

Motor units MTR-DCI, intelligent servo motors

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Key features

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General information

The motor unit MTR-DCI is an innovative motor with integrated power electronics for positioning tasks.

Four components in one housing

Integrated in the MTR-DCI are the motor, gear unit, controller and power electronics. This means that there is no need for a control cabinet or extensive cabling.

Reliable

The integrated power electronics and controller removes the need for motor cables and improves the electromagnetic compatibility. Additional monitoring functions are integrated.

Uncomplicated

The complete commissioning process can be performed directly on the MTR-DCI via the optional LCD display or on a PC via the user-friendly menus in the FCT (Festo Configuration Tool). No matter which approach is used, all parameters are continuously controlled.

At a glance

- Compact design
- Smooth profile prevents the ingress of dirt
- DC motor with planetary gear unit and encoder
- Gear unit ratio: 7:1; 14:1, 22:1
- Protection class IP54

Positioning functionality

- 16 traversing records (including homing)
- Constant acceleration and braking
- Positioning control

Protective functions

- Temperature monitoring
- Current monitoring
- Voltage failure detection
- Following error monitoring
- Software end-position detection

Easy actuation via

- I/O interface
- Profibus
- CANopen
- DeviceNet



CANopen

DeviceNet

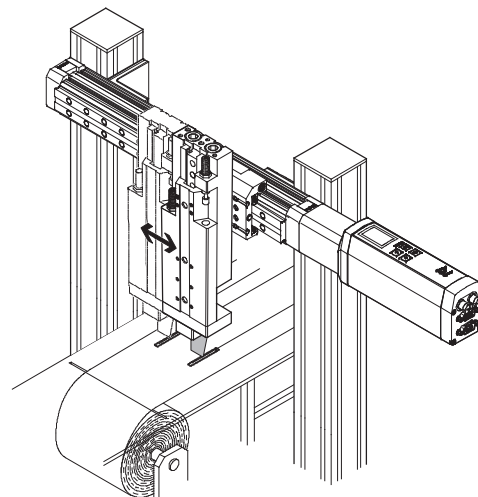
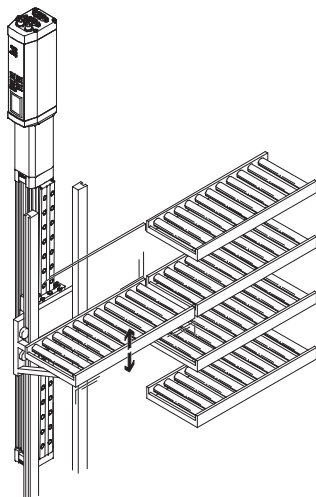
- 1 Control panel with integrated display (optional)
- 2 Input for reference limit switches
- 3 RS232 interface
- 4 Operator interface: I/O interface
- 5 Power supply
- 6 Gear unit



Typical applications

Adjusting sorting conveyors

Programming formats for paper or foil cutting machines



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Type codes

		MTR	-	DCI	-	42		S	-	VC		SC	-	E		G7	-	H2		IO
Type																				
MTR	Motor																			
Motor type																				
Size																				
Torque class																				
S	Standard																			
Nominal voltage																				
VC	24 V DC																			
VD	48 V DC																			
Plug design																				
SC	Straight plug outlet																			
Measuring system																				
E	Encoder																			
Gear unit ratio																				
G7	7:1																			
G14	14:1																			
G22	22:1																			
Parameterisation interface																				
R2	RS232																			
H2	RS232 and control panel																			
Electrical connection technology																				
IO	I/O interface																			
CO	CANopen interface																			
PB	Profibus interface																			
DN	DeviceNet interface																			

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Technical data

-N- Size
32 ... 62 mm
Voltage
24, 48 V DC

Fieldbus interfaces



CANopen

DeviceNet



General technical data				
Size	32	42	52	62
Rotary position generator	Optical encoder			
No. of increments/revolution	300 (1,200) ¹⁾	500 (2,000) ¹⁾		
Controller operating mode	PWM MOSFET power amplifier			
Display resolution	128 x 64 pixels			
Type of mounting	Can be bolted on or clamped to gearing unit flange			
Gearing unit type	Planetary gearing			
Gear unit ratio	G7	6.75 (7:1); 1-stage		
	G14	13.73 (14:1); 2-stage		
	G22	–		
				22.21 (22:1); 2-stage

1) Internal 4-fold evaluation

Electrical data – Motor				
Size	32	42	52	62
Nominal voltage [V DC]	24 ±10%			48 –10%/+5%
Nominal current (motor) [A]	0.73	2	5	6.19
Peak current [A]	2.1	3.8	7.7	20
Motor constant [Ncm/A]	4.5	6.1	6.4	12.1
Nominal power (motor) [W]	17	48	122	316
Max. current (digital logic outputs) [mA]	200		60	
Parameterisation interface	RS232; 9,600 baud			

Mechanical data – Motor									
Size	32	42	52	62					
Gear unit ratio	G7	G14	G7	G14	G7	G14	G7	G14	G22
Gearing unit output speed [rpm]	481	237	444	218	444	218	504	248	153
Gearing unit torsional backlash [°]	≤ 1.9	≤ 1.55	≤ 1.3	≤ 0.95	≤ 1.1	≤ 0.75	≤ 1	≤ 1.5	≤ 1.5
Gearing unit output torque [Nm]	0.15	0.29	0.59	1.13	1.62	3.08	3.78	7.2	11.66
Gearing unit efficiency	0.75	0.7	0.8	0.75	0.8	0.75	0.8	0.75	0.75
Mass moment of inertia (rotor) [kg cm ²]	0.024	0.323	1.209	3.3					
Mass moment of inertia (gearing unit) [kg cm ²]	0.00089	0.00149	0.00235	0.00441	0.01132	0.01711	0.017	0.035	0.022
Radial shaft load [N]	40	70	160	230	200	320	240	360	360
Axial shaft load [N]	10	20	50	80	60	100	50	70	70
Product weight [kg]	0.72	0.74	1.72	1.83	3.1	3.3	7.6	8.0	8.0

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Technical data

Operating and environmental conditions				
Size	32	42	52	62
Digital logic outputs	Not electrically isolated		Electrically isolated	
Insulation protection class to VDE 60034	F			
Protection class	IP54			
Protective functions	I ² T monitoring			
	Following error monitoring			
	Software end position detection			
	Voltage failure detection			
	Current monitoring			
	Temperature monitoring: Silicon absolute temperature sensor, switches off at temperatures >70 °C			
Ambient temperature	[°C]	0 ... +50		
Storage temperature	[°C]	−25 ... +60		
Relative air humidity	[%]	0 ... 95 (non-condensing)		
CE mark (see declaration of conformity)	In accordance with EU EMC directive			
Certification	C-Tick			
Note on materials	Contains paint wetting impairment substances			

Materials	
Motor unit housing	Anodised aluminium
Motor unit cover	Aluminium, precision casting, coated (size 62 milled)

Technical data – I/O/fieldbus interface				
Type	MTR-DCI-...-IO	MTR-DCI-...-CO	MTR-DCI-...-PB	MTR-DCI-...-DN
Interface	I/O interface for 15 traversing records and homing	CANopen	Profibus DP	DeviceNet
Number of digital logic inputs	6	–	–	–
Number of digital logic outputs	2	–	–	–
Max. current of digital logic outputs (size)	32/42	200	–	–
	52/62	60	–	–
Bus terminating resistor ¹⁾	–	Not integrated in the device	Not integrated in the device	Not integrated in the device
Communication profile	–	DS301 / FHPP	DP-V0/V1 / FHPP	FHPP
	–	DS301; DSP402	Step7 functional modules	Device type 0C _H
Max. fieldbus baud rate [kbps]	–	1,000	12,000	500

1) Details of bus terminating resistor → 10

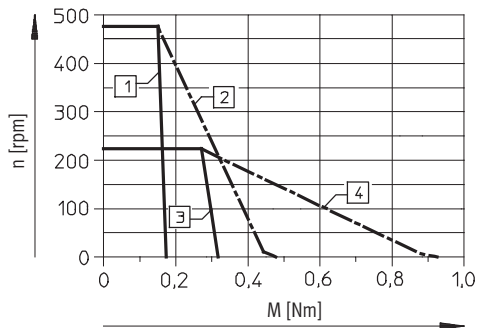
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Technical data

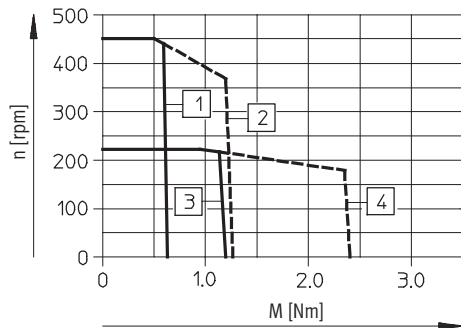
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Torque M as a function of rotational speed n

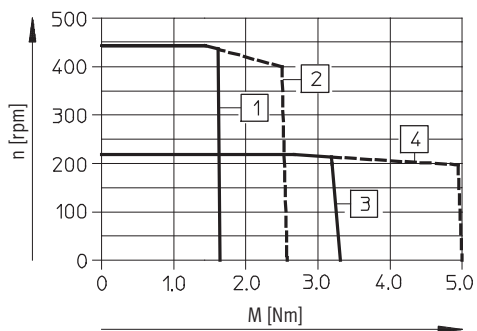
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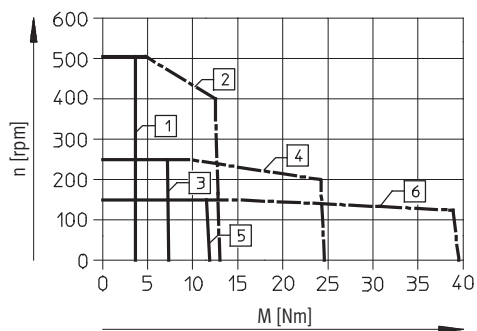
Size 42



Size 52



Size 62



Gear unit ratio 7:1

- 1 Torque, nom.
- 2 Torque, max.

Gear unit ratio 14:1

- 3 Torque, nom.
- 4 Torque, max.

Gear unit ratio 22:1

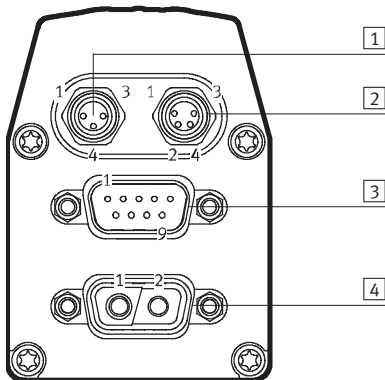
- 5 Torque, nom.
- 6 Torque, max.

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Technical data

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Pin allocation



1 Reference switch, 3-pin M8 socket

Pin	Function
1	24 V
4	Reference input
3	0 V
–	

2 RS 232 interface, 4-pin M8 socket

Pin	Function
1	0 V
2	Transmitted data (TxD)
3	Received data (RxD)
4	–

3 I/O interface, 9-pin Sub-D plug

Pin	Function
1	Traversing record coding, bit 0
2	Traversing record coding, bit 1
3	Traversing record coding, bit 2
4	Traversing record coding, bit 3
5	Start bit
6	Enable bit
7	Ready signal output
8	MC signal output
9	0 V

3 CANopen interface, 9-pin Sub-D plug

Pin	Function
1	–
2	CAN_L
3	CAN_GND
4	–
5	CAN_SHLD
6	CAN_V–
7	CAN_H
8	–
9	CAN_V+

3 Profibus interface, 9-pin Sub-D socket

Pin	Function
1	–
2	Logic_GND
3	RxD/TxD-P
4	CNTR-P
5	DGND
6	VP
7	Logic_V (24 V DC)
8	RxD/TxD-N
9	–

3 DeviceNet interface, 9-pin Sub-D plug

Pin	Function
1	–
2	CAN_L
3	CAN_GND
4	–
5	CAN_SHLD
6	CAN_V–
7	CAN_H
8	–
9	CAN_V+

4 Power supply, 2-pin plug

Pin	Function
1	24 V DC (for MTR-DCI-32/42/52), 48 V DC (for MTR-DCI-62)
2	0 V
–	
–	
–	
–	
–	
–	

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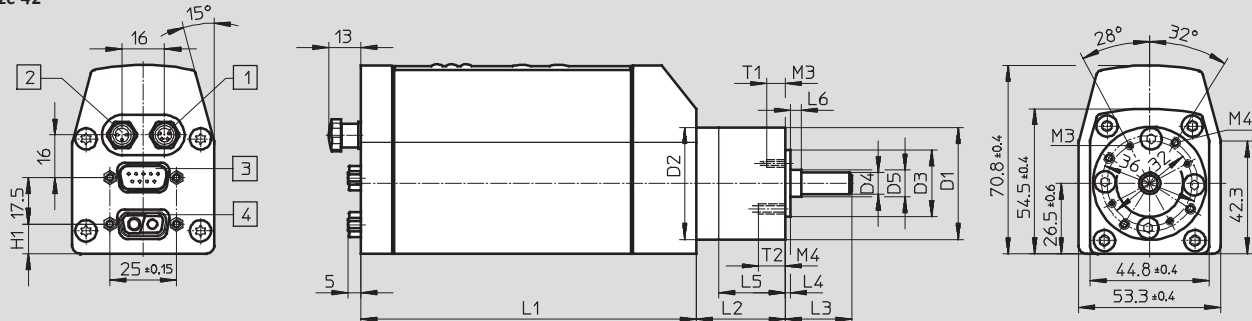
Technical data

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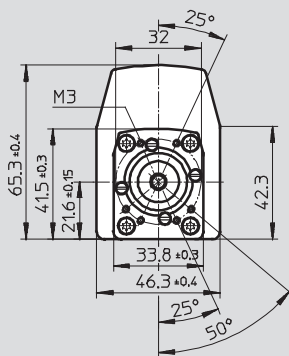
Dimensions

Download CAD Data → www.festo.com/us/cad

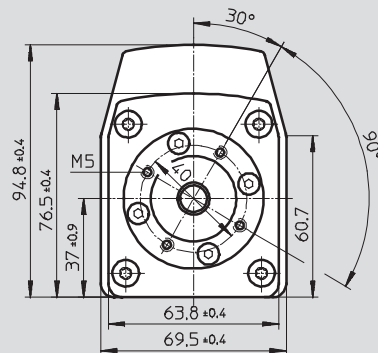
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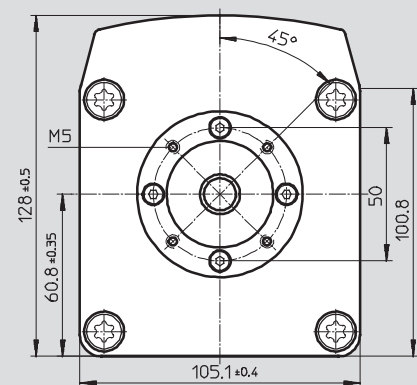
Size 32



Size 52



Size 62



- 1 M8x1, 4-pin
- 2 M8x1, 3-pin
- 3 Sub-D, 9-pin
- 4 Sub-D, 2-pin

Type	D1 Ø g10	D2 Ø ±0.1	D3 Ø h8	D4 Ø h7	D5 Ø	H1	L1 ±1	L2 ±1	L3	L4	L5	L6	T1	T2 +2
MTR-DCI-32S-...-G7	–	–	21.5	6	–	13±0.2	175.5	–	18.7±0.6	2.5±0.3	–	–	6	–
MTR-DCI-32S-...-G14	–	–	21.5	6	–	13±0.2	175.5	–	18.7±0.6	2.5±0.3	–	–	6	–
MTR-DCI-42S-...-G7	42	42	25	8	–	11	176	33.3	25±1	2±0.1	25	–	7+2	10
MTR-DCI-42S-...-G14	42	42	25	8	–	11	176	46.3	25±1	2±0.1	25	–	7+2	10
MTR-DCI-52S-...-G7	52	52	32	12	–	17.3	194	39	33±1	3±0.3	31	–	10	–
MTR-DCI-52S-...-G14	52	52	32	12	–	17.3	194	53	33±1	3±0.3	31	–	10	–
MTR-DCI-62S-...-G7	62	62	40	14	15	61.3	270	47	39±1	5±0.3	31.3	9	10	–
MTR-DCI-62S-...-G14	62	62	40	14	15	61.3	270	47	39±1	5±0.3	31.3	9	10	–
MTR-DCI-62S-...-G22	62	62	40	14	15	61.3	270	47	39±1	5±0.3	31.3	9	10	–

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Ordering data – Modular products

M Mandatory data										
Module No.	Motor unit		Flange/size		Nominal voltage		Measuring system		Parameterisation interface	
	Motor type		Torque class		Plug design		Gearing unit		Electrical connection technology	
533 736	MTR	DCI	32	S	VC	SC	E	G7	R2	IO
533 742			42		VD			G14	H2	CO
533 748			52					G22		PB
533 754			62							DN
Order example										
533 742	MTR	- DCI	- 42	S	- VC	SC	- E	G7	- R2	IO

Ordering table								
Size	32	42	52	62	Conditions	Code		Enter code
M	Module No.	533 736	533 742	533 748	533 754			
	Motor unit	Motor unit					MTR	MTR
	Motor type	DC servo motor with integrated position controller					-DCI	-DCI
	Flange/size	32	42	52	62		-...	
	Torque class	Standard torque class					S	S
	Nominal voltage [V]	24 DC			–		-VC	
	[V]	–			48 DC		-VD	
	Plug design	Straight plug					SC	SC
	Measuring system	Encoder					-E	-E
	Gearing unit	Integrated planetary gearing i = 6.75					G7	
		Integrated planetary gearing i = 13.73					G14	
		–			Integrated planetary gearing i = 22.21		G22	
	Parameterisation interface	RS232 interface					-R2	
		RS232 interface + control panel					-H2	
	Electrical connection technology	I/O interface					IO	
		CANopen					CO	
		Profibus DP					PB	
		DeviceNet					DN	

Transfer order code

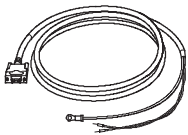
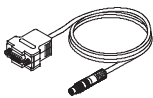
	MTR	-	DCI		S		SC	-	E		-		-	
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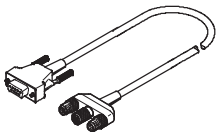
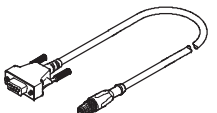
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Accessories

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Ordering data – Cables				
	Brief description	Cable length	Part No.	Type
	Supply cable Allocation → 7	2.5 m	537 931	KPWR-MC-1-SUB-9HC-2,5
		5 m	537 932	KPWR-MC-1-SUB-9HC-5
		10 m	537 933	KPWR-MC-1-SUB-9HC-10
	Control cable for I/O connection to any PLC controller Allocation → 7	2.5 m	537 923	KES-MC-1-SUB-9-2,5
		5 m	537 924	KES-MC-1-SUB-9-5
		10 m	537 925	KES-MC-1-SUB-9-10
	Programming cable For parameterisation and commissioning via the RS232 interface using FCT software Allocation → 7	2.5 m	537 926	KDI-MC-M8-SUB-9-2,5

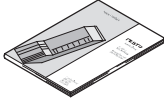
Ordering data – Plugs			
	Brief description	Part No.	Type
Fieldbus adapter for Profibus			
	– 9-pin Sub-D plug to 5-pin round M12 plug/socket, plus round M12 plug for logic voltage supply – Bus terminating resistor must be connected externally	537 934	FBA-PB-SUB-9-3XM12
Fieldbus adapter for CANopen and DeviceNet			
	– 9-pin Sub-D plug to 5-pin round M12 plug – Bus terminating resistor must be connected externally	540 324	FBA-CO-SUB-9-M12

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Ordering data – Software			
	Brief description	Part No.	Type
	Operator package contains: – CD-ROM – with user documentation for MTR-DCI, in the languages de, en, es, fr, it, sv – with FCT (Festo Configuration Tool) configuration software – Brief description This package is included in the scope of delivery.	550 905	PBP-MTR-DCI

Ordering data – Documentation ¹⁾						
	Language	Part No.		Type	Part No.	
		For I/O interface			For Profibus interface	
	DE	539 615	PBE-MTR-DCI-IO-DE		539 623	PBE-MTR-DCI-PB-DE
	EN	539 616	PBE-MTR-DCI-IO-EN		539 624	PBE-MTR-DCI-PB-EN
	ES	539 617	PBE-MTR-DCI-IO-ES		539 625	PBE-MTR-DCI-PB-ES
	FR	539 618	PBE-MTR-DCI-IO-FR		539 626	PBE-MTR-DCI-PB-FR
	IT	539 619	PBE-MTR-DCI-IO-IT		539 627	PBE-MTR-DCI-PB-IT
	SV	539 620	PBE-MTR-DCI-IO-SV		539 628	PBE-MTR-DCI-PB-SV
		For CANopen interface			For DeviceNet interface	
	DE	539 629	PBE-MTR-DCI-CO-DE		553 530	PBE-MTR-DCI-DN-DE
	EN	539 630	PBE-MTR-DCI-CO-EN		553 531	PBE-MTR-DCI-DN-EN
	ES	539 631	PBE-MTR-DCI-CO-ES		553 532	PBE-MTR-DCI-DN-ES
	FR	539 632	PBE-MTR-DCI-CO-FR		553 533	PBE-MTR-DCI-DN-FR
	IT	539 633	PBE-MTR-DCI-CO-IT		553 534	PBE-MTR-DCI-DN-IT
	SV	539 634	PBE-MTR-DCI-CO-SV		553 535	PBE-MTR-DCI-DN-SV

1) User documentation in paper form is not included in the scope of delivery

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Our experienced engineers provide complete support at every stage of your development process, including: conceptualization, analysis, engineering, design, assembly, documentation, validation, and production.



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Electromechanical actuators, motors, controllers & drives



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