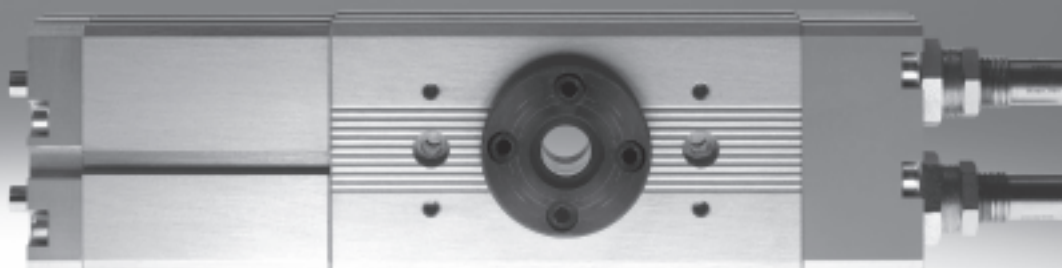


Semi-rotary drives DRQD/DRQD-B, twin pistons

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Semi-rotary drives DRQD/DRQD-B, twin pistons

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Key features

General

- Rack and pinion principle
- High accuracy
- Extremely good rigidity
- Backlash-free and dynamic
- Piston $\varnothing$ 6 ... 50 mm
- Torque 0.16 ... 50 Nm
- Swivel angle 0 ... 360°
- Defined interfaces
- End-position adjustment -60 ... +6°
- End-position adjustment with end-position cushioning P1J -320 ... +6°
- Choice of mounting options
- Supply port at one end
- Ideal for use in handling applications

Wide choice of variants

Spigot shaft



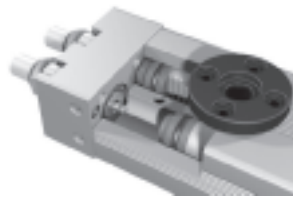
- Piston $\varnothing$ 6 ... 50 mm

Flanged shaft



- Piston $\varnothing$ 6 ... 50 mm

Adjustable end-position cushioning



- Piston $\varnothing$ 16 ... 50 mm
- PPVJ – pneumatic, adjustable
- YSRJ – hydraulic shock absorber, self-adjusting
- Piston $\varnothing$ 16 ... 32 mm
- P1J – flexible cushioning elements, adjustable

Intermediate position



- Piston $\varnothing$ 16 ... 50 mm
- Allows positioning of the drive shaft in a mid-position

Position sensing



- Piston $\varnothing$ 6 ... 50 mm
- For piston $\varnothing$ 6 ... 12 mm: proximity sensor SME/SMT-10
- For piston $\varnothing$ 16 ... 50 mm: proximity sensor SME/SMT-8

Adapter kits for grippers and drive combinations



- Piston $\varnothing$ 6 ... 50 mm

Energy through-feed



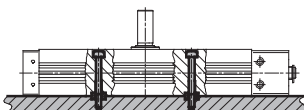
- Piston $\varnothing$ 6 ... 50 mm
- Simple and space-saving installation of tubing through the hollow flanged shaft
- DRQD-...-SD... 1 ... 4 DUO tubes



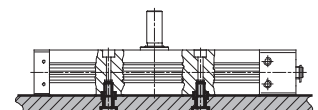
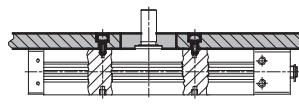
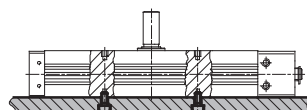
- Piston $\varnothing$ 16 ... 50 mm
- Simple and space-saving installation of tubing and cables through the hollow flanged shaft
- DRQD-...-E... 1 ... 2 DUO tubes and 2 ... 4 electrical cables

Mounting options

using through holes



via thread in housing profile

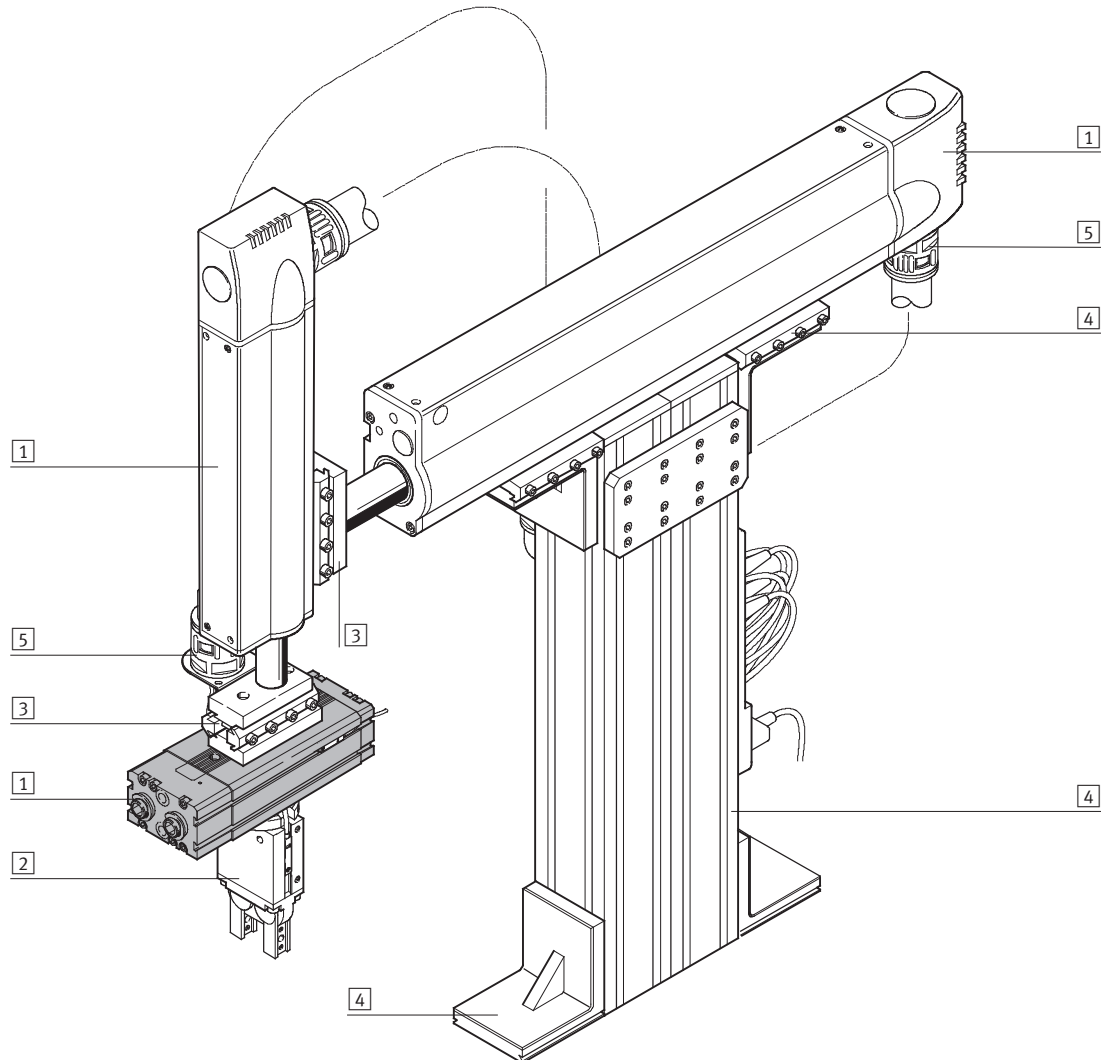


Semi-rotary drives DRQD/DRQD-B, twin pistons

System example

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System product for handling and assembly technology

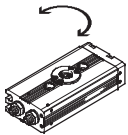
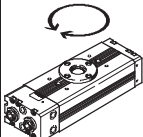


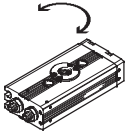
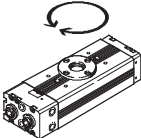
System elements and accessories		
	Brief description	→ Page/Internet
1 Drive units	Wide range of combination options within handling and assembly technology	drive
2 Grippers	Wide range of combination options within handling and assembly technology	gripper
3 Adapters	For drive/drive and drive/gripper combinations	adapter kit
4 Basic mounting components	Profiles and profile connectors as well as profile/drive connectors	basic component
5 Installation components	For achieving a clear-cut, safe layout for electrical cables and tubing	installation component
– Axes	Wide range of combination options within handling and assembly technology	axes
– Motors	Servo and stepper motors, with or without gearing	motor

Semi-rotary drives DRQD/DRQD-B, twin pistons

Product range overview

FESTO

Function	Version	Type	Piston Ø [mm]	Swivel angle [°]	Adjustable end-position range [°]	Position sensing A	End-position adjustment with flexible buffers in the end positions J...
Double-actin g	Basic version						
		DRQD	6, 8, 12	90	-20 ... +6		
				180	-60 ... +6		
		DRQD-B	16, 20, 25, 32	90	-20 ... +6		-
				180	-320 ... +6		
				360			
				0 ... 340			
		DRQD	40, 50	90	-20 ... +6		-
				180			
				360			
				0 ... 340			

Function	Version	Type	Piston Ø [mm]	Output shaft		
				Spigot shaft ZW	Flanged shaft FW	Integrated adapter for direct mounting of grippers A...
Double-actin g	Basic version					
		DRQD	6, 8, 12			
		DRQD-B	16, 20, 25, 32			—
		DRQD	40, 50			—

Semi-rotary drives DRQD/DRQD-B, twin pistons

Product range overview

FESTO

Type	Piston Ø [mm]	Type of cushioning			Pneumatic connection	
		Pneumatic cushioning, adjustable PPV]	Flexible cushioning elements, adjustable P1]	Hydraulic shock absorber, self-adjusting YSRJ]	left AL	right AR
Basic version						
DRQD	6, 8, 12	–	–	–	–	■
DRQD-B	16, 20, 25, 32	■	■	■	■	■
DRQD	40, 50	■	–	■	■	■

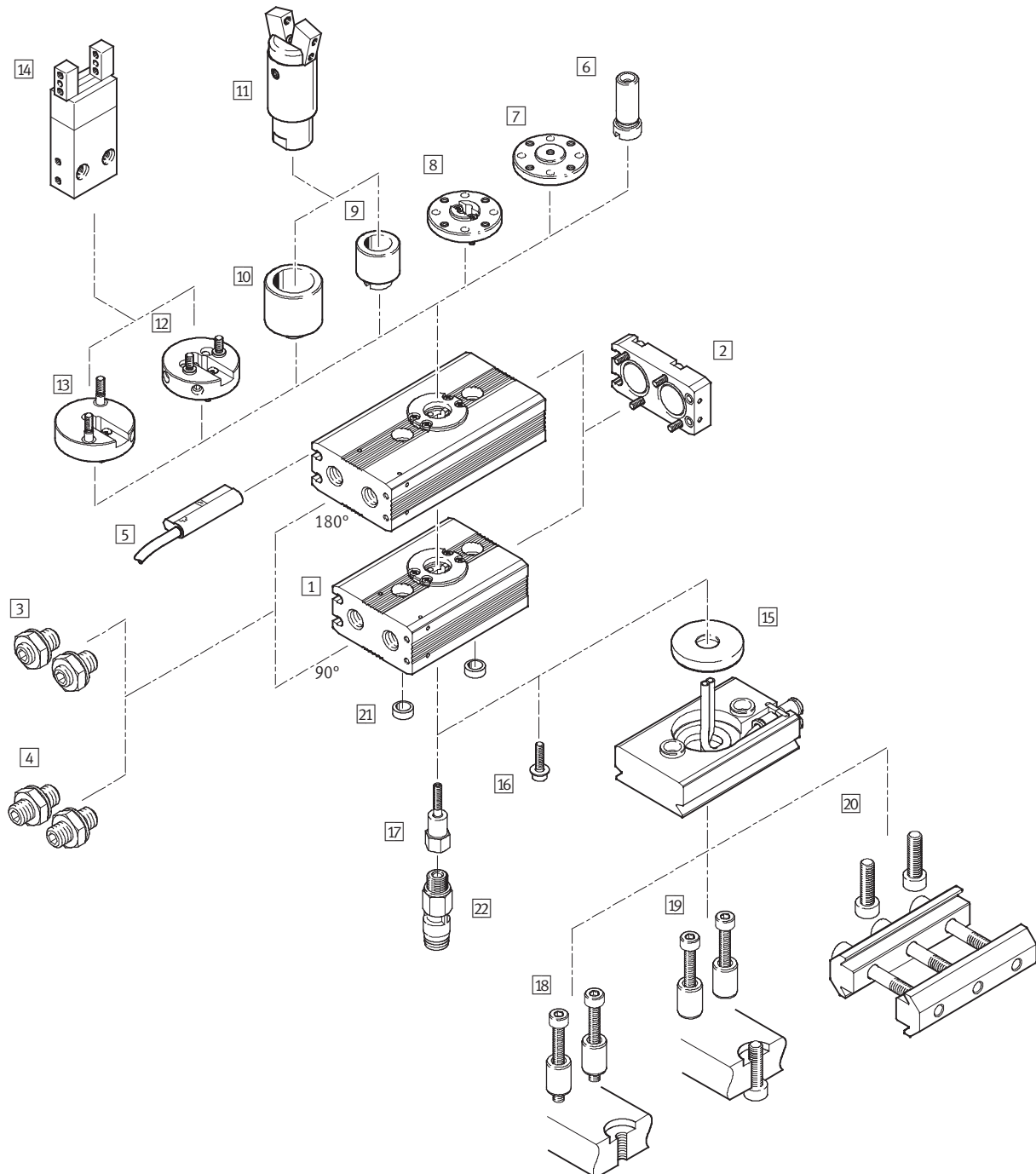
Type	Piston Ø	Intermediate position	Energy through-feed	Adapter kits for grippers	➔ Page/Internet
	[mm]	Z1	SD..., E...		
Basic version					
DRQD	6, 8, 12	–	■	■	6
DRQD-B	16, 20, 25, 32	■	■	■	22
DRQD	40, 50	■	■	■	22

Semi-rotary drives DRQD-6 ... 12, twin-pistons

Peripherals overview

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Piston $\varnothing$ 6 ... 12



Semi-rotary drives DRQD-6 ... 12, twin-pistons

Peripherals overview

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Variants, mounting attachments and accessories					
	Brief description	Piston Ø			→ Page/Internet
		6	8	12	
1 Centre section	Centre section for 90° or 180° swivel angle	■	■	■	9
2 Connector cap	With integrated compressed air directional function	■	■	■	
3 End-position adjustment J20	Flexible end position cushioning with adjustable end positions (–20 ... +6°)	■	■	■	
4 End-position adjustment J60	Flexible end position cushioning with adjustable end positions (–60 ... +6°)	■	■	■	
5 Position sensing A	Contactless via proximity sensors SME-/SMT-10	■	■	■	63
6 Spigot shaft ZW ¹⁾	Hollow with woodruff key	■	■	■	9
7 Flanged shaft FW ¹⁾	Hollow	■	■	■	
8 Flanged shaft FW-SD32	Hollow, for energy through-feed	–	■	■	
9 Adapters A08 ²⁾	For grippers HGWM-08-...-G8 and HGPM-08-...-G8	■	■	■	
10 Adapters A12 ²⁾	For grippers HGWM-12-...-G8 and HGPM-12-...-G8	■	■	■	
11 Grippers HGPM/HGWM	HGPM-...-G8 and HGWM-...-G8	■	■	■	gripper
12 Adapters AS1	For grippers HGP-06-A, HGR-10-A and HGW-10-A	–	■	■	9
13 Adapters AS2	For grippers HGD-16-A	–	■	■	
14 Grippers HGP/HGD/HGR/HGW	HGP-06-A, HGD-16-A, HGR-10-A, HGW-10-A	–	■	■	gripper
15 Energy through-feed SD32	2 tubes with O.D. 3 mm	–	■	■	14
16 Socket head screw ZS	Mounting of ZW and FW	■	■	■	9
17 Hollow bolt HS	Mounting of ZW, FW, A08, A12 and air supply for attachments	■	■	■	
18 Type of mounting B1	For connection of DRQD/FW-SD32: Locking screws in centring sleeves	■	■	■	
19 Type of mounting B2	For connection of DRQD/FW-SD32: Through screws in attachment	■	■	■	
20 Type of mounting B3	For connection of DRQD/FW-SD32: Clamping via profile, grid 40 mm	■	■	■	
21 Centring sleeve ZBH	For centring (2 pieces included in scope of delivery for DRQD)	■	■	■	14
22 Rotary push-in fitting ³⁾ QS	Quick Star push-in fittings, rotatable with ball bearing	■	■	■	

1) The socket head screw ZS is included in the scope of delivery. The hollow bolt HS must be ordered separately

2) Only in conjunction with hollow bolt HS. The hollow bolt HS must be ordered separately

3) For energy through-feed in combination with HS

Semi-rotary drives DRQD-6 ... 12, twin-pistons

Type codes

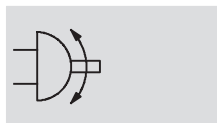
		DRQD	-	6	-	180	-	J60	-	A	-	A12	-		-	HS	-	B2	-	B
Type																				
Double-acting																				
DRQD	Semi-rotary drive																			
Piston Ø [mm]																				
Swivel angle [°]																				
End-position adjustment [°]																				
J20	-20 ... +6																			
J60	-60 ... +6																			
Position sensing																				
A	For proximity sensing																			
Output shaft/adaptor																				
ZW	Spigot shaft																			
FW	Flanged shaft																			
A08	Adapter for micro, angle and parallel grippers																			
A12	Adapter for parallel, three-point, angle and radial grippers																			
Energy through-feed																				
SD32	2 tubes with O.D. 3 mm																			
Type of screw																				
ZS	Socket head screw																			
HS	Hollow bolt																			
Type of mounting																				
B1	Locking screws in centring sleeves																			
B2	Through screws in attachment																			
B3	Clamping via profile, 40 mm																			
User's manual																				
	German																			
E	English																			
F	French																			
S	Spanish																			
I	Italian																			
V	Swedish																			
B	Express waiver – no user manual to be included (already available)																			

Semi-rotary drives DRQD-6 ... 12, twin-pistons

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Technical data

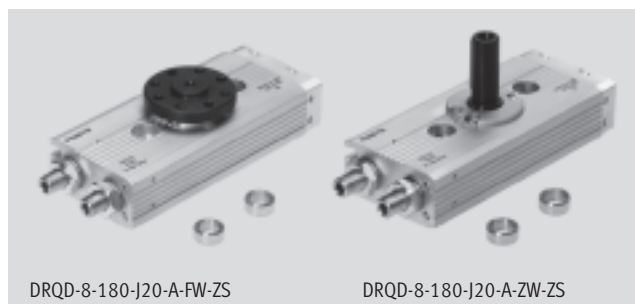
Function



-  - Diameter
6 ... 12 mm
-  - Force
0.16 ... 0.76 Nm

Variants

- 90° and 180° swivel angle
- Spigot or flanged shaft
- Adapters for grippers
- End-position adjustment
- Position sensing
- Energy through-feed
- Different types of mounting



DRQD-8-180-J20-A-FW-ZS

DRQD-8-180-J20-A-ZW-ZS

www.festo.com/en/
Spare_parts_service

General technical data			
Piston Ø	6	8	12
Pneumatic connection	M3		
	HS	M5	
	SD32	–	QS...-3 for tube O.D. 3 mm
Constructional design	Semi-rotary drive with twin pistons based on the rack and pinion principle		
Cushioning	Flexible buffer at both ends		
Position sensing	For proximity sensing		
Type of mounting	Via through-hole		
	Via female thread		
Assembly position	Any		

Operating and environmental conditions			
Piston Ø	6	8	12
Operating medium	Filtered compressed air, lubricated or unlubricated		
Operating pressure [bar]	1 ... 8		
	SD32	–	1.5 ... 8
Adjustable end-position range per end position [°]	J20	–20 ... +6	
	J60	–60 ... +6	
Max. permissible swivelling frequency at 6 bar (for completed cycle of motion) [Hz]	90°	5	4
	180°	3.5	2.5
	SD32	–	A reduction of max. 5% of the values indicated above
Repetition accuracy [°]	< 0.2		
Ambient temperature ¹⁾ [°C]	–10 ... +60		
Corrosion resistance class CRC ²⁾	1		
ATEX	Specified types → www.festo.com		

1) Note operating range of proximity sensors

2) Corrosion resistance class 1 according to Festo standard 940 070

Components requiring low corrosion resistance. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers

Semi-rotary drives DRQD-6 ... 12, twin-pistons

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Technical data

Forces and torques			
Piston Ø	6	8	12
Theoretical torque [Nm]	0.16	0.33	0.76
at 6 bar	SD32 –	0.28	0.72
	 Note: If torque acts against the direction of rotation in the end position, a drive with a rating of twice the maximum theoretical torque should be selected.		
Max. permissible radial and axial forces	Diagrams → 13		
Max. permissible mass moment of inertia [kgm ²]	0.075 x 10 ⁻⁴	0.25 x 10 ⁻⁴	0.7 x 10 ⁻⁴
	The data applies to the variants ZW, FW, A... without grippers, unthrottled.		

Weights [g]			
Piston Ø	6	8	12
Centre section	90° J20	66	90
	J60	67	92
	180° J20	82	111
	J60	83	113
Output shaft	ZW	2	4
	FW	4	7
Adapters	A08	6	11
	A12	6	11
	AS1	–	13
	AS2	–	15
Screws	ZS	1	
	HS	4	5
Flanged shaft with energy through-feed	SD32	–	71
Mounting in combination with SD32	B1	–	17
	B2	–	17
	B3	–	18
		81	

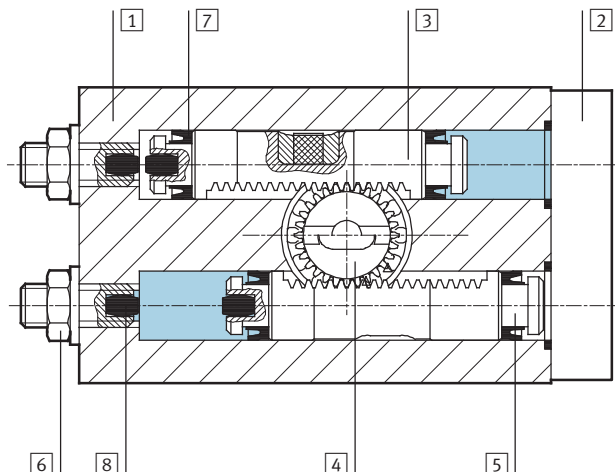
Semi-rotary drives DRQD-6 ... 12, twin-pistons

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Technical data

Materials

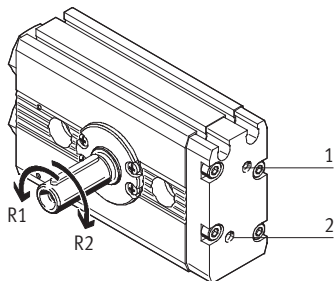
Sectional view



Piston Ø		6	8	12
1	Cylinder barrel (centre section)	Anodised aluminium		
2	Connector cap	Anodised aluminium		
3	Gear rack	Anodised aluminium		
4	Pinion	Stainless steel; milled teeth		
5	Piston	Anodised aluminium		
6	Threaded pin, hex nuts	Galvanised steel		
7	Piston seal	Nitrile rubber	Polyurethane	
8	Buffer for end-position cushioning	Nitrile rubber		
–	DUO spiral tubing	Polyurethane		
–	Woodruff key	Steel		
–	Hollow bolt, centring sleeves	Stainless steel		
–	Static seals	Steel, nitrile rubber		
–	Material note	Copper, PTFE and silicone-free		

Direction of rotation of the drive shaft

Pneumatic actuation of ports 1 or 2 produces a rotational movement in direction R1 or R2 respectively.



Semi-rotary drives DRQD-6 ... 12, twin-pistons

Technical data

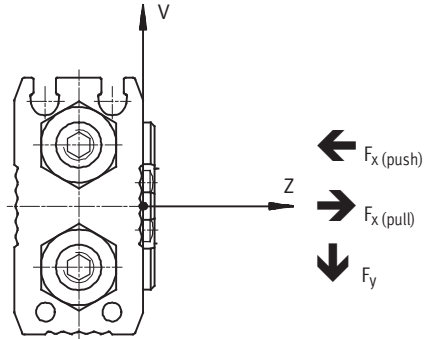
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Max. permissible radial and axial forces on the drive shaft

Combined load

A semi-rotary drive DRQD-8-... is to be statically loaded with a radial force $F_y = 60 \text{ N}$, which is at a distance of $Z = 5 \text{ mm}$ from the housing, and an

axial force $F_{x, \text{push}} = 30 \text{ N}$, which is at a distance of $V = 12 \text{ mm}$ from the shaft (→ diagram of flanged shaft on right).



Question:

Is it permissible to statically load a semi-rotary drive DRQD-8-... with these combined forces?

Answer:

Graph 1 (→ 13) indicates that the maximum permissible radial force is $F_{y, \text{max. (stat.)}} (5) = 193 \text{ N}$ for a distance

$Z = 5 \text{ mm}$. Graph 3 (→ 13) indicates that the maximum axial force is

$F_{x, \text{push max. (stat.)}} (12) = 169 \text{ N}$ for a distance $V = 12 \text{ mm}$.

The following equation applies to combined loads:

$$\frac{F_y (z)}{F_{y, \text{max. (z)}}} + \frac{F_{x, \text{push}} (v)}{F_{x, \text{push, max. (v)}}} + \frac{F_{x, \text{pull}} (v)}{F_{x, \text{pull, max. (v)}}} \leq 1$$

The following values are assumed:

$F_y (5) = 60 \text{ N}$
 $F_{x, \text{push (stat.)}} (12) = 30 \text{ N}$
 $F_{y, \text{max. (stat.)}} (5) = 193 \text{ N}$
 $F_{x, \text{max. (stat.)}} (12) = 169 \text{ N}$

With values inserted:

$$\frac{60 \text{ N}}{193 \text{ N}} + \frac{30 \text{ N}}{169 \text{ N}} \leq 1$$

$$0.311 + 0.178 \leq 1$$

$$0.489 \leq 1$$

Thus the drive may be statically loaded with the forces indicated above.

Semi-rotary drives DRQD-6 ... 12, twin-pistons

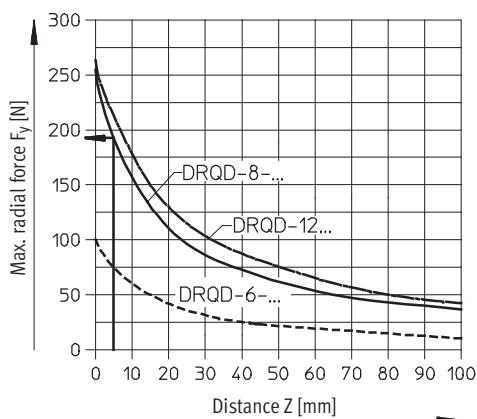
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Technical data

Maximum static radial force

Graph 1

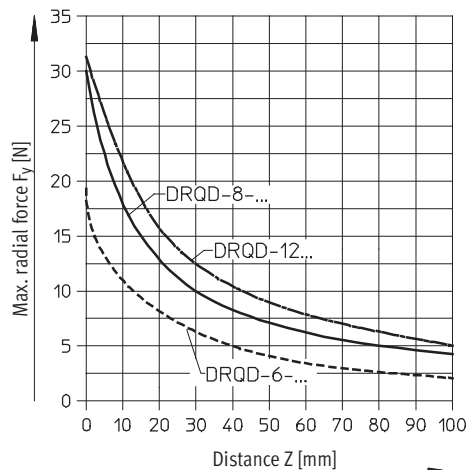
$$F_{y, \max. (stat.)} = f(z)$$



Maximum dynamic radial force

Graph 2

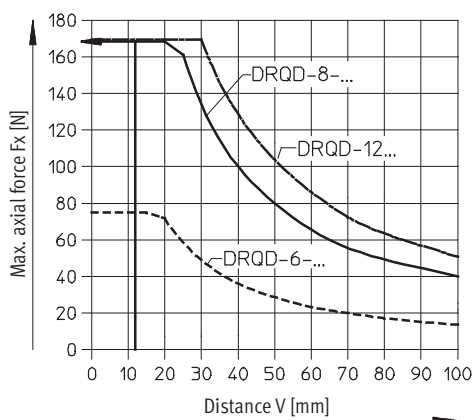
$$F_{y, \max. (dyn.)} = f(z)$$



Maximum static pull and push axial forces

Graph 3

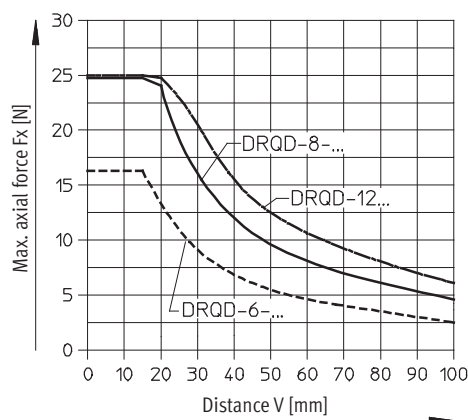
$$F_{x, \max. (stat.)} = f(v)$$



Maximum dynamic pull and push axial forces

Graph 4

$$F_{x, \max. (dyn.)} = f(v)$$



Semi-rotary drives DRQD-6 ... 12, twin-pistons

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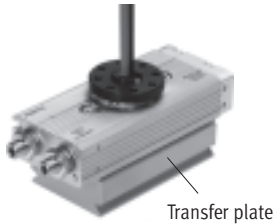
Technical data

Energy through-feed

The energy through-feed consists of DUO tubing (two lengths of tubing are fused together into a pair), whereby each tube has an O.D. of 3 mm. Compressed air is supplied via the

push-in fittings in the transfer plate. Only Quick-Star push-in fittings may be used to connect compressed air tubing to consuming devices (e.g. grippers).

DRQD-...-SD...



- For piston $\varnothing$ 8 ... 12
- Swivel angles of up to 180° are possible
- 1 DUO tube

Technical data		
Piston $\varnothing$	8	12
Number of spiral tubes	1 DUO tube	
Standard nominal flow rate per tube [l/min]	min. 70	
Theoretical air consumption per tube at 6 bar [cm ³]	5.3	
Operating pressure as a function of ambient temperature [bar]	0 ... 10 (at -10 ... +30 °C) 0 ... 9 (at +30 ... +40 °C) 0 ... 7.8 (at +40 ... +60 °)	
Push-in fittings for connection to consuming device	QS...-3 for tube O.D. of 3 mm	

Semi-rotary drives DRQD-6 ... 12, twin-pistons

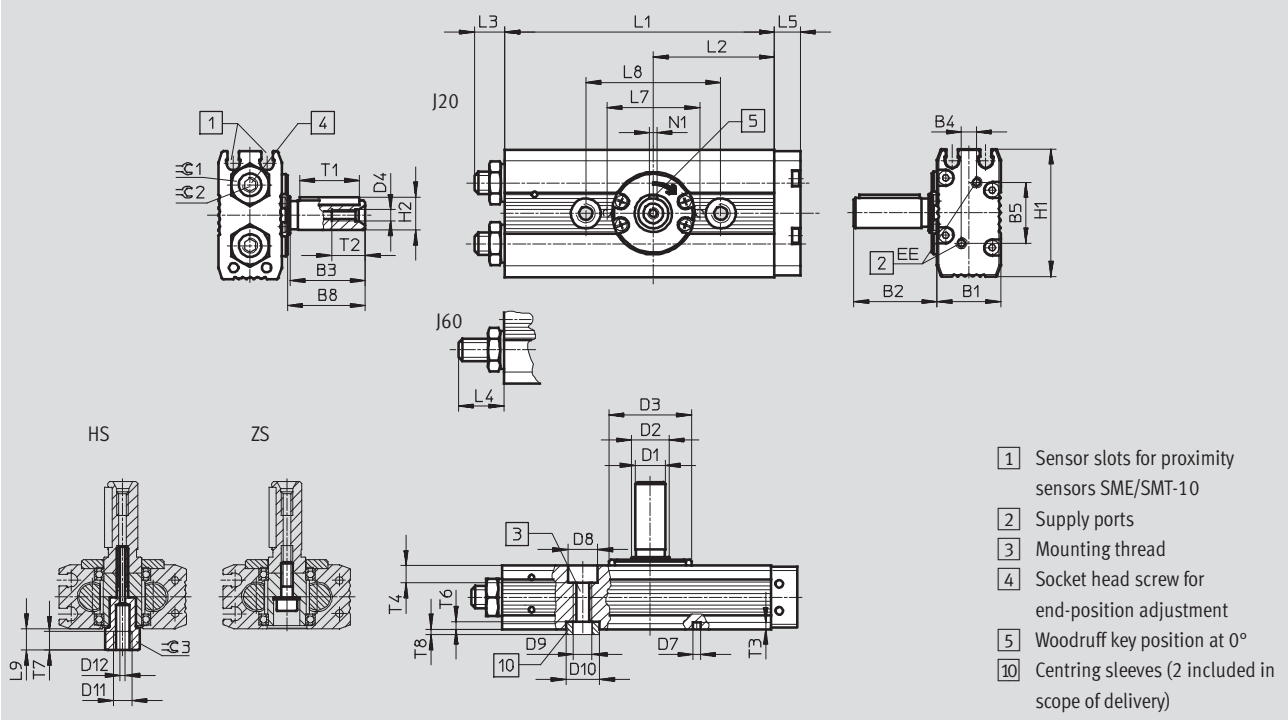
Technical data

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Dimensions

Download CAD Data → www.festo.com/us/cad

ZW – Spigot shaft



Ø	Swivel angle	B1	B2	B3	B4	B5	B8	D1	D2	D3 ¹⁾	D4	D7	D8	D9	D10	D11	D12	EE	H1	H2
[mm]	[°]							Ø g7	Ø g6	Ø f7		Ø H8	Ø H8		Ø H7					
6	90	15.4	18.2	16	2	13.6	16.7	6	8	20	M2.5	2	6	M4	7	M5	1.3	M3	31	6.8
	180																			
8	90	17	22.2	20	4	16.2	20.7	8	10	22	M3	–	8	M5	9	M5	1.3	M3	34	8.8
	180																			
12	90	21	22.2	20	6	18.2	20.7	8	10	22	M3	–	8	M5	9	M5	1.3	M3	41	8.8
	180																			

Ø	Swivel angle	L1	L2	L3	L4	L5	L7	L8	L9	N1	T1	T2	T3	T4	T6	T7	T8	≡C1	≡C2	≡C3
[mm]	[°]			max.	max.		±0.03	±0.03		P9										
6	90	46.7	20.2	7.1	11.1	7.5	20	30	6.2	2	12	7	1.8	3.4	1.6	5	1.4	8	2.5	8
	180	61.8	27.75																	
8	90	54.2	23.45	8.1	12.1	7	–	36	5.7	2	16	9	–	4.6	2	5	2	10	3	8
	180	71.8	32.25																	
12	90	59.2	25.95	9.1	13.1	8	–	36	5.7	2	16	9	–	4.6	2	5	2	13	4	8
	180	76.8	34.75																	

1) Centring possible with D3

Semi-rotary drives DRQD-6 ... 12, twin-pistons

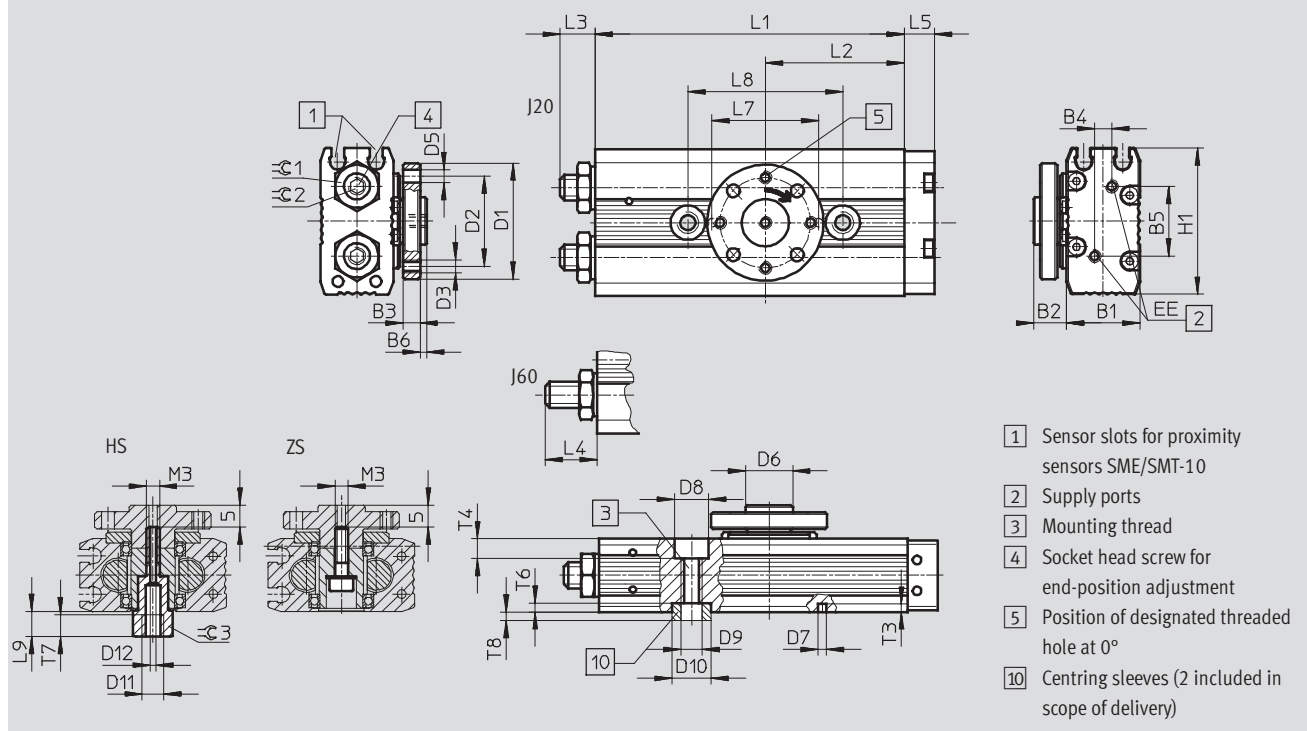
Technical data

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Dimensions

Download CAD Data → www.festo.com/us/cad

FW – Flanged shaft



Ø [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	D1 Ø	D2 Ø	D3	D5 Ø H7	D6 Ø g7	D7 Ø H8	D8 Ø H8	D9	D10 Ø H7	D11	D12 Ø
6	90	15.4	7.7	4	2	13.6	1.5	23	16	M3	3	8	2	6	M4	7	M5	1.3
	180																	
8	90	17	7.7	4	4	16.2	1.5	27	21	M3	3	11	–	8	M5	9	M5	1.3
	180																	
12	90	21	7.7	4	6	18.2	1.5	27	21	M3	3	11	–	8	M5	9	M5	1.3
	180																	

Ø [mm]	Swivel angle [°]	EE	H1	L1	L2	L3 max.	L4 max.	L5	L7 ±0.03	L8 ±0.03	L9	T3	T4	T6	T7	T8	≈C1	≈C2	≈C3
6	90	M3	31	46.7	20.20	7.1	11.1	7.5	20	30	6.2	1.8	3.4	1.6	5	1.4	8	2.5	8
	180			61.8	27.75														
8	90	M3	34	54.2	23.45	8.1	12.1	7	–	36	5.7	–	4.6	2	5	2	10	3	8
	180			71.8	32.25														
12	90	M3	41	59.2	25.95	9.1	13.1	8	–	36	5.7	–	4.6	2	5	2	13	4	8
	180			76.8	34.75														

Semi-rotary drives DRQD-6 ... 12, twin-pistons

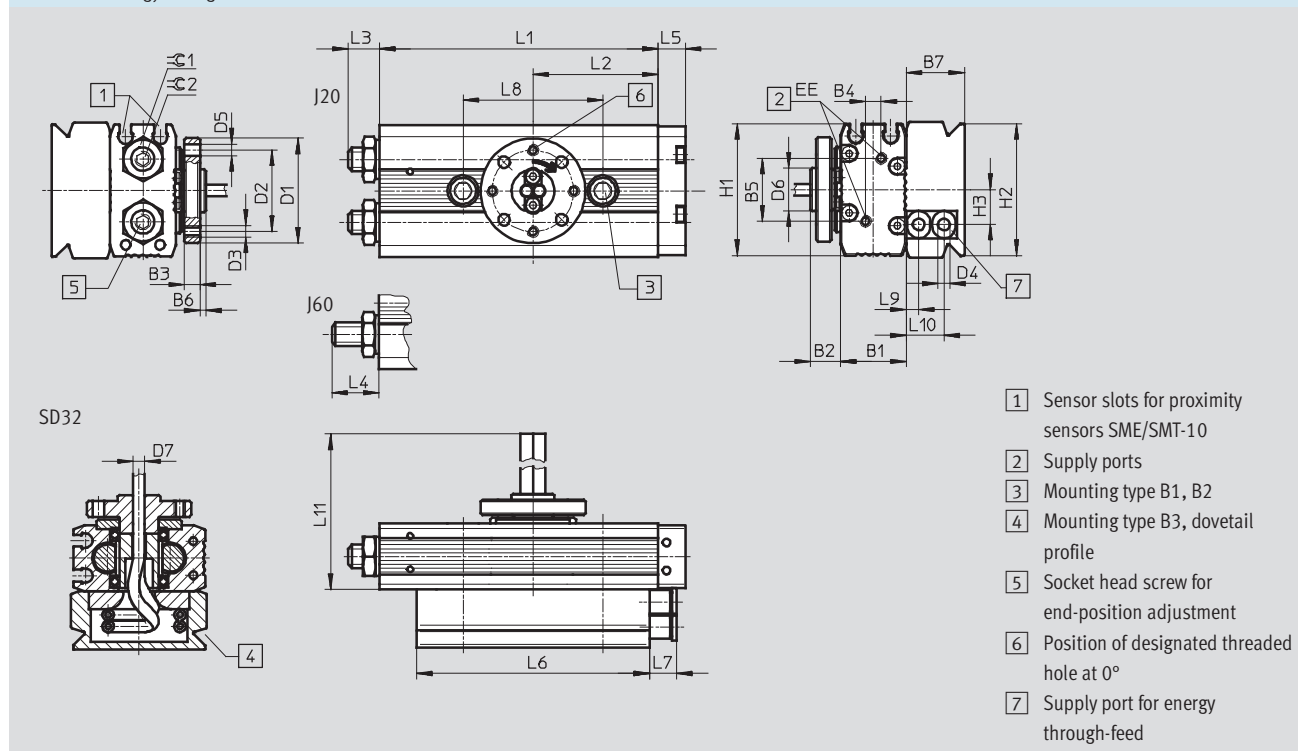
Technical data

FESTO

Dimensions

Download CAD Data → www.festo.com/us/cad

FW-SD32 – Energy through-feed



Ø	Swivel angle	B1	B2	B3	B4	B5	B6	B7	D1	D2	D3	D4	D5	D6	D7	EE
[mm]	[°]								Ø	Ø	Ø	Ø	Ø	Ø	Ø	
8	90	17	7.7	4	4	16.2	1.5	15	27	21	M3	3	3	11	3	M3
	180															
12	90	21	7.7	4	6	18.2	1.5	15	27	21	M3	3	3	11	3	M3
	180															

Ø	Swivel angle	H1	H2	H3	L1	L2	L3	L4	L5	L6	L7	L8	L9	L10	L11	≈C1	≈C2
[mm]	[°]						max.	max.			±0.03						
8	90	34	35	9	54.2	23.45	8.1	12.1	7	60	7	36	3.2	9.7	292	10	3
	180				71.8	32.25											
12	90	41	35	9	59.2	25.95	9.1	13.1	8	60	7	36	3.2	9.7	292	13	4
	180				76.8	34.75											

Semi-rotary drives DRQD-6 ... 12, twin-pistons

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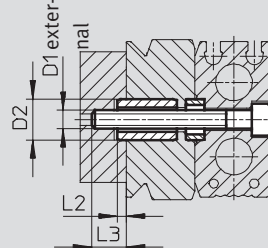
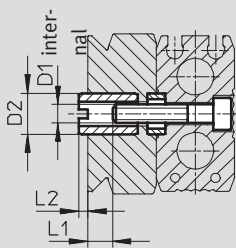
Technical data

Dimensions – Mounting type

Download CAD Data → www.festo.com/us/cad

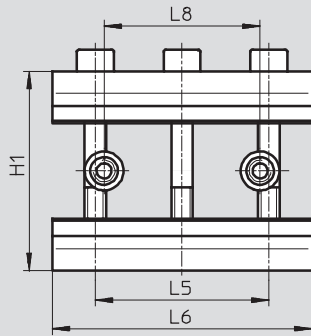
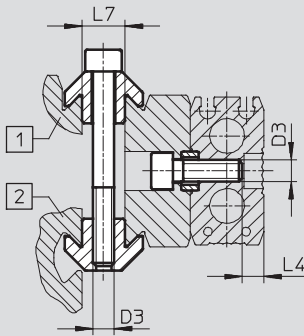
B1 – Counter screws in centring sleeves

B2 – Through screws in attachment



For Ø [mm]	Swivel angle [°]	D1	D2 Ø h7	L1	L2	L3
8	90	M4	9	4.9	2	8.2
	180					
12	90			5.9		9.2
	180					

B3 – Clamping via profile



- 1 Dovetail profile
- 2 Profile slot

For Ø [mm]	Swivel angle [°]	D3	H1	L4	L5	L6	L7 +0.1	L8 ±0.03
8	90	M5	46	5	40	60	10	36
	180							
12	90			9				
	180							

Semi-rotary drives DRQD-6 ... 12, twin-pistons

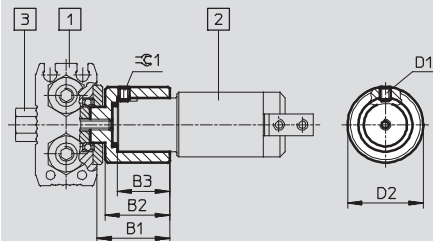
Technical data

FESTO

Dimensions – Adapter for gripper

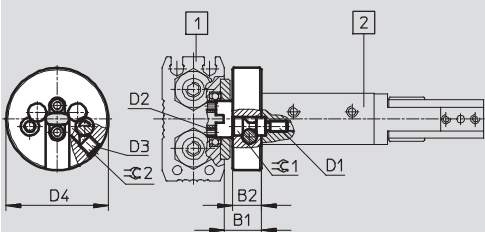
Download CAD Data → www.festo.com/us/cad

A08/A12

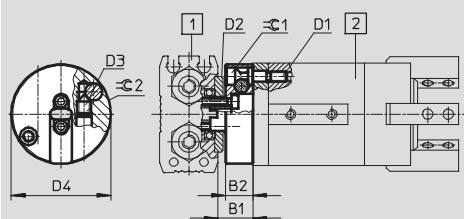


For adapter	1 Drive	2 Grippers	3 Type of screw	B1	B2	B3 ±0.03	D1	D2 Ø	⌀1
A08	DRQD-6-... DRQD-8-... DRQD-12-...	HGWM-08-...-G8 HGPM-08-...-G8	HS	15.2	13	9.6	M3	16	1.5
A12	DRQD-6-... DRQD-8-... DRQD-12-...	HGWM-12-...-G8 HGPM-12-...-G8	HS	20.2	18	14.6	M3	21	1.5

AS1



AS2



For adapter	1 Drive	2 Grippers	B1	B2	D1	D2	D3	D4 Ø	⌀1	⌀2
AS1	DRQD-8-... DRQD-12-...	DHPS-06-... DHRS-10-... DHWS-10-...	10.2	8	M3	M2	M4	28	2.5	2
AS2	DRQD-8-... DRQD-12-...	DHDS-16-...	10.2	8	M3	M2	M4	29	2.5	2

Semi-rotary drives DRQD-6 ... 12, twin-pistons

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Ordering data – Modular products

M Mandatory data →						
Module No.	Function	Size	Swivel angle	End-position adjustment	Position sensing	Output shaft/adapter
187 431	DRQD	6	90	J20	A	ZW
187 432		8	180	J60		FW
187 433		12				A08 A12 AS1 AS2
Ordering example						
187 432	DRQD	- 8	- 180	- J60	- A	- A12

Ordering table						
Size	6	8	12	Conditions	Code	Enter code
M Module No.	187 431	187 432	187 433			
Function	Semi-rotary drive with twin pistons				DRQD	DRQD
Piston Ø [mm]	6	8	12		~...	
Swivel angle	90°				-90	
	180°				-180	
End-position adjustment	Adjusting range +6°/-20°				-J20	
	Adjusting range +6°/-60°				-J60	
Position sensing	For proximity sensing				-A	-A
Output shaft/adaptor	Spigot shaft			1	-ZW	
	Flanged shaft			2	-FW	
	Adapter for HGWM-08	Adapter for HGPM-08/HGWM-08		3	-A08	
	Adapter for HGWM-12	Adapter for HGPM-12/HGWM-12		3	-A12	
	-	Adapter for DHWS/DHRS-10-A, DHPS-6-A		4	-AS1	
	-	Adapter for DHDS-16-A		4	-AS2	

- 1 **ZW** Not with energy through-feed SD32
Only with screw type ZS, HS
- 2 **FW** Required for energy through-feed SD32
Only with screw type ZS, HS

- 3 **A08, A12** Not with energy through-feed SD32
Only with screw type HS
- 4 **AS1, AS2** Required for energy through-feed SD32
Not with screw type ZS, HS

Transfer order code

	DRQD	-		-		-	A	-	
--	------	---	--	---	--	---	---	---	--

Semi-rotary drives DRQD-6 ... 12, twin-pistons

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Ordering data – Modular products

→ [0] Options

Energy through-feed	Type of screw	Type of mounting	User's manual
SD32	ZS HS	B1 B2 B3	E F S I V B
- SD32	- HS	- B2	- B

Ordering table						
Size	6	8	12	Condition s	Code	Enter code
[0] Energy through-feed	–	2x tubing O.D. 3 mm		[5]	-SD32	
Type of screw	Socket head screw				-ZS	
	Hollow bolt				-HS	
Type of mounting	–	Mounting type 1		[6]	-B1	
	–	Mounting type 2		[6]	-B2	
	–	Mounting type 3		[6]	-B3	
Alternative language user documentation (standard is German)	English				-E	
	French				-F	
	Spanish				-S	
	Italian				-I	
	Swedish				-V	
	Express waiver – no user manual to be included (already available)				-B	

[5] SD32 Only with mounting type B1, B2, B3

[6] B1, B2, B3 Only with energy through-feed SD32

Transfer order code

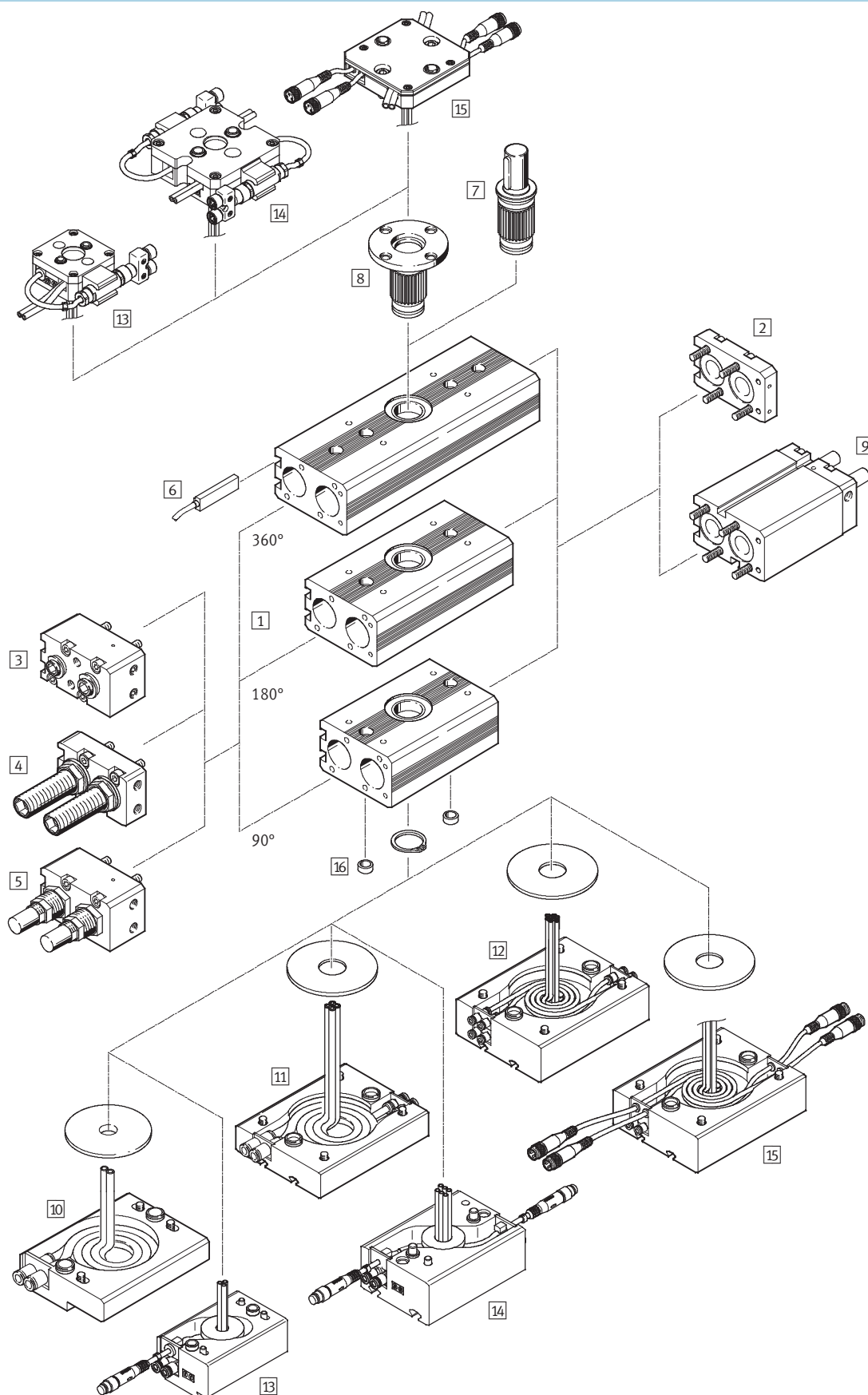
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Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Peripherals overview

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Piston Ø 16 ... 50



Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

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Peripherals overview

Variants, mounting attachments and accessories								
	Brief description	Piston Ø						→ Page/Internet
		16	20	25	32	40	50	
1 Centre section	Centre section for 90°, 180° or 360° swivel angle	■	■	■	■	■	■	58
2 End cap	With integrated compressed air directional function	■	■	■	■	■	■	
3 Connector cap PPVJ	Flexible end position cushioning with adjustable end positions (–20° ... +6°)	■	■	■	■	■	■	
4 Connector cap P1J	Adjustable cushioning elements with adjustable end positions	■	■	■	■	–	–	
5 Connector cap YSRJ	Adjustable shock absorbers with adjustable end positions (–20° ... +6°)	■	■	■	■	■	■	
6 Position sensing A	Contactless via proximity sensors SME-/SMT-8	■	■	■	■	■	■	63
7 Spigot shaft ZW	With woodruff key	■	■	■	■	■	■	58
8 Flanged shaft FW	Hollow, for energy through-feed	■	■	■	■	■	■	
9 Intermediate position Z1	Mid-position at centre of nominal angles of rotation of 90° and 180° (±10°)	■	■	■	■	■	■	35
10 Energy through-feed SD32, SD42	2 tubes with O.D. 3 or 4 mm	■	■	■	■	–	–	36
	Energy through-feed SD62	–	–	–	–	■	■	
11 Energy through-feed SD64	4 tubes with O.D. 6 mm	–	–	–	–	■	■	
12 Energy through-feed SD48	8 tubes with O.D. 4 mm	–	–	–	–	■	■	
13 Energy through-feed E422	2 tubes with O.D. 4 mm and 1 4-pin cable to 2 3-pin cables	■	■	–	–	–	–	
14 Energy through-feed E444	4 tubes with O.D. 4 mm and 2 4-pin cables to 4 3-pin cables	–	–	■	■	–	–	
15 Energy through-feed E644	4 tubes with O.D. 6 mm and 4 3-pin cables	–	–	–	–	■	■	
16 Centring sleeve ZBH	For centring (2 pieces included in scope of delivery for DRQD)	■	■	■	■	■	■	62

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

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Type codes

		DRQD	–	B	–	32	–	90	–	YSRJ	–	A	–	AR	–	FW
Type																
Double-acting																
DRQD	Semi-rotary drive															
Product design																
B	Function-optimized															
Piston Ø [mm]																
Swivel angle [°]																
Type of cushioning																
PPVJ	Adjustable end-position cushioning															
P1J	Adjustable flexible cushioning elements															
YSRJ	Adjustable shock absorbers															
Position sensing																
A	For proximity sensing															
Pneumatic connection																
AL	Supply port, left															
AR	Supply port, right															
Output shaft																
ZW	Spigot shaft															
FW	Flanged shaft															

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

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Type codes

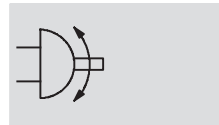
		–		–	SD42	–	B
Intermediate position							
Z1	1 intermediate position (mid-position)						
Energy through-feed							
SD32	2 tubes with O.D. 3 mm						
SD42	2 tubes with O.D. 4 mm						
SD48	8 tubes with O.D. 4 mm						
SD62	2 tubes with O.D. 6 mm						
SD64	4 tubes with O.D. 6 mm						
E422	2 tubes with O.D. 4 mm and 1 4-pin cable to 2 3-pin cables						
E444	4 tubes with O.D. 4 mm and 2 4-pin cables to 4 3-pin cables						
E644	4 tubes with O.D. 6 mm and 4 3-pin cables						
User's manual							
	German (standard)						
E	English						
F	French						
S	Spanish						
I	Italian						
V	Swedish						
B	Express waiver – no user manual to be included (already available)						

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

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Technical data

Function

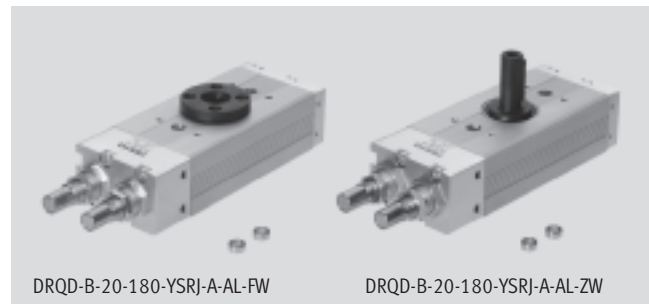


⌀ - Diameter
16 ... 50 mm

≡ - Force
1.6 ... 50 Nm

Variants

- 90°, 180° and 360° or X swivel angle
- Spigot or flanged shaft
- Adjustable end-position cushioning or shock absorbers
- Position sensing
- Intermediate position
- Energy through-feed
- Different types of mounting



www.festo.com/en/
Spare_parts_service

General technical data									
Piston Ø		16	20	25	32	40	50		
Pneumatic connection		M5			G1/8		G1/4		
		SD32	QS...-3 for tubing O.D. Ø 3 mm ¹⁾				–	–	
		SD42/SD48	QS...-4 for tubing O.D. Ø 4 mm ¹⁾				–	–	
		E422	QS...-4 for tubing O.D. 4 mm		–				
		E444	–		QS...-4 for tubing O.D. 4 mm		–		
		SD62/SD64/ E644	–				QS...-6 for tubing O.D. 6 mm		
Constructional design		Semi-rotary drive with twin pistons based on the rack and pinion principle							
Cushioning	PPVJ	Adjustable, pneumatic							
	P1J	Adjustable, flexible cushioning elements				–			
	YSRJ	Adjustable, hydraulic shock absorbers							
Position sensing		For proximity sensing							
Type of mounting		Via through-hole							
		Via female thread							
Assembly position		Any							
Adjustable end-position range per end position	°	PPVJ	–20 ... +6						
		P1J	–270 ... +6	–320 ... +6	–280 ... +6	–210 ... +6	–		
		YSRJ	–20 ... +6						
Max. permissible swivelling frequency at 6 bar (for completed cycle of motion)	Hz	PPVJ	90°	4	3	2	1.2	1.2	1.2
			180°	3	2.2	1.3	0.8	0.9	0.9
			360°	1.5	1.2	0.8	0.5	0.5	0.5
		P1J	90°	3.6	3	2.5	2.2	–	–
			180°	2.5	2.2	1.9	1.6	–	–
			360°	1.5	1.2	1	0.8	–	–
		YSRJ	90°	2	2	1.5	1.2	1	0.9
			180°	1.8	1.8	1.5	1.2	1	0.8
			360°	1	1	0.9	0.8	0.7	0.6
	SD.../E...		A reduction of max. 5% of the values indicated above						
			- $\frac{1}{2}$ - Note: At temperatures < 0 °C, a max. frequency of 1 Hz applies in the case of variant YSRJ						

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

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Technical data

General technical data									
Piston Ø				16	20	25	32	40	50
Minimum cycle times in conjunction with Z1 (from the end position to the intermediate position)	[s]	PPVJ	90°	0.20	0.22	0.18	0.21	0.20	0.18
			180°	0.26	0.41	0.20	0.26	0.21	0.35
	YSRJ	90°	0.20	0.22	0.17	0.20	0.47	0.35	
		180°	0.23	0.31	0.22	0.23	1.10	0.99	
Repetition accuracy (approached from both ends)	[°]		≤ 0.05						
	Z1		≤ 0.15				≤ 0.25	≤ 0.20	≤ 0.30

Operating and environmental conditions							
Piston Ø		16	20	25	32	40	50
Operating medium		Filtered compressed air, lubricated or unlubricated					
Operating pressure	[bar]	PPVJ	1 ... 10				
		P1J	3 ... 10			–	
		YSRJ	2 ... 10				
		Z1	1 ... 10				
Ambient temperature		[°C]	–10 ... +60				
Corrosion resistance class CRC ¹⁾		1					
ATEX		Specified types → www.festo.com					

1) Corrosion resistance class 1 according to Festo standard 940 070

Components requiring low corrosion resistance. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers

Forces and torques								
Piston Ø			16	20	25	32	40	50
Theoretical torque at 6 bar	[Nm]		1.6	3.1	6.1	12.5	25	50
		Z1	1.7	3.6	6.2	13.5	32.2	78.6
			Note: If torque acts against the direction of rotation in the end position, a drive with a rating of twice the maximum theoretical torque should be selected.					
Max. permissible radial and axial forces			Graphs ➔ 33					
Max. permissible mass moment of inertia	[kgm ²]	PPVJ	5 x 10 ⁻⁴	10 x 10 ⁻⁴	20 x 10 ⁻⁴	40 x 10 ⁻⁴	200 x 10 ⁻⁴	500 x 10 ⁻⁴
		P1J	Graphs ➔ 30					–
		YSRJ	Graphs ➔ 31					
		PPVJ-Z1	5 x 10 ⁻⁴	10 x 10 ⁻⁴	20 x 10 ⁻⁴	40 x 10 ⁻⁴	200 x 10 ⁻⁴	500 x 10 ⁻⁴
		YSRJ-Z1	–	–	–	–	1000 x 10 ⁻⁴	2000 x 10 ⁻⁴
			The data applies to the variants ZW, FW, without grippers and unthrottled.					

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

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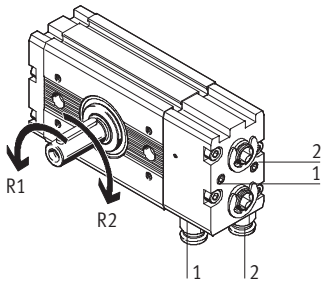
Technical data

Weights [g]			16	20	25	32	40	50	
Piston Ø									
Connection cap AL/AR		PPVJ	116	220	358	609	1,170	2,320	
		P1J	140	240	335	610	–		
		YSRJ	140	240	441	917	2,170	4,270	
Centre section/output shaft	90°	ZW	379	609	1,026	1,891	3,330	6,860	
		FW	380	586	1,018	1,848	3,960	7,010	
	180°	ZW	467	753	1,267	2,325	4,340	8,850	
		FW	468	730	1,259	2,282	4,570	9,000	
	360°	ZW	643	1,039	1,741	3,199	6,350	12,890	
		FW	644	1,016	1,733	3,165	6,580	13,040	
End cap			40	53	82	140	370	610	
Intermediate position	90°	Z1	235	315	550	805	2,510	3,960	
	180°	Z1	235	315	550	805	2,510	3,960	
Flanged shaft with energy through-feed	SD32	152				303		–	
		SD42	152			303		–	
	SD48		–					1,220	
	SD62		–					900	
	SD64		–					930	
	E422		400			–			
	E444		–			800		–	
	E644		–					2,700	

Direction of rotation of the drive shaft

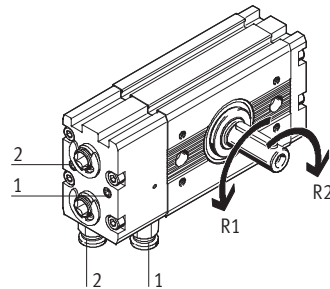
Connection cap on right (AR)

Pneumatic actuation of ports 1 or 2 produces a rotational movement in direction R1 or R2 respectively.



Connection cap on left (AL)

Pneumatic actuation of ports 1 or 2 produces a rotational movement in direction R1 or R2 respectively.



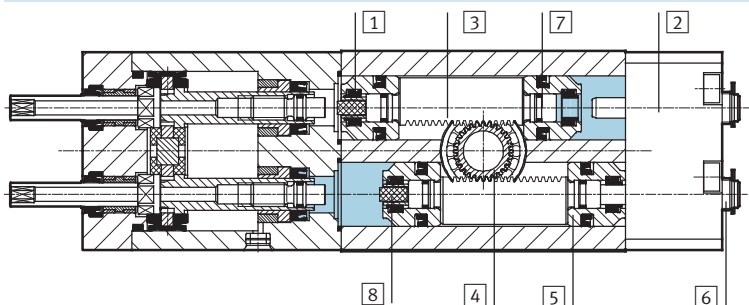
Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

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Technical data

Materials

Sectional view



Piston Ø	16	20	25	32	40	50
Basic drive						
1	Cylinder barrel (centre section)	Anodised aluminium				Wrought aluminium alloy, anodised
2	Connector cap	Anodised aluminium				
3	Gear rack	High-alloy stainless steel, hardened				High-alloy steel
4	Pinion	Tempered steel				
5	Piston	Anodised aluminium				
6	Adjustable sleeve	Galvanised steel				
	P1J	Stainless steel				
7	Piston seal	Polyurethane				
–	Material note	Copper, PTFE and silicone-free				
		RoHS-compliant				
Function end cap PPVJ						
–	Cushioning seal	Nitrile rubber/polyurethane				Polyurethane
–	Buffer sleeve, regulating screw	Anodised aluminium				
Function end cap P1J						
–	Cap, housing	Aluminium				–
–	Seals	Nitrile rubber/thermoplastic polyurethane elastomer				–
Function end cap YSRJ						
–	Buffer	Delrin				
–	Rod wiper seal	Nitrile rubber/polyurethane				
Energy through-feed SD.../E...						
–	Transfer plate/sliding disc	Anodised aluminium				
–	DUO spiral tubing	Polyurethane				
Z1 intermediate position module						
–	Piston	Stainless steel; nitrile rubber				
–	Piston rod, nut	Stainless steel				
–	Bearings	POM				
–	Rod wiper seal	Polyurethane				

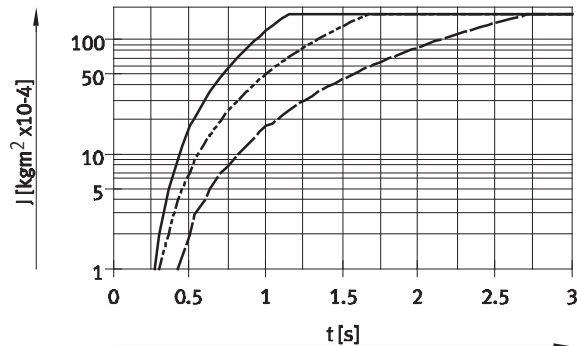
Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

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Technical data

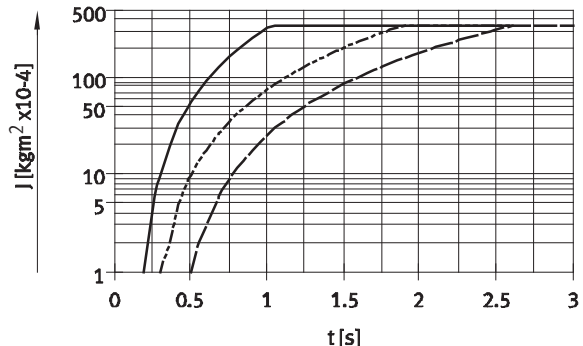
Maximum permitted mass moment of inertia J on the output shaft as a factor of swivel time t

DRQD-B-16-...-P1J



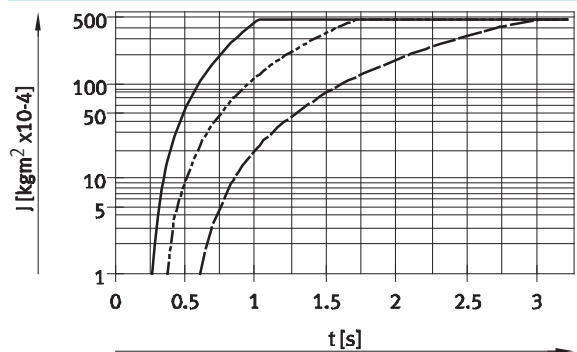
Max. permitted mass moment = $175 \text{ kgm}^2 \times 10^{-4}$

DRQD-B-20-...-P1J



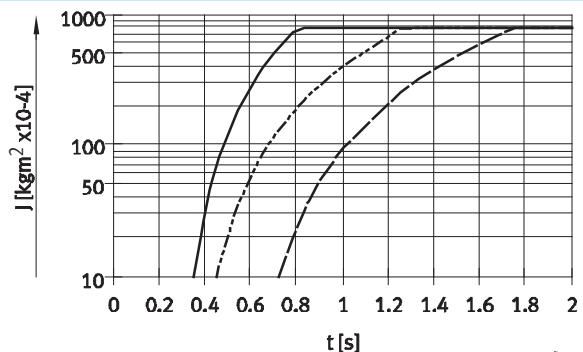
Max. permitted mass moment = $350 \text{ kgm}^2 \times 10^{-4}$

DRQD-B-25-...-P1J



Max. permitted mass moment = $500 \text{ kgm}^2 \times 10^{-4}$

DRQD-B-32-...-P1J



Max. permitted mass moment = $800 \text{ kgm}^2 \times 10^{-4}$

— 90°
- - - 180°
- · - 360°

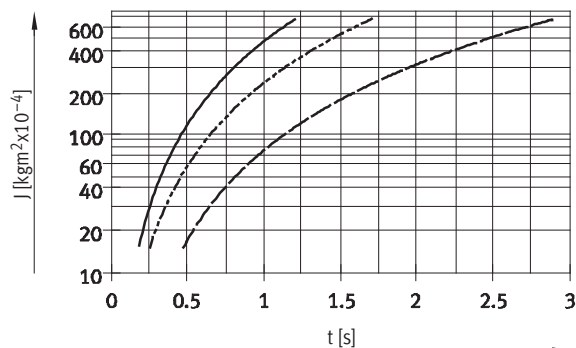
Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

FESTO

Technical data

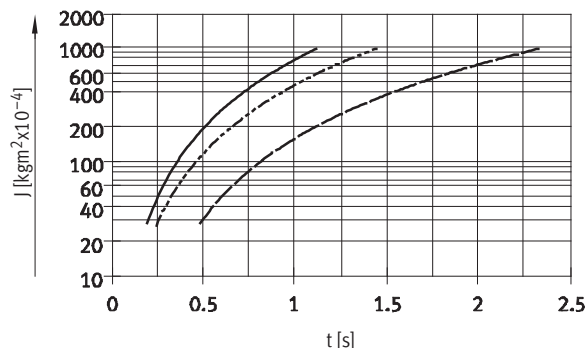
Maximum permitted mass moment of inertia J on the output shaft as a factor of swivel time t

DRQD-B-16-...-YSRJ



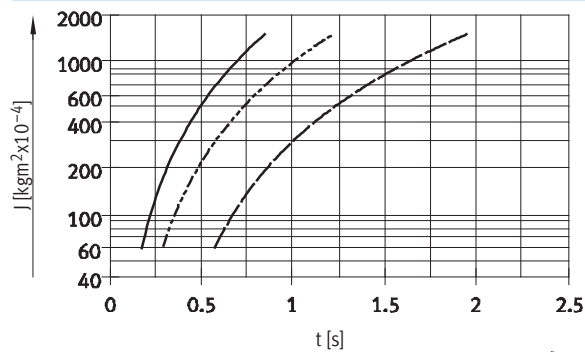
Max. permitted mass moment = $700 \text{ kgm}^2 \times 10^{-4}$

DRQD-B-20-...-YSRJ



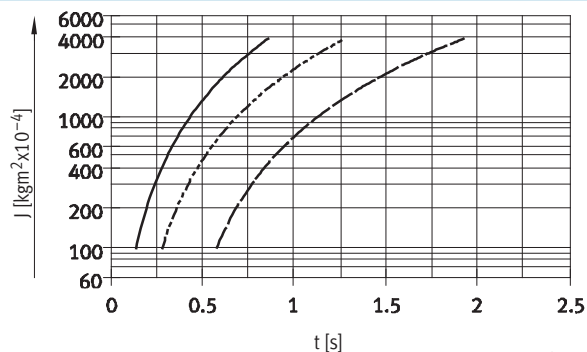
Max. permitted mass moment = $1\,000 \text{ kgm}^2 \times 10^{-4}$

DRQD-B-25-...-YSRJ



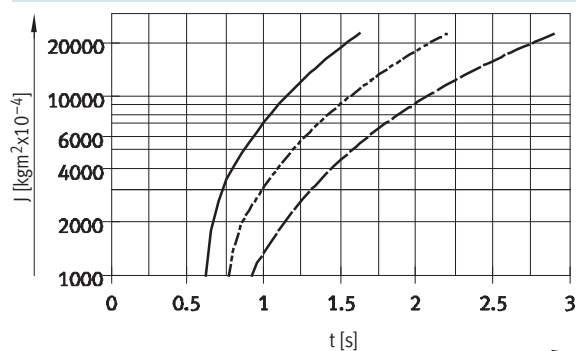
Max. permitted mass moment = $1\,500 \text{ kgm}^2 \times 10^{-4}$

DRQD-B-32-...-YSRJ



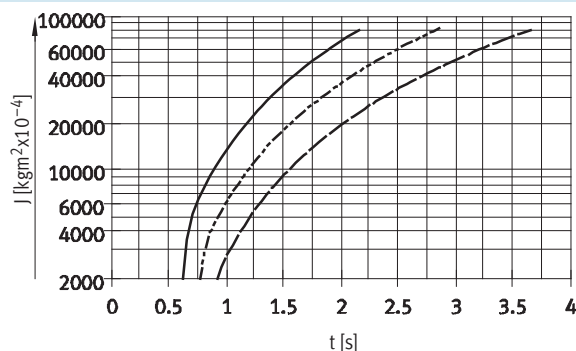
Max. permitted mass moment = $4\,000 \text{ kgm}^2 \times 10^{-4}$

DRQD-40-...-YSRJ



Max. permitted mass moment = $23\,000 \text{ kgm}^2 \times 10^{-4}$

DRQD-50-...-YSRJ



Max. permitted mass moment = $83\,000 \text{ kgm}^2 \times 10^{-4}$

— 90°
- - - 180°
- · - 360°

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

FESTO

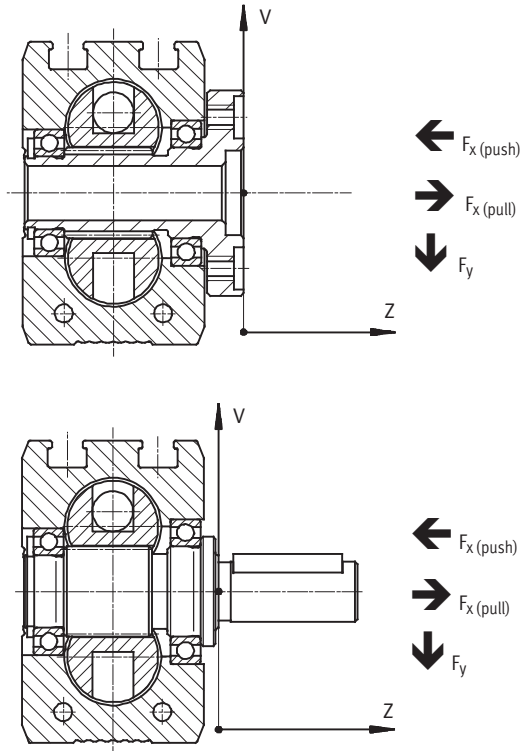
Technical data

Max. permissible radial and axial forces on the drive shaft

Combined load

A DRQD-B-16-...-FW is to be statically loaded with a radial force $F_y = 300 \text{ N}$, which is at a distance of $Z = 15 \text{ mm}$ from the flanged shaft, and an axial

force $F_{x, \text{push}} = 100 \text{ N}$, which is at a distance of $V = 25 \text{ mm}$ from the shaft (→ diagram of flanged shaft on right).



Question:

Is it permissible to statically load a DRQD-B-16-...-FW with these combined forces?

Answer:

According to graph 1 (→ 33), a distance of $Z = 15 \text{ mm}$ results in a maximum permissible radial force

$F_{y, \text{max. (stat.)}} (15) = 400 \text{ N}$.
According to graph 3 (→ 33), a distance of $V = 25 \text{ mm}$ results in a

maximum permissible axial force
 $F_{x, \text{push max. (stat.)}} (25) = 550 \text{ N}$.

The following equation applies to combined loads:

$$\frac{F_y(z)}{F_{y, \text{max. (z)}}} + \frac{F_{x, \text{push (v)}}}{F_{x, \text{push, max. (v)}}} + \frac{F_{x, \text{pull (v)}}}{F_{x, \text{pull, max. (v)}}} \leq 1$$

The following values are assumed:

$F_y(15) = 300 \text{ N}$
 $F_{x, \text{push (stat.)}} (25) = 100 \text{ N}$
 $F_{y, \text{max. (stat.)}} (15) = 400 \text{ N}$
 $F_{x, \text{max. (stat.)}} (25) = 550 \text{ N}$

With values inserted:

$$\frac{300 \text{ N}}{400 \text{ N}} + \frac{100 \text{ N}}{550 \text{ N}} \leq 1$$

$$0.75 + 0.182 \leq 1$$

$$0.932 \leq 1$$

Thus the drive may be statically loaded with the forces indicated above.

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

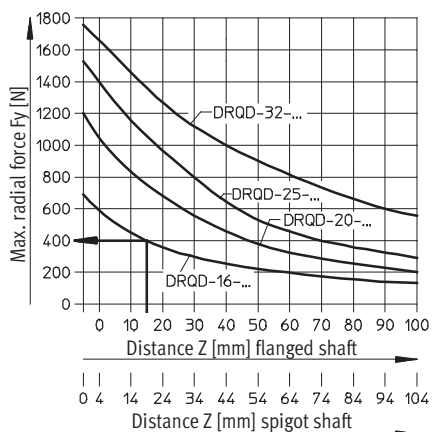
FESTO

Technical data

Maximum static radial force

Graph 1

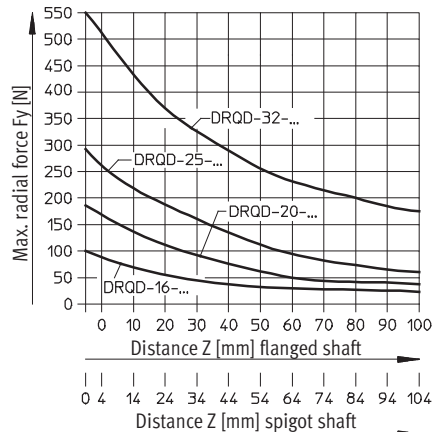
$$F_{y, \text{max. (stat.)}} = f_{(z)}$$



Maximum dynamic radial force

Graph 2

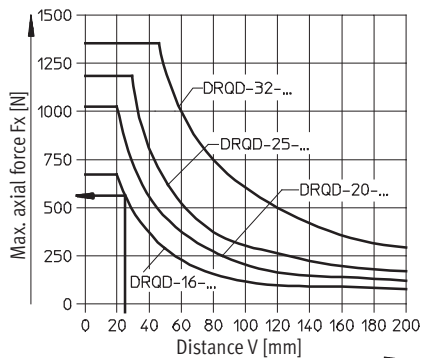
$$F_{y, \text{max. (dyn.)}} = f_{(z)}$$



Maximum static axial pushing force

Graph 3

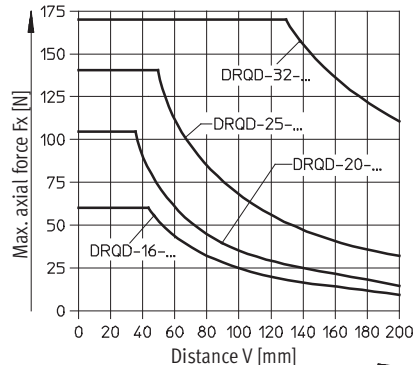
$$F_{x, \text{push max. (stat.)}} = f_{(v)}$$



Maximum dynamic axial pushing force

Graph 4

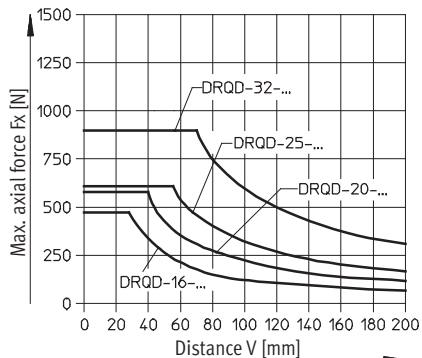
$$F_{x, \text{push max. (dyn.)}} = f_{(v)}$$



Maximum static axial pulling force

Graph 5

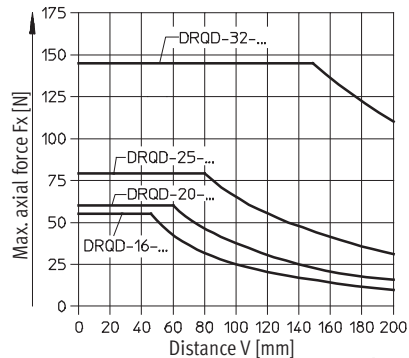
$$F_{x, \text{pull max. (stat.)}} = f_{(v)}$$



Maximum dynamic axial pulling force

Graph 6

$$F_{x, \text{pull max. (dyn.)}} = f_{(v)}$$



Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

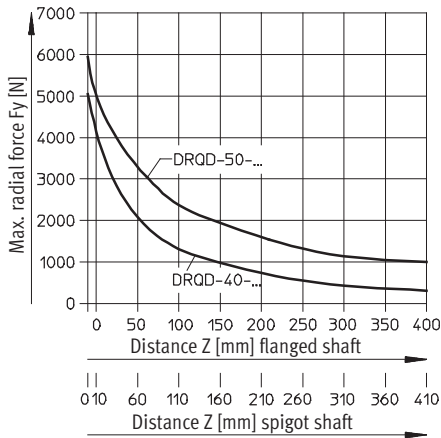
FESTO

Technical data

Maximum static radial force

Graph 1

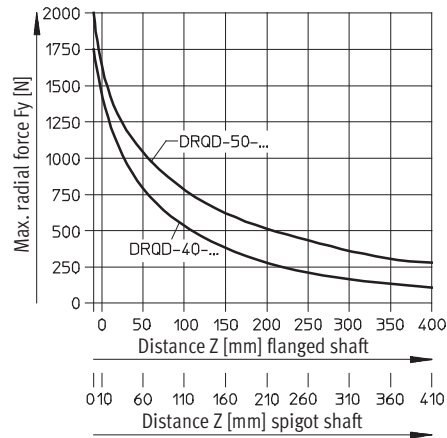
$$F_{y, \text{max. (stat.)}} = f_{(z)}$$



Maximum dynamic radial force

Graph 2

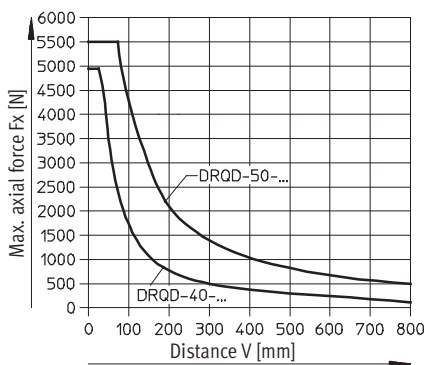
$$F_{y, \text{max. (dyn.)}} = f_{(z)}$$



Maximum static axial pushing force

Graph 3

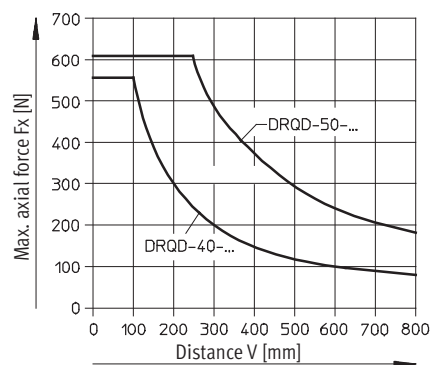
$$F_{x, \text{push max. (stat.)}} = f_{(v)}$$



Maximum dynamic axial pushing force

Graph 4

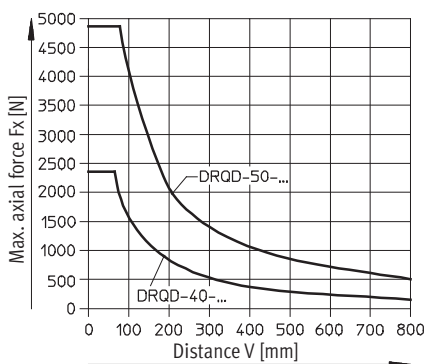
$$F_{x, \text{push max. (dyn.)}} = f_{(v)}$$



Maximum static axial pulling force

Graph 5

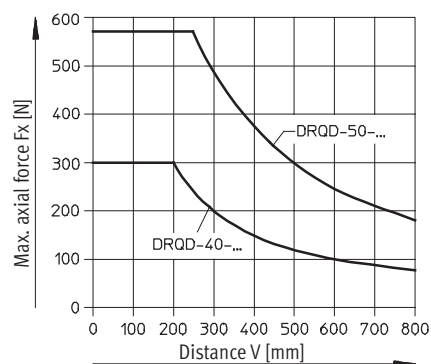
$$F_{x, \text{pull max. (stat.)}} = f_{(v)}$$



Maximum dynamic axial pulling force

Graph 6

$$F_{x, \text{pull max. (dyn.)}} = f_{(v)}$$



Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

FESTO

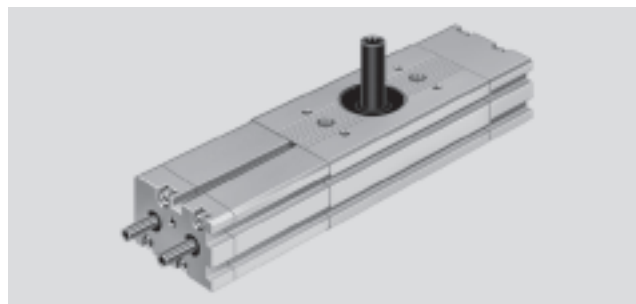
Technical data

Z1 intermediate position module

For $\varnothing 16 \dots 50$

The intermediate position module is fitted in place of the end cap, and allows for adjustable, backlash-free positioning of the drive at 50% of its nominal rotation angle. The intermediate position module is available for nominal rotation angles of 90° and 180°.

The intermediate position module cannot be used in combination with cushioning type DRQD-...-P1J.



Function

A piston incorporating two screw fastened piston rods is pressurised and shifts the semi-rotary drive gear racks until both make full contact with

the piston rods in the mid-position module. The mid-position can be accurately adjusted within a range of $\pm 10^\circ$ with the adjusting screws in the

piston rods. Thanks to the hollow shaft design of the piston rod, adjustment can be performed under pressure.

The through rods in the mid-position module are guided by means of multiple bearings in the cover and in the adapter.

Actuation

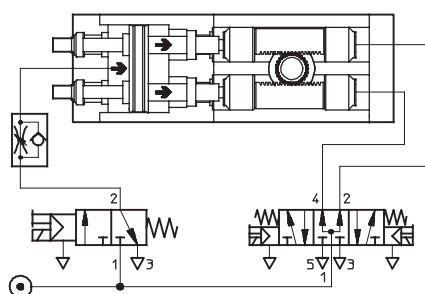
In order for the mid-position module to function, the DRQD basic actuator must be pressurised at both sides.

This can be accomplished with two different types of actuation:

Actuation type 1

- Mid-position module (supply air must be restricted) with a 3/2-way valve

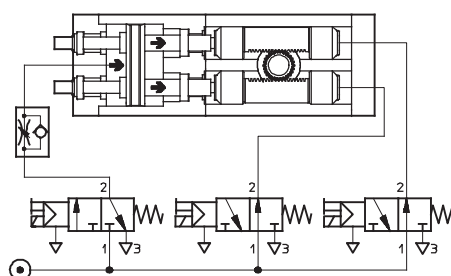
- DRQD basic drive with a 5/3-way valve, mid-position pressurised



Actuation type 2

- Mid-position module (supply air must be restricted) with a 3/2-way valve

- DRQD basic drive with two 3/2-way valves, spring return



Note

Even if the semi-rotary drives DRQD-B-16 to 32 have been equipped with shock absorbers (type YSRJ), the mid-position may not be loaded with

more than the max. permissible mass moment of inertia for the PPVJ variant! The reason for this is the cushioning: Whereas loads can be absorbed in the

end positions with the shock absorbers, the mid-position is only equipped with basic flexible cushioning. Additional information on

the permissible mass moment of inertia for the sizes 40 and 50 mm: [→ 27](#)

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

FESTO

Technical data

Energy through-feed

DRQD-...-SD...

The energy through-feed consists of one to max. four DUO tubes (fused tubing pair), whereby each tube has an O.D. of 3 ... 6 mm. Compressed air is supplied via the push-in fittings in

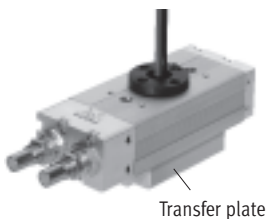
the transfer plate. Only Quick-Star push-in fittings may be used to connect compressed air tubing to consuming devices (e.g. grippers).

DRQD-...-E...

The energy through-feed consists of one to max. two DUO tubes (fused tubing pair), whereby each tube has an O.D. of 4 ... 6 mm. Compressed air is supplied via the push-in fittings in the transfer plate. Only Quick-Star

push-in fittings may be used to connect compressed air tubing to consuming devices (e.g. grippers). In addition, up to four proximity sensors can be connected by means of this energy through-feed.

DRQD-...-SD...



- For piston Ø 16 ... 50
- Swivel angles of up to 360° are possible
- 1 ... 4 DUO tubes

Technical data			16	20	25	32	40	50
Piston Ø								
Number of DUO tubes	SD32		1				–	
	SD42		1				–	
	SD48		–				4	
	SD62		–				1	
	SD64		–				2	
Standard nominal flow rate (per tube) [l/min]	SD32		min. 70				–	
	SD42		min. 130				–	
	SD48		–				min. 130	
	SD62		–				min. 250	
	SD64		–				min. 250	
Theoretical air consumption per line at 6 bar [cm ³]	SD32		5.3				–	
	SD42		9.5				–	
	SD48		–				9.5	
	SD62		–				24.4	
	SD64		–				24.4	
Operating pressure as a function of ambient temperature [bar]			0 ... 10 (at –10 ... +30 °C) 0 ... 9 (at –30 ... +40 °C) 0 ... 7 (at –40 ... +60 °)					
Tube O.D. on flanged shaft drive side [mm]	SD32		3				–	
	SD42		4				–	
	SD48		–				4	
	SD62		–				6	
	SD64		–				6	
Push-in fittings for connection to consuming device [mm]	SD32		QS-...-3 for tube O.D. 3 mm				–	
	SD42		QS-...-4 for tube O.D. 4 mm				–	
	SD48		–				QS-...-4 for tube O.D. 4 mm	
	SD62		–				QS-...-6 for tube O.D. 6 mm	
	SD64		–				QS-...-6 for tube O.D. 6 mm	

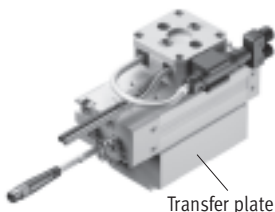
Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

FESTO

Technical data

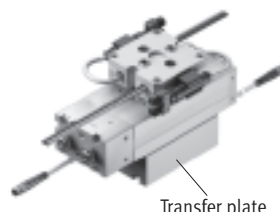
Energy through-feed

DRQD-...-E422



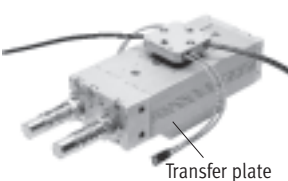
- For piston Ø 16/20
- Swivel angles of up to 180° are possible
- 1 DUO tube with O.D. 4 mm
- 1 4-pin cable to 2 3-pin cables

DRQD-...-E444



- For piston Ø 25/32
- Swivel angles of up to 180° are possible
- 2 DUO tubes each with O.D. 4 mm
- 2 4-pin cables to 4 3-pin cables

DRQD-...-E644



- For piston Ø 40/50
- Swivel angles of up to 180° are possible
- 2 DUO tubes each with O.D. 6 mm
- 4 3-pin cables

Technical data			16	20	25	32	40	50	
Piston Ø									
Number of DUO tubes	E422		1		–				
	E444		–		2	–			
	E644		–		2				
Standard nominal flow rate (per tube)	[l/min]	E422	min. 130		–				
		E444	–		min. 130		–		
		E644	–		–		min. 250		
Theoretical air consumption per line at 6 bar	[cm ³]	E422	9.5		–				
		E444	–		9.5		–		
		E644	–		–		24.4		
Operating pressure as a function of ambient temperature	[bar]	0 ... 10 (at –10 ... +30 °C) 0 ... 9 (at +30 ... +40 °C) 0 ... 7 (at +40 ... +60 °C)							
Tube O.D. on flanged shaft drive side	[mm]	E422	4		–				
		E444	–		4		–		
		E644	–		–		6		
Push-in fittings for connection to consuming device	[mm]	E422	QS-...-4 for tube O.D. 4 mm		–				
		E444	–		QS-...-4 for tube O.D. 4 mm		–		
		E644	–		–		QS-...-6 for tube O.D. 6 mm		

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

FESTO

Technical data

Ø [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	B8	D1 Ø g6	D2 Ø	D3 Ø	D4	D7	D8 Ø H13	D9 Ø	D10	D11 Ø H7	D12
16	90	30	25.5	23	17.8	4	14.8	22	23.5	10	12	18	M3	M4	8	4.2	M5	9	M12
	180																		
	360																		
20	90	36	32.5	30	21.8	4	19.8	26	30.5	12	15	24	M4	M4	8	4.2	M5	9	M14
	180																		
	360																		
25	90	42	42.5	40	24.8	4	24.8	30	40.5	16	20	30	M5	M5	10	5.3	M6	9	M16
	180																		
	360																		
32	90	51	52.5	50	29.8	2	29.8	36	50.5	20	25	35	M6	M5	10	5.3	M6	9	M22
	180																		
	360																		

Ø [mm]	Swivel angle [°]	EE	H1	H2	L1	L2	L3	L4	L5	L6		L7		L8	L9	L10	L11	L16
										min.	max.	min.	max.	±0.03	±0.03			
16	90	M5	50	11.2	71	35.5	10	24	20.8	1.7	5.7	23.4	28.2	60	–	7.6	5.3	14
	180				93	46.5									–			
	360				137	68.5									20			
20	90	M5	56	13.5	78.4	39.2	10	31.5	27	2.4	7	28.6	35.9	60	–	8	5	13.5
	180				104.8	52.4									–			
	360				157.6	78.8									20			
25	90	M5	67	18	91.2	45.6	11	36.5	33	2.6	8.9	42	50.2	60	–	11	5	15
	180				124	62									–			
	360				189.2	94.6									20			
32	90	G½	79	22.5	114.8	57.4	13	39	39	4.3	11.8	59.4	70.1	80	–	13.1	8	20
	180				155.6	77.8									20			
	360				237.4	118.7									20			

Ø [mm]	Swivel angle [°]	L17		L18	N1 P9	T1	T2	T3	T4	T5	T6	T7	≈C1	≈C2	≈C3	≈C4	≈C6	≈C7	≈C8
		min.	max.																
16	90	6.7	41	5.8	3	18.1	9	3.5	5	10	2	2	4	9	13	17	15	4	8
	180																		
	360																		
20	90	8.5	59.5	5	4	25.1	10	3.5	5	12	2	2	7	11	15	19	17	4	8
	180																		
	360																		
25	90	9	61.4	5	5	36.1	12.5	5	6	12	2	2	7	15	19	24	19	5	10
	180																		
	360																		
32	90	10	60	8	6	45.1	16	5	6	14	2	2	8	20	27	32	27	5	10
	180																		
	360																		

Semi-rotary drives DRQD-40 ... 50, twin-pistons

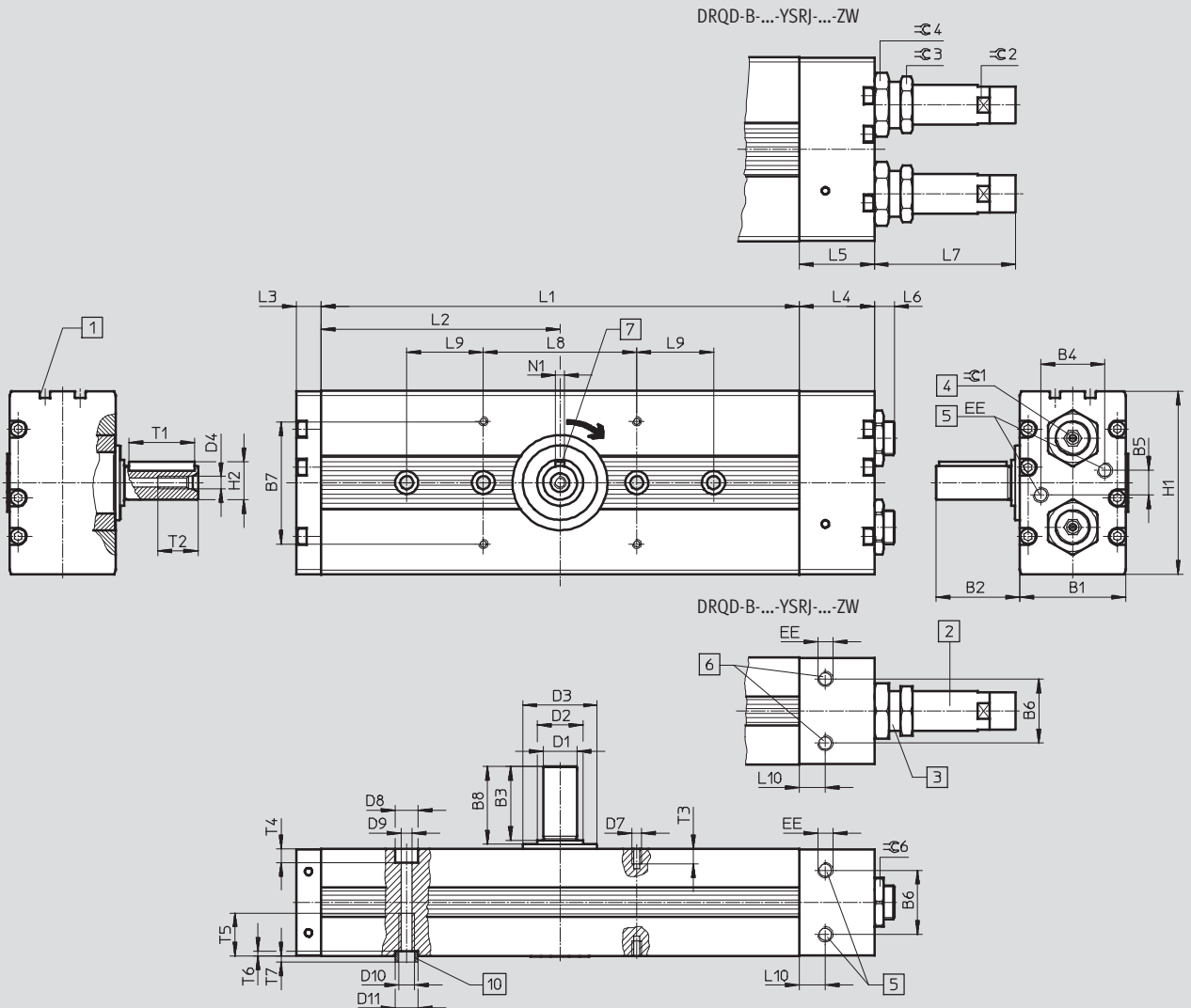
Technical data

FESTO

Dimensions

Download CAD Data → www.festo.com/us/cad

ZW – Spigot shaft



- | | | | |
|---|---|---|---|
| <p>1 T-slots for proximity sensors SME/SMT-8</p> <p>2 Self-adjusting shock absorber for end-position cushioning</p> | <p>3 Adjustable sleeve for end-position adjustment for type DRQD-...-YSRJ</p> <p>4 Socket head screw for end-position adjustment with integral regulating screw for end-position cushioning</p> | <p>5 Variant PPVJ: both supply ports on one end cap, optionally at front or side</p> <p>6 Variant YSRJ: both supply ports on one end cap, front side only</p> | <p>7 Woodruff key position at 0°</p> <p>10 Centring sleeves (2 included in scope of delivery)</p> |
|---|---|---|---|

Semi-rotary drives DRQD-40 ... 50, twin-pistons

FESTO

Technical data

Ø [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	B8	D1 Ø g6	D2 Ø	D3 Ø	D4	D7	D8 Ø H13	D9 Ø
40	90	70	53.5	50	42	4	42	80	50.5	22	30	48.5	M8	M6	15	8.5
	180															
	360															
50	90	86	63.5	60	50	16	50	80	60.9	28	38	58.5	M12	M6	15	8.5
	180															
	360															

Ø [mm]	Swivel angle [°]	D10	D11 Ø H7	EE	H1	H2	L1	L2	L3	L4	L5	L6		L7		L8 ±0.03
												min.	max.	min.	max.	
40	90	M10	15	G1/8	120	24.5	146.8	73.4	16	49	41.5	5	14.6	85.1	96.4	100
	180						201.8	100.9								
	360						311.8	155.9								
50	90	M10	15	G1/4	144	31	191.4	95.7	18	64	55	8	20.7	107.8	120.6	100
	180						262.8	131.4								
	360						405.8	202.9								

Ø [mm]	Swivel angle [°]	L9 ±0.03	L10	N1 P9	T1	T2 +2	T3	T4	T5	T6	T7	≈C1	≈C2	≈C3	≈C4	≈C6
40	90	–	17	6	45.1	26	10	10	28	3	3	10	24	32	36	27
	180	–														
	360	50														
50	90	–	21.2	8	56.1	28	10	11	28	3	3	14	28	36	46	41
	180	50														
	360	100														

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

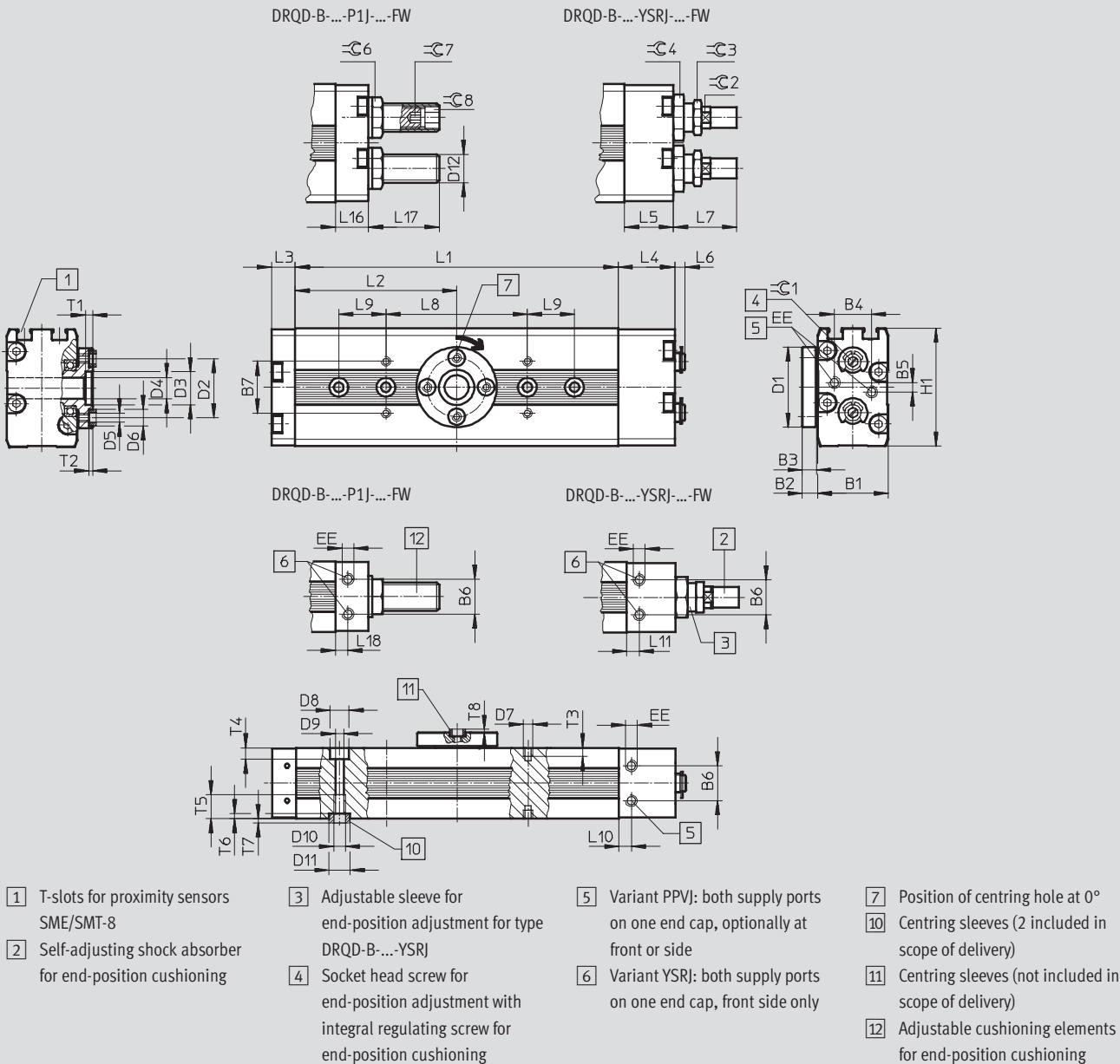
Technical data

FESTO

Dimensions

Download CAD Data → www.festo.com/us/cad

FW – Flanged shaft



Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

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Technical data

Ø	Swivel angle	B1	B2	B3	B4	B5	B6	B7	D1	D2	D3	D4	D5	D6	D7	D8	D9	D10	D11
[mm]	[°]								Ø	Ø ±0.025	Ø H8	Ø		Ø H7		Ø H13	Ø		Ø H7
16	90	30	6.5	6	17.8	4	14.8	22	34	25	14	9	M4	7	M4	8	4.2	M5	9
	180																		
	360																		
20	90	36	6.5	6	21.8	4	19.8	26	38	28	16	11	M4	7	M4	8	4.2	M5	9
	180																		
	360																		
25	90	42	9.5	9	24.8	4	24.8	30	48	34	16	12	M6	9	M5	10	5.3	M6	9
	180																		
	360																		
32	90	51	9.5	9	29.8	2	29.8	36	58	45	19	14	M6	9	M5	10	5.3	M6	9
	180																		
	360																		

Ø	Swivel angle	D12	EE	H1	L1	L2	L3	L4	L5	L6		L7		L8	L9	L10	L11	L16
										min.	max.	min.	max.	±0.03	±0.03			
16	90	M12	M5	50	71	35.5	10	24	20.8	1.7	5.7	23.4	28.2	60	–	7.6	5.3	14
	180				93	46.5									–			
	360				137	68.5									20			
20	90	M14	M5	56	78.4	39.2	10	31.5	27	2.4	7	28.6	35.9	60	–	8	5	13.5
	180				104.8	52.4									–			
	360				157.6	78.8									20			
25	90	M16	M5	67	91.2	45.6	11	36.5	33	2.6	8.9	42	50.2	60	–	11	5	15
	180				124	62									–			
	360				189.2	94.6									20			
32	90	M22	G $\frac{1}{8}$	79	114.8	57.4	13	39	39	4.3	11.8	59.4	70.1	80	–	13.1	8	20
	180				155.6	77.8									20			
	360				237.4	118.7									20			

Ø	Swivel angle	L17		L18	T1	T2	T3	T4	T5	T6	T7	T8	≈C1	≈C2	≈C3	≈C4	≈C6	≈C7	≈C8
		min.	max.																
16	90	6.7	41	5.8	3	1.6	3.5	5	10	2	2	1.4	4	9	13	17	15	4	8
	180																		
	360																		
20	90	8.5	59.5	5	3	1.6	3.5	5	12	2	2	1.4	7	11	15	19	17	4	8
	180																		
	360																		
25	90	9	61.4	5	3	2	5	6	12	2	2	2	7	15	19	24	19	5	10
	180																		
	360																		
32	90	10	60	8	3	2	5	6	14	2	2	2	8	20	27	32	27	5	10
	180																		
	360																		

Semi-rotary drives DRQD-40 ... 50, twin-pistons

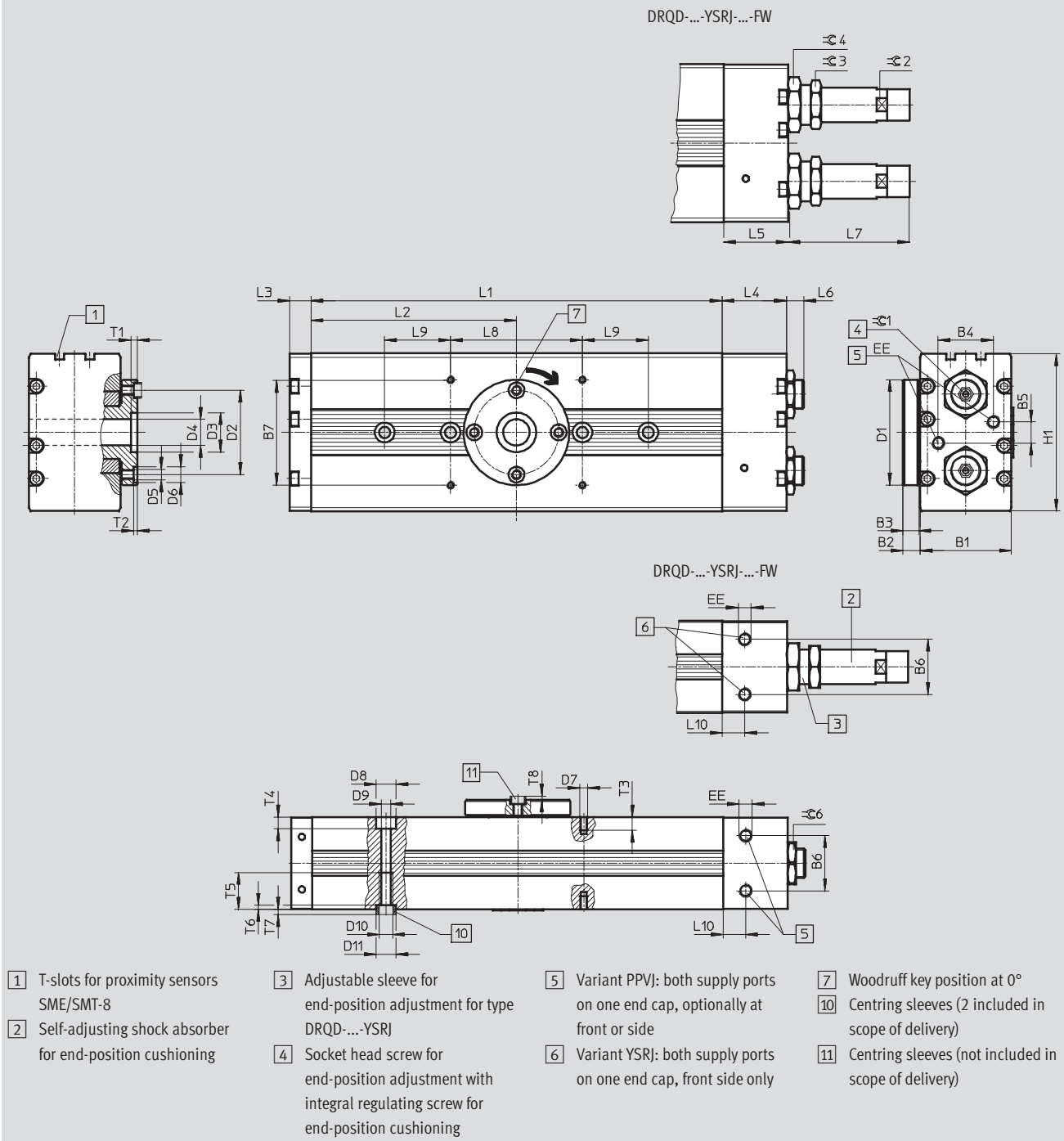
Technical data

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Dimensions

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FW – Flanged shaft



Semi-rotary drives DRQD-40 ... 50, twin-pistons

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Technical data

Ø [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	D1 Ø	D2 Ø ±0.025	D3 Ø H7	D4	D5	D6 Ø H7	D7	D8 Ø H13
40	90	70	13	12	42	4	42	80	80	64	30	20	M8	12	M6	15
	180															
	360															
50	90	86	13	12	50	16	50	80	85	64	30	24	M8	12	M6	15
	180															
	360															

Ø [mm]	Swivel angle [°]	D9 Ø	D10	D11 Ø H7	EE	H1	L1	L2	L3	L4	L5	L6		L7	
												min.	max.	min.	max.
40	90	8.5	M10	15	G1/8	120	146.8	73.4	16	49	41.5	5	14.6	85.1	96.4
	180						201.8	100.9							
	360						311.8	155.9							
50	90	8.5	M10	15	G1/4	144	191.4	95.7	18	64	55	8	20.7	107.8	120.6
	180						262.8	131.4							
	360						405.8	202.9							

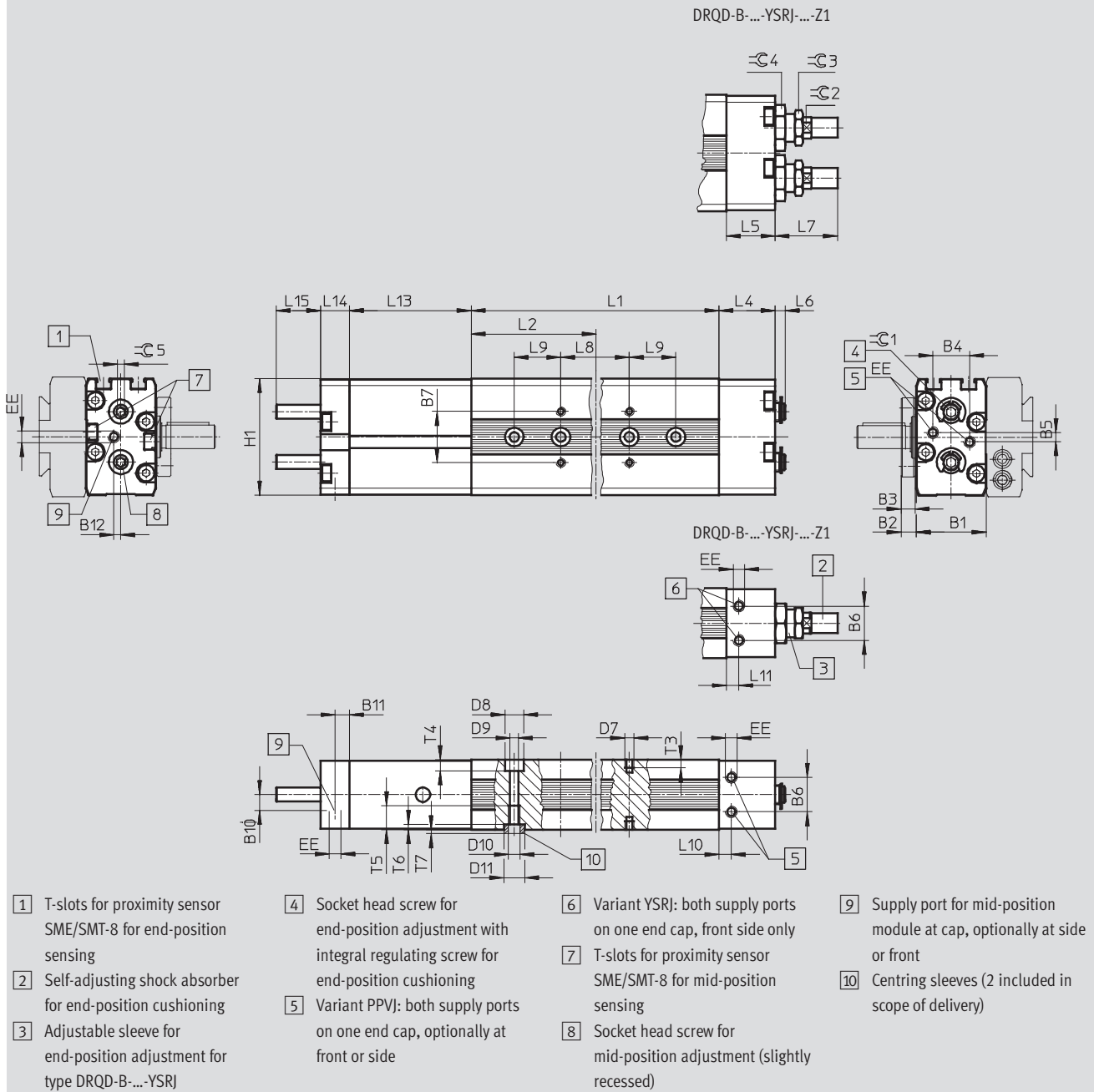
Ø [mm]	Swivel angle [°]	L8 ±0.03	L9 ±0.03	L10	T1	T2	T3	T4	T5	T6	T7	≈C1	≈C2	≈C3	≈C4	≈C6
40	90	100	–	17	4	2.7	10	10	28	3	3	10	24	32	36	27
	180		–													
	360		50													
50	90	100	–	21.2	4	2.7	10	11	28	3	3	14	28	36	46	41
	180		50													
	360		100													

Technical data

Dimensions

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Z1 – Intermediate position module (energy through-feed is optional)



Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

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Technical data

Ø [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	B10	B11	B12	D7	D8 Ø H13	D9 Ø	D10	D11 Ø H7
16	90	30	6.5	6	17.8	4	14.8	22	6.4	4.5	3	M4	8	4.2	M5	9
	180															
20	90	36	6.5	6	21.8	4	19.8	26	6.5	4.5	5.6	M4	8	4.2	M5	9
	180															
25	90	42	9.5	9	24.8	4	24.8	30	9.1	6.9	8.2	M5	10	5.3	M6	9
	180															
32	90	51	9.5	9	29.8	2	29.8	36	9	8	9	M5	10	5.3	M6	9
	180															

Ø [mm]	Swivel angle [°]	EE	H1	L1	L2	L4	L5	L6		L7		L8 ±0.03	L9 ±0.03	L10	L11
								min.	max.	min.	max.				
16	90	M5	50	71	35.5	24	20.8	1.7	5.7	23.4	28.2	60	–	7.6	5.3
	180			93	46.5								–		
20	90	M5	56	78.4	39.2	31.5	27	2.4	7	28.6	35.9	60	–	8	5
	180			104.8	52.4								–		
25	90	M5	67	91.2	45.6	36.5	33	2.6	8.9	42	50.2	60	–	11	5
	180			124	62								–		
32	90	G1/8	79	114.8	57.4	39	39	4.3	11.8	59.4	70.1	80	–	13.1	8
	180			155.6	77.8								20		

Ø [mm]	Swivel angle [°]	L13	L14	L15		T3	T4	T5	T6	T7	≈C1	≈C2	≈C3	≈C4	≈C5
				min.	max.										
16	90	52.2	12.3	0	19.1	3.5	5	10	2	2	4	9	13	17	3
	180														
20	90	55.4	12.3	0	21.8	3.5	5	12	2	2	7	11	15	19	3
	180														
25	90	62.1	15	0	26	5	6	12	2	2	7	15	19	24	4
	180														
32	90	68.2	15.5	0	31.5	5	6	14	2	2	8	20	27	32	4
	180														

Semi-rotary drives DRQD-40 ... 50, twin-pistons

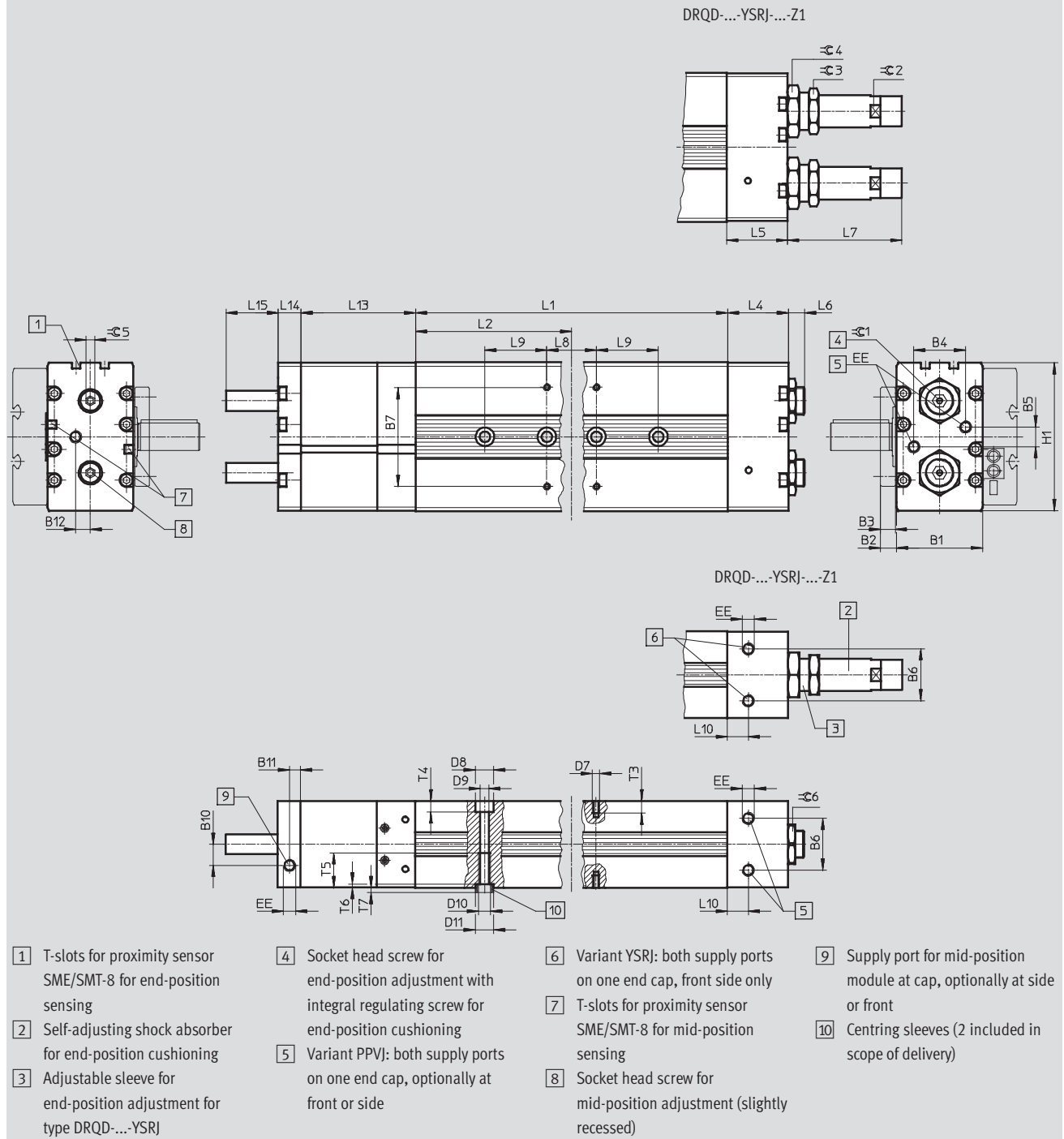
Technical data

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Dimensions

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Z1 – Intermediate position module (energy through-feed is optional)



Semi-rotary drives DRQD-40 ... 50, twin-pistons

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Technical data

Ø [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	B10	B11	B12	D7	D8 Ø H13	D9 Ø	D10
40	90	70	13	12	42	4	42	80	92.5	9	12	M6	15	8.5	M10
	180														
	360														
50	90	86	13	12	50	16	50	80	105.7	9	14	M6	15	8.5	M10
	180														
	360														

Ø [mm]	Swivel angle [°]	D11 Ø H7	EE	H1	L1	L2	L4	L5	L6		L7		L8 ±0.03	L9 ±0.03	L10
									min.	max.	min.	max.			
40	90	15	G $\frac{1}{8}$	120	146.8	73.4	49	41.5	5	14.6	85.1	96.4	100	–	17
	180				201.8	100.9								–	
	360				311.8	155.9								50	
50	90	15	G $\frac{1}{4}$	144	191.4	95.7	64	55	8	20.7	107.8	120.6	100	–	21.2
	180				262.8	131.4								50	
	360				405.8	202.9								100	

Ø [mm]	Swivel angle [°]	L13	L14	L15		T3	T4	T5	T6	T7	=C1	=C2	=C3	=C4	=C5	=C6
				min.	max.											
40	90	92.5	18.5	0	41.95	10	10	28	3	3	10	24	32	36	7	27
	180															
	360															
50	90	105.7	20.5	0	52.95	10	11	28	3	3	14	28	36	46	7	41
	180															
	360															

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

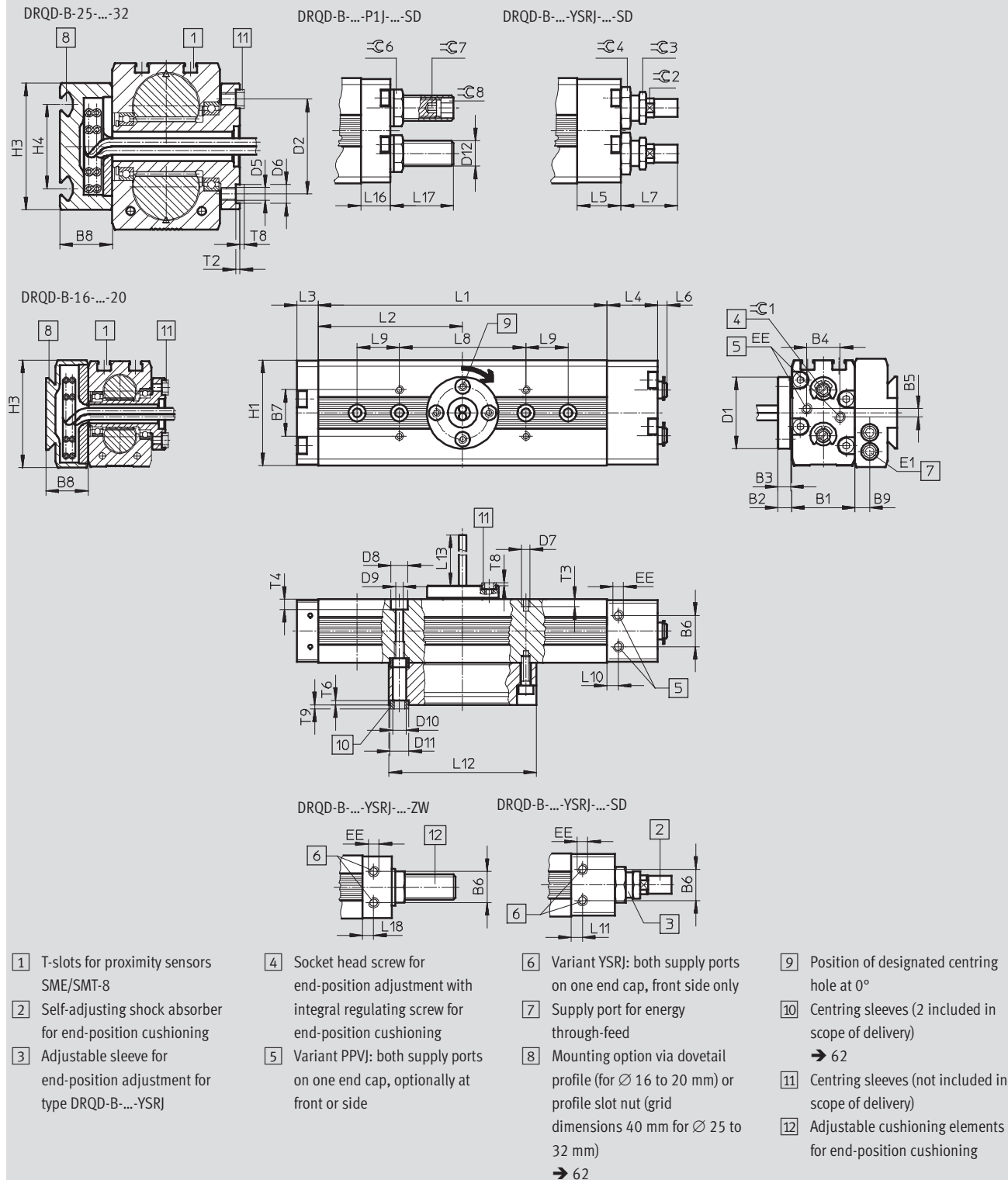
Technical data

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Dimensions

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FW-SD – Energy through-feed



Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

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Technical data

Ø [mm]	Swivel angle [°]	B1	B2	B3	B4	B5	B6	B7	B8	B9	D1 Ø	D2 Ø ±0.025	D5	D6 Ø H7	D7	D8 Ø H13	D9 Ø	D10 Ø H13	D11 Ø H7
16	90	30	6.5	6	17.8	4	14.8	22	20	7	34	25	M4	7	M4	8	4.2	5.5	9
	180																		
	360																		
20	90	36	6.5	6	21.8	4	19.8	26	20	7	38	28	M4	7	M4	8	4.2	5.5	9
	180																		
	360																		
25	90	42	9.5	9	24.8	4	24.8	30	25	7	48	34	M6	9	M5	10	5.3	6.6	9
	180																		
	360																		
32	90	51	9.5	9	29.8	2	29.8	36	25	7	58	45	M6	9	M5	10	5.3	6.6	9
	180																		
	360																		

Ø [mm]	Swivel angle [°]	D12	EE	E1 Ø	H1	H3	H4	L1	L2	L3	L4	L5	L6		L7		L8 ±0.03	L9 ±0.03	L10
													min.	max.	min.	max.			
16	90	M12	M5	4	50	51	–	71	35.5	10	24	20.8	1.7	5.7	23.4	28.2	60	–	7.6
	180							93	46.5										
	360							137	68.5										
20	90	M14	M5	4	56	51	–	78.4	39.2	10	31.5	27	2.4	7	28.6	35.9	60	–	8
	180							104.8	52.4										
	360							157.6	78.8										
25	90	M16	M5	4	67	60	40	91.2	45.6	11	36.5	33	2.6	8.9	42	50.2	60	–	11
	180							124	62										
	360							189.2	94.6										
32	90	M22	G1/8	4	79	60	40	114.8	57.4	13	39	39	4.3	11.8	59.4	70.1	80	–	13.1
	180							155.6	77.8										
	360							237.4	118.7										

Ø [mm]	Swivel angle [°]	L11	L12	L13 min.	L16	L17		L18	T2	T3	T4	T6	T8	T9	≈C1	≈C2	≈C3	≈C4	≈C6	≈C7	≈C8
						min.	max.														
16	90	5.3	72	255	14	6.7	41	5.8	1.6	3.5	5	2.1	1.4	2	4	9	13	17	15	4	8
	180																				
	360																				
20	90	5	72	250	13.5	8.5	59.5	5	1.6	3.5	5	2.1	1.4	2	7	11	15	19	17	4	8
	180																				
	360																				
25	90	5	95	240	15	9	61.4	5	2	5	6	2.1	2	2	7	15	19	24	19	5	10
	180																				
	360																				
32	90	8	95	230	20	10	60	8	2	5	6	2.1	2	2	8	20	27	32	27	5	10
	180																				
	360																				

Semi-rotary drives DRQD-40 ... 50, twin-pistons

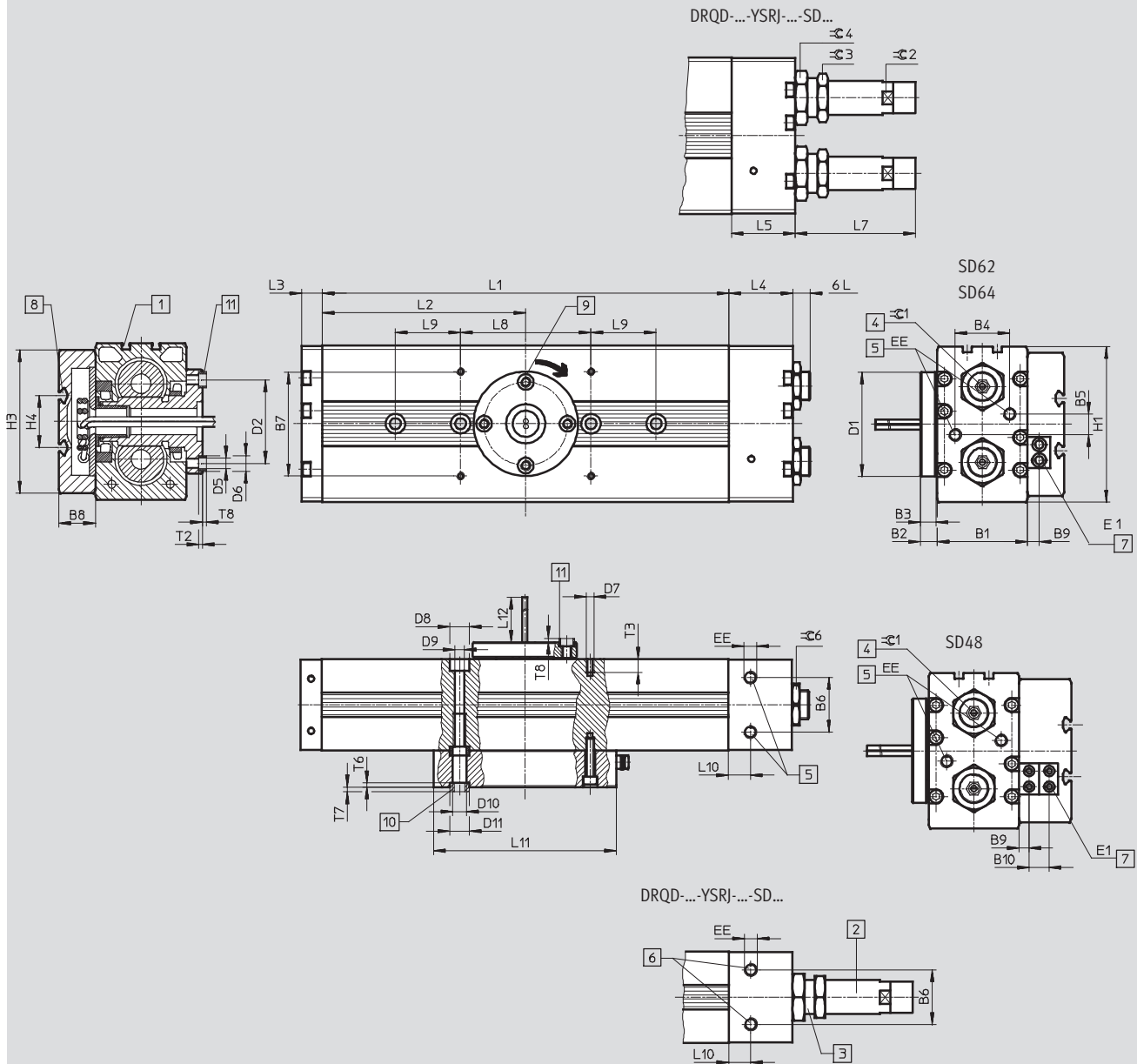
Technical data

FESTO

Dimensions

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FW-SD – Energy through-feed



- 1 T-slots for proximity sensors SME/SMT-8
- 2 Self-adjusting shock absorber for end-position cushioning
- 3 Adjustable sleeve for end-position adjustment for type DRQD-...-YSRJ

- 4 Socket head screw for end-position adjustment with integral regulating screw for end-position cushioning
- 5 Variant PPVJ: both supply ports on one end cap, optionally at front or side

- 6 Variant YSRJ: both supply ports on one end cap, front side only
- 7 Supply port for energy through-feed
- 8 Mounting option via profile slot nut (grid dimensions 40 mm) → 62

- 9 Position of designated centring hole at 0°
- 10 Centring sleeves (2 included in scope of delivery) → 62
- 11 Centring sleeves (not included in scope of delivery)

Semi-rotary drives DRQD-40 ... 50, twin-pistons

FESTO

Technical data

Ø [mm]	Swivel angle [°]	Variant	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	D1 Ø	D2 Ø ±0.05	D3 Ø H7	D4 Ø	D5	D6 Ø H7	D7	D8 Ø H13
40	90	SD62/SD64	70	13	12	42	4	42	80	28	9	–	80	64	30	20	M8	12	M6	15
		SD48								40	7.75	15.5								
	180	SD62/SD64	70	13	12	42	4	42	80	28	9	–	80	64	30	20	M8	12	M6	15
		SD48								40	7.75	15.5								
	360	SD62/SD64	70	13	12	42	4	42	80	28	9	–	80	64	30	20	M8	12	M6	15
		SD48								40	7.75	15.5								
50	90	SD62/SD64	86	13	12	50	16	50	80	28	9	–	85	64	30	24	M8	12	M6	15
		SD48								40	7.75	15.5								
	180	SD62/SD64	86	13	12	50	16	50	80	28	9	–	85	64	30	24	M8	12	M6	15
		SD48								40	7.75	15.5								
	360	SD62/SD64	86	13	12	50	16	50	80	28	9	–	85	64	30	24	M8	12	M6	15
		SD48								40	7.75	15.5								

Ø [mm]	Swivel angle [°]	Variant	D9 Ø	D10 Ø	D11 Ø H7	EE	E1	H1	H3	H4	L1	L2	L3	L4	L5	L6		L7	
																min.	max.	min.	max.
40	90	SD62/SD64	8.5	M10	15	G1/8	6	120	110	40	146.8	73.4	16	49	41.5	5	14.6	85.1	96.4
		SD48					4												
	180	SD62/SD64	8.5	M10	15	G1/8	6	120	110	40	201.8	100.9	16	49	41.5	5	14.6	85.1	96.4
		SD48					4												
	360	SD62/SD64	8.5	M10	15	G1/8	6	120	110	40	311.8	155.9	16	49	41.5	5	14.6	85.1	96.4
		SD48					4												
50	90	SD62/SD64	8.5	M10	15	G1/4	6	144	110	40	191.4	95.7	18	64	55	8	20.7	107.8	120.6
		SD48					4												
	180	SD62/SD64	8.5	M10	15	G1/4	6	144	110	40	262.8	131.4	18	64	55	8	20.7	107.8	120.6
		SD48					4												
	360	SD62/SD64	8.5	M10	15	G1/4	6	144	110	40	405.8	202.9	18	64	55	8	20.7	107.8	120.6
		SD48					4												

Ø	Swivel angle	Variant	L8	L9	L10	L11	L12	T1	T2	T3	T4	T5	T6	T7	T8	≈C1	≈C2	≈C3	≈C4	≈C6
[mm]	[°]		±0.03	±0.03					min.				±0.15							
40	90	SD62/SD64	100	–	17	140	42	4	2.7	10	10	28	3	3	2.3	10	24	32	36	27
		SD48																		
	180	SD62/SD64	100	–	17	140	42	4	2.7	10	10	28	3	3	2.3	10	24	32	36	27
		SD48																		
	360	SD62/SD64	100	50	17	140	42	4	2.7	10	10	28	3	3	2.3	10	24	32	36	27
		SD48																		
50	90	SD62/SD64	100	–	21.2	140	26	4	2.7	10	11	28	3	3	2.3	14	28	36	46	41
		SD48																		
	180	SD62/SD64	100	50	21.2	140	26	4	2.7	10	11	28	3	3	2.3	14	28	36	46	41
		SD48																		
	360	SD62/SD64	100	100	21.2	140	26	4	2.7	10	11	28	3	3	2.3	14	28	36	46	41
		SD48																		

Semi-rotary drives DRQD-B-16 ... 20, twin-pistons

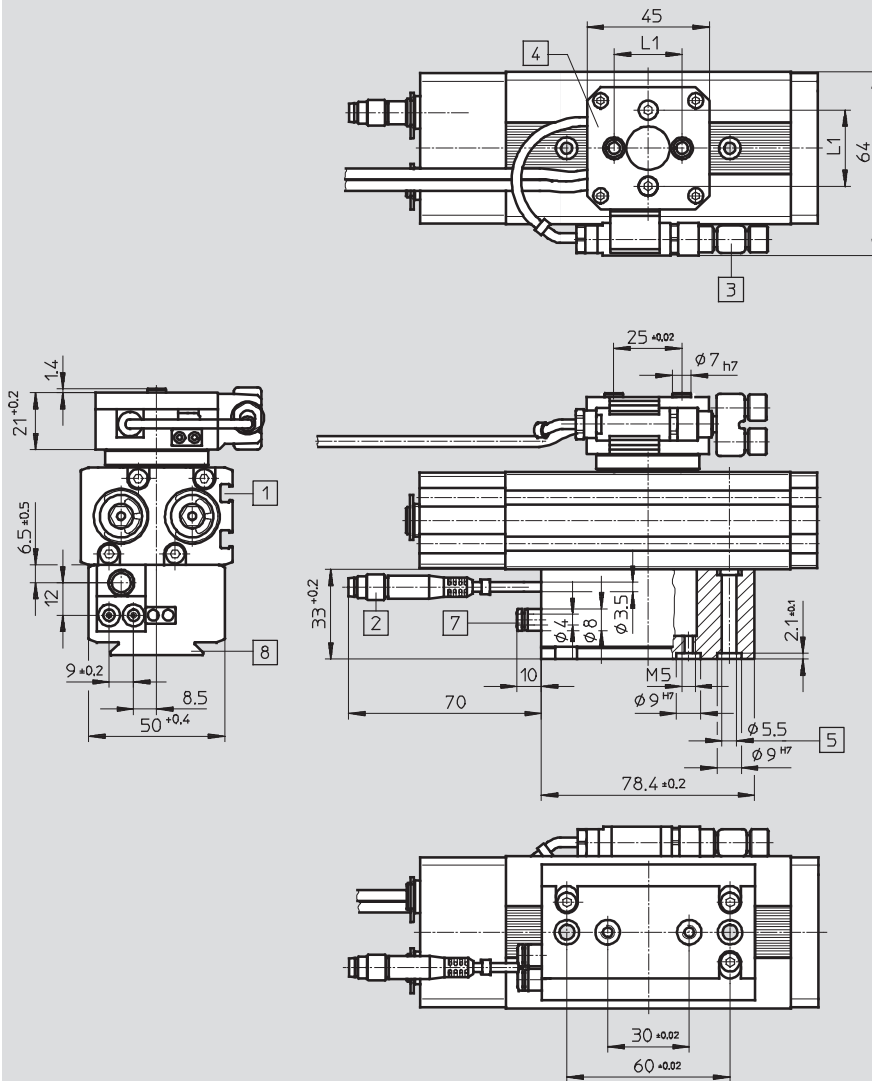
Technical data

FESTO

Dimensions

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FW E422 – Energy through-feed



L1

for Ø 16: 25 ± 0.02 mm

for Ø 20: 28 ± 0.02 mm

- | | |
|---|--|
| 1 T-slots for proximity sensors
SME/SMT-8 | 5 Screw-through option with screw
M4 |
| 2 Plug M8x1, 4-pin | 7 Supply port for energy
through-feed for tubing O.D.
4 mm |
| 3 Socket M8x1 for proximity sensor
SME/SMT | 8 Mounting option via dovetail
connection |
| 4 Output plate can be repositioned
by 90° | |

Basic dimensions

→ 42

Semi-rotary drives DRQD-B-25 ... 32, twin-pistons

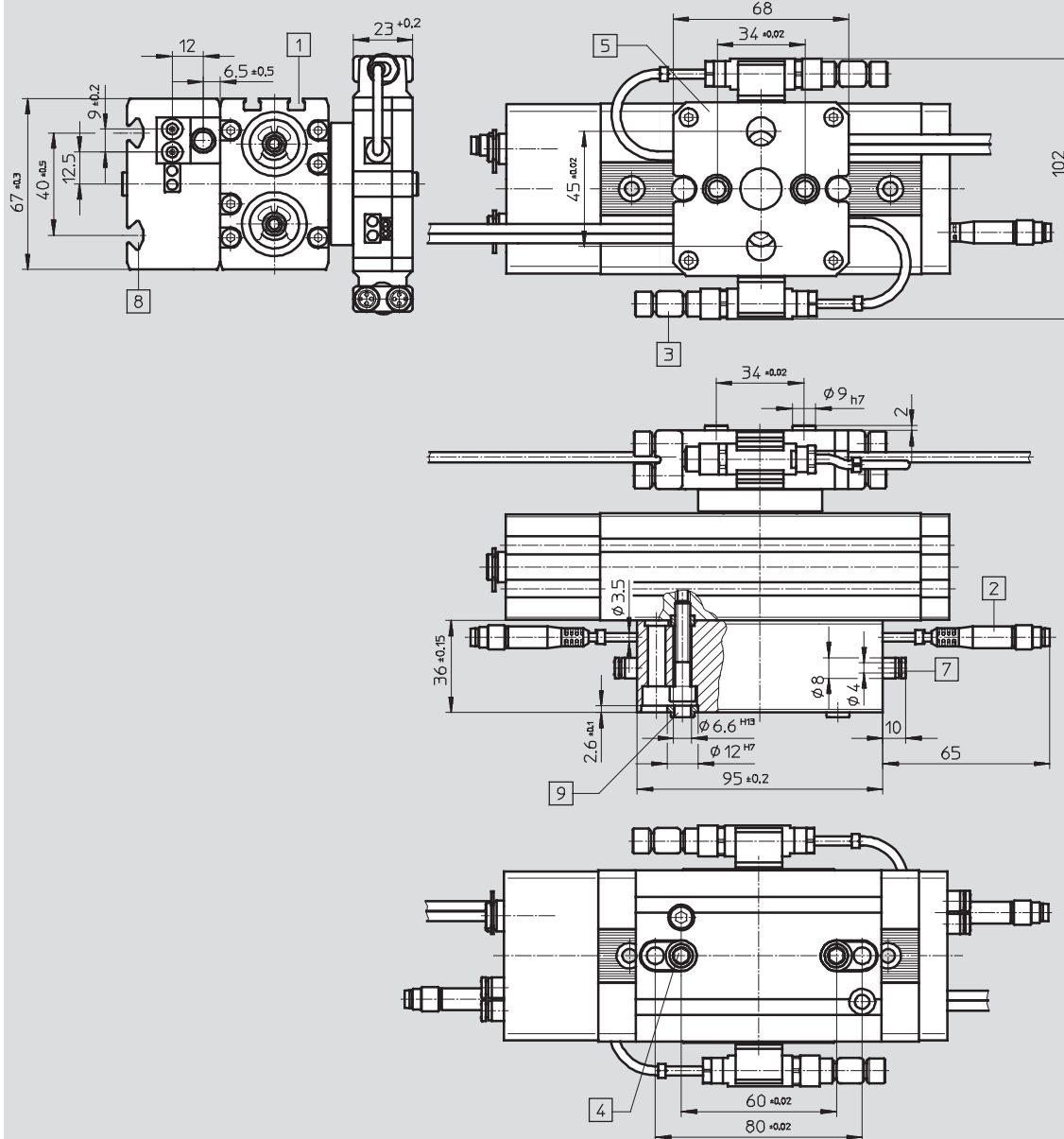
Technical data

FESTO

Dimensions

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FW-E444 – Energy through-feed



1 T-slots for proximity sensors
SME/SMT-8

2 Plug M8x1, 4-pin

3 Socket M8x1 for proximity
sensor SME/SMT

4 Mounting via through-holes
possible with screw M5
(retaining screws must be
removed beforehand)

5 Centring hole can be
repositioned by 90°

7 Supply port for energy
through-feed for tubing O.D.
4 mm

8 Mounting option via profile slot
nut

9 Centring sleeves (2 pieces
included in scope of delivery)
→ 62

Basic dimensions
→ 42

Semi-rotary drives DRQD-40 ... 50, twin-pistons

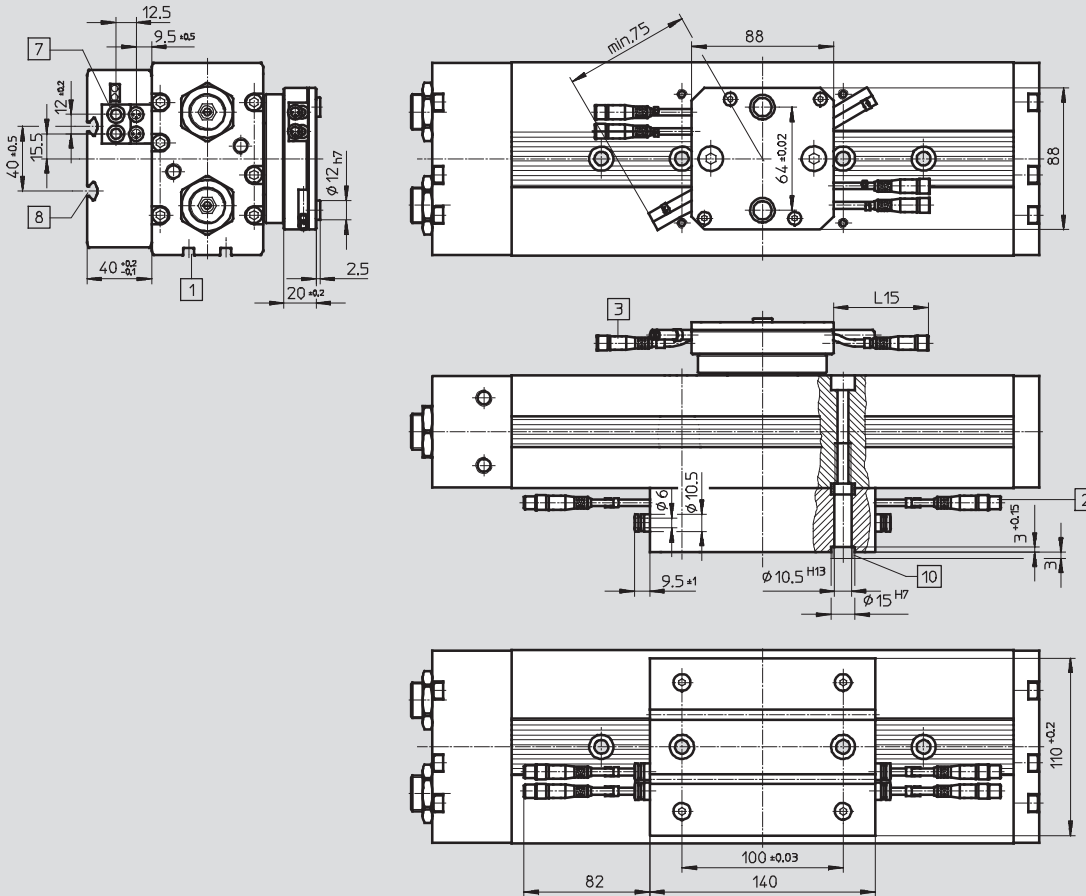
Technical data

FESTO

Dimensions

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FW-E644 – Energy through-feed



L15
for $\varnothing 40$: 150 mm
for $\varnothing 50$: 130 mm

- 1 T-slots for proximity sensors
SME/SMT-8
- 2 Plug M8x1
- 3 Socket M8x1
- 7 Supply port for energy
through-feed for tubing O.D.
6 mm

- 8 Mounting option via profile slot
nut (grid dimensions 40 mm)
→ 62
- 10 Centring sleeves (2 pieces
included in scope of delivery)
→ 62

Basic dimensions
→ 44

Semi-rotary drives DRQD-B-16 ... 32, DRQD-40 ... 50, twin-pistons

Technical data

Ordering data – Standard types					
DRQD	Ø [mm]	Swivel angle [°]	Part No.	Type	
PPVJ – Adjustable end-position cushioning					
	AL – Connection on left				
	16	180	563341	DRQD-B-16-180-PPVJ-A-AL-FW	
	20		563342	DRQD-B-20-180-PPVJ-A-AL-FW	
	25		563343	DRQD-B-25-180-PPVJ-A-AL-FW	
	32		563344	DRQD-B-32-180-PPVJ-A-AL-FW	
	AR – Connection on right				
	16	90	563367	DRQD-B-16-90-PPVJ-A-AR-FW	
	16	180	563353	DRQD-B-16-180-PPVJ-A-AR-FW	
	20		563354	DRQD-B-20-180-PPVJ-A-AR-FW	
	25		563355	DRQD-B-25-180-PPVJ-A-AR-FW	
	32		563356	DRQD-B-32-180-PPVJ-A-AR-FW	
	P1J – Adjustable flexible cushioning elements				
		AL – Connection on left			
16		180	1177954	DRQD-B-16-180-P1J-A-AL-FW	
20			1177955	DRQD-B-20-180-P1J-A-AL-FW	
25			1177956	DRQD-B-25-180-P1J-A-AL-FW	
32			1177957	DRQD-B-32-180-P1J-A-AL-FW	
AR – Connection on right					
16		180	1177950	DRQD-B-16-180-P1J-A-AR-FW	
20			1177951	DRQD-B-20-180-P1J-A-AR-FW	
25			1177952	DRQD-B-25-180-P1J-A-AR-FW	
32			1177953	DRQD-B-32-180-P1J-A-AR-FW	
YSRJ – Adjustable shock absorbers					
		AL – Connection on left			
		16	180	563337	DRQD-B-16-180-YSRJ-A-AL-FW
	20	563338		DRQD-B-20-180-YSRJ-A-AL-FW	
	25	563339		DRQD-B-25-180-YSRJ-A-AL-FW	
	32	563340		DRQD-B-32-180-YSRJ-A-AL-FW	
	AR – Connection on right				
	16	180	563349	DRQD-B-16-180-YSRJ-A-AR-FW	
	20		563350	DRQD-B-20-180-YSRJ-A-AR-FW	
	25		563351	DRQD-B-25-180-YSRJ-A-AR-FW	
	32		563352	DRQD-B-32-180-YSRJ-A-AR-FW	

New Cushioning P1J

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

Ordering data – Modular products

FESTO

Mandatory data →									
Module No.	Function	Product design	Size	Swivel angle	Cushioning	Position sensing	Pneumatic connection	Output shaft	
563 345	DRQD	B	16	90	PPVJ	A	AL	ZW	
563 346			20	180	P1J		AR	FW	
563 347			25	360	YSRJ				
563 348			32	1 ... 340					
Ordering example									
563348	DRQD	- B	- 32	- 280	- YSRJ	- A	- AR	- FW	

Ordering table								
Size	16	20	25	32	Condition s	Code	Enter code	
M Module No.	563 345	563 346	563 347	563 348				
Function	Semi-rotary drive with twin pistons					DRQD		DRQD
Product design	Function-optimized					-B		-B
Piston Ø [mm]	16	20	25	32		-...		
Swivel angle (standard)	90°					-90		
Adjusting range +6°/-20°	180°					-180		
(not preset)	360°					[1] -360		
X-rotation angle	1° ... 70°, with centre section 90°					-...		
Adjusting range ±6°	100° ... 160°, with centre section 180°					-...		
Angle preset ±1°	190° ... 340°, with centre section 360°					[1] -...		
Cushioning	Adjustable end-position cushioning					-PPVJ		
	Adjustable shock absorbers					-YSRJ		
	Adjustable flexible cushioning elements					[2] -P1J		
Position sensing	For proximity sensing					-A		-A
Pneumatic connection	Connection on left					-AL		
	Connection on right					-AR		
Output shaft	Spigot shaft					[3] -ZW		
	Flanged shaft					[4] -FW		

[1] 190 ... 360 Not with energy through-feed E422, E444

[2] P1J Not with Z1, only with standard swivel angle (90°, 180°, 360°)

[3] ZW Not with energy through-feed SD32, SD42, E422, E444

[4] FW Required for energy through-feed SD32, SD42, E422, E444

Transfer order code

DRQD - B - 32 - 280 - YSRJ - A - AR - FW

Semi-rotary drives DRQD-B-16 ... 32, twin-pistons

Ordering data – Modular products

FESTO

Options		
Intermediate position	Energy through-feed	User's manual
Z1	SD32 SD42 E422 E444	B E F S I V
-	- SD42	- B

Ordering table							
Size	16	20	25	32	Condition s	Code	Enter code
Options	Intermediate position	1 intermediate position (mid-position)			5	-Z1	
	Energy through-feed	2x tubing O.D. 3 mm				-SD32	
		2x tubing O.D. 4 mm				-SD42	
		2x tubing O.D. 4 mm, 1x 4-pin cable to 2x 3-pin cable	-	-		-E422	
		-	-	4x tubing O.D. 4 mm, 2x 4-pin cable to 4x 3-pin cable		-E444	
	Alternative language user documentation (standard is German)	No user manual to be included				-B	
		User manual English				-E	
		User manual French				-F	
		User manual Spanish				-S	
		User manual Italian				-I	
		User manual Swedish				-V	

5 Z1 Cannot be combined with swivel angle (standard) 360° and X swivel angle

Transfer order code

- - -

Semi-rotary drives DRQD-40 ... 50, twin-pistons

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Ordering data – Modular products

M Mandatory data →							
Module No.	Function	Size	Swivel angle	Cushioning	Position sensing	Pneumatic connection	Output shaft
197 373 197 374	DRQD	40 50	90 180 360 1 ... 340	PPVJ YSRJ	A	AL AR	ZW FW
Ordering example							
197 373	DRQD	- 40	- 280	- YSRJ	- A	- AR	- FW

Ordering table							
Size	40	50	Condition s	Code	Enter code		
M Module No.	197 373	197 374					
Function	Semi-rotary drive with twin pistons			DRQD		DRQD	
Piston Ø [mm]	40	50		-...			
Swivel angle (standard)	90°			-90			
Adjusting range +6°/-20° (not preset)	180°			-180			
	360°		1	-360			
X-rotation angle	1° ... 70°, with centre section 90°			-...			
Adjusting range ±6°	100° ... 160°, with centre section 180°			-...			
Angle preset ±1°	190° ... 340°, with centre section 360°		1	-...			
Cushioning	Adjustable end-position cushioning			-PPVJ			
	Adjustable shock absorbers			-YSRJ			
Position sensing	For proximity sensing			-A		-A	
Pneumatic connection	Connection on left			-AL			
	Connection on right			-AR			
Output shaft	Spigot shaft		2	-ZW			
	Flanged shaft		3	-FW			

1 190 ... 360 Not with energy through-feed E644

2 ZW Not with energy through-feed SD48, SD62, SD64, E644

3 FW

Required for energy through-feed SD48, SD62, SD64, E644

Transfer order code

	DRQD	-		-		-	A	-		-	
--	------	---	--	---	--	---	---	---	--	---	--

Semi-rotary drives DRQD-40 ... 50, twin-pistons

FESTO

Ordering data – Modular product system

→ 0 Options

Intermediate position	Energy through-feed	User's manual
Z1	SD48 SD62 SD64 E644	B E F S I V
-	- SD64	- B

Ordering table					
Size	40	50	Condition s	Code	Enter code
0 Intermediate position	1 intermediate position (mid-position)		4	-Z1	
Energy through-feed	8x tubing O.D. 4 mm			-SD48	
	2x tubing O.D. 6 mm			-SD62	
	4x tubing O.D. 6 mm			-SD64	
	4x tubing O.D. 6 mm, 4x 3-pin cable			-E644	
Alternative language user documentation (standard is German)	No user manual to be included			-B	
	User manual English			-E	
	User manual French			-F	
	User manual Spanish			-S	
	User manual Italian			-I	
	User manual Swedish			-V	

4 Z1 Cannot be combined with swivel angle (standard) 360° and X swivel angle

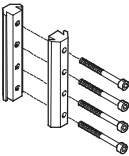
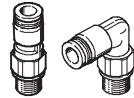
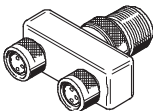
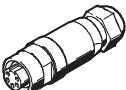
Transfer order code

- - -

Semi-rotary drives DRQD/DRQD-B, twin pistons

Accessories

FESTO

Ordering data						
	For Ø	Remarks	Design	Part No.	Type	PU ¹⁾
Centring sleeve ZBH				Technical data → Internet: zbh		
	6	For centring the drive on attachments		186 717	ZBH-7	10
	8 ... 32			150 927	ZBH-9	
	40/50			191 409	ZBH-15	
	16/20	For centring attachments on the flanged shaft FW		186 717	ZBH-7	
	25/32			150 927	ZBH-9	
	40/50			189 653	ZBH-12	
Connecting sleeve ZBV				Technical data → Internet: zbv		
	25 ... 32	For centring the semi-rotary drive with a drive		548 806	ZBV-12-9	1
Adapter kit HMSV				Technical data → Internet: hmsv		
	16/20	Mounting via dovetail profile for variant with energy through-feed SD... and E...		177 647	HMSV-1	1
Slot nut HMBN				Technical data → Internet: hmbn		
	25 ... 50	Mounting via profile slot nut for variant with energy through-feed SD... and E...		547 264	HMBN-5-1M5	10
				186 566	HMBN-5-2M5	
Rotary push-in fitting				Technical data → Internet: quick star		
	6 ... 12 Only in combination with hollow bolt HS	With ball bearing, for standard O.D. tubing	Straight	153 526	QSR-M5-4	1
			L-shape	153 529	QSRL-M5-4	
T-connector NEDU				Technical data → Internet: nedu		
	16 ... 32	Included in the scope of delivery if semi-rotary drive DRQD is ordered with energy through-feed E422 and E444. Suitable for connection of two proximity sensors SME/SMT-8 or SME/SMT-10		544 391	NEDU-M8D3-M8T4	1
Cable socket NECU				Technical data → Internet: necu		
	16 ... 32	Included in the scope of delivery if semi-rotary drive DRQD is ordered with energy through-feed E422 and E444.		544 392	NECU-M8G4	1

1) Packaging unit quantity

Semi-rotary drives DRQD/DRQD-B, twin pistons

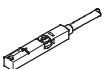
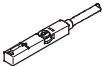
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Accessories

Ordering data – Proximity sensors for C-slot, magneto-resistive					Technical data → Internet: smt	
	Type of mounting	Switch output	Electrical connection, connection direction	Cable length [m]	Part No.	Type
N/O contact						
	Insertable in the slot from above, flush with cylinder profile	PNP	Cable, 3-wire, in-line	2.5	525 915	SMT-10F-PS-24V-K2,5L-OE
			Plug M8x1, 3-pin, in-line	0.3	525 916	SMT-10F-PS-24V-K0,3L-M8D
			Plug M8x1, 3-pin, lateral	0.3	526 675	SMT-10F-PS-24V-K0,3Q-M8D
	Insertable in the slot lengthwise	PNP	Plug M8x1, 3-pin, in-line	0.3	173 220	SMT-10-PS-SL-LED-24
			Cable, 3-wire, in-line	2.5	173 218	SMT-10-PS-KL-LED-24

Ordering data – Proximity sensors for C-slot, magnetic reed					Technical data → Internet: sme	
	Type of mounting	Switch output	Electrical connection, connection direction	Cable length [m]	Part No.	Type
N/O contact						
	Insertable in the slot from above, flush with cylinder profile	Contacting	Plug M8x1, 3-pin, in-line	0.3	525 914	SME-10F-DS-24V-K0,3L-M8D
			Cable, 3-wire, in-line	2.5	525 913	SME-10F-DS-24V-K2,5L-OE
			Cable, 2-wire, in-line	2.5	526 672	SME-10F-ZS-24V-K2,5L-OE
	Insertable in the slot lengthwise	Contacting	Plug M8x1, 3-pin, in-line	0.3	173 212	SME-10-SL-LED-24
			Cable, 3-wire, in-line	2.5	173 210	SME-10-KL-LED-24

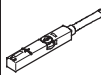
Ordering data – Connecting cables				Technical data → Internet: nebu	
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 333	NEBU-M8G3-K-2.5-LE3
			5	541 334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 338	NEBU-M8W3-K-2.5-LE3
			5	541 341	NEBU-M8W3-K-5-LE3

Ordering data – Proximity sensors for T-slot, magneto-resistive					Technical data → Internet: smt	
	Type of mounting	Switch output	Electrical connection	Cable length [m]	Part No.	Type
N/O contact						
	Insertable in the slot from above, flush with cylinder profile	PNP	Cable, 3-wire	2.5	543 867	SMT-8M-PS-24V-K-2,5-OE
			Plug M8x1, 3-pin	0.3	543 866	SMT-8M-PS-24V-K-0,3-M8D
			Plug M12x1, 3-pin	0.3	543 869	SMT-8M-PS-24V-K-0,3-M12
		NPN	Cable, 3-wire	2.5	543 870	SMT-8M-NS-24V-K-2,5-OE
			Plug M8x1, 3-pin	0.3	543 871	SMT-8M-NS-24V-K-0,3-M8D
	Insertable in the slot lengthwise, flush with the cylinder profile	PNP	Cable, 3-wire	2.5	175 436	SMT-8-PS-K-LED-24-B
			Plug M8x1, 3-pin	0.3	175 484	SMT-8-PS-S-LED-24-B
N/C contact						
	Insertable in the slot from above, flush with cylinder profile	PNP	Cable, 3-wire	7.5	543 873	SMT-8M-PO-24V-K7,5-OE

Semi-rotary drives DRQD/DRQD-B, twin pistons

FESTO

Accessories

Ordering data – Proximity sensors for T-slot, magnetic reed					Technical data → Internet: sme	
	Type of mounting	Switch output	Electrical connection	Cable length [m]	Part No.	Type
N/O contact						
	Insertable in the slot from above, flush with cylinder profile	Contacting	Cable, 3-wire	2.5	543 862	SME-8M-DS-24V-K-2,5-OE
				5.0	543 863	SME-8M-DS-24V-K-5,0-OE
			Cable, 3-wire	2.5	543 872	SME-8M-ZS-24V-K-2,5-OE
			Plug M8x1, 3-pin	0.3	543 861	SME-8M-DS-24V-K-0,3-M8D
	Insertable in the slot lengthwise, flush with the cylinder profile	Contacting	Cable, 3-wire	2.5	150 855	SME-8-K-LED-24
			Plug M8x1, 3-pin	0.3	150 857	SME-8-S-LED-24
N/C contact						
	Insertable in the slot lengthwise, flush with the cylinder profile	Contacting	Cable, 3-wire	7.5	160 251	SME-8-O-K-LED-24

Ordering data – Connecting cables				Technical data → Internet: nebu	
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 333	NEBU-M8G3-K-2.5-LE3
			5	541 334	NEBU-M8G3-K-5-LE3
	Straight socket, M12x1, 5-pin	Cable, open end, 3-wire	2.5	541 363	NEBU-M12G5-K-2.5-LE3
			5	541 364	NEBU-M12G5-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 338	NEBU-M8W3-K-2.5-LE3
			5	541 341	NEBU-M8W3-K-5-LE3
	Angled socket, M12x1, 5-pin	Cable, open end, 3-wire	2.5	541 367	NEBU-M12W5-K-2.5-LE3
			5	541 370	NEBU-M12W5-K-5-LE3

Ordering data – Slot cover for T-slot					
	Assembly	Length [m]	Part No.	Type	
	Insertable from above	2x 0.5	151 680	ABP-5-S	

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