Stopper cylinders STA/STAF

FESTO



Stopper cylinders STA/STAF



At a glance

- Single-acting or double-acting
- Versions
 - Trunnion
 - Roller
 - Toggle lever
- Direct mounting of solenoid valves on flange plate
- Fast and simple set-up of conveyor
- Workpiece carriers, pallets and packages weighing up to 150 kg can be safely stopped
- Gentle stopping without impact vibrations or noise with toggle lever version
- Simple actuation via valve terminal (e.g. in combination with other cylinders at an assembly station)
- Flanged solenoid valve permits fast actuation even over long distances and with individual stopper cylinders
- Space-saving sensing via integrated proximity sensors

Trunnion version



Roller version

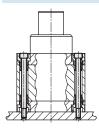


Toggle lever version

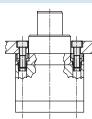


Mounting options

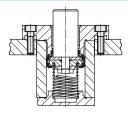
Through-hole mounting



Direct mounting

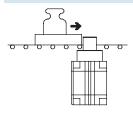


Flange mounting

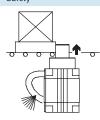


Application options and versions

For heavy masses



Safety



By means of spring return of the piston rod in the event of pressure failure.

Highly effective, low noise level

Toggle lever version with integrated shock absorber facilitates precise and gentle stopping of the workpiece carrier.

Stopper cylinders STA/STAF Product range overview



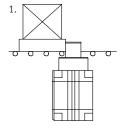
3

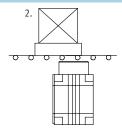
Function	Version	Туре	Piston \varnothing	Stroke	Type of mou	nting	Cushioning	Position	→ Page/Internet
					direct	via flange		sensing	
			[mm]	[mm]			P	A	
Single-	Trunnion versi								
or double-	9	STAP-A STAFP-A	20	15	•	_	•	•	4
acting			32	20	•	•	-	•	
			50	30	•	•	-	•	
	Roller version		<u>'</u>		1	1		1	
		STAP-A-R STAFP-A-R	20	15	•	_	-	•	10
			32	20	•	•	-	•	
			50	30	•	•	•	•	
			80	30, 40	-	•	•	•	
	Toggle lever ve	ersion	<u>'</u>		1	1		1	
		STAFP-A-K	32	20	-	•	•	•	20

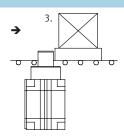
Stopper cylinders STA/STAF, trunnion Functional sequence and type codes



Functional sequence

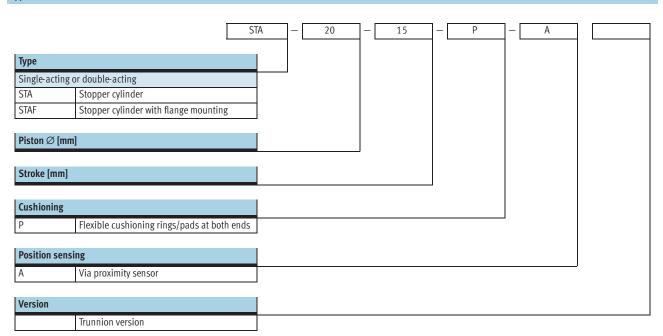






- 1. Sudden braking of the workpiece carrier via the piston rod.
- The workpiece carrier is released by activating the cylinder. The control system must hold the piston down until the workpiece carrier has passed the stopper cylinder.
- 3. The piston rod then advances by means of spring force or compressed air. The next workpiece carrier can then be stopped.

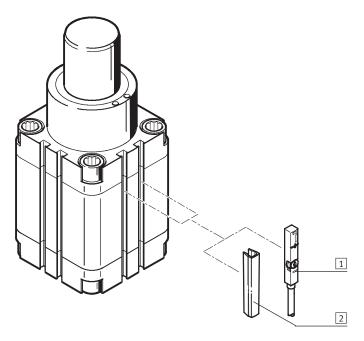
Type codes



Stopper cylinders STA/STAF, trunnion Peripherals overview



5



Acce	Accessories					
		Brief description	→ Page/Internet			
1	Proximity sensor SME/SMT-8	Can be integrated in the cylinder profile barrel	28			
2	Slot cover ABP	For protecting against ingress of dirt	28			

Stopper cylinders STA/STAF, trunnion Technical data



Function





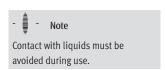
Diameter 20 ... 50 mm



Stroke length 15 ... 30 mm



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General technical data							
Piston Ø		20	32	50			
Pneumatic connection	STA	M5	G1/8	G ¹ /8			
	STAF	-	M5	G1/8			
Stroke	[mm]	15	20	30			
Piston rod \varnothing	[mm]	12	20	32			
Operating pressure	[bar]	10	•	<u>.</u>			
Operating medium		Filtered compressed air, lubricated or unlubricated					
Constructional design		Piston cylinder with spring return					
Cushioning		Flexible cushioning rings/pads at both ends					
Position sensing		Via proximity sensor					
Type of mounting		Via through-holes					
			Via female thread				
Mounting position		Any					
Mode of operation		Single-acting or double-acting					
Protection against rotation		None					
Ambient temperature ¹⁾	[°C]	+5 +60					

- 1) Note operating range of proximity sensors.

Forces [N]						
Piston ∅	20	32	50			
Permissible impact force on the advanced piston rod	260	1,000	2,900			
Spring force	13 18	20 42	43 60			

Under "impact force" we understand the maximum of a force-time curve $% \left(1\right) =\left(1\right) \left(1\right$ during impact/braking of the moveable mass. It is effective vertical to the movement axis of the piston rod. If one regards the elastic components as linear springs, the permitted impact energy can be calculated from the

permitted impact force. This serves for selecting the correct stopper.

The stopper must not switch under this force. Depending on the mass to be stopped, it may be advisable to provide an elastic buffer in order to cushion the impact, to reduce noise and to optimize the impact energy.



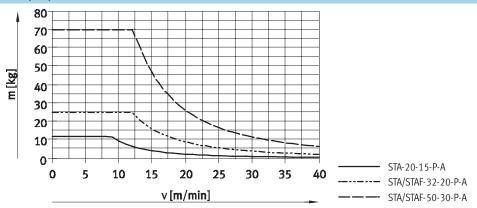
→ = Direction of impact force

Stopper cylinders STA/STAF, trunnion Technical data

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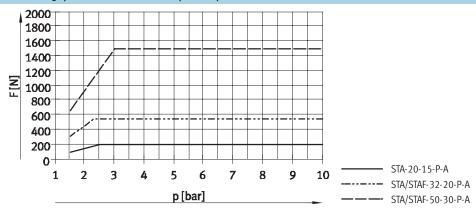
Permissible mass m as a function of the conveyor speed v

The values in the graph opposite are based on the assumption that the workpiece carrier is fitted with a flexible buffer with a deformation path of 1 mm.



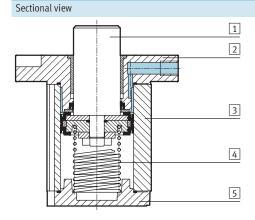
Permissible transverse force F₀ during the switching operation as a function of the pressure p

Under "permitted lateral force" during the switching procedure, we understand the force which still exists vertical to the direction of movement of the piston rod after the impact or braking procedure, e.g. by bands still running or the slope power take-off force of an inclined rolling surface. The force is effective statically. The stopper must not switch under this force. In order that the functioning of the cylinder can be guaranteed, a certain minimum pressure must be applied.





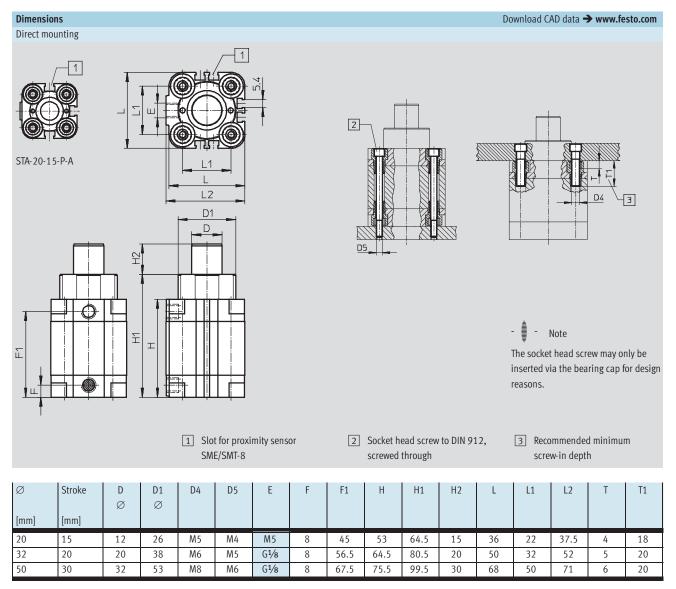
Materials



Stop	Stopper cylinder					
1	Piston rod	Stainless steel				
2	Flange	Die-cast aluminium				
3	Cylinder barrel	Anodised aluminium				
4	Springs	Spring steel				
5	End cap	Anodised aluminium				
-	Seals	Polyurethane				
-	Note on materials	Free of copper, PTFE and silicone				

Stopper cylinders STA/STAF, trunnion Technical data

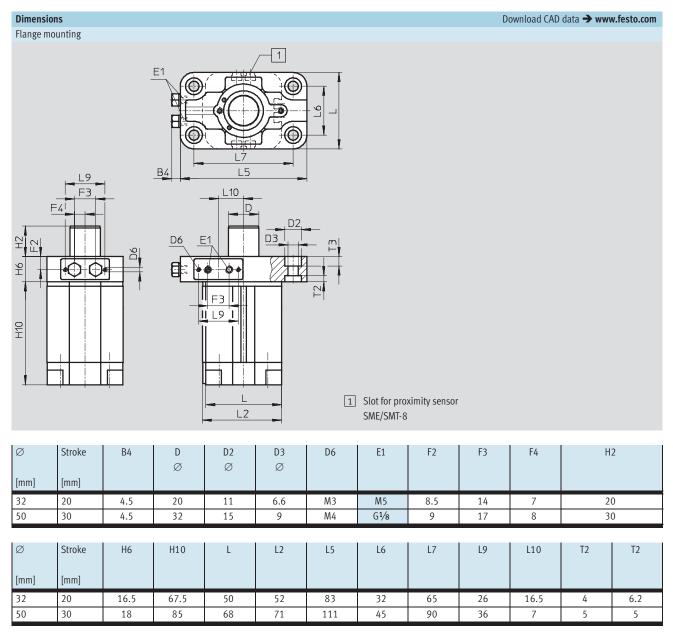




 $^{\|\}cdot\|$ Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.

Stopper cylinders STA/STAF, trunnionTechnical data





 $^{\|\}cdot\|$ Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.

Ordering data							
Piston \varnothing	Stroke	Direct mounting		Flange mounting			
[mm]	[mm]	Part No. Type		Part No. Type			
20	15	164 887 STA-20-15-P-A					
32	20	164 888 STA-32-20-P-A		164 890 STAF-32-20-P-A			
50	30	164 889 STA-50-30-P-A		164 891 STAF-50-30-P-A			

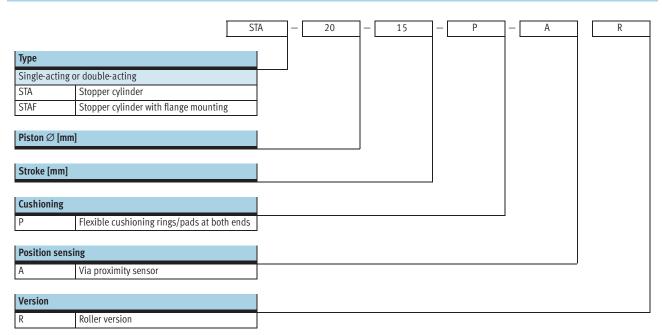
Stopper cylinders STA/STAF, roller Functional sequence and type codes



Functional sequence

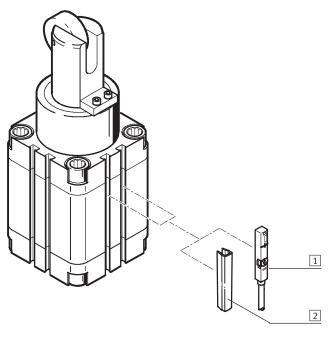
- 1. Sudden braking of the workpiece carrier via the piston rod.
- The workpiece carrier is released by activating the cylinder.
- 3. The piston rod then advances by means of spring force or compressed air until the roller makes contact with the workpiece carrier. The workpiece carrier continues to move forward.
- 4. After the workpiece carrier has passed, the piston rod advances to the end position. The next workpiece carrier can then be stopped.

Type codes



Stopper cylinders STA/STAF, roller Peripherals overview

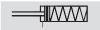




Acce	Accessories					
		Brief description	→ Page/Internet			
1	Proximity sensor SME/SMT-8	Can be integrated in the cylinder profile barrel	28			
2	Slot cover ABP	For protecting against ingress of dirt	28			

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Function





Diameter 20 ... 80 mm



Stroke length 15 ... 40 mm



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Note Contact with liquids must be avoided during use.



General technical data							
Piston Ø		20	32	50	80		
Pneumatic connection	STA	M5	G½8	G½8	-		
	STAF	-	M5	G1/8	G ¹ /8		
Stroke	[mm]	15	20	30	30/40		
Piston rod Ø	[mm]	12	20	32	50		
Operating pressure	[bar]	10	<u>.</u>		·		
Operating medium		Filtered compressed air, lubricated or unlubricated					
Constructional design		Piston cylinder with spring return					
Cushioning		Flexible cushioning rings/pads at both ends					
Position sensing		Via proximity sensor					
Type of mounting		Via through-holes					
			Via female thread				
Mounting position		Any					
Mode of operation		Single-acting or double-acting					
Protection against rotation		Flat-sided piston rod					
Ambient temperature ¹⁾	[°C]	+5 +60					

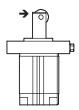
¹⁾ Note operating range of proximity sensors. $\|\cdot\| \cdot \text{ Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.}$

Forces [N]					
Piston Ø	20	32	50	80	
Stroke	15	20	30	30	40
Permissible impact force on the advanced piston rod	170	830	2,300	14,600	13,300
Spring force	13 18	20 42	43 60	79 115	101 170

Under "impact force" we understand the maximum of a force-time curve $% \left(1\right) =\left(1\right) \left(1\right$ during impact/braking of the moveable mass. It is effective vertical to the movement axis of the piston rod. If one regards the elastic components as linear springs, the permitted impact energy can be calculated from the

permitted impact force. This serves for selecting the correct stopper. The stopper must not switch under

this force. Depending on the mass to be stopped, it may be advisable to provide an elastic buffer in order to cushion the impact, to reduce noise and to optimize the impact energy.

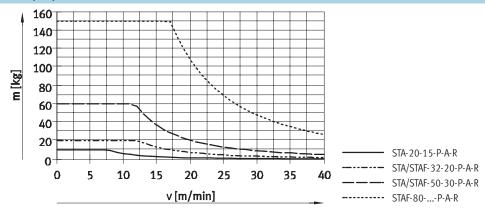


→ = Direction of impact force

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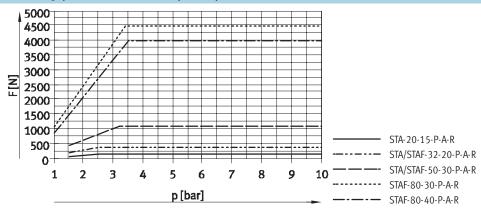
Permissible mass m as a function of the conveyor speed v

The values in the graph opposite are based on the assumption that the workpiece carrier is fitted with a flexible buffer with a deformation path of 1 mm.



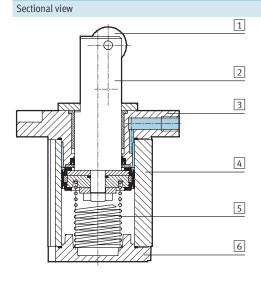
Permissible transverse force FQ during the switching operation as a function of the pressure p

Under "permitted lateral force" during the switching procedure, we understand the force which still exists vertical to the direction of movement of the piston rod after the impact or braking procedure, e.g. by bands still running or the slope power take-off force of an inclined rolling surface. The force is effective statically. The stopper must not switch under this force. In order that the functioning of the cylinder can be guaranteed, a certain minimum pressure must be applied.



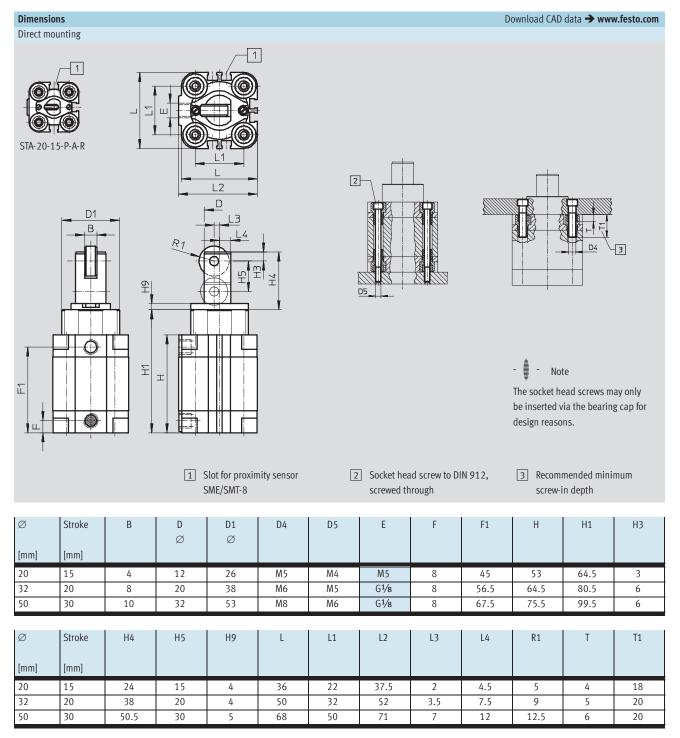


Materials



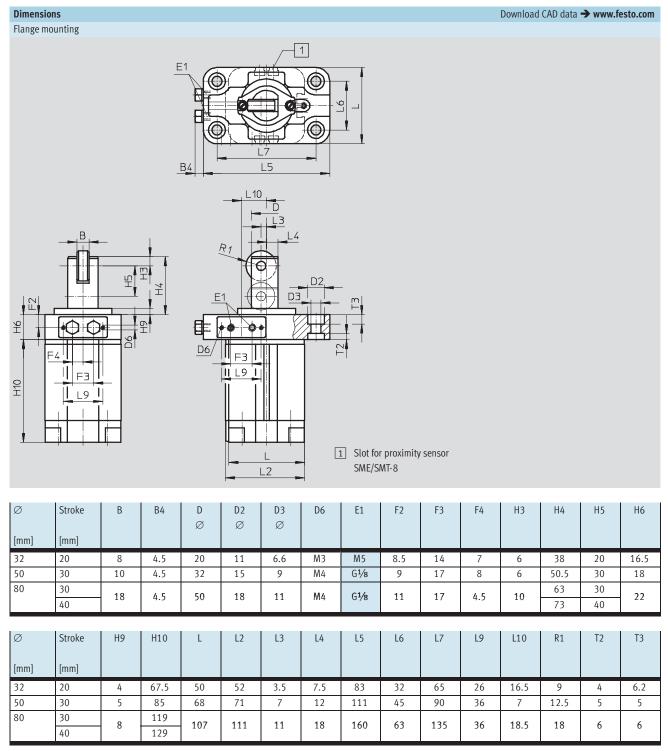
Stopper cy	Stopper cylinder					
1 Rolle	r	Steel				
2 Pisto	n rod	Stainless steel				
3 Flang	ge	Die-cast aluminium				
4 Cylin	der barrel	Anodised aluminium				
5 Sprir	igs	Spring steel				
6 End	сар	Anodised aluminium				
- Seals	5	Polyurethane				
Note	on materials	Free of copper, PTFE and silicone				





 $^{\|\}cdot\|$ Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.





 $^{\|\}cdot\|$ Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.

Ordering data							
Piston Ø	Stroke	Direct mounting		Flange mounting			
[mm]	[mm]	Part No. Type		Part No. Type			
20	15	164 883 STA-20-15-P-A-R					
32	20	164 884 STA-32-20-P-A-R		164 892 STAF-32-20-P-A-R			
50	30	164 885 STA-50-30-P-A-R		164 893 STAF-50-30-P-A-R			
80	30			164 886 STAF-80-30-P-A-R			
80	40			164 894 STAF-80-40-P-A-R			

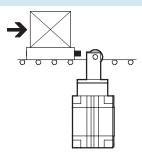
Stopper cylinders STA/STAF

FESTO Technical data

Selection aid

Stopping a workpiece carrier

The stopper cylinder is used to brake an individual workpiece carrier.



Example

Given:

Friction value $\mu = 0.1$

Delivery speed v = 10 m/min

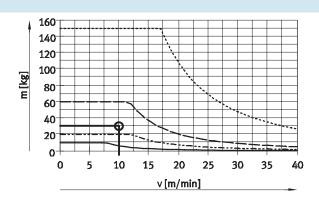
Workpiece carrier with workpiece m = 30 kg

Operating pressure p = 6 bar

Choice: Stopper cylinder STA...-50-...-R

1. Checking the permissible mass

The maximum permissible mass at a delivery speed of 10 m/min is 60 kg. This means that the total mass of the workpiece carrier and workpiece of 30 kg is permissible.



STA-20-15-P-A-R ---- STA/STAF-32-20-P-A-R ---- STA/STAF-50-30-P-A-R ----- STA/STAF-80-...-P-A-R

2. Checking the permissible transverse force during the switching operation

Transverse force F_Q = friction force

 $\mathsf{F}_{\mathsf{Friction}}$

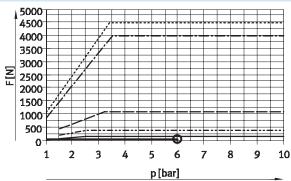
 $\mathsf{F}_{\mathsf{Friction}}$ $= \mu x m x g$

 $= 0.1 \times 30 \text{ kg} \times 9.81 \text{ m/s}^2$

= approx. 30 N

The maximum permissible transverse force at an operating pressure of 6 bar is 1,100 N.

This means that the transverse force of 30 N is permissible.



STA-20-15-P-A-R STA/STAF-32-20-P-A-R STA/STAF-50-30-P-A-R STA/STAF-80-30-P-A-R —-- STA/STAF-80-40-P-A-R

Stopper cylinders STA/STAF

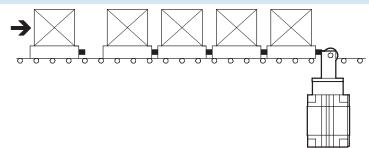
Technical data



Selection aid

Stopping or separating several workpiece carriers

The stopper cylinder is used to separate workpiece carriers. Further workpiece carriers accumulate behind carriers already at the stopper cylinder. It is vital that a buffer is mounted between the workpiece carriers (e.g. elastomer elements).



Example

Given:

Friction value $\mu = 0.1$

Delivery speed v = 10 m/min

Workpiece carrier with workpiece m = 30 kg

Operating pressure p = 6 bar

Maximum number of workpiece carriers accumulating simultaneously n_{Group} = 1

Maximum number of all queued workpiece carriers n_{Queue} = 5

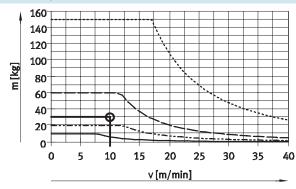
Maximum number of all advancing workpiece carriers n_{Queue-1} = 4

Spring travel of the workpiece carrier buffer $s_F = 1 \text{ mm}$

Choice: Stopper cylinder STA...-50-...-R

1. Checking the permissible mass of the first workpiece carrier

The maximum permissible mass at a delivery speed of 10 m/min is 60 kg. This means that the total mass of the workpiece carrier and workpiece of 30 kg is permissible.



STA-20-15-P-A-R
STA/STAF-32-20-P-A-R
STA/STAF-50-30-P-A-R
STA/STAF-80-...-P-A-R

2a. Calculation of the maximum permissible impact force when workpiece carriers accumulate behind a carrier at the stopper cylinder

With the STA...-50, the maximum permissible impact force is 2,300 N. This means that with a total force of 1,000 N, the number of workpiece carriers is permissible.

Impact force calculation:

$$F_{Impact} = \frac{(n_{Group} \times m) \times v^2}{s_F} = \frac{(1 \times 30 kg) \times (10 m/60 s)^2}{0.001 m} = ca.850 N$$

Friction force

$$F_{Friction} = \mu \times (n_{Queue} \times m) \times g = 0.1 \times (5 \times 30 kg) \times 9.81 m/s^2 = ca.150 N$$

Max. total force:

$$F_{Total \, force} = F_{Impact} + F_{Friction} = 850N + 150N = 1000N$$

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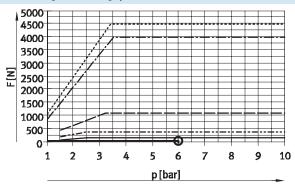
Selection aid

2b. Checking the permissible transverse force during the switching operation

Transverse force $F_Q =$ friction force F_{Friction} $F_{Friction} = 150 \text{ N}$

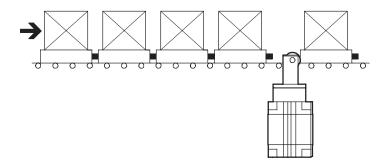
The maximum permissible transverse force at an operating pressure of 6 bar is 1,100 N.

This means that the transverse force of 150 N is permissible.

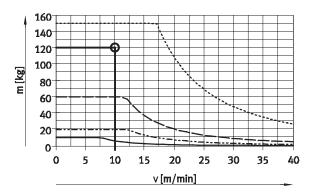


STA-20-15-P-A-R STA/STAF-32-20-P-A-R STA/STAF-50-30-P-A-R ----- STA/STAF-80-30-P-A-R --- STA/STAF-80-40-P-A-R

3. Separating and advancing the workpiece carriers



The maximum permissible mass with the STA...-50-...-R at a delivery speed of 10 m/min is 60 kg. Since the total mass of the four workpiece carriers advancing on the stopper cylinder is 120 kg, the next largest stopper cylinder must be selected for separating.



- STA-20-15-P-A-R ----- STA/STAF-32-20-P-A-R ---- STA/STAF-50-30-P-A-R ------ STA/STAF-80-...-P-A-R

Max. total mass:

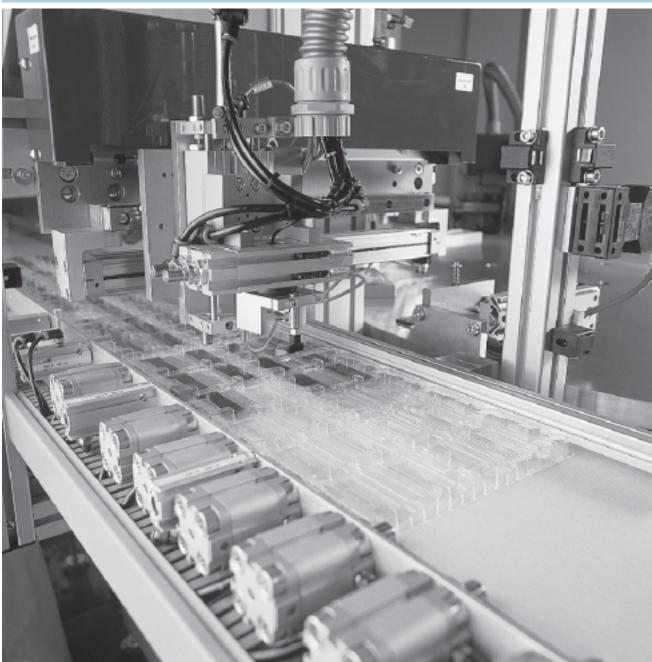
 $m_{Total \, force} = n_{Queue-1} \times m = 4 \times 30 kg = 120 kg$

Result

The stopper cylinder STA...-80-...-R must be selected for separating five workpiece carriers.



Application example

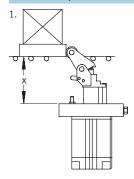


Stopper cylinders STAF, toggle lever

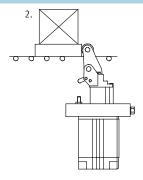
Functional sequence

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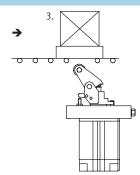
Functional sequence



1. Gentle stopping of heavy masses via a hydraulic shock absorber in the piston rod.



2. The toggle lever is locked into the workpiece carrier cannot be pushed back by the shock absorber.



3. The workpiece carrier is released

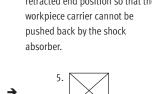
the toggle lever is released

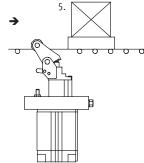
simultaneously.

by means of compressed air, and

X = 62.8 ... 63.4 mm

retracted end position so that the





4. The piston is advanced by means 5. The toggle lever is raised by of spring force or compressed air. means of spring force and stops The toggle lever tips back which the next workpiece carrier. prevents the workpiece carrier from being pushed up.



Protection against rotation: The guide rod always aligns the toggle lever precisely to the approaching workpiece carrier.



Integrated shock absorber: absorbs impact energy and stops the workpiece carrier gently, and with low noise levels.

The impact energy can be adjusted using the regulating screw in the toggle lever.



Detenting roller lever: the workpiece carrier cannot be pushed back by the shock absorber.



Locking mechanism for disabling the stopper function: the workpiece carrier is able to pass the holding point without activating the cylinder.



Note

Trunnion or roller type stopper cylinders can be mounted in any position.

Stopper cylinders with toggle lever must be mounted in the vertical, upright position.

Stopper cylinders STAF, toggle lever



Key features

Mounting options for solenoid valves and valve functions

An MEH, MEBH, MOEH or MOEBH solenoid valve can be mounted on the stopper cylinder for quick, direct actuation of the cylinder. This type of

actuation is only possible for stopper cylinders with flange mounting. The valve must be mounted on the flange

plate via a valve sub-base ZVA. The position of the piston rod when the solenoid valve is in the normal

position depends upon the valve type and the position of the valve on the cylinder.

Application	Piston rod in initial position	Required solenoid valve	Type of mounting for the solenoid valve with sub-base ZVA
	Single-acting		
	12 2 1 V3	Normally advanced 173 125 MEH-3/2-5,0-B 172 999 MEBH-3/2-5,0-B	
	12 Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z	Normally retracted 173 429 MOEH-3/2-5,0-B 173 002 MOEBH-3/2-5,0-B	
	Double estina		
	Double-acting	Marmally advanced	
	14 2 2 4 2 4 5 V V 3 9	Normally advanced 173 128 MEH-5/2-5,0-B 173 005 MEBH-5/2-5,0-B	
	14 2 W 3 S 4 5 V 3 S	Normally retracted 173 128 MEH-5/2-5,0-B 173 005 MEBH-5/2-5,0-B	



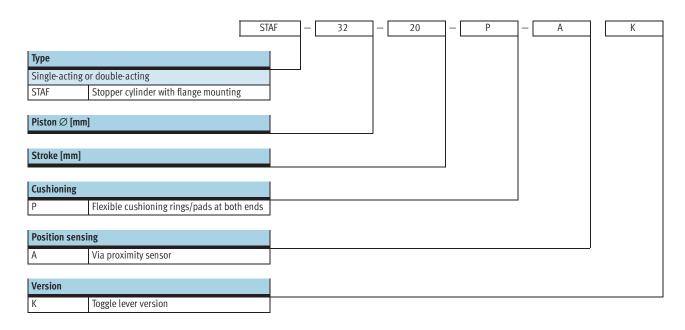
- Note

Cylinders are always supplied singleacting with spring. If a double-acting stopper cylinder is required, the filter nipple in the exhaust port must be removed. The exhaust port is then used as a supply port.

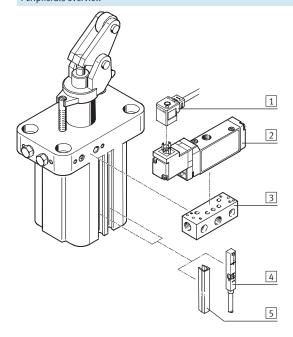
Solenoid valves MEH, MEBH
→ Internet: solenoid valve

Stopper cylinders STAF, toggle lever Type codes and peripherals overview





Peripherals overview



Acce	Accessories						
		Brief description	→ Page/Internet				
1	Plug socket with cable KMEB	-	kmeb				
2	3/2-way valve MEBH	For fast and direct actuation of the stopper cylinder	mebh				
3	Sub-base ZVA	For stopper cylinder with flange	26				
4	Proximity sensor SME/SMT-8	Can be integrated in the cylinder profile barrel	28				
5	Slot cover ABP	For protecting against ingress of dirt	28				

Stopper cylinders STAF, toggle lever Technical data

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Function





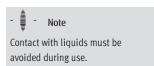
Diameter 32 mm



Stroke length 20 mm



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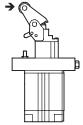


General technical data		
Pneumatic connection		M5
Stroke	[mm]	20
Piston rod \varnothing	[mm]	20
Operating pressure	[bar]	10
Operating medium		Filtered compressed air, lubricated or unlubricated
Constructional design		Piston cylinder with spring return
Cushioning		Flexible cushioning rings/pads at both ends
Position sensing		Via proximity sensor
Type of mounting		Via through-holes
Mounting position		Vertical, upright
Mode of operation		Single-acting or double-acting
Protection against rotation		Guide rod
Ambient temperature ¹⁾	[°C]	+5 +60

- 1) Note operating range of proximity sensors. . $\|\cdot\|$ Note: This product conforms to ISO 1179-1 and to ISO 228-1

Forces [N]					
Permissible impact force on the rollers	480				
of the toggle lever when the piston rod					
is advanced and the toggle lever is					
pushed into its end position					
Spring force	20 42				

Impact force is the basis for the calculation of permissible impact energy. Depending upon the type of load to be stopped, it is advisable to use a flexible buffer to cushion the impact, reduce noise levels and to optimise impact energy.



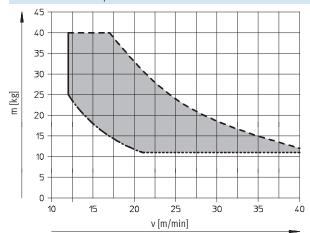
→ = Direction of impact force

Stopper cylinders STAF, toggle lever Technical data



Permissible mass m as a function of the conveyor speed v

With a friction value of $\mu = 0.1$

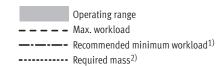


Note

The required mass for reliable pushing into the end position is dependent on the friction pairing between the conveyor and conveyed goods, other friction values on request.

Cushioning time is increased for partial loads.

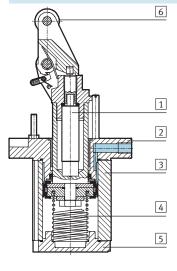
Energy values valid for ambient temperature T = 20 °C.



- 1) For optimum operation of the damper
- Required mass for reliable pushing of the toggle lever into the end position with this friction value

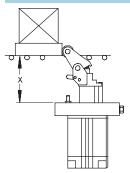
Materials

Sectional view



Stop	Stopper cylinder						
1	Piston rod	Stainless steel					
2	Flange	Die-cast aluminium					
3	Cylinder barrel	Anodised aluminium					
4	Springs	Spring steel					
5	End cap	Anodised aluminium					
6	Roller	Polyacetate					
-	Seals	Polyurethane					
-	Note on materials	Free of copper, PTFE and silicone					

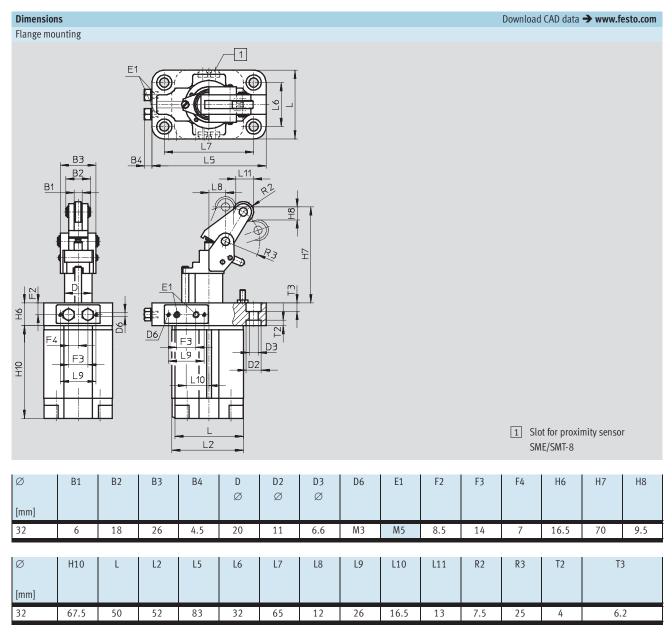
Minimum distance to the conveyor



X = 62.8 ... 63.4 mm

Stopper cylinders STAF, toggle lever Technical data





Note: This product conforms to ISO 1179-1 and to ISO 228-1

Ordering data	Ordering data						
Piston \varnothing	Stroke	Flange mounting					
[mm]	[mm]	Part No. Type					
32	20	164 880 STAF-32-20-P-A-K					

Stopper cylinders STA/STAF Accessories

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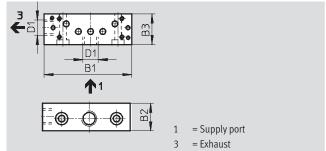
Sub-base ZVA

for stopper cylinder with flange

Material:

Wrought aluminium alloy Free of copper, PTFE and silicone





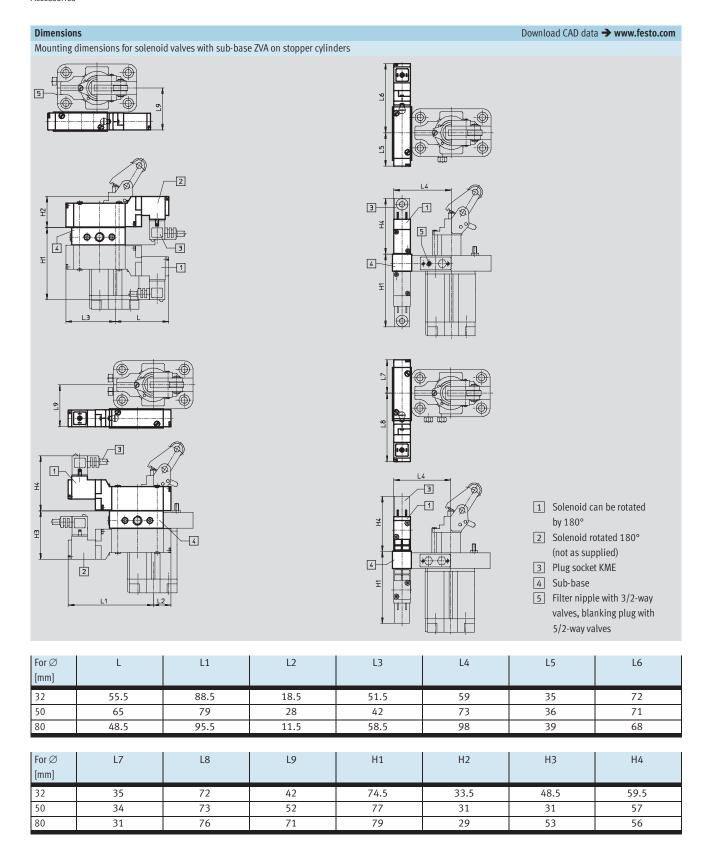
Dimensions and ordering data									
For \varnothing	B1	B2	В3	D1	CRC ¹⁾	Weight	Part No. Type		
[mm]						[g]			
32	56	18	20	G1/8	2	50	164 896 ZVA-1		
50/80	57.5	18	20	G1/8	2	52	164 897 ZVA-2		

¹⁾ Corrosion resistance class 2 as per Festo standard 940 070
Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Stopper cylinders STA/STAF

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Accessories



Stopper cylinders STA/STAF Accessories



Ordering data	- Proximity sensors for T-slot, magneto-re	esistive				Technical data → Internet: smt
	Type of mounting	Switch	Electrical connection	Cable length	Part No.	Туре
		output		[m]		
N/O contact						
~/	Insertable in the slot from above, flush	PNP	Cable, 3-wire	2.5	543 867	SMT-8M-PS-24V-K-2,5-0E
	with cylinder profile		Plug M8x1, 3-pin	0.3	543 866	SMT-8M-PS-24V-K-0,3-M8D
			Plug M12x1, 3-pin	0.3	543 869	SMT-8M-PS-24V-K-0,3-M12
		NPN	Cable, 3-wire	2.5	543 870	SMT-8M-NS-24V-K-2,5-0E
			Plug M8x1, 3-pin	0.3	543 871	SMT-8M-NS-24V-K-0,3-M8D
NA CONTRACTOR OF THE PARTY OF T	Insertable in the slot lengthwise, flush	PNP	Cable, 3-wire	2.5	175 436	SMT-8-PS-K-LED-24-B
	with the cylinder profile		Plug M8x1, 3-pin	0.3	175 484	SMT-8-PS-S-LED-24-B
				•	•	
N/C contact						
CT ST	Insertable in the slot from above, flush with cylinder profile	PNP	Cable, 3-wire	7.5	543 873	SMT-8M-PO-24V-K7,5-OE

Ordering data	- Proximity sensors for T-slot, magnetic	reed				Technical data → Internet: sme
	Type of mounting	Switch	Electrical connection	Cable length	Part No.	Туре
		output		[m]		
N/O contact						
_/	Insertable in the slot from above, flush	Contacting	Cable, 3-wire	2.5	543 862	SME-8M-DS-24V-K-2,5-0E
	with cylinder profile			5.0	543 863	SME-8M-DS-24V-K-5,0-OE
			Cable, 2-wire	2.5	543 872	SME-8M-ZS-24V-K-2,5-0E
			Plug M8x1, 3-pin	0.3	543 861	SME-8M-DS-24V-K-0,3-M8D
NS .	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	2.5	150 855	SME-8-K-LED-24
	with the cylinder profile		Plug M8x1, 3-pin	0.3	150 857	SME-8-S-LED-24
N/C sontast						
N/C contact	I	Ta	Tall	T = -		
	Insertable in the slot lengthwise, flush with the cylinder profile	Contacting	Cable, 3-wire	7.5	160 251	SME-8-O-K-LED-24

Ordering data	- Connecting cables	Technical data → Internet: nebu			
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 333	NEBU-M8G3-K-2.5-LE3
6			5	541 334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 338	NEBU-M8W3-K-2.5-LE3
			5	541 341	NEBU-M8W3-K-5-LE3

Ordering dat	Ordering data – Slot cover for T-slot							
	Assembly	Length	Part No.	Туре				
		[m]						
	Insertable from	2x 0.5	151 680	ABP-5-S				
A	above							

Product Range and Company Overview

A Complete Suite of Automation Services

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Custom Automation Components Complete custom engineered solutions



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Complete Systems Shipment, stocking and storage services

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Pneumatics Pneumatic linear and rotary actuators, valves, and air supply



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To meet this commitment, we strive to ensure a consistent, integrated, and systematic approach to management that will meet or exceed the requirements of the ISO 9001 standard for Quality Management and the ISO 14001 standard for Environmental Management.



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