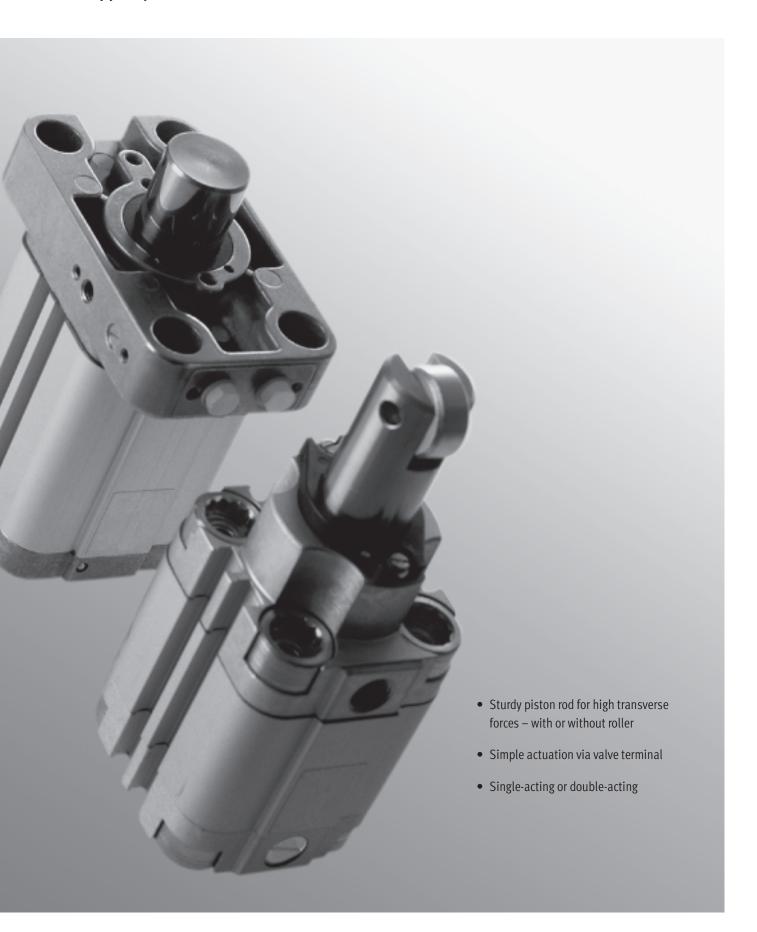
Stopper cylinders STA/STAF





Stopper cylinders STA/STAF

FESTO

At a glance

- Single-acting or double-acting
- Versions
 - Trunnion
 - Roller
 - Toggle lever
- Direct mounting of solenoid valves on flange plate
- Fast and simple set-up of conveyor
- Workpiece carriers, pallets and packages weighing up to 150 kg can be safely stopped
- Gentle stopping without impact vibrations or noise with toggle lever version
- Simple actuation via valve terminal (e.g. in combination with other $% \left\{ 1\right\} =\left\{ 1\right\} =\left\{$ cylinders at an assembly station)
- Flanged solenoid valve permits fast actuation even over long distances and with individual stopper cylinders
- Space-saving sensing via integrated proximity sensors

Trunnion version



Roller version

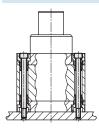


Toggle lever version

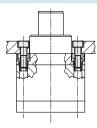


Mounting options

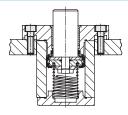
Through-hole mounting



Direct mounting



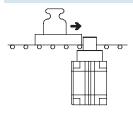
Flange mounting



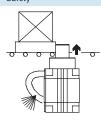
Application options and versions

For heavy masses

2



Safety



By means of spring return of the piston rod in the event of pressure failure.

Highly effective, low noise level

Toggle lever version with integrated shock absorber facilitates precise and gentle stopping of the workpiece carrier.

Stopper cylinders STA/STAF Product range overview

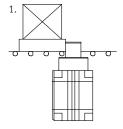


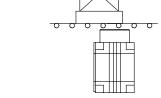
Function	Version	Туре	Piston \varnothing	Stroke	Type of mour	nting	Cushioning	Position	→ Page/Internet
					direct	via flange		sensing	
			[mm]	[mm]			P	Α	
Single-	Basic version	_							
or double-	A	Trunnion version	20	15	-	-	-	-	4
acting			32	20	-	•	-	-	
			50	30	-	•	•	-	
				•	•	•	•	•	
		Roller version	20	15		-			10
			32	20					
			50	30	-	-	•		
			80	30, 40	-				
		1	100	1	+	_	1	1	Las
		Toggle lever version	32	20	-	•	•	•	20
			50	30	-	•	-	•	
			80	40	-	•	-	-	

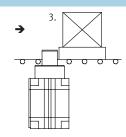
Stopper cylinders STA/STAF, trunnion Functional sequence and type codes



Functional sequence

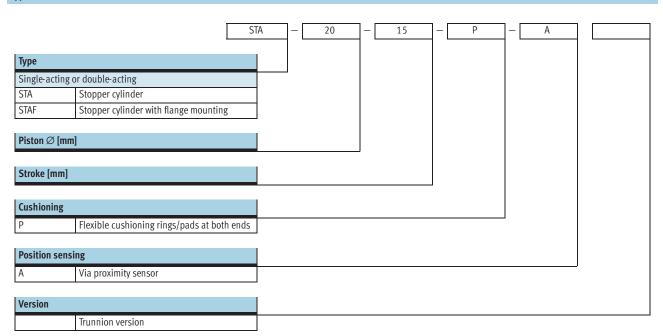






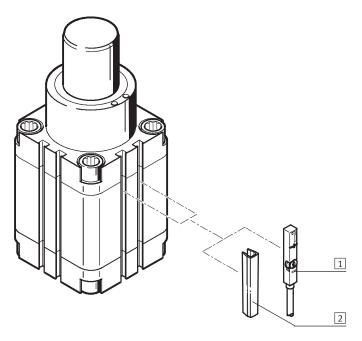
- 1. Sudden braking of the workpiece carrier via the piston rod.
- The workpiece carrier is released by activating the cylinder. The control system must hold the piston down until the workpiece carrier has passed the stopper cylinder.
- 3. The piston rod then advances by means of spring force or compressed air. The next workpiece carrier can then be stopped.

Type codes



Stopper cylinders STA/STAF, trunnion Peripherals overview





Acce	Accessories					
		Brief description	→ Page/Internet			
1	Proximity sensor SME/SMT-8	Can be integrated in the cylinder profile barrel	30			
2	Slot cover ABP	For protecting against ingress of dirt	30			

Stopper cylinders STA/STAF, trunnion Technical data



Function





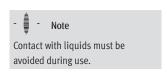
Diameter 20 ... 50 mm



Stroke length 15 ... 30 mm



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General technical data						
$Piston\varnothing$		20	32	50		
Pneumatic connection	STA	M5	G½	G ¹ / ₈		
	STAF	-	M5	G ¹ / ₈		
Stroke	[mm]	15	20	30		
Piston rod Ø	[mm]	12	20	32		
Operating pressure	[bar]	10				
Operating medium		Filtered compressed air, lubricated or unlubricated				
Constructional design		Piston cylinder with spring return				
Cushioning		Flexible cushioning rings/pads at both ends				
Position sensing		Via proximity sensor				
Type of mounting		Via through-holes				
		Via female thread				
Mounting position		Any				
Mode of operation		Single-acting or double-acting				
Protection against rotation		None				
Ambient temperature ¹⁾	[°C]	+5 +60				

¹⁾ Note operating range of proximity sensors. $\|\cdot\| \cdot \text{ Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.}$

Forces [N]					
Piston ∅	20	32	50		
Permissible impact force on the advanced piston rod	260	1,000	2,900		
Spring force	13 18	20 42	47 64		

Impact force is the basis for the $calculation\ of\ permissible\ impact$ energy. Depending upon the type of load to be stopped, it is advisable to use a flexible buffer to cushion the impact, reduce noise levels and to optimise impact energy.



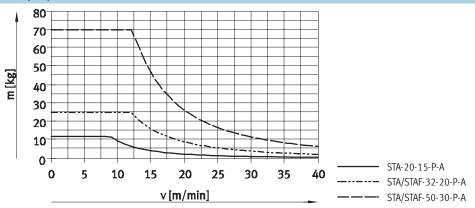
→ = Direction of impact force

Stopper cylinders STA/STAF, trunnion Technical data

FESTO

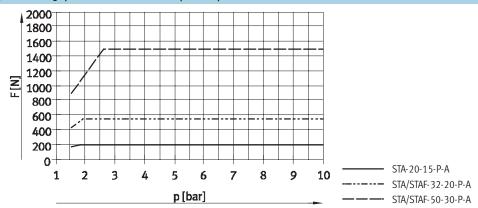
Permissible mass m as a function of the conveyor speed v

The values in the graph opposite are based on the assumption that the $\,$ workpiece carrier is fitted with a flexible buffer with a deformation path of 1 mm.



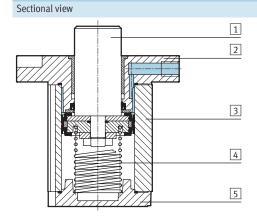
Permissible transverse force F_O during the switching operation as a function of the pressure p

The applied load causes a transverse force to act on the piston rod. To ensure the function of the cylinder, a certain minimum pressure must be applied.





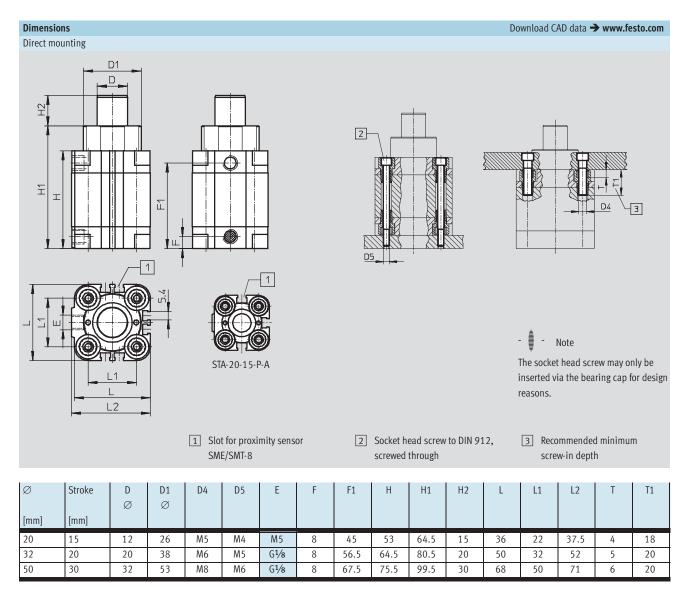
Selection aid → 16 Materials



Stop	Stopper cylinder					
1	Piston rod	Stainless steel				
2	Flange	Die-cast aluminium				
3	Cylinder barrel	Anodised aluminium				
4	Springs	Spring steel				
5	End cap	Anodised aluminium				
-	Seals	Polyurethane				
-	Note on materials	Free of copper, PTFE and silicone				

Stopper cylinders STA/STAF, trunnion Technical data

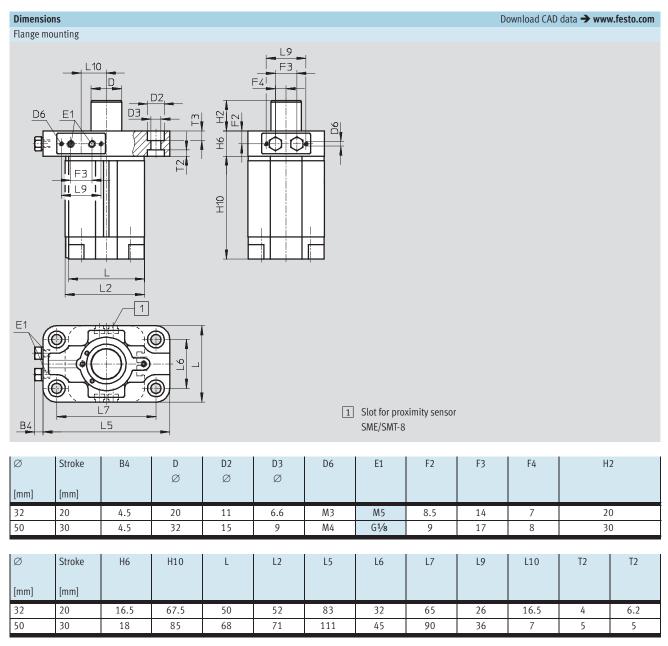




 $^{\|\}cdot\|$ Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.

Stopper cylinders STA/STAF, trunnionTechnical data





 $[\]parallel$. Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.

Ordering data				
Piston \varnothing	Stroke	Direct mounting		Flange mounting
[mm]	[mm]	Part No. Type		Part No. Type
20	15	164 887 STA-20-15-P-A		
32	20	164 888 STA-32-20-P-A	1	164 890 STAF-32-20-P-A
	1	164 889 STA-50-30-P-A	1	164 891 STAF-50-30-P-A

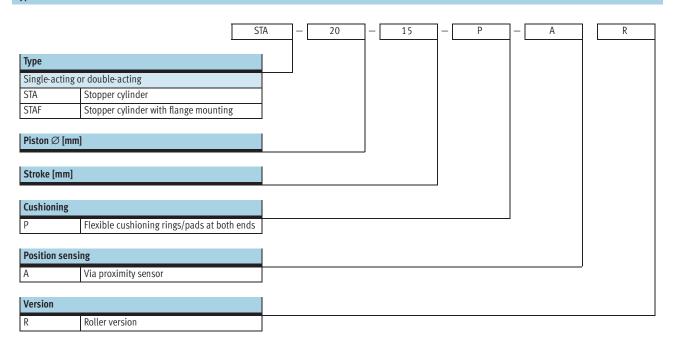
Stopper cylinders STA/STAF, roller Functional sequence and type codes



Functional sequence

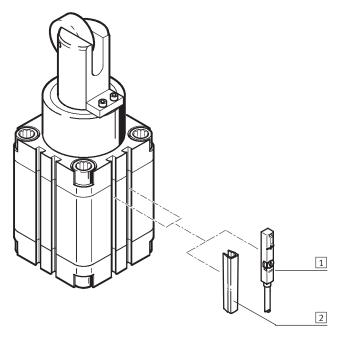
- 1. Sudden braking of the workpiece carrier via the piston rod.
- The workpiece carrier is released by activating the cylinder.
- 3. The piston rod then advances by means of spring force or compressed air until the roller makes contact with the workpiece carrier. The workpiece carrier continues to move forward.
- 4. After the workpiece carrier has passed, the piston rod advances to the end position. The next workpiece carrier can then be stopped.

Type codes



Stopper cylinders STA/STAF, roller Peripherals overview





Acce	Accessories					
		Brief description	→ Page/Internet			
1	Proximity sensor SME/SMT-8	Can be integrated in the cylinder profile barrel	30			
2	Slot cover ABP	For protecting against ingress of dirt	30			

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Function





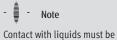
Diameter 20 ... 80 mm



Stroke length 15 ... 40 mm



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avoided during use.

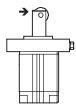


General technical data								
Piston Ø		20	32	50	80			
Pneumatic connection	STA	M5	G1/8	G1/8	-			
	STAF	-	M5	G1/8	G ¹ / ₈			
Stroke	[mm]	15	20	30	30/40			
Piston rod \varnothing	[mm]	12	20	32	50			
Operating pressure	[bar]	10	•		·			
Operating medium		Filtered compressed air, lubricated or unlubricated						
Constructional design		Piston cylinder with spring return						
Cushioning		Flexible cushioning rings/pads at both ends						
Position sensing		Via proximity sensor						
Type of mounting		Via through-holes						
			Via female thread					
Mounting position		Any						
Mode of operation		Single-acting or double-acting						
Protection against rotation		Flat-sided piston r	Flat-sided piston rod					
Ambient temperature ¹⁾	[°C]	+5 +60						

¹⁾ Note operating range of proximity sensors. $\cdot \parallel \cdot \ \ \text{Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.}$

Forces [N]					
Piston ∅	20	32	50	80	
Stroke	15	20	30	30	40
Permissible impact force on the ad-	170	830	2,300	14,600	13,300
vanced piston rod					
Spring force	13 18	20 42	47 64	79 115	101 170

Impact force is the basis for the $calculation\ of\ permissible\ impact$ energy. Depending upon the type of load to be stopped, it is advisable to use a flexible buffer to cushion the impact, reduce noise levels and to optimise impact energy.

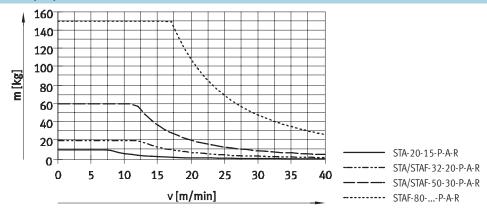


→ = Direction of impact force

FESTO

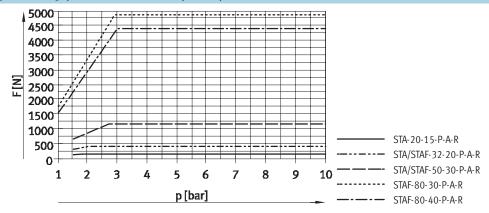
Permissible mass m as a function of the conveyor speed v

The values in the graph opposite are based on the assumption that the workpiece carrier is fitted with a flexible buffer with a deformation path of 1 mm.



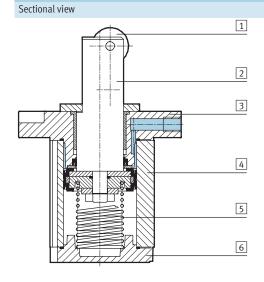
Permissible transverse force $F_{\mathbb{Q}}$ during the switching operation as a function of the pressure p

The applied load causes a transverse force to act on the piston rod. To ensure the function of the cylinder, a certain minimum pressure must be applied.



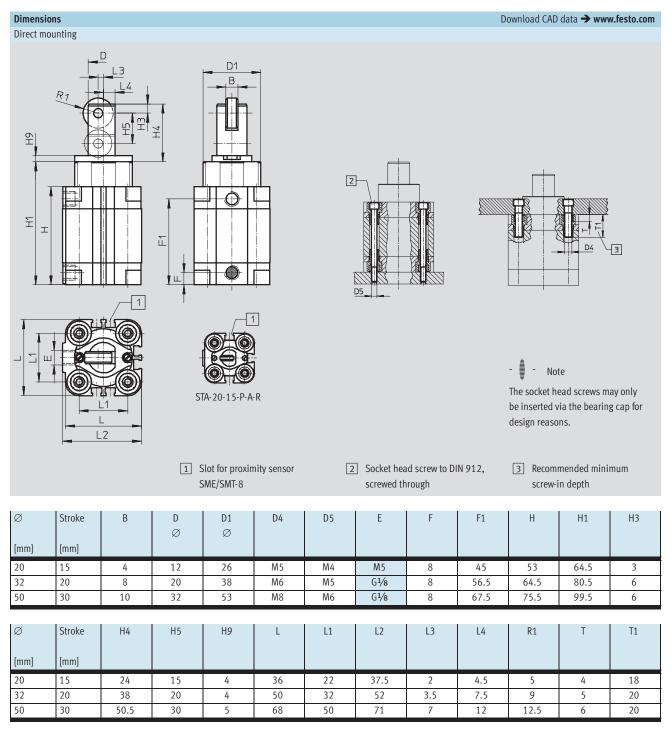


Selection aid → 16 Materials



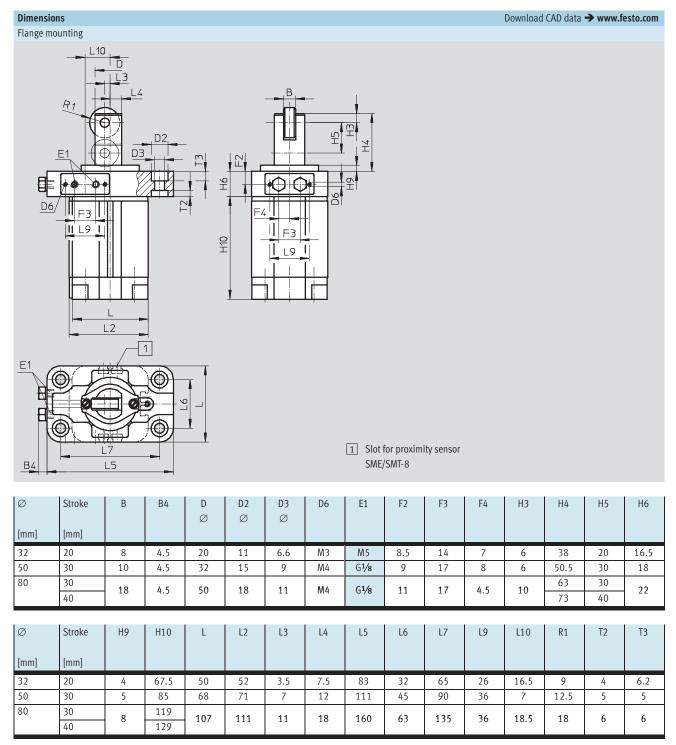
Stop	Stopper cylinder					
1	Roller	Polymer				
2	Piston rod	Stainless steel				
3	Flange	Die-cast aluminium				
4	Cylinder barrel	Anodised aluminium				
5	Springs	Spring steel				
6	End cap	Anodised aluminium				
-	Seals	Polyurethane				
-	Note on materials	Free of copper, PTFE and silicone				





 $^{\|\}cdot\|$ Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.





 $^{\|\}cdot\|$ Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.

Ordering data	Ordering data						
Piston \varnothing	Stroke	Direct mounting	Flange mounting				
[mm]	[mm]	Part No. Type	Part No. Type				
20	15	164 883 STA-20-15-P-A-R					
32	20	164 884 STA-32-20-P-A-R	164 892 STAF-32-20-P-A-R				
50	30	164 885 STA-50-30-P-A-R	164 893 STAF-50-30-P-A-R				
80	30		164 886 STAF-80-30-P-A-R				
80	40		164 894 STAF-80-40-P-A-R				

Stopper cylinders STA/STAF

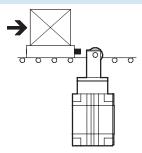
Technical data

FESTO

Selection aid

Stopping a workpiece carrier

The stopper cylinder is used to brake an individual workpiece carrier.



Example

Given:

Friction value $\mu = 0.1$

Delivery speed v = 10 m/min

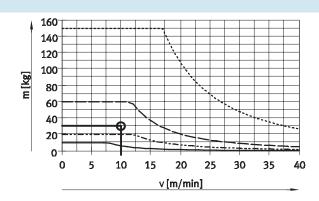
Workpiece carrier with workpiece m = 30 kg

Operating pressure p = 6 bar

Choice: Stopper cylinder STA...-50-...-R

1. Checking the permissible mass

The maximum permissible mass at a delivery speed of 10 m/min is 60 kg. This means that the total mass of the workpiece carrier and workpiece of 30 kg is permissible.



STA-20-15-P-A-R
STA/STAF-32-20-P-A-R
STA/STAF-50-30-P-A-R
STA/STAF-80-...-P-A-R

2. Checking the permissible transverse force during the switching operation

Transverse force F_Q = friction force

 $\mathsf{F}_{\mathsf{Friction}}$

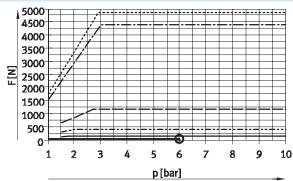
 $F_{Friction} \quad = \mu \ x \ m \ x \ g$

 $= 0.1 \times 30 \text{ kg} \times 9.81 \text{ m/s}^2$

= approx. 30 N

The maximum permissible transverse force at an operating pressure of 6 bar is 1,200 N.

This means that the transverse force of 30 N is permissible.



STA-20-15-P-A-R
STA/STAF-32-20-P-A-R
STA/STAF-50-30-P-A-R
STA/STAF-80-30-P-A-R
STA/STAF-80-40-P-A-R

Stopper cylinders STA/STAF

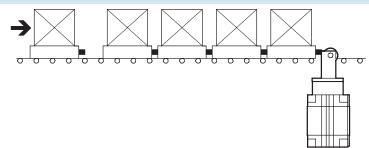
Technical data



Selection aid

Stopping or separating several workpiece carriers

The stopper cylinder is used to separate workpiece carriers. Further workpiece carriers accumulate behind carriers already at the stopper cylinder. It is vital that a buffer is mounted between the workpiece carriers (e.g. elastomer elements).



Example

Given:

Friction value $\mu = 0.1$

Delivery speed v = 10 m/min

Workpiece carrier with workpiece m = 30 kg

Operating pressure p = 6 bar

Maximum number of workpiece carriers accumulating simultaneously n_{Group} = 1

Maximum number of all queued workpiece carriers n_{Queue} = 5

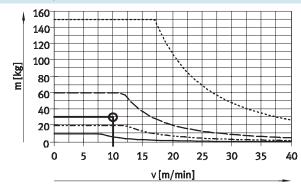
Maximum number of all advancing workpiece carriers n_{Queue-1} = 4

Spring travel of the workpiece carrier buffer $s_F = 1 \text{ mm}$

Choice: Stopper cylinder STA...-50-...-R

1. Checking the permissible mass of the first workpiece carrier

The maximum permissible mass at a delivery speed of 10 m/min is 60 kg. This means that the total mass of the workpiece carrier and workpiece of 30 kg is permissible.



2a. Calculation of the maximum permissible impact force when workpiece carriers accumulate behind a carrier at the stopper cylinder

With the STA...-50, the maximum permissible impact force is 2,300 N. This means that with a total force of 1,000 N, the number of workpiece carriers is permissible.

Impact force calculation:

$$F_{Impact} = \frac{(n_{Group} \times m) \times v^2}{s_F} = \frac{(1 \times 30 kg) \times (10m/60s)^2}{0.001m} = ca.850N$$

Friction force

$$F_{Friction} = \mu \times (n_{Queue} \times m) \times g = 0.1 \times (5 \times 30 kg) \times 9.81 m/s^2 = ca.150 N$$

Max. total force:

$$F_{Total \, force} = F_{Impact} + F_{Friction} = 850N + 150N = 1000N$$

FESTO

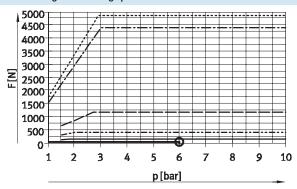
Selection aid

2b. Checking the permissible transverse force during the switching operation

Transverse force $F_Q =$ friction force F_{Friction} $F_{Friction} = 150 \text{ N}$

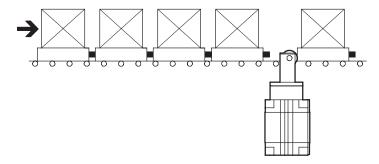
The maximum permissible transverse force at an operating pressure of 6 bar is 1,200 N.

This means that the transverse force of 150 N is permissible.



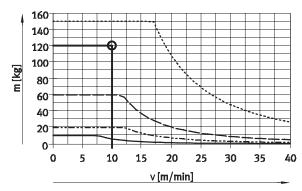
STA-20-15-P-A-R STA/STAF-32-20-P-A-R STA/STAF-50-30-P-A-R ----- STA/STAF-80-30-P-A-R --- STA/STAF-80-40-P-A-R

3. Separating and advancing the workpiece carriers



The maximum permissible mass with the STA...-50-...-R at a delivery speed of 10 m/min is 60 kg. Since the total mass of the four workpiece carriers advancing on the stopper cylinder is 120 kg, the next largest stopper cylinder must be

selected for separating.



- STA-20-15-P-A-R ----- STA/STAF-32-20-P-A-R ---- STA/STAF-50-30-P-A-R ------ STA/STAF-80-...-P-A-R

Max. total mass:

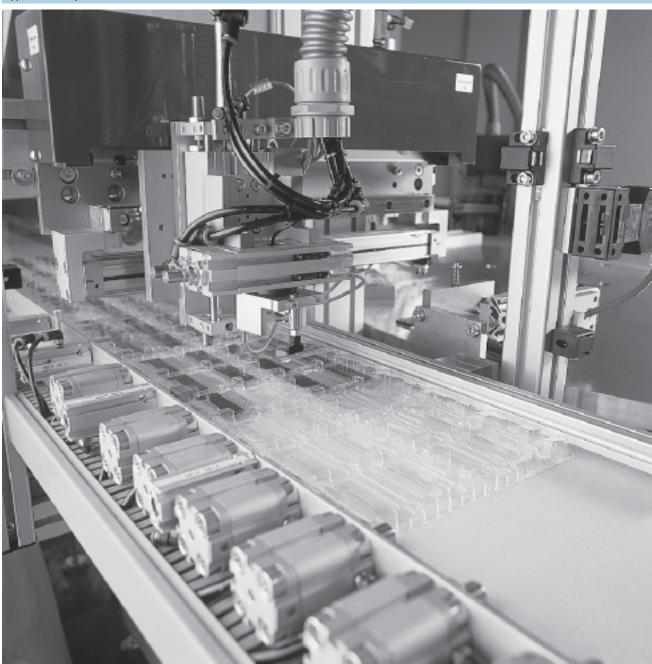
 $m_{Total \, force} = n_{Queue-1} \times m = 4 \times 30 kg = 120 kg$

Result

The stopper cylinder STA...-80-...-R must be selected for separating five workpiece carriers.



Application example



Stopper cylinders STA/STAF, toggle lever

Functional sequence

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62.8 ... 63.4 mm

96.5 ... 99.5 mm

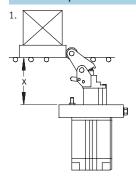
163 ... 166 mm

X = STAF-32:

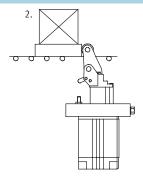
STAF-50:

STAF-80:

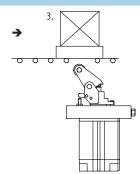
Functional sequence



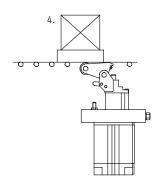
 Gentle stopping of heavy masses via a hydraulic shock absorber in the piston rod.



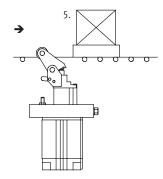
2. The toggle lever is locked into the retracted end position so that the workpiece carrier cannot be pushed back by the shock absorber.



3. The workpiece carrier is released by means of compressed air, and the toggle lever is released simultaneously.



 The piston is advanced by means of spring force or compressed air.
 The toggle lever tips back which prevents the workpiece carrier from being pushed up.



 The toggle lever is raised by means of spring force and stops the next workpiece carrier.



Protection against rotation:
The guide rod always aligns the toggle lever precisely to the approaching workpiece carrier.



Integrated shock absorber: absorbs impact energy and stops the workpiece carrier gently, and with low noise levels.

The impact energy can be adjusted using the regulating screw in the toggle lever.



Detenting roller lever: the workpiece carrier cannot be pushed back by the shock absorber.



Locking mechanism for disabling the stopper function: the workpiece carrier is able to pass the holding point without activating the cylinder.



Note

Trunnion or roller type stopper cylinders can be mounted in any position.

Stopper cylinders with toggle lever must be mounted in the vertical, upright position.

Stopper cylinders STA/STAF, toggle lever



Key feature:

Mounting options for solenoid valves and valve functions

An MEH, MEBH, MOEH or MOEBH solenoid valve can be mounted on the stopper cylinder for quick, direct actuation of the cylinder. This type of

actuation is only possible for stopper cylinders with flange mounting. The valve must be mounted on the flange

plate via a valve sub-base ZVA. The position of the piston rod when the solenoid valve is in the normal

position depends upon the valve type and the position of the valve on the cylinder.

Application	Piston rod in initial position	Required solenoid valve	Type of mounting for the solenoid valve with sub-base ZVA
- 30	Single-acting	Normally advanced	
	12 2 2 3 3 5 5 6 5 6 7 5 6 7 5 6 7 6 7 6 7 6 7 6 7	173 125 MEH-3/2-5,0-B 172 999 MEBH-3/2-5,0-B	
	12 Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z	Normally retracted 173 429 MOEH-3/2-5,0-B 173 002 MOEBH-3/2-5,0-B	
	Double-acting		
	12 2 2 3 4 5 V 3 3 9	Normally advanced 173 128 MEH-5/2-5,0-B 173 005 MEBH-5/2-5,0-B	
	14 2 2 3 4 5 V 3 9 9	Normally retracted 173 128 MEH-5/2-5,0-B 173 005 MEBH-5/2-5,0-B	



- Note

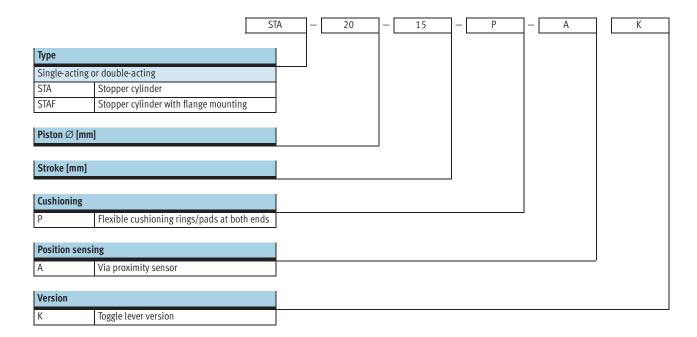
Cylinders are always supplied singleacting with spring. If a double-acting stopper cylinder is required, the filter nipple in the exhaust port must be removed. The exhaust port is then used as a supply port.

Solenoid valves MEH, MEBH

→ Internet: solenoid valve

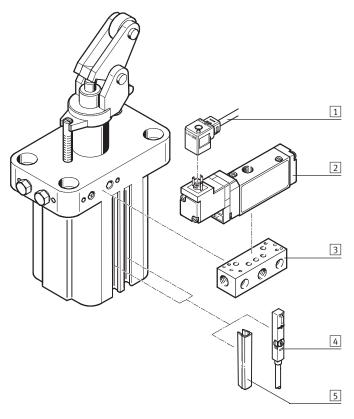
Stopper cylinders STA/STAF, toggle lever Type codes





Stopper cylinders STA/STAF, toggle lever Peripherals overview





Acce	ccessories							
		Brief description	→ Page/Internet					
1	Plug socket with cable KMEB	-	kmeb					
2	3/2-way valve MEBH	For fast and direct actuation of the stopper cylinder	mebh					
3	Sub-base ZVA	For stopper cylinder with flange	28					
4	Proximity sensor SME/SMT-8	Can be integrated in the cylinder profile barrel	30					
5	Slot cover ABP	For protecting against ingress of dirt	30					



Function





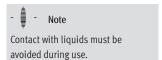
Diameter 32 ... 80 mm



Stroke length 20 ... 40 mm



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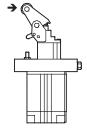


General technical data						
Piston Ø		32	50	80		
Pneumatic connection		M5	G1/8	G1/8		
Stroke	[mm]	20	30	40		
Piston rod \varnothing	[mm]	20	32	50		
Operating pressure	[bar]	10	•			
Operating medium		Filtered compressed air, lubricated or unlubricated				
Constructional design		Piston cylinder with spring return				
Cushioning		Flexible cushioning rings/pads at both ends				
Position sensing		Via proximity sensor				
Type of mounting		Via through-holes				
Mounting position		Vertical, upright				
Mode of operation		Single-acting or double-acting				
Protection against rotation		Guide rod				
Ambient temperature ¹⁾	[°C]	+5 +60	+5 +60			

- 1) Note operating range of proximity sensors. $\|\cdot\| \cdot \text{ Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.}$

Forces [N]							
Piston ∅	32	50	80				
Permissible impact force on the rollers	480	1,200	6,400				
of the toggle lever when the piston rod							
is advanced and the toggle lever is							
pushed into its end position							
Spring force	20 42	47 64	101 170				

Impact force is the basis for the $calculation\ of\ permissible\ impact$ energy. Depending upon the type of load to be stopped, it is advisable to use a flexible buffer to cushion the impact, reduce noise levels and to optimise impact energy.

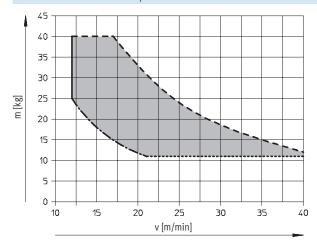


→ = Direction of impact force

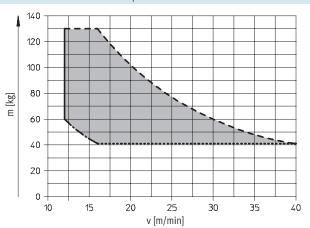


Permissible mass m as a function of the conveyor speed v

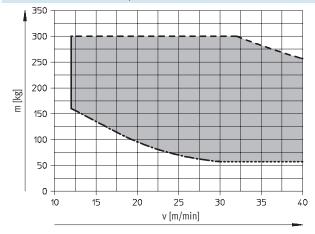
STAF-32 with a friction value of $\mu = 0.1$

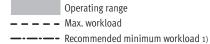


STAF-50 with a friction value of $\mu = 0.1$



STAF-80 with a friction value of $\mu = 0.1$





----- Required mass 2)

- 1) For optimum operation of the damper
- $2) \quad \text{Required mass for reliable pushing of the toggle lever into the end position with this friction value} \\$



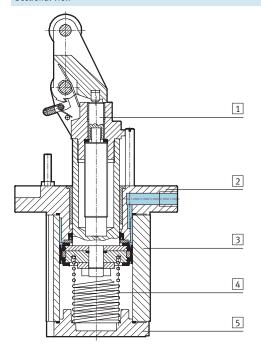
The required mass for reliable pushing into the end position is dependent on the friction pairing between the conveyor and conveyed goods, other friction values on request.

Cushioning time is increased for partial loads. Energy values valid for ambient temperature T = 20 °C



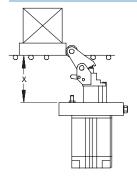
Materials

Sectional view



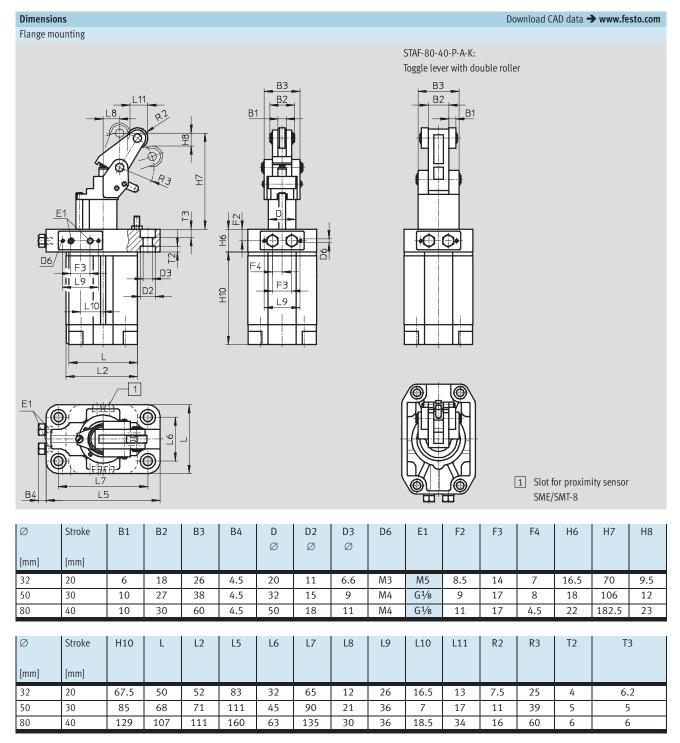
Stop	Stopper cylinder						
1	Piston rod	Stainless steel					
2	Flange	Die-cast aluminium					
3	Cylinder barrel	Anodised aluminium					
4	Springs	Spring steel					
5	End cap	Anodised aluminium					
-	Seals	Polyurethane					
-	Note on materials	Free of copper, PTFE and silicone					

Minimum distance to the conveyor



X = STAF-32: 62.8 ... 63.4 mm STAF-50: 96.5 ... 99.5 mm STAF-80: 163 ... 166 mm





Note: This product conforms with the ISO 1179-1 standard and the ISO 228-1 standard.

Ordering data	Ordering data								
Piston ∅	Stroke	Flange mounting							
[mm]	[mm]	Part No. Type							
32	20	164 880 STAF-32-20-P-A-K							
50	30	164 881 STAF-50-30-P-A-K							
80	40	164 895 STAF-80-40-P-A-K							

Stopper cylinders STA/STAF Accessories

FESTO

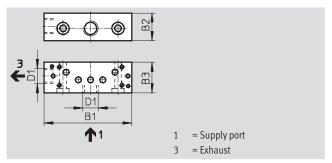
Sub-base ZVA

for stopper cylinder with flange

Material:

Wrought aluminium alloy Free of copper, PTFE and silicone



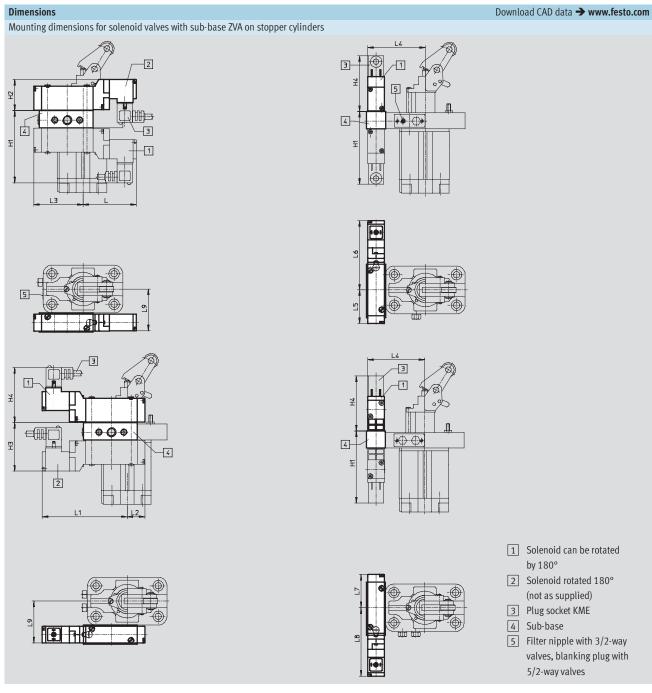


Dimension	Dimensions and ordering data									
For Ø	B1	B2	В3	D1	CRC ¹⁾	Weight	Part No. Type			
[mm]						[g]				
32	56	18	20	G1/8	2	50	164 896 ZVA-1			
50/80	57.5	18	20	G1/8	2	52	164 897 ZVA-2			

¹⁾ Corrosion resistance class 2 as per Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Stopper cylinders STA/STAF Accessories

FESTO



For Ø [mm]	L	L1	L2	L3	L4	L5	L6
32	55.5	88.5	18.5	51.5	59	35	72
50	65	79	28	42	73	36	71
80	48.5	95.5	11.5	58.5	98	39	68

For Ø [mm]	L7	L8	L9	H1	H2	H3	H4
32	35	72	42	74.5	33.5	48.5	59.5
50	34	73	52	77	31	31	57
80	31	76	71	79	29	53	56

Stopper cylinders STA/STAF Accessories



Ordering data	Ordering data – Proximity sensors for T-slot, magneto-resistive								
	Type of mounting	Switch output	Electrical connection	Cable length [m]	Part No.	Туре			
N/O contact		'		•	•				
1	Insertable in the slot from above, flush	PNP	Cable, 3-wire	2.5	543 867	SMT-8M-PS-24V-K-2,5-OE			
	with cylinder profile		Plug M8x1, 3-pin	0.3	543 866	SMT-8M-PS-24V-K-0,3-M8D			
			Plug M12x1, 3-pin	0.3	543 869	SMT-8M-PS-24V-K-0,3-M12			
		NPN	Cable, 3-wire	2.5	543 870	SMT-8M-NS-24V-K-2,5-OE			
			Plug M8x1, 3-pin	0.3	543 871	SMT-8M-NS-24V-K-0,3-M8D			
NS CONTRACTOR	Insertable in the slot lengthwise, flush	PNP	Cable, 3-wire	2.5	175 436	SMT-8-PS-K-LED-24-B			
	with the cylinder profile		Plug M8x1, 3-pin	0.3	175 484	SMT-8-PS-S-LED-24-B			
					•				
N/C contact									
13	Insertable in the slot from above, flush with cylinder profile	PNP	Cable, 3-wire	7.5	543 873	SMT-8M-PO-24V-K7,5-OE			

Ordering data	- Proximity sensors for T-slot, magnetic	reed				Technical data → Internet: sme
	Type of mounting	Switch	Electrical connection	Cable length	Part No.	Туре
		output		[m]		
N/O contact						
1	Insertable in the slot from above, flush	Contacting	Cable, 3-wire	2.5	543 862	SME-8M-DS-24V-K-2,5-OE
	with cylinder profile			5.0	543 863	SME-8M-DS-24V-K-5,0-OE
			Cable, 2-wire	2.5	543 872	SME-8M-ZS-24V-K-2,5-0E
			Plug M8x1, 3-pin	0.3	543 861	SME-8M-DS-24V-K-0,3-M8D
NS .	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	2.5	150 855	SME-8-K-LED-24
	with the cylinder profile		Plug M8x1, 3-pin	0.3	150 857	SME-8-S-LED-24
N/C contact						
68	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	7.5	160 251	SME-8-0-K-LED-24
	with the cylinder profile					

Ordering data	- Connecting cables	Technical data → Internet: nebu			
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 333	NEBU-M8G3-K-2.5-LE3
6			5	541 334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 338	NEBU-M8W3-K-2.5-LE3
			5	541 341	NEBU-M8W3-K-5-LE3

C	Ordering data – Slot cover for T-slot								
		Assembly	Length	Part No.	Туре				
			[m]						
Г		Insertable from	2x 0.5	151 680	ABP-5-S				
É		above							