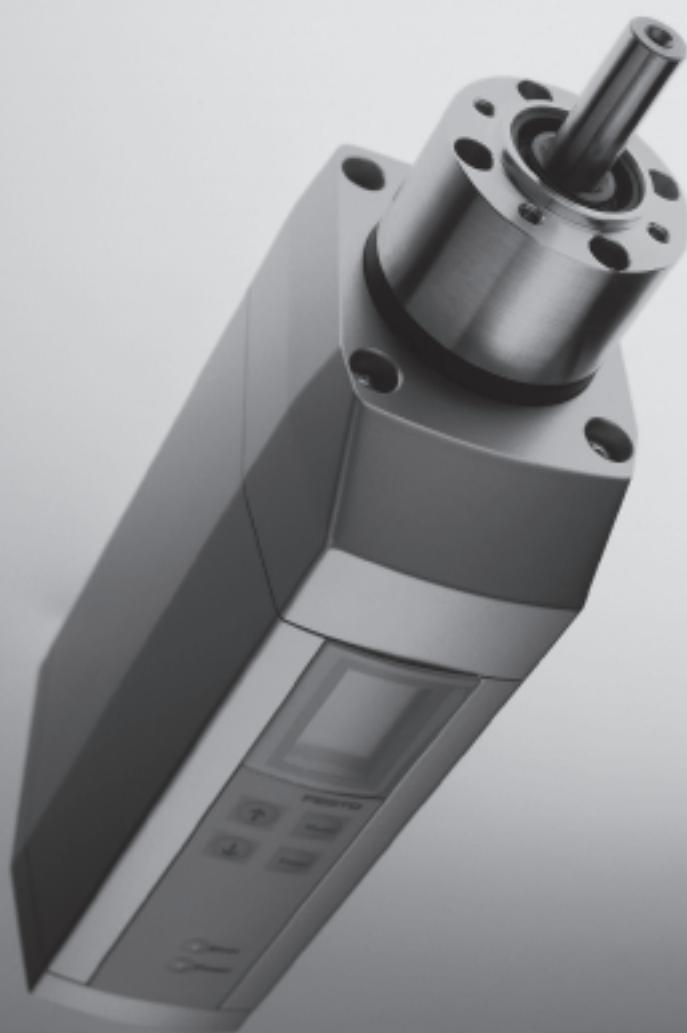


Intelligent motor units MTR-DCI

FESTO



- Servo-motor with integrated gearing and positioning controller
- Compact design
- Actuation via I/O connection
- Protection class IP54



Motor units MTR-DCI, intelligent control motors

Key features

General data

The motor unit MTR-DCI is an innovative motor with integrated power electronics for positioning tasks.

Four components in one housing

Integrated in the MTR-DCI are the motor, gearing, controller and power electronics. This means that there is no need for a control cabinet or extensive cabling.

Reliable

The integrated power electronics and controller obviates the need for motor cables and improves the electromagnetic compatibility. Additional monitoring functions are integrated.

Uncomplicated

The complete commissioning process can be performed directly on the MTR-DCI via the optional LCD display or on a PC using the user-friendly menus of the FCT (Festo Configuration Tool). No matter which approach is used, all parameters are continuously controlled.

At a glance

- Compact design
- Profile insensitive to the ingress of dirt thanks to smooth surfaces
- Direct current motor with planetary gearing and encoder
- Gear reduction ratio: 7:1; 14:1, 22:1
- Protection class IP54

Positioning functionality

- 16 traversing records (including homing)
- Constant acceleration and braking
- Positioning control

Protective functions

- Temperature monitoring
- Current monitoring
- Voltage failure detection
- Drag fault monitoring
- Software end-position detection

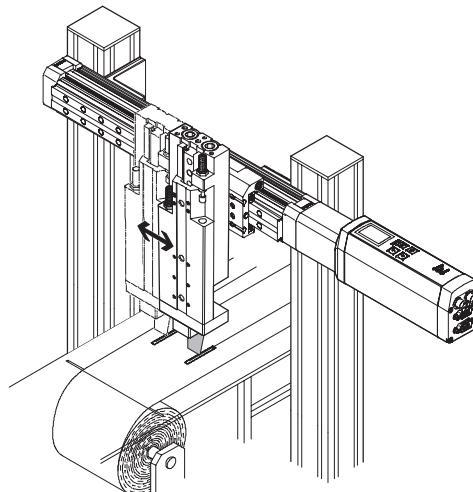
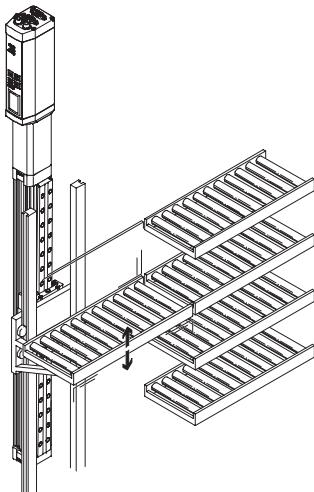
- 1 Control panel with integrated display (optional)
- 2 Input for reference end switches
- 3 RS232 interface
- 4 Operator interface: I/O interface
- 5 Power supply
- 6 Gear unit



Typical applications

Adjusting sorting conveyors

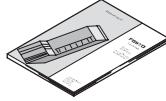
Programming formats for paper or foil cutting machines



Motor units MTR-DCI, intelligent control motors

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Key features

Accessories		→ 5 / 2.2-10	
Cable		Description and configuration software	
Supply cable	Cable lengths: 2.5 ... 10 m Allocation → 5 / 2.2-6	Description	User documentation in paper form, in the languages DE, GB, ES, FR, IT, SE, is not included in the scope of delivery.
			
Control cable	For I/O connection to any PLC controller Cable lengths: 2.5 ... 10 m Allocation → 5 / 2.2-6	Documentation package	User documentation on CD-ROM, in the languages DE, GB, ES, FR, IT, SE, is included in the scope of delivery for the motor unit MTR-DCI.
			
Programming cable	For parameterisation and commissioning via the RS232 interface using FCT software Cable length: 2.5 m Allocation → 5 / 2.2-6	Configuration package FCT	The configuration on CD-ROM is included in the scope of delivery for the motor unit MTR-DCI.
			

Type codes

Type	MTR	-	DCI	-	42	-	S	-	VC	-	SC	-	E	-	G7	-	H2	-	IO
Motor type	MTR	Motor																	
Size																			
Torque class	S	Standard																	
Nominal voltage	VC	24 V DC																	
	VD	48 V DC																	
Plug design	SC	Straight plug outlet																	
Measuring system	E	Encoder																	
Gear reduction ratio	G7	7:1																	
	G14	14:1																	
	G22	22:1																	
Parameterisation interface	R2	RS232																	
	H2	RS232 and control panel																	
Electrical connection technology	IO	I/O connection																	

Motor units MTR-DCI, intelligent control motors

Technical data

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- Ø - Size
32 ... 62
- L - Voltage
24, 48 V DC



General technical data				
Size	32	42	52	62
Rotary position generator	Optical encoder			
No. of increments/revolution	300			
Controller operating mode	PWM MOSFET power amplifier			
Protective functions	I ² T monitoring Following error monitoring Software end position detection Voltage failure detection Current monitoring Temperature monitoring: Silicon absolute temperature sensor, switches off at temperatures > 70 °C			
Display resolution	128 x 64 pixels			
Type of mounting	Can be screwed on or clamped to gearing flange			
Gearing type	Planetary gear unit			
Gear reduction ratio	G7	6.75 (7:1); 1-stage		
	G14	13.73 (14:1); 2-stage		
	G22	–	22.21 (22:1); 2-stage	

Electrical data						
Size	32	42	52	62		
Nominal voltage [V DC]	24 ±10%					
Nominal current (motor) [A]	0.73	2	5	6.19		
Peak current [A]	2.1	3.8	7.7	20		
Motor constant [Nm/A]	4.5	6.1	6.4	12.1		
Nominal power (motor) [W]	17.5	48	122.4	316.8		
Max. current [mA] (digital logic outputs)	200		60			
No. of digital logic inputs (with I/O connection)	6					
No. of digital logic outputs (with I/O connection)	2					
Parameterisation interface	RS232, 9,600 baud					

Motor units MTR-DCI, intelligent control motors

Technical data

Mechanical data									
Size	32		42		52		62		
Gear reduction ratio	G7	G14	G7	G14	G7	G14	G7	G14	G22
Gearing output speed [rpm]	481	237	444	218	444	218	504	248	153
Gearing torsional backlash [°]	≤ 1.9	≤ 1.55	≤ 1.3	≤ 0.95	≤ 1.1	≤ 0.75	≤ 1	≤ 1.5	≤ 1.5
Gearing output torque [Nm]	0.15	0.29	0.59	1.13	1.62	3.08	3.78	7.2	11.66
Gearing efficiency	0.75	0.7	0.8	0.75	0.8	0.75	0.8	0.75	0.75
Mass moment of inertia (rotor) [kg cm ²]	0.024		0.323		1.209		3.3		
Mass moment of inertia (gearing) [kg cm ²]	0.00089		0.00149		0.00235		0.00441		0.01132
Radial shaft load [N]	40	70	160	230	200	320	240	360	360
Axial shaft load [N]	10	20	50	80	60	100	50	70	70
Product weight [kg]	0.711	0.735	1.715	1.824	3.104	3.285	7.605	7.963	7.951

Operating and environmental conditions						
Size	32	42	52	62		
Digital logic outputs	Not electrically isolated		Electrically isolated			
Insulation protection class to VDE 60034	F					
Protection class	IP54					
CE symbol (declaration of conformance)	In accordance with EU EMC Directive					
Ambient temperature [°C]	0 ... +50					
Storage temperature [°C]	-25 ... +60					
Relative air humidity [%]	0 ... 95 (non-condensing)					

Materials	
Motor unit housing	Anodised aluminium
Motor unit, cover	Aluminium, precision casting, coated (size 62 milled)

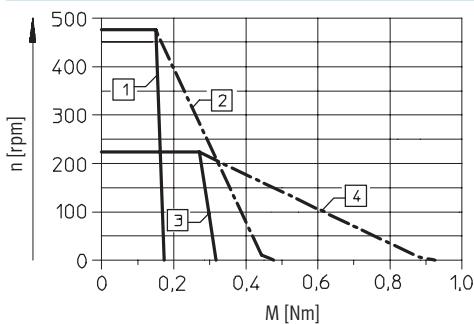
Motor units MTR-DCI, intelligent control motors

Technical data

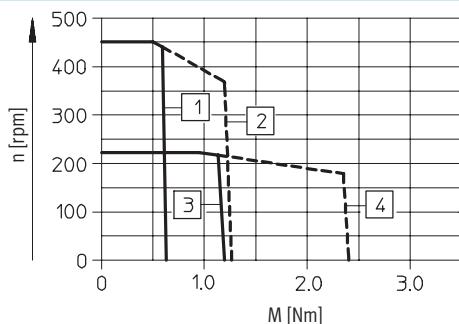
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Torque M as a function of n (rpm)

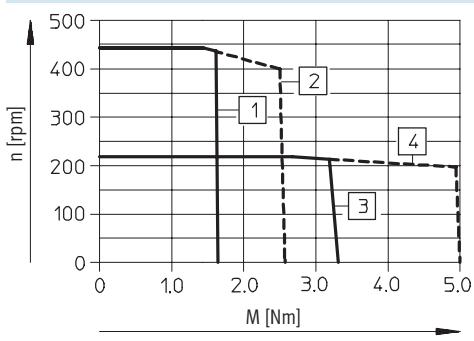
Size 32



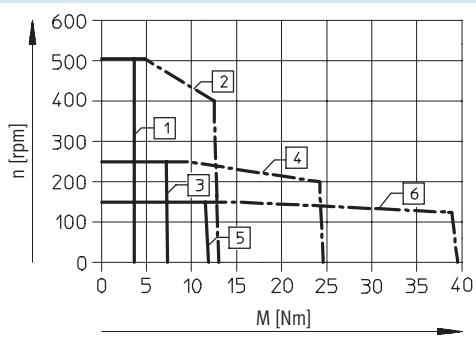
Size 42



Size 52



Size 62



Gear reduction ratio 7:1

- [1] Torque, nom.
- [2] Torque, max.

Gear reduction ratio 14:1

- [3] Torque, nom.
- [4] Torque, max.

Gear reduction ratio 22:1

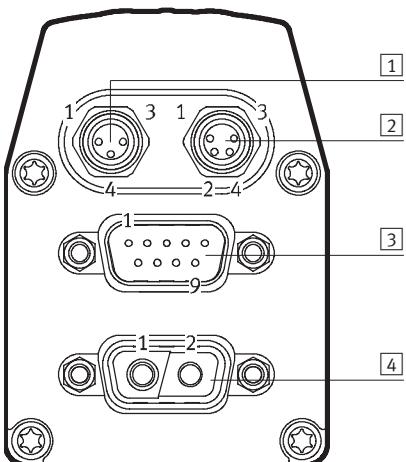
- [5] Torque, nom.
- [6] Torque, max.

Motor units MTR-DCI, intelligent control motors

Technical data

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Pin allocation



[1] Reference switch, 3-pin M8 socket

Pin	Function
1	24 V
4	Reference input
3	0 V
-	

[2] RS 232 interface, 4-pin M8 socket

Pin	Function
1	0 V
2	Transmitted Data (TxD)
3	Received Data (RxD)
4	-

[3] I/O interface, 9-pin Sub-D plug

Pin	Function
1	Traversing record coding, bit 0
2	Traversing record coding, bit 1
3	Traversing record coding, bit 2
4	Traversing record coding, bit 3
5	Start bit
6	Enable bit
7	Ready signal output
8	MC signal output
9	0 V

[4] Power supply, 2-pin plug

Pin	Function
1	24 V DC (for MTR-DCI-32/42/52), 48 V DC (for MTR-DCI-62)
2	0 V
-	
-	
-	
-	
-	
-	
-	

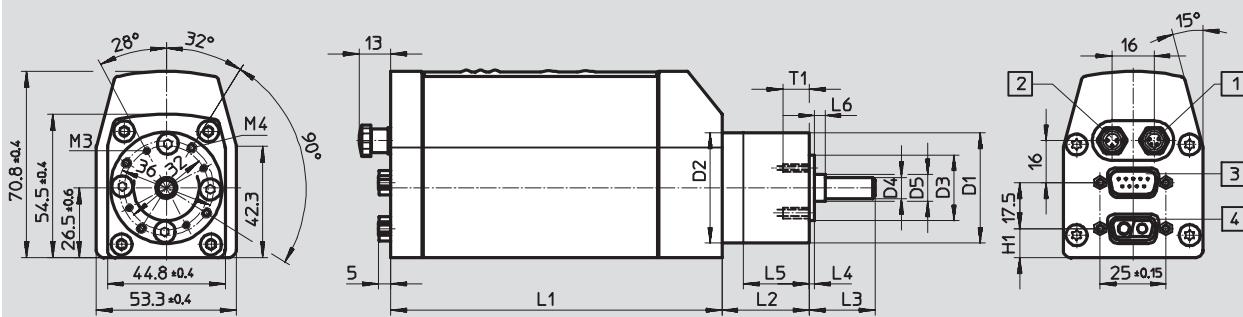
Motor units MTR-DCI, intelligent control motors

Technical data

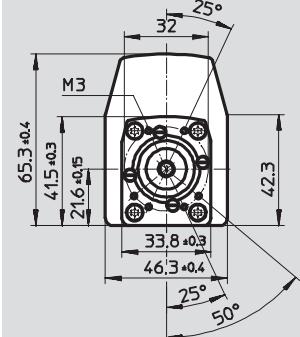
Dimensions

Download CAD data → www.festo.com/en/engineering

Size 42

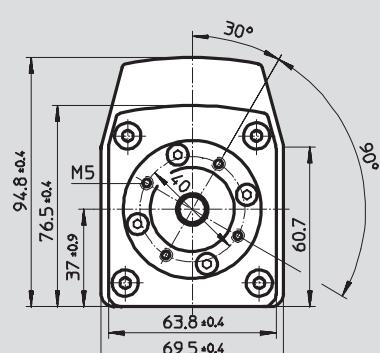


Size 32



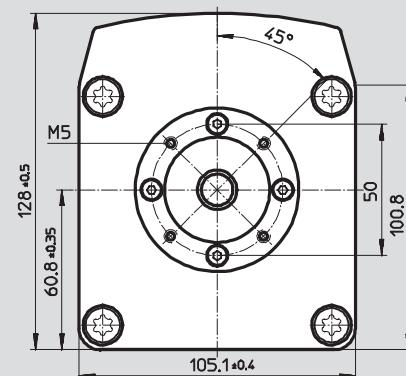
- [1] M8x1, 4-pin
- [2] M8 x 1, 3-pin

Size 52



- [3] Sub-D, 9-pin
- [4] Sub-D, 2-pin

Size 62



Type	D1 ∅ g10	D2 ∅ ±0.1	D3 ∅ h8	D4 ∅ h7	D5 ∅	H1	L1	L2	L3	L4	L5	L6	T1
MTR-DCI-32S-...-G7	-	-	21.5	6	-	13 ± 0.2	175.5	-	18.7 ± 0.6	2.5 ± 0.3	-	-	6
MTR-DCI-32S-...-G14	-	-	21.5	6	-	13 ± 0.2	175.5	-	18.7 ± 0.6	2.5 ± 0.3	-	-	6
MTR-DCI-42S-...-G7	42	42	25	8	-	11	176	33.3	25 ± 1	2 ± 0.2	25	-	10
MTR-DCI-42S-...-G14	42	42	25	8	-	11	176	46.3	25 ± 1	2 ± 0.2	25	-	10
MTR-DCI-52S-...-G7	52	52	32	12	-	17.3	194	39	33 ± 1	3 ± 0.3	31	-	10
MTR-DCI-52S-...-G14	52	52	32	12	-	17.3	194	53	33 ± 1	3 ± 0.3	31	-	10
MTR-DCI-62S-...-G7	62	62	40	14	15	61.3	270	47	39 ± 1	5 ± 0.3	31.3	9	10
MTR-DCI-62S-...-G14	62	62	40	14	15	61.3	270	47	39 ± 1	5 ± 0.3	31.3	9	10
MTR-DCI-62S-...-G22	62	62	40	14	15	61.3	270	47	39 ± 1	5 ± 0.3	31.3	9	10

Motor units MTR-DCI, intelligent control motors

Ordering data – Modular products

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M Mandatory data										
Module No.	Motor unit	Motor type	Flange/size	Torque class	Nominal voltage	Plug design	Measuring system	Gearing	Parameterisation interface	Electrical connection technology
533 736	MTR	DCI	32	S	VC	SC	E	G7	R2	IO
533 742			42		VD			G14	H2	
533 748			52					G22		
533 754			62							
Order example	533 742	MTR	DCI	42	S	VC	SC	G7	R2	IO

Ordering table										
Size	32	42	52	62	Conditions	Code		Enter code		
Module No.	533 736	533 742	533 748	533 754						
Motor unit	Motor unit								MTR	
Motor type	DC servo motor with integrated position controller								-DCI	
Flange/size	32	42	52	62					-...	
Torque class	Standard torque class								S	
Nominal voltage [V]	24 DC			–					-VC	
	[V] –			48 DC					-VD	
Plug design	Straight plug								SC	
Measuring system	Encoder								-E	
Gearing	Integrated planetary gearing $i = 6.75$								G7	
	Integrated planetary gearing $i = 13.73$								G14	
	–			Integrated planetary gearing $i = 22.21$					G22	
Parameterisation interface	RS232 interface								-R2	
	RS232 interface + control panel								-H2	
Electrical connection technology	I/O connection								IO	

Motor units MTR-DCI, intelligent control motors

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Accessories

Ordering data – Cables				
	Brief description	Cable length	Part No.	Type
	Supply cable	2.5 m	537 931	KPWR-MC-1-SUB-9HC-2,5
		5 m	537 932	KPWR-MC-1-SUB-9HC-5
		10 m	537 933	KPWR-MC-1-SUB-9HC-10
	Control cable for I/O connection to any PLC controller	2.5 m	537 923	KES-MC-1-SUB-9-2,5
		5 m	537 924	KES-MC-1-SUB-9-5
		10 m	537 925	KES-MC-1-SUB-9-10
	Programming cable	2.5 m	537 926	KDI-MC-M8-SUB-9-2,5

Ordering data – Documentation and software				
	Brief description	Language	Part No.	Type
	User documentation in paper form is not included in the scope of delivery.	DE	539 615	P.BE-MTR-DCI-IO-DE
		EN	539 616	P.BE-MTR-DCI-IO-EN
		ES	539 617	P.BE-MTR-DCI-IO-ES
		FR	539 618	P.BE-MTR-DCI-IO-FR
		IT	539 619	P.BE-MTR-DCI-IO-IT
		SV	539 620	P.BE-MTR-DCI-IO-SV
	Documentation package	DE, EN, ES, FR, IT, SV	539 621	P.BE-MTR-DCI-UDOK
	The configuration package FCT (Festo Configuration Tool) on CD-ROM is included in the scope of delivery for the motor unit MTR-DCI.	DE, EN	539 622	P.SW-FCT