FESTO

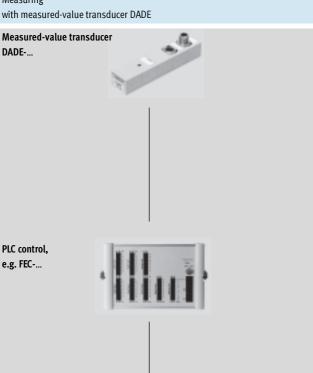




Components for positioning and measuring using the standard cylinder DNCI



Measuring



Operator unit e.g. FED-...



Positioning

with end-position controller SPC11 or controller module CPX-CMAX/-CMPX



Proportional directional



End-position controller SPC11-INC



Proportional directional control valve VPWP-...



Sensor interface CASM-S-D3-R7



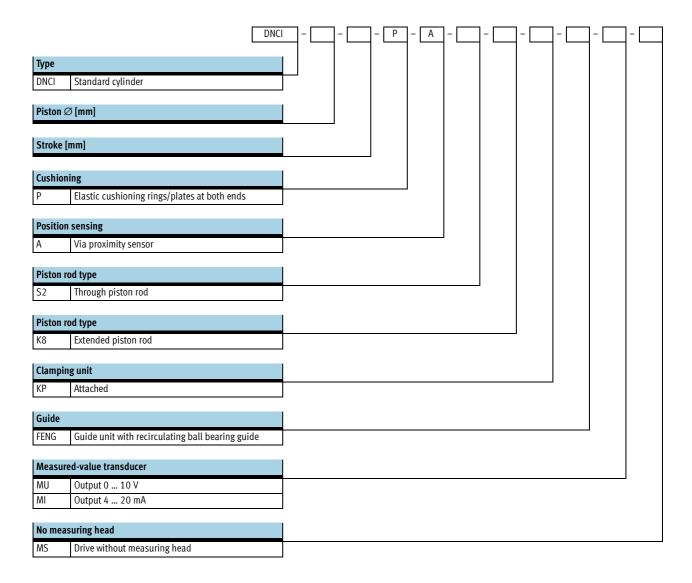
Controller module CPX-CMAX, CPX-CMPX





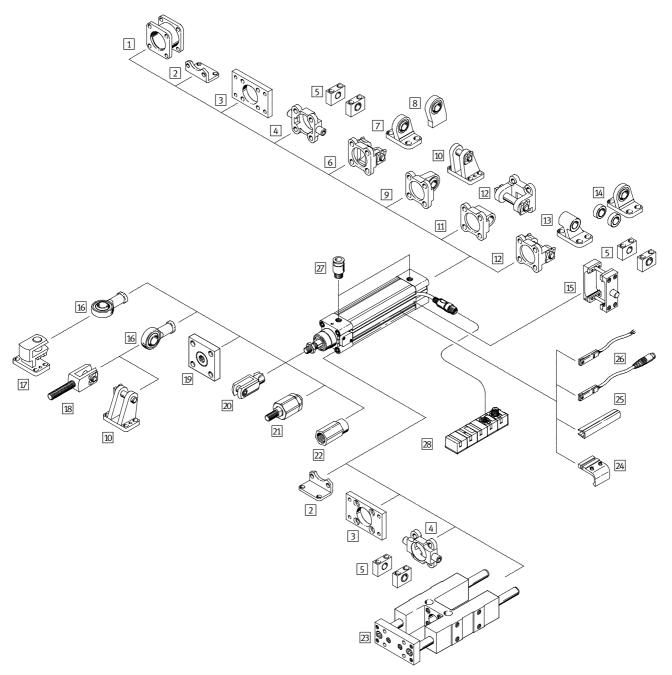
3

Type codes



Standard cylinders DNCI, with measured-value transducer DADE Peripherals overview





Acce	Accessories										
	Туре	Brief description	→ Page/Internet								
1	Adapter kit ¹⁾ DPNC	For connecting two cylinders with identical piston \varnothing to form a multi-position cylinder	dpnc								
2	Foot mounting HNC	For mounting the drive on the bearing and end caps	hnc								
3	Flange mounting FNC	For mounting the drive on the bearing and end caps	fnc								
4	Trunnion flange ZNCF/CRZNG	For swivelling movements of the drive on the bearing or end caps	trunnion flange								
5	Trunnion support LNZG/CRLNZG	-	lnzg								

Standard cylinders DNCI, with measured-value transducer DADE Peripherals overview



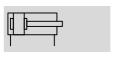
Acce	ccessories Type Brief description								
	Туре	Brief description	→ Page/Internet						
6	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap	snc						
	SNC								
7	Clevis foot mounting ¹⁾	With spherical bearing	lsng						
	LSNG								
8	Clevis foot mounting ¹⁾	Weld-on, with spherical bearing	lsnsg						
	LSNSG								
9	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap, with spherical bearing	sncs						
_	SNCS								
10	Clevis foot mounting ¹⁾	-	lbg						
_	LBG								
11	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap	sncl						
_	SNCL								
12	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap	sncb						
	SNCB								
13	Clevis foot mounting ¹⁾	-	lng						
_	LNG/CRLNG								
14	Clevis foot mounting ¹⁾	With spherical bearing	lsn						
ئت	LSN	,							
15	Trunnion mounting kit	For swivelling movements of the drive	zncm						
10	ZNCM	To simeting movements of the unite	Ziiciii						
16	Rod eye	With spherical bearing	sgs						
10	SGS/CRSGS	With Spherical bearing	353						
17	Right-angle clevis foot	_	lqg						
1/	LQG		145						
18	Rod clevis	With male thread	cas						
10	SGA	with mate timeau	sga						
19	Coupling piece	To compensate for radial deviations	ksg						
19	KSG	to compensate for radial deviations	KSg						
		For cylinders with a non-rotating piston rod to compensate for radial deviations	ksz						
	Coupling piece	roi cylinders with a non-rotating piston rod to compensate for radial deviations	KSZ						
	KSZ	D 10 1 112 4 64 12 1 1							
20	Rod clevis	Permits a swivelling movement of the cylinder in one plane	sg						
	SG/CRSG		a						
21	Self-aligning rod coupler	For compensating radial and angular misalignments	fk						
20	FK	For a self-or any other self-or attaches at	- 4						
22	Adapter	For a suction cup with connection attachments	ad						
22	AD Cuida unit	For each office shoulded with down and a track of the Co. 1	4.2						
23	Guide unit	For protecting standard cylinders against rotation at high torque loads	12						
	FENG	F II III ONFIONE A LI II	1.0.0						
24	Mounting kit	For mounting proximity sensors SME/SMT-8 in combination with guide unit FENG	smb-8-feng						
	SMB-8-FENG		 						
25	Slot cover	For protecting the sensor cable and keeping dirt out of the sensor slots	abp						
_	ABP-5-S								
26	Proximity sensor	Can be integrated in the cylinder profile barrel	proximity sensor						
	SME/SMT-8								
27	Push-in fitting	For connecting outer toleranced compressed air tubing	quick star						
	QS								
28	Measured-value transducer	Converts sensor signals of the standard cylinder DNCI into a voltage signal of 0 10 V and/or	16						
	MU, MI	a current signal of 4 20 mA							

Not with variant S2
 Guide unit FENG-KF must be attached to the piston rod in a way that eliminates backlash



Technical data

Function



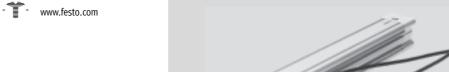




32 ... 63 mm



Stroke length 10 ... 2000 mm



General Technical data								
Piston \varnothing		32	40	50	63			
Based on standard		ISO 15552						
Design		Piston						
		Piston rod						
		Profile barrel						
Mode of operation		Double-acting						
Guide ¹⁾		Guide rod with yoke, with	h ball bearing guide					
Mounting position		Any						
Type of mounting		Via accessories						
Cushioning		Elastic cushioning rings/plates at both ends						
Position sensing		Integrated displacement encoder						
		Via proximity sensor ²⁾						
Measuring principle (displacement encoder)		Encoder, contactless and relative measurement						
Pneumatic connection		G1/8	G1/4	G1/4	G3/8			
Stroke			•	•	•			
DNCI ³⁾	[mm]	10 2,000						
DNCIFENG	[mm]	100 500						
Extended piston rod	[mm]	1 500						

- 1) Guide unit FENG-KF can be ordered via the modular product system (feature FENG) and is supplied attached. The maximum stroke is restricted.
- Not included in the scope of delivery, can be ordered as an option
- Can only be used without restriction as a positioning drive in the range from 100 ... 750 mm. Note stroke reduction in combination with CPX-CMAX, $\ensuremath{\mathsf{SPC200}}$

Operating and environmental conditions							
Operating pressure [bar]	0.6 12						
Operating pressure ¹⁾ [bar]	4 8						
Operating medium ²⁾	Compressed air to ISO 8573-1:2010 [6:4:4]						
Note on operating/pilot medium	ubricated operation not possible						
	Pressure dew point 10°C below ambient/medium temperature						
Ambient temperature ³⁾ [°C]	-20 +80						
Vibration resistance to DIN/IEC 68, Part 2-6	Severity level 2						
Continuous shock resistance to DIN/IEC 68, Part 2-82	Severity level 2						
CE marking (see declaration of conformity) ⁴⁾	To EU EMC Directive						
Corrosion resistance class CRC ⁵⁾	1						

- Only applies to applications with end-position controller CPX-CMPX, SPC11 and axis controller CPX-CMAX, SPC200 The proportional directional control valve VPWP, MPYE requires these characteristic values
- Note operating range of proximity sensors
- For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com -> Support -> User documentation.
- If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.
- Corrosion resistance class 1 according to Festo standard 940 070
 - Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.



Forces [N] and impact energy [Nm]										
Piston \varnothing		32	40	50	63					
Theoretical force at 6 bar		483	754	1,178	1,870					
Advancing	S2	415	633	990	1,682					
Theoretical force at 6 bar		415	633	990	1,682					
Retracting	S2	415	633	990	1,682					
Impact energy at the end positions		0.1	0.2	0.2	0.5					

Permissible impact velocity:

Permissible impact velocity v_{perm}. E_{perm}. Maximum impact energy $m_{Intrinsic} \ \ Moving \ mass \ (drive)$

m_{Load} Moving payload

 $m_{Load} = \frac{2 \times E_{perm.}}{v^2} - m_{Intrinsic}$ Maximum permissible load:

- Note

These specifications represent the maximum values that can be achieved. Note the maximum permissible impact energy.

Output signal		Analogue
Linearity error		
Strokes up to 500 mm	[mm]	< ±0.08
Strokes up to 1,000 mm	[mm]	<±0.09
Strokes above 1,000 mm	[mm]	<±0.11
Maximum travel speed	[m/s]	1.5
Protection class		IP65
CE marking (see declaration of conformity)		To EU EMC Directive ¹⁾
Maximum permitted magnetic interference	[kA/m]	10
$field^{2)}$		
Electrical connection		Cable with 8-pin plug, round design, M12
Cable length	[m]	1.5

- 1) For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com \Rightarrow Support \Rightarrow User documentation. If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.
- 2) At a distance of 100 mm

Pin allocation for plug



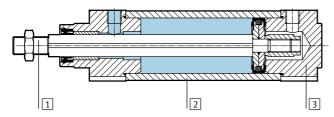
	Pin	Function	Colour
i	1	5V	Black
ĺ	2	GND	Brown
ĺ	3	sin+	Red
	4	sin-	Orange
	5	cos-	Green
	6	COS+	Yellow
	7	Screened	Screened
ĺ	8	n.c.	-



Weight [g]					
Piston \varnothing		32 40		50	63
DNCI					
	Product weight with 0 mm stroke	521	853	1,319	1,914
	Additional weight per 10 mm stroke	30	44	62	71
	Moving load with 0 mm stroke	95	175	316	383
	Additional weight per 10 mm stroke	8	14	23	23
DNCIS2 –	through piston rod				
	Product weight with 0 mm stroke	586	981	1,553	2,165
	Additional weight per 10 mm stroke	39	60	87	96
	Moving mass with 0 mm stroke	155	164	297	364
	Additional weight per 10 mm stroke	17	30	48	48
DNCIK8 –	additional weight with piston rod extension				
	Additional weight per 10 mm stroke	8	14	23	23
DNCIKP –	additional weight with clamping unit				
	Product weight	234	394	700	1,147
DNCIFENG	6 – additional weight with guide unit				
	Product weight with 0 mm stroke	1,530	2,370	4,030	5,410
	Additional weight per 10 mm stroke	18	32	50	62

Materials

Sectional view



Standard cylinder	
1 Piston rod	High-alloy steel
2 Cylinder barrel	Anodised aluminum
3 Bearing/end caps	Die-cast aluminum
- Dynamic seals	Polyurethane TPE-U
 Static seals 	Nitrile rubber
Note on materials	RoHS-compliant
Displacement encoder	
 Sensor housing 	Polyacetal
- Cable sheath	Polyurethane
 Plug housing 	Polybutylene terephthalate
 Mounting plate 	Polyacetal
 Screws for mounting plate 	Steel

FESTO

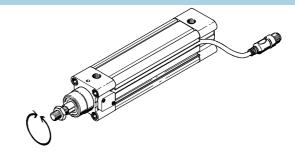
Technical data

Torques and lateral forces

The piston rod must not absorb any torque. We therefore recommend using an external guide unit FENG-KF with the drive DNCI. The guide unit is supplied attached.

The permissible static and dynamic characteristic load values with and without attached guide as well as with regard to the technical data of the variants (S2, S8, S9)

→ Internet: dnc



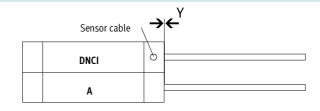
Mounting conditions

The following conditions must be observed, when mounting a drive A with magnet (for position sensing) next to a standard cylinder DNCI:

- X Minimum distance between the drives
- Y Offset between the drives on the bearing cap

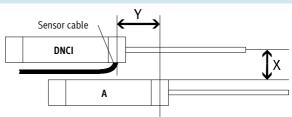
Parallel assembly

The drives can be assembled directly next to one another if the offset Y = 0 mm.



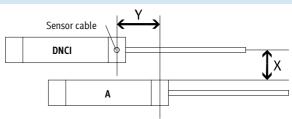
Off-set assembly, cable outlet between the drives

A distance of X > 70 mm must be observed, if the offset is Y > 0 mm and the cable outlet is between the drives.



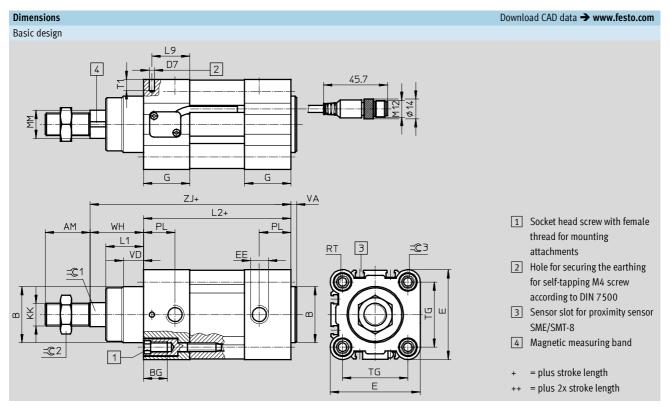
Off-set assembly, cable outlet upwards or downwards

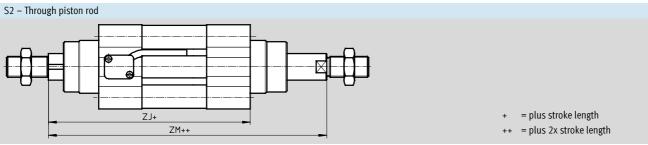
A distance of X > 60 mm must be observed, if the offset is Y > 0 mm and the cable outlet is up or down.

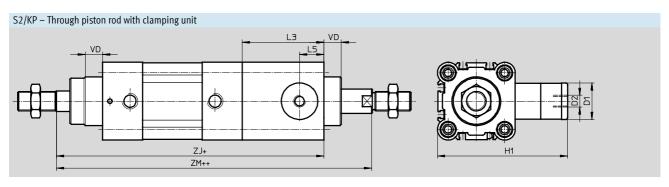


FESTO

Technical data





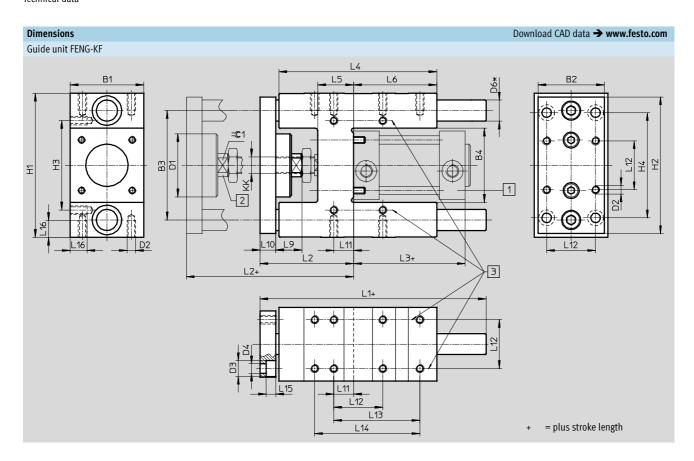




FESTO

Ø	AM	A2 max.	B Ø	BG	D1 Ø	D2	D7 Ø	E	EE	G	H1
[mm]			d11	4.6	f9	***	0.7		01/	20	4=
32	22	500	30	16	20	M5	3.7	45	G1/8	28	67
40	24	500	35	16	24	G1/8	3.7	54	G1/4	33	88
50	32	500	40	17	30	G1/8	3.7	64	G1/4	33	107
63	32	500	45	17	38	G1/8	3.7	75	G3⁄/8	40.5	123
	_										
Ø	KK	L1	L2	L3	L5	L9	MM	PL	RT	T1	TG
							Ø				
[mm]							f8				
32	M10x1.25	18	94	45	14	22.5	12	15.6	M6	8	32.5
40	M12x1.25	21.3	105	53	16	27	16	14	M6	8	38
50	M16x1.5	26.8	106	67	20	27	20	14	M8	8	46.5
63	M16x1.5	27	121	76	24	33	20	17	M8	8	56.5
Ø	VA	VD	WH	Z	J	ZI	M	= ©1	= ©2	≕	3
[mm]					KP		KP				
32	4	10	26	120	165	148	193	10	16	6	
40	4	10.8	30	135	188	167	220	13	18	6	
50	4	14.3	37	143	210	183	250	17	24	8	3
63	4	14.5	37	158	234	199	275	17	24	8	





FESTO

For \varnothing	B1	B2	В3	B4	D1	D2	D3	D4	D6	H1	
					Ø		Ø	Ø	Ø		
[mm]	-0.3		±0.2	±0.3					h6		
32	50	45	74	50.5	44	M6	11	6.6	12	97 _{-0.4}	
40	58	54	87	58.5	44	M6	11	6.6	16	115 _{-0.4}	
50	70	63	104	70.5	60	M8	15	9	20	137 _{-0.5}	
63	85	80	119	85.5	60	M8	15	9	20	152 _{-0.5}	
For Ø	H2	Н3	H4	KK	L1	L2	L3	L4	L5	L6	
[mm]		±0.2	±0.2								
32	90	61	78	M10x1.25	155	67+5	94	125	24	76	
40	110	69	84	M12x1.25	170	75 ₊₅	105	140	28	81	
50	130	85	100	M16x1	188	89+10	106	150	34	79	
63	145	100	105	M16x1	220	89+10	121	182	34	111	
For Ø	L9	L10	L11	L12	L13	L14	L15	L16	=3	1	
[mm]				±0.2	±0.2	±0.2					
32	20	12	4.3	32.5	70.3	78	6.5	12	15		
40	22	12	11	38	84	-	6.5	14	15		
50	25	15	18.8	46.5	81.8	100	9	16	1	9	
63	25	15	15.3	56.5	105	-	9	16	1	9	

Standard cylinders DNCI, with measured-value transducer DADE Ordering data – Modular products



Ordering table											
Pi	Piston \varnothing		32	40	50	63	Condi-	Code		Enter	
							tions			code	
M	Module No.		535411	535412	535413	535414					
	Function		Standard cylinder with integrated displacement encoder, non-rotating piston rod					DNCI		DNCI	
	Piston Ø	[mm]	32	40	50	63					
	Stroke	[mm]	10 2,000								
	Cushioning Elastic cushioning rings/plates at both ends							-P		-P	
Ψ	Position sensing		For proximity sensor					-A		-A	

Transfer order co	ode							
	DNCI	_	-	_	P	-	Α] -



Ordering data – Modular product

2 **K8**

Or	Ordering table										
Piston ∅		32 40 50 63				Condi- tions	Code	Enter code			
0	Piston rod type	Through piston rod					-S2				
	Piston rod extended at [mm] 1 500						K8				
	front	front									
	Clamping unit Attached						-KP				
	Guide Guide unit with ball bearing guide on the sensor head side					4	-FENG				
	Measured-value transducer Output 0 10 V						-MU				
	Output 4 20 mA										
	Measuring head No measuring head										

3 **KP**

Can only be combined with piston rod type S2

combination with piston rod type S2.

4 FENG

Maximum stroke length 500 mm

The piston rod is only extended at the front (side closest to the measuring head) in $\,$

- Note

In the case of repairs, the standard cylinder can be ordered without a measuring head (→ code MS).

The existing measuring head can then be installed in the new standard cylinder (→ operating instructions for DNCI).

	Transfer order code						
-[- [-	-[-	-	



Measured-value transducer DADE-MVC-010 DADE-MVC-420 (Order code MU, MI)

The measured-value transducer converts sensor signals from the standard cylinder DNCI into a voltage signal of 0 ... 10 V or a current signal of $4 \dots 20$ mA. These signals can be evaluated by a PLC with an appropriate signal input.



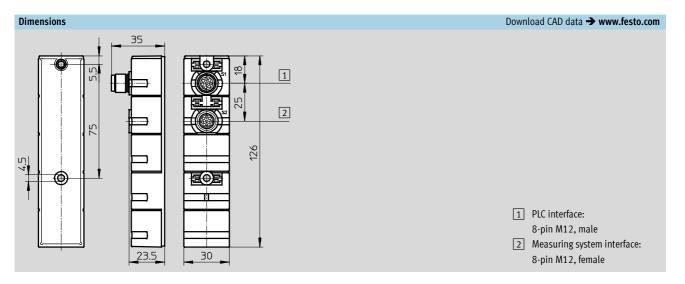
General technical data						
Type of mounting		Via through-hole				
Mounting position		Any				
Repetition accuracy in relation to ≤ 400		±0.1 mm				
effective stroke	≤ 750	±0.2 mm				
	≤ 1200	±0.3 mm				
	≤ 1600	±0.4 mm				
	≤ 2000	±0.5 mm				
Protection against short circuit		Yes				
Protection against incorrect polarity		Yes				
Diagnostic function		Display via LED				

General electrical data	eneral electrical data							
Analogue output	[V]	0 10 (according to EN 61131-2)						
	[mA]	4 20 (according to EN 61131-2)						
Nominal operating voltage	[V DC]	24 ±25%						
Residual ripple	[%]	4 (at 50 Hz)						
Current consumption at nominal	[mA]	20 30						
operating voltage								
Switching logic at outputs		PNP						
Switching logic at inputs		PNP						
Debounce time at inputs	[ms]	3						
Linearity error FS		0.2%						

Operating and environmental conditions							
Ambient temperature [°C]	0 55						
Protection class	IP65						
Relative air humidity	95% non-condensing						
CE marking (see declaration of conformity)	To EU EMC Directive						
Corrosion resistance class CRC ¹⁾	1						
Product weight [g]	128						
Note on material for housing	Polybutylene terephthalate						

¹⁾ Corrosion resistance class 1 according to Festo standard 940 070 Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.

FESTO

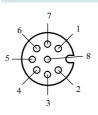


Pin allocation

PLC interface



Measuring system interface



Pin	Function	Cable colour
1	24V	White
2	Analogue measurement signal	Brown
3	Reference output	Green
4	0 V measurement signal	Yellow
5	Reference input	Grey
6	Calibration input	Pink
7	Ready output	Blue
8	0 V power supply and inputs/	Red
	outputs	

Pin	Function
1	Ub
2	0 V
3	Signal sine +
4	Signal sine –
5	Signal cosine –
6	Signal cosine +
7	Screening / earth
8	-

Ordering data								
		Description	Part no.	Туре				
Measured-value transducer								
	With voltage signal	0 10 V	542 117	DADE-MVC-010				
	With current signal	4 20 mA	542 118	DADE-MVC-420				
Accessories				Technical data → Internet: sim				
	Connecting cable	PLC connecting cable (length 2 m)	525 616	SIM-M12-8GD-2-PU				
		PLC connecting cable (length 5 m)	525 618	SIM-M12-8GD-5-PU				