate issuing authority		German Technical Control Board (TÜV) 01/205/5165.02/19				
Proof test interval		20a				
PFH		1.27 x 10 <sup>-10</sup>				
Diagnostic coverage	[%]	97				
Safe failure fraction (SFF)	[%]	99.2				
Hardware fault tolerance		1				
CE marking (see declaration of conformity	)1)	To EU EMC Directive				
		To EU Machinery Directive				
UKCA marking (see declaration of conform	iity)1)	To UK instructions for EMC				
		To UK instructions for machines				

1) More information www.festo.com/catalogue/camc ----> Support/Downloads

#### Technical data

Technical data		
Control input STO-A/STO-B		
Nominal voltage	[V DC]	24 (related to OV-A/B)
Operating range	[V]	19.2 28.8
Nominal current	[mA]	20 (typical; max. 30)
Max. positive test pulse length with logic 0	[ms]	0.3 (related to nominal voltage 24 V and intervals > 2 s between pulses)
Max. allowable time for test pulses at 24 V signal	[ms]	< 2 6
Key features		Galvanically isolated
Monitoring contact C1, C2		
Nominal voltage	[V DC]	24
Max. voltage	[V DC]	< 30 (overvoltage-resistant up to 60 V)
Nominal current	[mA]	< 200 (not short-circuit-proof)
Design		Potential-free signal contact
Switching logic		Contact closes at STO

#### Ordering data – Plug-in card

Ordering data – Plug-in card			
	Description	Part no.	Туре
	<ul> <li>Safety module:</li> <li>One of the plug-in cards CAMC-G-S1, CAMC-G-S3 or CAMC-DS-M1 must be inserted in slot [7] (→ page 11) in order to operate the motor controller.</li> <li>The plugs are included in the scope of delivery. To reorder plug NEKM → page 19</li> </ul>	☆ 1501330	CAMC-G-S1

 $\star$ ☆ Generally ready for dispatch from the factory within 24 hours Generally ready for dispatch from the factory within 5 days

→ Internet: www.festo.com/catalogue/...

## Accessories

#### Safety module CAMC-G-S3

The safety module serves as an extension to achieve the safety functions:

Only for motor controller: CMMP-AS-...-M3

- Safe torque off (STO)
- Safe stop 1 (SS1)
- Safe brake control (SBC)Safe operating stop (SOS)
- Safe stop 2 (SS2)
- Safely limited speed (SLS)
- Safe speed range (SSR)
- Safe speed monitor (SSM)

#### Safety data

Safety data					
Safety function to EN 61800-5-2	Safe torque off (STO)				
	Safe stop 1 (SS1)				
	Safe brake control (SBC)				
	Safe operating stop (SOS)				
	Safe stop 2 (SS2) Safely limited speed (SLS) Safe speed range (SSR)				
	Safe speed monitor (SSM)				
Performance Level (PL) to EN ISO 13849-1	Up to category 4, Performance Level e				
Safety Integrity Level (SIL) to EN 61800-5-2, EN 62061,	SIL 3				
EN 61508					
Certificate issuing authority	German Technical Control Board (TÜV) 01/205/5165.02/19				
Proof test interval	20a				
PFH	9.5 x 10 <sup>-9</sup>				
Diagnostic coverage [%]	97.5				
Safe failure fraction (SFF) [%]	99.5				
Hardware fault tolerance	1				
CE marking (see declaration of conformity) <sup>1)</sup>	To EU EMC Directive				
	To EU Machinery Directive				
UKCA marking (see declaration of conformity) <sup>1)</sup>	To UK instructions for EMC				
	To UK instructions for machines				

 $1) \qquad {\rm More\ information\ www.festo.com/catalogue/camc \longrightarrow Support/Downloads}$ 



Technical data
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Technical data		
General		
Parameterisation		Using SafetyTool, integrated into the FCT plug-in for CMMP-AS
Digital safe inputs DIN 40A/B to DIN	43A/B	
Specification	•	IEC 61131-2, type 3
Number of 2-channel inputs		4
Nominal voltage	[V DC]	24
Operating range	[V]	-3 30
Nominal current	[mA]	15
Max. nominal current	[mA]	200
Key features		Suitable for emergency-stop switchgear, protective door circuit, light curtain, enabling button,
		two-hand operator unit;
		Inputs switching equivalently/antivalently;
		Test pulses can be configured;
		Function can be configured
Digital safe inputs DIN 44 to DIN 49		·
Specification		IEC 61131-2, type 3
Number of 1-channel inputs		6
Nominal voltage	[V DC]	24
Operating range	[V DC]	-330
Nominal current	[mA]	15
Max. nominal current	[mA]	200
Key features		Suitable for start button, brake feedback, mode selector, error acknowledgement, restart blocking;
		Test pulses can be configured;
		Function can be configured
Digital safe outputs DOUT 40A/B to 4	2A/B	
Number of 2-channel outputs		3
Output		High-side switch with pull-down
Nominal voltage	[V DC]	24
Operating range	[V DC]	18 30
Permissible output current	[mA]	< 50
Key features		Semiconductor outputs: parameterisable PNP (positive switching)
		Outputs switching equivalently/antivalently
		Test pulses can be configured
		Function can be configured
Monitoring contact C1, C2		
Nominal voltage	[V DC]	24
Max. voltage	[V DC]	< 30 (overvoltage-resistant up to 60 V)
Nominal current	[mA]	< 200 (not short-circuit-proof)
Design		Potential-free signal contact
Key features		Suitable for the diagnostics of safety functions
		Function can be configured

#### Supported position encoders

- Resolver via X2A
- SIN/COS incremental encoder
- SICK Hiperface shaft encoder (only process data channel)

The manufacturers of SIL-certified shaft encoders publish guidelines for their use in safety applications.

- Heidenhain EnDat encoder
- Incremental encoder with digital
  - A/B signals

The safety module CAMC-G-S3 takes the following manufacturer specifications into account when evaluating the encoder signals:

- BISS position sensors for linear motors
- Incremental encoder with digital A/B signals
- Implementation Manual HIPER-FACE<sup>®</sup> Safety dated 21.12.2010 (801412 0/2010-12-21)
  - → www.sick.com
- Specification of the E/E/PES safety requirements for EnDat Master dated 19.10.2009 (D533095-04-G-01)
  - → www.heidenhain.de (in preparation)

#### Permissible combinations of position encoders

First encoder	Second encoder	Achievable safe	ety level	Note
Resolver	Other encoder	SIL 3	Cat. 3/PL d; Cat. 3/	-
			PL e	
Resolver	Incremental encoder	SIL 3	Cat. 4/PL e	-
Resolver	None	SIL 2	Cat. 3/PL d	Please see the note below
SIN/COS incremental encoder	None	SIL 3	Cat. 3/PL d	Requires SIL classification of the encoder
SIN/COS incremental encoder	Incremental encoder	SIL 3	Cat. 4/PL e	Please see the note below
Hiperface incremental encoder	Incremental encoder	SIL 3	Cat. 3/PL e	Please see the note below
Hiperface incremental encoder	None	SIL 2 or 3	Cat. 3/PL d; Cat. 4/	Requires SIL classification of the encoder
			PL e	
EnDat encoder	Incremental encoder	SIL 3	Cat. 4/PL e	Encoder setting: "Other encoder"
				Please see the note below
EnDat encoder	None	SIL 2	Cat. 3/PL d	In preparation.
				Requires SIL classification of the encoder
Other encoder	Incremental encoder	SIL 2	Cat. 3/PL d	-

#### · 📲 - Note

- Please check whether your selected position encoder is sufficiently accurate to fulfil the monitoring task, in particular the SOS safety function.
- In applications with only one shaft encoder/position encoder, it must have the SIL classification required in accordance with the risk assessment. In most cases, the classification requires additional requirements or fault exclusions in the mechanical system. Please check carefully that these requirements are fulfilled in your application and that the appropriate fault exclusions can be performed.
- In applications with only one shaft encoder/position encoder with analogue signal interface (resolver, SIN/COS, Hiperface, etc.), the restrictions on diagnostic coverage as well as the restrictions on the achievable accuracy of standstill and speed monitoring must be taken into account.
- When using two functional encoders without SIL classification, the suitability of the encoder combination for use in safe systems up to SIL3 must be proven separately (for example, the following are required: diversity of the encoder systems with regard to CCF, MTTFd, etc., suitability of the encoders for the operating and ambient conditions, EMC, etc.).

Ordering data – Plug-in card			
	Description	Part no.	Туре
	<ul> <li>Safety module:</li> <li>One of the plug-in cards CAMC-G-S1, CAMC-G-S3 or CAMC-DS-M1 must be inserted in slot [7] (→ page 11) in order to operate the motor controller.</li> <li>The plugs are included in the scope of delivery. To reorder plug NEKM → page 19</li> </ul>	☆ 1501331	CAMC-G-S3

### Accessories

Ordering data – Plug-in card								
	Description	Part no.	Туре					
	Switch module: • One of the plug-in cards CAMC-G-S1, CAMC-G-S3 or CAMC-DS-M1 must be inserted in slot [7] (→ page 11) in order to operate the motor controller CMMP-ASM3.	☆ 1501329	CAMC-DS-M1					

#### Ordering data – Plug-in cards for bus protocols

		Description	Part no.	Туре
-		For PROFIBUS DP	🛧 547450	CAMC-PB
		For PROFINET RT	☆ 1911916	CAMC-F-PN
1		For DeviceNet	547451	CAMC-DN
		For EtherCAT	☆ 567856	CAMC-EC
	<i>ع</i> ا	For EtherNet/IP	☆ 1911917	CAMC-F-EP

#### Ordering data – Memory card

 oracing auta memory cara				
	Description	Part no.	Туре	
$\bigcirc$	Memory card, for data backup and firmware download	☆ 1436343	CAMC-M-S-F10-V1	

#### Ordering data - Connection options from I/O interface to the controller Description Cable length Part no. Туре [m] Control cable • For I/O interface to any controller 2.5 552254 NEBC-S1G25-K-2.5-N-LE26 • Recommended for analogue signals since the cable is shielded ☆ 8001373 NEBC-S1G25-K-3.2-N-LE25 • For I/O interface to any controller 3.2 • Cannot be used if the incremental encoder interface (plug X10) is in Ø use **Connection block** 8001371 NEFC-S1G25-C2W25-S7 Ensures simple and clear wiring. The connection to the motor controller is established via the connecting cable NEBC-S1G25-K-... Connecting cable • Connects the motor controller to the manifold block. 1.0 8001374 NEBC-S1G25-K-1.0-N-S1G25 • Cannot be used if the incremental encoder interface (input) is in use 2.0 8001375 NEBC-S1G25-K-2.0-N-S1G25 Ø 5.0 8001376 NEBC-S1G25-K-5.0-N-S1G25 Plug • 25-pin Sub-D plug. Each single core can be individually assembled 📩 8001372 NEFC-S1G25-C2W25-S6 using screw terminals. · Cannot be used if the incremental encoder interface (input) is in use

★ ☆ Generally ready for dispatch from the factory within 24 hours Generally ready for dispatch from the factory within 5 days

Ordering data – Cables an	Ordering data – Cables and plugs						
	Description	Cable length [m]	Part no.	Туре			
Programming cable							
	For CMMP-ASM0, CMMP-ASM3	1.8	1501332	NEBC-U1G4-K-1.8-N-U2G4			
Encoder plug							
	For incremental encoder interface	_	564264	NECC-A-S-S1G9-C2M			
Plugs							
	For PROFIBUS interface	-	533780	FBS-SUB-9-WS-PB-K			
	For CANopen interface	-	533783	FBS-SUB-9-WS-CO-K			
	For DeviceNet interface	-	525635	FBSD-KL-2X5POL			

Ordering data – Assortment of	Ordering data – Assortment of plugs					
	Description	Part no.	Туре			
	Assortment of plugs for:					
	Motor controller CMMP-AS-C5/-C10-11A-P3-M0	☆ 552256	NEKM-C-3 <sup>1)</sup>			
AND	Motor controller CMMP-AS-C5/-C10/-C15-11A-P3-M3					
	Interface CAMC-D-8E8A	569959	NEKM-C-5 <sup>2)</sup>			
Canada and C	Motor controller CMMP-AS-C2/-C5-3A-M0	📩 1659228	NEKM-C-7 <sup>1)</sup>			
(j)un	Motor controller CMMP-AS-C2/-C5-3A-M3					
	Safety module CAMC-G-S1	📩 1660640	NEKM-C-8 <sup>3)</sup>			
	Motor controller CMMP-ASM0					
	Safety module CAMC-G-S3	☆ 1660937	NEKM-C-9 <sup>4)</sup>			

1) Plugs are included in the scope of delivery of the motor controller CMMP-AS-...-M0, CMMP-AS-...-M3

2) Plugs are included in the scope of delivery of the plug-in card CAMC-D-8E8A

3) Plug is included in the scope of delivery of the plug-in card CAMC-G-S1

Plug is included in the scope of delivery of the motor controller CMMP-AS-...-M0

4) Plug is included in the scope of delivery of the plug-in card CAMC-G-S3

Ordering data - EMC filter for servo motors EMME-AS

For cable lengths  $\geq$  10 m, the use of the EMC filter is recommended to reduce EMC interference.

For encoder cables  $\ge$  10 m, the filter is included in the scope of delivery of the cable.

	Degree of protection	Ambient temperature	Part no.	Туре
	IP30	-40 +80°C	4825847	CAMF-C5-FC
	(in mounted state)			
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Festo core product range

★ ☆ Data sheets → Internet: emme-as

## Accessories

Ordering data – Braking re			1		Data sheets → Internet: ca
	For type	Resistance value	Nominal power	Part no.	Туре
		[Ω]	[W]		
CACR-LE2					
	CMMP-AS-C2-3A	50	200	2882342	CACR-LE2-50-W500 <sup>1)</sup>
	CMMP-AS-C5-3A	72	200	1336611	CACR-LE2-72-W500
CACR-KL2					
Man	CMMP-AS-C5-11A-P3	67	720	1336617	CACR-KL2-67-W1800
	CMMP-AS-C10-11A-P3	40	800	2882343	CACR-KL2-40-W2000 <sup>1)</sup>
	CMMP-AS-C15-11A-P3				

1) Recommended braking resistor

Ordering data – Mains filter							
	For type	Operating voltage	Input current	Dimensions	Part no.	Туре	
		[V]	[A]	[mm]			
	CMMP-AS-C15-11A-P3	520/300		Length: 230 Width: 50 Height: 70	3947275	CADF-C15-11A-P3	

## - 🌡 - Note

 $Re\bar{\bar{g}}$  ardless of the length of the motor cable, the mains filter is mandatory for compliance with the CE and EN standards.

#### Ordering data – Software and documentation

Description	→ Internet
<ul> <li>The following descriptions are available on the Festo website:</li> <li>Hardware: mounting and installation of all variants</li> <li>Functions: instructions on commissioning with FCT + functional description</li> <li>FHPP: control and parameterisation of the motor controller via the FHPP profile</li> <li>DS402: control and parameterisation of the motor controller via the device profile CiA 402 (DS402)</li> <li>Safety module: functional safety engineering for the motor controller with the safety function STO</li> </ul>	www.festo.com/net/SupportPortal

#### Ordering data – Software and documentation for the cam editor

Description	Part no.	Туре
Software package contains: • CD-ROM – With user documentation in de, en, es, fr, it, ru, zh The software package is not included in the scope of delivery	570903	GSPF-CAM-MC-ML

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