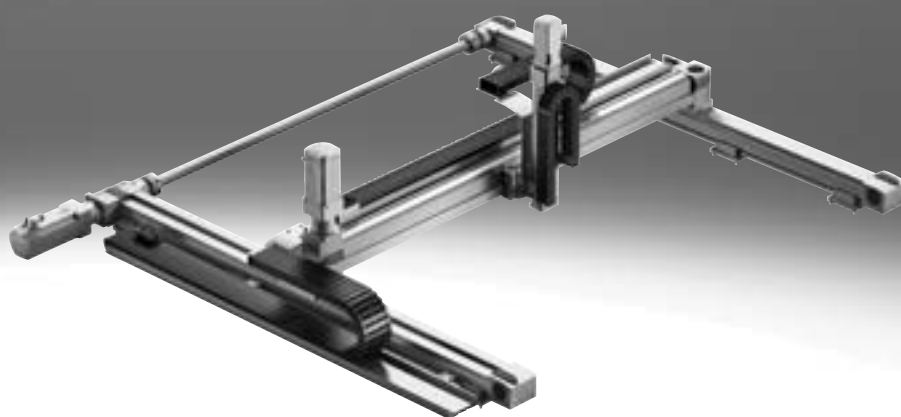


## 3-dimensional gantries

**FESTO**



### Key features

#### At a glance

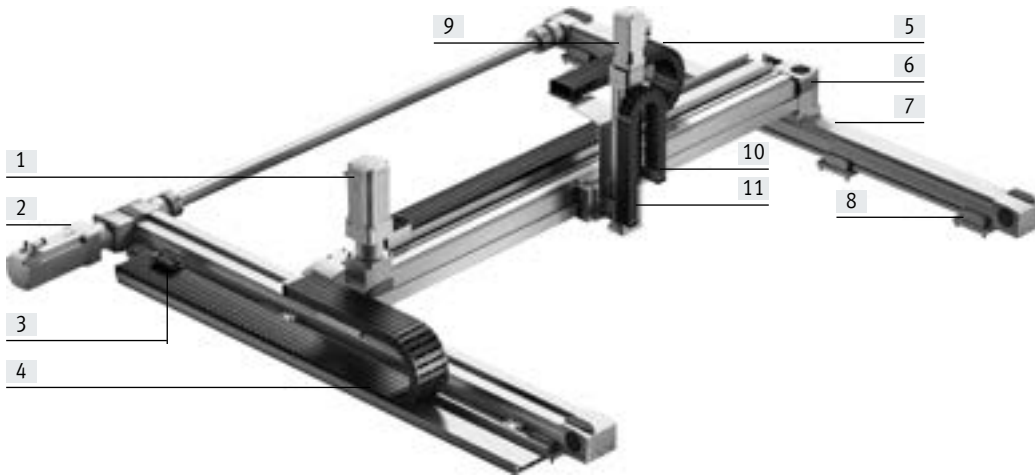
The 3-dimensional gantry facilitates movement in 3D space. Depending on the requirements, the gantry is either composed of several axis modules (YXCR) or using the planar surface gantries EXCM or EXCH (YXMR). All of these are tried-and-tested components from Festo.

- Can be used universally for handling light to heavy workpieces or high payloads
- Especially suitable for very long strokes
- High mechanical rigidity and sturdy design

- Pneumatic and electric components – freely combinable
- As an electrical solution – freely positionable/any intermediate positions

#### Range of application:

- For any movements in 3D space
- Very high requirements for precision and/or very heavy workpieces combined with long strokes



- [1] Servo motor for the Y-module
- [2] Servo motor for the X-module
- [3] Multi-pin plug distributor which collectively transfers all electrical signals such as for end-position sensing
- [4] Energy chain for the X-module
- [5] Energy chain for the Y-module
- [6] Y-axis
- [7] X-axis
- [8] Profile mounting/adjusting kit
- [9] Servo motor for the Z-module
- [10] Energy chain for the Z-module
- [11] Z-axis

#### Description of the modules

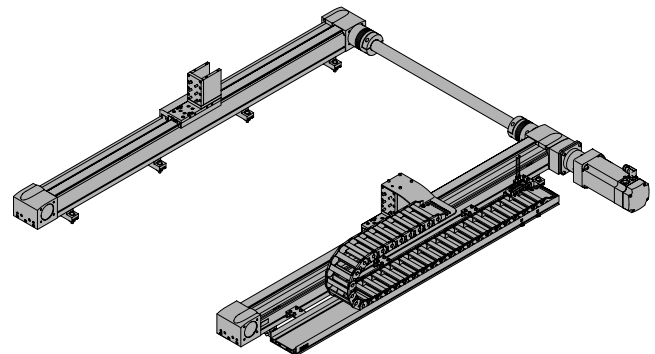
##### X-module

#### Design:

The X-module EHMx comprises two parallel toothed belt axes which are connected by a connecting shaft and they are powered by a servo motor. Adapters are mounted on the slides of the X-axes to connect the Y-module. The position of the motor and energy chain can be selected using the configurator. The following components are located on the motor side:

- Energy chain
- Multi-pin plug distributor for proximity sensor (if a sensor package has been selected)

#### Sample image:



## Key features

### Description of the modules

#### Y-module

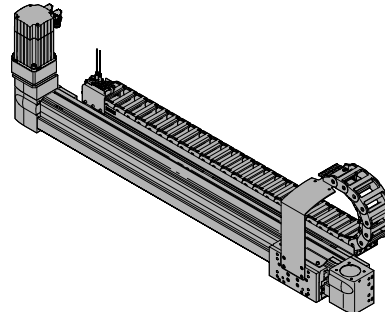
##### Design:

The Y-module EHY comprises a linear axis which is powered by a servo motor. Adapters are installed on the slides of the Y-axis to connect the Z-module. The position of the motor and energy chain is dependent on the position of the motor on the X-module.

The following components are located on the motor side:

- Energy chain
- Multi-pin plug distributor for proximity sensor (if a sensor package has been selected)

##### Sample image:



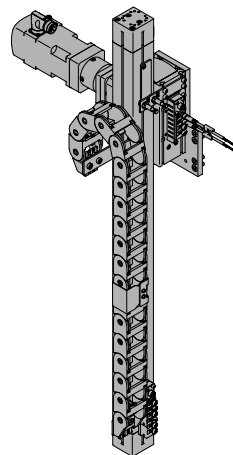
#### Z-module

##### Design:

The Z-module EHZ comprises an electric drive, the DHMZ comprises a pneumatic drive. In both variants, an energy chain is attached as a cable guide.

The Z-module can be selected using the configurator, depending on the application.

##### Sample image:



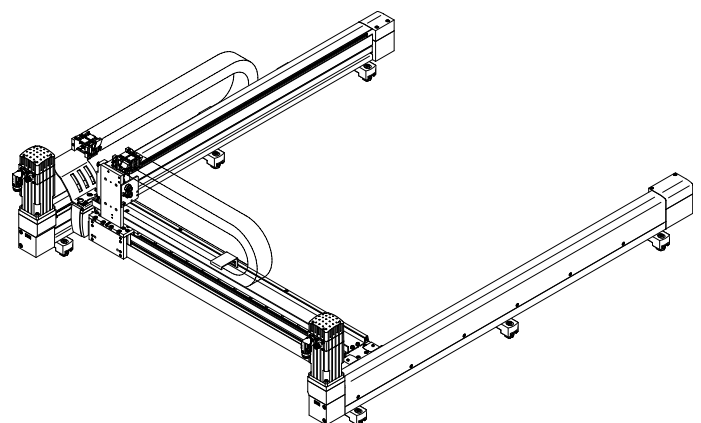
#### XY-module (EXCM, EXCH)

##### Design:

A slide is moved in a 2-dimensional space (X-axis/Y-axis) via a toothed belt. The system is powered by two fixed motors that are coupled to the toothed belt. The belt is guided via pulleys so that the slide can move to any position in a working space when the motors are actuated.

When using attachment components, additional processes can be carried out by independent Z-axes.

##### Sample image:



Key features

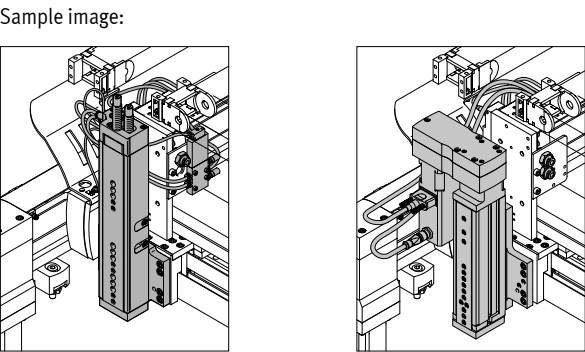
Description of the modules

Z-module (EXCM, EXCH)

Design:

The Z-module comprises either an electric drive (EHMZ) or a pneumatic drive (DHMZ).

The Z-module can be selected using the configurator, depending on the application.



Dispatch options

Fully assembled: Partially assembled:

The 3-dimensional gantry is fully assembled. All cables and tubing are installed and connected. The system is already set up on delivery, but must be adapted to the particular mounting surface during installation.

Note flatness → table below.

The 3-dimensional gantry is delivered partially assembled. This means that all three axis modules (X-/Y-/Z-axis) are assembled, each with the optional motors. The partially assembled system must be completed by the customer. Help can be found in the assembly instructions provided.

Optional accessories (→ page 11) are enclosed.

Note flatness → table below.

System overview <sup>1)</sup>				
Size	YXCR-1	YXCR-2	YXCR-3	YXCR-4
Max. working stroke	X: 1900 mm Y: 1900 mm Z: 50 mm	X: 3000 mm Y: 2000 mm Z: 800 mm	X: 3000 mm Y: 2000 mm Z: 800 mm	X: 3000 mm Y: 2000 mm Z: 800 mm
Max. payload	Dependent on the selected dynamic response			
Required flatness of the mounting surface	≤ 0.1 mm/m			
Mounting position	Horizontal			

Size	YXMR-1	YXMR-2	YXMR-3
Max. working stroke	X: 700 mm Y: 510 mm Z: 100 mm (electric) 150 mm (pneumatic)	X: 2000 mm Y: 1000 mm Z: 200 mm (electric) 150 mm (pneumatic)	X: 2500 mm Y: 1500 mm Z: 200 mm
Max. payload	Dependent on the selected dynamic response		
Required flatness of the mounting surface	≤ 0.1 mm/m		
Mounting position	Horizontal		

1) Drive package depends on configuration selected.

## Key features

### Configurator: Handling Guide Online (HGO)

#### Selecting a handling system

Planning complex handling systems takes a lot of time. You can use the configurator "Handling Guide Online" (HGO) to design a customised handling system for your application in just a few steps.




You can choose from the following systems:

- Single-axis system
- 2D linear gantry
- 2D planar surface gantry
- 3-dimensional gantry

#### Advantages:

- Automatic selection of all relevant components
- Automatic design and calculation of workload
- Quote created automatically
- CAD model available immediately
- Fully automated processing
- Fully assembled or unassembled systems can be ordered through the Online Shop
- Lots of possible options

**Selecting the handling solution**  
Select your handling system:

<input type="radio"/> Single-axis system		Single-axis movement. Single-axis module as a complete system. Easy to connect to your own fixed unit. <input type="checkbox"/> Animation
<input type="radio"/> 2D linear gantry		Movements in 2D in the vertical working space. Linear gantries as complete systems. Electric and pneumatic axes can be combined. <input type="checkbox"/> Animation
<input type="radio"/> 2D gantry		Movements in 2D in the horizontal working space. Planar surface gantries as complete systems. Combining electric axes. Easy to connect to your own Z unit. <input type="checkbox"/> Animation
<input checked="" type="radio"/> 3D gantry		Movements in 3D. Three-dimensional gantries as complete systems. Electric and pneumatic axes can be combined. <input type="checkbox"/> Animation

Data protection Continue

#### Entering the application data

- Payload
- Drive system of the axis
- Distance from the centre of the load
- Working stroke
- Reference cycle

**Axis definition and payload**  
Axis definition:

Drive system of the axis:

- X: ☒ Electric; several positions
- Y: ☐ Electric; several positions
- Z: ☐ Electric; several positions ☒ Hydraulic; several positions

Required working stroke:

- X:  mm
- Y:  mm
- Z:  mm

Working stroke in Z direction:

- Z:  mm

Take the stroke reserve into account in your specification.


Payload:

Sum of the weights of the fixed unit and the workpiece:  kg

Distance from the centre of the load:

- X:  mm
- Y:  mm
- Z:  mm

Data protection Back Continue



3-dimensional gantries

Key features

Configurator: Handling Guide Online (HGO)  
Result of calculation

You will be offered a selection of systems calculated based on the application data you entered.

- The following are available immediately:
- CAD model
  - Data sheet of the selected system
  - Price information

Result of calculation

Select the appropriate system and continue with the configuration:

No.	System series	System workload (kg)	Repetition accuracy (mm)	Your price
<input checked="" type="checkbox"/>	1 YXCR1.1	50 %	0.15 mm	
<input type="checkbox"/>	2 YXCR1.2	40 %	0.15 mm	
<input type="checkbox"/>	5 YXCR1.2	62 %	0.15 mm	
<input type="checkbox"/>	7 YXCR1.2	32 %	0.15 mm	
<input type="checkbox"/>	26 YXCR1.2	68 %	0.7 mm	

Requires additional motion controller for interpolation ( e.g. CPX-E-CEC-M1- ... )

3D gantry YXCR 1.1:1

	X module: toothed belt axis EIOC-50	Y module: toothed belt axis EIOC-50	Z module: Electric mini slide EIOH-35
Kinematics type	Serial kinematics	Serial kinematics	Serial kinematics
Stroke	200 mm	200 mm	50 mm
Repetition accuracy (mm)	0.06 mm	0.06 mm	0.02 mm
Drive unit	S-1	S-1	Without
Type of motor	Servo motor (EMME-A)	Servo motor (EMME-A)	Servo motor (EMME-A)
Motor position	Right	Right	Top

Data protection

System overview

You will be given an overview of the whole system.  
You will also have the following options:

- Request price
- Send request
- Add to basket

Your handling solution

Your selected system overview:



Exemplary representation

Your system ID:  
**C1374165**

Your next steps:

- View price
- Send request
- Add to basket

Download CAD-Files

Your product Your system Your options

Feature	Value
Handling type	3D gantry
Payload	2 kg
Drive system of the X-axis	Electric: several positions
Drive system of the Y-axis	Electric: several positions

Data protection

## Key features

### Standard components within the handling system

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. The single axes installed will be displayed in the configurator HGO on the "Result of calculation" page.

### Drives/axes

#### X-axis

##### Toothed belt axis EGC-TB-KF



- Electric
- Rigid, closed profile
- Recirculating ball bearing guide for high loads and torques
- High dynamic response and minimum vibration

#### Y-axis

##### Toothed belt axis EGC-TB-KF



- Electric
- Rigid, closed profile
- Recirculating ball bearing guide for high loads and torques
- High dynamic response and minimum vibration

##### Toothed belt axis EGC-HD-TB



- Electric
- Flat drive unit with rigid, closed profile
- Duo guide rail
- For maximum loads and torques, high feed forces and speeds and long service life

#### Z-axis

##### Mini slide DGSL



- Pneumatic
- Flat design
- High load capacity
- High dynamic response
- Easy adjustment of end positions

##### Mini slide EGSL



- Electric
- Compact design
- High load capacity
- High dynamic response
- Easy adjustment of end positions

##### Spindle axis EGC-BS-KF



- Electric
- Rigid, closed profile
- Recirculating ball bearing guide for high loads and torques
- High dynamic response and minimum vibration
- Various spindle pitches

## Key features

### Drives/axes

Z-axis

#### Mini slide EGSC



- Electric
- Compact design
- High load capacity
- Precision guide and ball screw drive
- Easy adjustment of end positions

Possible axis combinations <sup>1)</sup>			
Size	X-module	Y-module	Z-module
YXCR-1	<ul style="list-style-type: none"> <li>• Toothed belt axis EGC-50-TB-KF</li> </ul>	<ul style="list-style-type: none"> <li>• Toothed belt axis EGC-50-TB-KF</li> </ul>	<ul style="list-style-type: none"> <li>• Mini slide pneumatic: DGSL-6</li> <li>electric: EGSL-35</li> </ul>
YXCR-2	<ul style="list-style-type: none"> <li>• Toothed belt axis EGC-80-TB-KF</li> </ul>	<ul style="list-style-type: none"> <li>• Toothed belt axis EGC-80-TB-KF</li> <li>• Toothed belt axis with heavy-duty guide EGC-HD-125-TB</li> </ul>	<ul style="list-style-type: none"> <li>• Mini slide pneumatic: DGSL-12/16</li> <li>electric: EGSL-45/55</li> <li>• Cantilever axis DGEA-18</li> <li>• Spindle axis EGC-70-BS-KF</li> </ul>
YXCR-3	<ul style="list-style-type: none"> <li>• Toothed belt axis EGC-120-TB-KF</li> </ul>	<ul style="list-style-type: none"> <li>• Toothed belt axis EGC-120-TB-KF</li> <li>• Toothed belt axis with heavy-duty guide EGC-HD-160-TB</li> </ul>	<ul style="list-style-type: none"> <li>• Mini slide pneumatic: DGSL-20/25</li> <li>electric: EGSL-75</li> <li>• Cantilever axis DGEA-25/40</li> <li>• Spindle axis EGC-80-BS-KF</li> </ul>
YXCR-4	<ul style="list-style-type: none"> <li>• Toothed belt axis EGC-185-TB-KF</li> </ul>	<ul style="list-style-type: none"> <li>• Toothed belt axis EGC-185-TB-KF</li> <li>• Toothed belt axis with heavy-duty guide EGC-HD-220-TB</li> </ul>	<ul style="list-style-type: none"> <li>• Cantilever axis DGEA-40</li> <li>• Spindle axis EGC-120-BS-KF</li> </ul>
YXMR-1	<ul style="list-style-type: none"> <li>• Planar surface gantry EXCM-30</li> </ul>	<ul style="list-style-type: none"> <li>• Planar surface gantry EXCM-30</li> </ul>	<ul style="list-style-type: none"> <li>• Mini slide pneumatic: DGSL-8/10/12</li> <li>electric: EGSC-25/32</li> </ul>
YXMR-2	<ul style="list-style-type: none"> <li>• Planar surface gantry EXCM-40, EXCH-40</li> </ul>	<ul style="list-style-type: none"> <li>• Planar surface gantry EXCM-40, EXCH-40</li> </ul>	<ul style="list-style-type: none"> <li>• Mini slide pneumatic: DGSL-16</li> <li>electric: EGSL-45</li> </ul>
YXMR-3	<ul style="list-style-type: none"> <li>• Planar surface gantry EXCH-60</li> </ul>	<ul style="list-style-type: none"> <li>• Planar surface gantry EXCH-60</li> </ul>	<ul style="list-style-type: none"> <li>• Mini slide pneumatic: DGSL-20</li> <li>electric: EGSL-55</li> </ul>

1) Drive package depends on configuration selected.



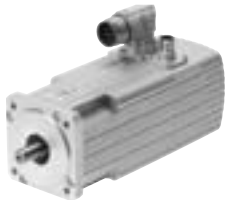
## Key features

### Standard components within the handling system

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. You can alter the scope and design of the drive package in the configurator HGO on the "System configuration" page.

### Motors and controllers

#### Servo motors EMMS-AS



- Dynamic, brushless, permanently excited servo motor
- Digital absolute displacement encoder in single-turn or multi-turn version
- With optional brake

#### Servo motors EMME-AS



- Dynamic, brushless, permanently excited servo motor
- Digital absolute displacement encoder in single-turn or multi-turn version
- With optional brake

#### Stepper motors EMMS-ST



- 2-phase hybrid technology
- Step angle 1.8°
- With optional brake

#### Gear unit EMGA



- Low-backlash planetary gear
- Gear ratio  
 $i = 3$  and  $5$
- Life-time lubrication

#### Motor controller CMMP-AS for servo motor



- Complete integration of all components for controller and power section, including USB interface
- Integrated brake chopper
- Integrated EMC filters
- Automatic activation for a brake

#### Options:

- Safety function: safe torque off (STO)/category 4, Performance Level e
- Additional digital inputs and outputs

- Bus protocols
  - CANopen
  - DeviceNet
  - EtherCAT
  - EtherNet/IP
  - PROFIBUS DP
  - PROFINET

### Key features

#### Standard components within the handling system

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. You can alter the scope and design of the drive package in the configurator HGO on the "System configuration" page.

#### Motor controller CMMS-ST for stepper motor



- Complete integration of all components for controller and power section, including RS232 interface
- Integrated brake chopper
- Integrated EMC filters
- Automatic activation for a brake

##### Options:

- Safety function: safe torque off (STO)/category 3, Performance Level d

- Bus protocols
  - CANopen
  - DeviceNet
  - PROFIBUS DP

#### Motor controller CMMO-ST for stepper motor



- Separate load and logic supply
- Monitoring of freely defined positions and torque ranges
- Backup file enables seamless device replacement

- Encoder option (closed loop), in other words no step losses, following errors are corrected

##### Options:

- Safety function: safe torque off (STO)/category 3, Performance Level e

- Easy activation via:
  - I/O interface
  - IO-Link or I-Port
  - Modbus TCP

#### Controller CMXH-ST2, for stepper motor



- The controller controls two stepper motors in servo mode which drive an H-shaped recirculating toothed belt. The toothed belt moves a slide whose position is calculated by the controller using the encoder signals from the motors

##### Options:

- Safety function: safe torque off (STO)/category 3, Performance Level e

- Bus protocols
  - I/O interface
  - CAN interface
  - Ethernet TCP/IP

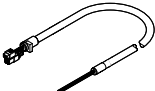
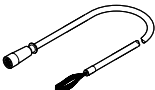
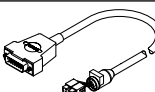
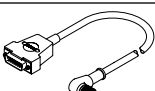
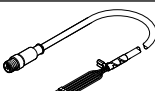
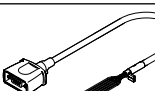
## Ordering data – Accessories

## Module/motor combinations

We recommend that the 3-dimensional gantry is operated with the proposed motors from Festo. These precisely match the mechanical system. When using third-party motors, it is essential that the technical limits are observed.

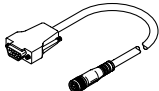
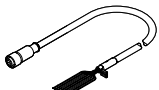
Module	Motor		
	Servo motor	Servo motor	Stepper motor
X-module			
EHMX-EGC-50-TB-KF	–	EMME-AS-40-M-LV-...	EMMS-ST-42-S-...
EHMX-EGC-80-TB-KF	EMMS-AS-70-M-LS-...	EMME-AS-60-M-LS-...	EMMS-ST-57-S-...
EHMX-EGC-120-TB-KF	EMMS-AS-100-M-HS-...	EMME-AS-80-S-LS-...	–
EHMX-EGC-185-TB-KF	EMMS-AS-140-L-HS-...	–	–
Y-module			
EHMY-...-EGC-50-TB-KF	–	EMME-AS-40-S-LV-...	EMMS-ST-57-M-...
EHMY-...-EGC-80-TB-KF	EMMS-AS-55-S-LS-...	EMME-AS-60-M-LS-...	EMMS-ST-57-S-...
EHMY-...-EGC-120-TB-KF	EMMS-AS-100-S-HS-...	EMME-AS-80-S-LS-...	EMMS-ST-87-S-...
EHMY-...-EGC-125-TB-HD	EMMS-AS-70-S-LS-...	EMME-AS-60-M-LS-...	EMMS-ST-57-S-...
EHMY-...-EGC-160-TB-HD	EMMS-AS-100-S-HS-...	EMME-AS-80-S-LS-...	EMMS-ST-87-S-...
EHMY-...-EGC-185-TB-KF	EMMS-AS-100-M-HS-...	EMME-AS-100-M-HS-...	–
	EMMS-AS-140-S-HS-...		
EHMY-...-EGC-220-TB-HD	EMMS-AS-100-M-HS-...	EMME-AS-100-M-HS-...	–
	EMMS-AS-140-S-HS-...		
Z-module			
EHMZ-DGEA-18-TB-KF	EMMS-AS-55-S-LS-...	EMME-AS-60-M-LS-...	EMMS-ST-57-S-...
EHMZ-DGEA-25-TB-KF	EMMS-AS-70-S-LS-...	EMME-AS-60-M-LS-...	EMMS-ST-57-S-...
EHMZ-DGEA-40-TB-KF	EMMS-AS-100-S-HS-...	EMME-AS-80-M-LS-...	–
EHMZ-EGC-70-BS-KF	EMMS-AS-55-S-LS-...	EMME-AS-60-M-LS-...	EMMS-ST-57-S-...
EHMZ-EGC-80-BS-KF	EMMS-AS-70-S-LS-...	EMME-AS-60-M-LS-...	EMMS-ST-57-S-...
EHMZ-EGC-120-BS-KF	EMMS-AS-100-S-HS-...	EMME-AS-80-S-LS-...	–
EHMZ-EGSL-35-BS-KF	–	EMME-AS-40-S-LV-...	EMMS-ST-28-L-...
EHMZ-EGSL-45-BS-KF	EMMS-AS-40-M-LS-...	EMME-AS-40-S-LV-...	EMMS-ST-57-S-...
EHMZ-EGSL-55-BS-KF	EMMS-AS-55-S-LS-...	EMME-AS-60-M-LS-...	EMMS-ST-57-S-...
EHMZ-EGSL-75-BS-KF	EMMS-AS-70-M-LS-...	EMME-AS-80-S-LS-...	EMMS-ST-87-S-...
XY-module (EXCM, EXCH)			
EXCM-30	–	–	EMMS-ST-42-S-...
EXCM-40	–	–	EMMS-ST-57-M-...
EXCH-40	EMMS-AS-70-M-LS-...	–	–
EXCH-40	EMMS-AS-100-S-HS-...	–	–
EXCH-60	EMMS-AS-100-M-HS-...	–	–
EXCH-60	EMMS-AS-140-S-HV-...	–	–
Z-module (EXCM, EXCH)			
EHMZ-EGSC-BS-KF-25-...-V1	–	–	EMMS-ST-28-L-...
EHMZ-EGSC-BS-KF-32-...-V1	–	–	EMMS-ST-42-S-...
EHMZ-EGSL-45-BS-KF	EMMS-AS-40-M-LS-...	–	–
EHMZ-EGSL-55-BS-KF	EMMS-AS-55-S-LS-...	–	–

## Ordering data – Accessories

Designation	Description	Cable length	Part no.	Type
For servo motor				
Motor cable <sup>1)</sup>				
	• For servo motor EMMS-AS-40-M-LS-.../ EMMS-AS-55-S-LS-...	5 m	550306	NEBM-T1G8-E-5-Q7N-LE8
		10 m	550307	NEBM-T1G8-E-10-Q7N-LE8
		15 m	550308	NEBM-T1G8-E-15-Q7N-LE8
Motor cable <sup>1)</sup>				
	• For servo motor EMMS-AS-70-S-LS-.../ EMMS-AS-70-M-LS-.../EMMS-AS-100-S-HS-.../ EMMS-AS-100-M-HS-.../EMMS-AS-140-S-HS-.../ EMMS-AS-140-L-HS-...	5 m	550310	NEBM-M23G8-E-5-Q9N-LE8
		10 m	550311	NEBM-M23G8-E-10-Q9N-LE8
		15 m	550312	NEBM-M23G8-E-15-Q9N-LE8
Encoder cable <sup>1)</sup>				
	• For servo motor EMMS-AS-40-M-LS-.../ EMMS-AS-55-S-LS-...	5 m	550314	NEBM-T1G8-E-5-N-S1G15
		10 m	550315	NEBM-T1G8-E-10-N-S1G15
		15 m	550316	NEBM-T1G8-E-15-N-S1G15
Encoder cable <sup>1)</sup>				
	• For servo motor EMMS-AS-70-S-LS-.../ EMMS-AS-70-M-LS-.../EMMS-AS-100-S-HS-.../ EMMS-AS-100-M-HS-.../EMMS-AS-140-S-HS-.../ EMMS-AS-140-L-HS-...	5 m	550318	NEBM-M12W8-E-5-N-S1G15
		10 m	550319	NEBM-M12W8-E-10-N-S1G15
		15 m	550320	NEBM-M12W8-E-15-N-S1G15
For stepper motor				
Motor cable <sup>1)</sup>				
	• For stepper motor EMMS-ST-28-L-...	1.5 m	1449600	NEBM-SM12G8-E-1.5-Q5-LE6
		2.5 m	1449601	NEBM-SM12G8-E-2.5-Q5-LE6
		5 m	1449602	NEBM-SM12G8-E-5-Q5-LE6
		7 m	1449603	NEBM-SM12G8-E-7-Q5-LE6
		10 m	1449604	NEBM-SM12G8-E-10-Q5-LE6
Motor cable <sup>1)</sup>				
	• For stepper motor EMMS-ST-42-S-.../EMMS-ST-57-M-...	2.5 m	1450369	NEBM-S1G9-E-2.5-Q5-LE6
		5 m	1450370	NEBM-S1G9-E-5-Q5-LE6

1) Cables especially suitable for the motor controller and motor.  
Degree of protection to IP65 (in assembled state)

## Ordering data – Accessories

Designation	Description	Cable length	Part no.	Type
For stepper motor				
Encoder cable <sup>1)</sup>				
	• For stepper motor EMMS-ST-28-L-.../EMMS-ST-42-S-.../ EMMS-ST-57-M-... and motor controller CMMS-ST	5 m	550748	NEBM-M12G8-E-5-S1G9
		10 m	550749	NEBM-M12G8-E-10-S1G9
		15 m	550750	NEBM-M12G8-E-15-S1G9
Encoder cable <sup>1)</sup>				
	• For stepper motor EMMS-ST-28-L-... and motor controller CMMO-ST	2.5 m	1451587	NEBM-M12G8-E-2.5-LE8
		5 m	1451588	NEBM-M12G8-E-5-LE8

1) Cables especially suitable for the motor controller and motor.  
Degree of protection to IP65 (in assembled state)

## Possible cable and tube lengths

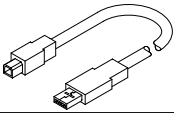
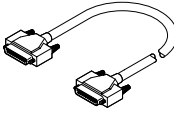
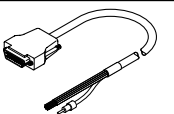
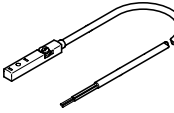

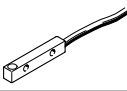
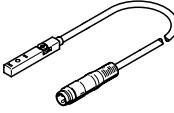
- Cables and tubing are selected so that the minimum length available from the energy chain output is the connection length specified when ordering.
- Cables and tubing are only available in fixed lengths as stated in the table below. This can mean that the cable plugs of the different cables do not end at the same point.

Length	1 m	2 m	5 m	7 m	10 m
Motor cable	–	■	■	■	■
Encoder cable	–	■	■	■	■
Multi-pin plug connecting cable	–	■	■	■	■
Tubing (for DHMZ only)	■	■	■	–	–

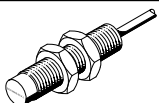
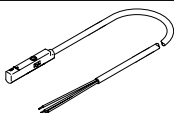
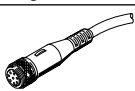
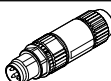
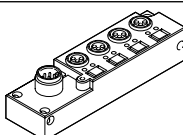
## Ordering data – Accessories

## Standard components within the handling system

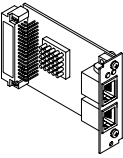
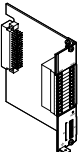
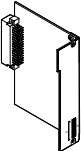

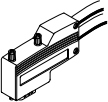
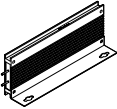
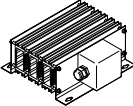
The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. You can alter the scope and design of the accessories in the configurator HGO on the "System configuration" page.

Designation	Description	Cable length	Part no.	Type	
Programming cable					
	<ul style="list-style-type: none"><li>High-speed USB 2.0 connecting cable</li><li>For controller CMMP-AS</li></ul>	1.8 m	1501332	NEBC-U1G4-K-1.8-N-U2G4	
	<ul style="list-style-type: none"><li>For controller CMMS-ST</li></ul>	2 m	160786	PS1-ZK11-NULLMODEM-2.0M	
Control cable (for I/O interface to any controller)					
	<ul style="list-style-type: none"><li>For controller CMMP-AS, CMMS-ST</li></ul>	2.5 m	552254	NEBC-S1G25-K-2.5-N-LE26	
	<ul style="list-style-type: none"><li>For controller CMMO-ST</li></ul>	3.2 m	8001373	NEBC-S1G25-K-3.2-N-LE25	
	<ul style="list-style-type: none"><li>For controller CMXH-ST2</li></ul>	2.5 m	2052917	NEBC-S1H15-E-2.5-N-LE15	
Proximity sensor (inductive) for sensing the position of the slide on the X-/Z-axis					
	Cable with open end				
	<ul style="list-style-type: none"><li>For toothed belt axis EGC-TB</li></ul>	PNP, N/C contact	7.5 m	551391	SIES-8M-PO-24V-K-7.5-OE
	<ul style="list-style-type: none"><li>For spindle axis EGC-BS</li></ul>	PNP, N/O contact	7.5 m	551386	SIES-8M-PS-24V-K-7.5-OE
	<ul style="list-style-type: none"><li>For mini slide EGSL</li></ul>	NPN, N/C contact	7.5 m	551401	SIES-8M-NO-24V-K-7.5-OE
	<ul style="list-style-type: none"><li>For direct voltage</li></ul>	NPN, N/O contact	7.5 m	551396	SIES-8M-NS-24V-K-7.5-OE
Included if the "Festo sensor package" is selected: <ul style="list-style-type: none"><li>2 pieces</li></ul>					
Proximity sensor for sensing the position of the slide on the X-axis					
	<ul style="list-style-type: none"><li>For EXCM-40, EXCH-40, EXCH-60</li></ul>	N/O contact	–	150491	SIES-V3B-PS-S-L
	<ul style="list-style-type: none"><li>For EXCM-40, EXCH-40, EXCH-60</li></ul>	N/C contact	–	174552	SIES-Q8B-PO-K-L
Proximity sensor (inductive) for sensing the position of the slide on the Y-axis					
	Cable with plug				
	<ul style="list-style-type: none"><li>For toothed belt axis EGC-TB, EGC-HD-TB</li></ul>	PNP, N/C contact	0.3	551392	SIES-8M-PO-24V-K-0.3-M8D
	<ul style="list-style-type: none"><li>For direct voltage</li></ul>	PNP, N/C contact	2.5	551393	SIES-8M-PO-24V-K-2.5-M8D
	Included if the "Festo sensor package" is selected: <ul style="list-style-type: none"><li>2 pieces</li></ul>	PNP, N/O contact	0.3	551387	SIES-8M-PS-24V-K-0.3-M8D
		PNP, N/O contact	2.5	551388	SIES-8M-PS-24V-K-2.5-M8D
		NPN, N/C contact	0.3	551402	SIES-8M-NO-24V-K-0.3-M8D
		NPN, N/C contact	2.5	551403	SIES-8M-NO-24V-K-2.5-M8D
		NPN, N/O contact	0.3	551397	SIES-8M-NS-24V-K-0.3-M8D
		NPN, N/O contact	2.5	551398	SIES-8M-NS-24V-K-2.5-M8D

## Ordering data – Accessories

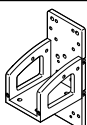
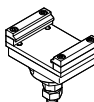
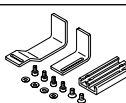

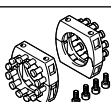
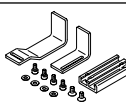
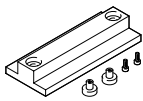
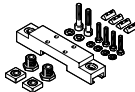
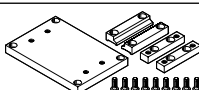
Designation	Description	Cable length	Part no.	Type	
Proximity sensor (inductive) for sensing the position of the slide on the Z-axis					
	<b>Cable with open end</b> <ul style="list-style-type: none"><li>For cantilever axis DGEA</li><li>For direct voltage</li></ul> Included if the "Festo sensor package" is selected: <ul style="list-style-type: none"><li>2 pieces</li></ul>	PNP, N/C contact	2.5 m	150398	SIEN-M8NB-PO-K-L
		PNP, N/O contact	2.5 m	150394	SIEN-M8NB-PS-K-L
		NPN, N/C contact	2.5 m	150396	SIEN-M8NB-NO-K-L
		NPN, N/O contact	2.5 m	150392	SIEN-M8NB-NS-K-L
Proximity sensor (magnetoresistive) for sensing the position of the slide on the Z-axis					
	<b>Cable with open end</b> <ul style="list-style-type: none"><li>For mini slide DGSL</li><li>For direct voltage</li></ul> Included if the "Festo sensor package" is selected: <ul style="list-style-type: none"><li>2 pieces</li></ul>	PNP, N/O contact	2.5 m	551373	SMT-10M-PS-24V-E-2.5-L-OE
		NPN, N/O contact	2.5 m	551377	SMT-10M-NS-24V-E-2.5-L-OE
Designation	Description	Cable length	Part no.	Type	
Plug socket with cable					
	• Connection between multi-pin plug distributor and control cabinet	5 m	525618	SIM-M12-8GD-5-PU	
		10 m	570008	SIM-M12-8GD-10-PU	
Plugs					
	• For connection to the multi-pin plug distributor	–	562024	NECU-S-M8G3-HX	
Multi-pin plug distributor					
	• With the help of the multi-pin plug distributor, electrical signals such as for end-position sensing can be transferred collectively Options: <ul style="list-style-type: none"><li>– 4 individual connections</li><li>– 6 individual connections</li></ul>	–	574586	NEDU-L4R1-M8G3L-M12G8	
			574587	NEDU-L6R1-M8G3L-M12G8	

## Ordering data – Accessories

Designation	Description	Part no.	Type
<b>Interface</b>			
	For additional I/Os	567855	CAMC-D-8E8A
	For DeviceNet	547451	CAMC-DN
	For EtherCAT	567856	CAMC-EC
	For EtherNet/IP	1911917	CAMC-F-EP
	For PROFINET RT	1911916	CAMC-F-PN
	For PROFIBUS DP	547450	CAMC-PB
<b>Safety module</b>			
	<ul style="list-style-type: none"> <li>For safe torque off (STO)</li> </ul>	1501330	CAMC-G-S1
<b>Switch module</b>			
	<ul style="list-style-type: none"> <li>If the safety module CAMC-G-S1 is not used, the switch module is absolutely essential for operating the motor controller CMMP-AS-...-M3</li> </ul>	1501329	CAMC-DS-M1
<b>Bus connection</b>			
	<ul style="list-style-type: none"> <li>For DeviceNet interface</li> </ul>	525635	FBSD-KL-2X5POL
<b>Plugs</b>			
	<ul style="list-style-type: none"> <li>For CANopen interface</li> </ul>	533783	FBS-SUB-9-WS-CO-K
	<ul style="list-style-type: none"> <li>For PROFIBUS interface</li> </ul>	533780	FBS-SUB-9-WS-PB-K
<b>Braking resistor</b>			
	<ul style="list-style-type: none"> <li>For EXCH-40</li> <li>Essential in the case of a vertical mounting position</li> </ul>	2882342	CACR-LE2-50-W500
	<ul style="list-style-type: none"> <li>For EXCH-60</li> <li>Essential in the case of a vertical mounting position</li> </ul>	2882343	CACR-KL2-40-W2000



## Ordering data – Accessories

Designation	Description	Part no.	Type
Mounting kit			
	<ul style="list-style-type: none"><li>Mounting kit for the energy chain and a Z-axis, such as EGSL, DGSL</li></ul>	<ul style="list-style-type: none"><li>EXCM-30</li></ul>	<div>4070088</div> <div>EAHT-E9-FB-3D-30</div>
Adjusting kit			
	<ul style="list-style-type: none"><li>Height-adjustable mounting kit</li></ul>	<ul style="list-style-type: none"><li>EXCM-30</li></ul>	<div>4070088</div> <div>EADC-E11-30</div>
Sensor mounting			
	<ul style="list-style-type: none"><li>For homing in combination with third-party motors</li></ul>	<ul style="list-style-type: none"><li>EXCM-30</li></ul>	<div>4070088</div> <div>EAPR-E11-30</div>
Energy chain			
	<ul style="list-style-type: none"><li>For routing the cables for the Z-axis</li></ul>	<ul style="list-style-type: none"><li>EXCM-30</li></ul>	<div>8059999</div> <div>EADH-U-3D-30</div>
			<div>8060324</div> <div>EADH-U-3D-40</div>
Connector set			
	<ul style="list-style-type: none"><li>Holder for mounting the energy chain</li></ul>	<ul style="list-style-type: none"><li>EXCM-30</li></ul>	<div>8060325</div> <div>EAHT-AE-3D-30</div>
			<div>8060326</div> <div>EAHT-AE-3D-40</div>
Sensor mounting			
	<ul style="list-style-type: none"><li>For mounting the proximity sensors SIES-Q8B, SIES-V3B on the X-axis</li></ul>	<ul style="list-style-type: none"><li>EXCM-40, EXCH-40</li></ul>	<div>2536353</div> <div>EAPR-E12-40</div>
		<ul style="list-style-type: none"><li>EXCH-60</li></ul>	<div>2478805</div> <div>EAPR-E12-60</div>
Adjusting tool			
	<ul style="list-style-type: none"><li>For aligning and checking the flatness of the planar surface gantry</li></ul>	<div>3197697</div>	<div>EADT-W-E12</div>
Adjusting kit			
	<ul style="list-style-type: none"><li>Used to mount the handling system on the supporting surface</li><li>Can be used to easily compensate for any unevenness in the supporting surface</li></ul>	<ul style="list-style-type: none"><li>EHMY-...-EGC-50-TB-KF</li></ul>	<div>8047565</div> <div>EADC-E15-50-E7</div>
		<ul style="list-style-type: none"><li>EHMY-...-EGC-80-TB-KF</li></ul>	<div>8047566</div> <div>EADC-E15-80-E7</div>
		<ul style="list-style-type: none"><li>EHMY-...-EGC-120-TB-KF</li></ul>	<div>8047567</div> <div>EADC-E15-120-E7</div>
		<ul style="list-style-type: none"><li>EHMY-...-EGC-185-TB-KF</li></ul>	<div>8047568</div> <div>EADC-E15-185-E7</div>
Profile mounting			
	<ul style="list-style-type: none"><li>Used to mount the handling system on the supporting surface</li><li>It is not height-adjustable</li></ul>	<div>—</div>	

### Programming aid

#### FCT software – Festo Configuration Tool

Software platform for electric drives from Festo (→ [www.festo.com/sp/fct](http://www.festo.com/sp/fct))



- All drives in a system can be managed and saved in a common project
- Project and data management for all supported types of equipment
- Easy to use thanks to graphically supported parameter entry
- Universal mode of operation for all drives
- Work offline at your desk or online at the machine