

Parallel grippers HGPL, robust, with long stroke

FESTO

Handling units

7.0



- Sturdy
- Gripping forces of up to 605 N
- Reliable
- Space-saving

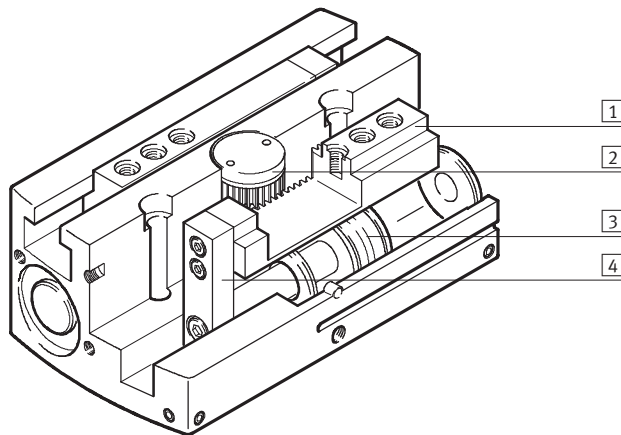
Parallel grippers HGPL, robust, with long stroke

Key features

FESTO

At a glance

- Space-saving and suitable for high forces
 - Two parallel and opposing pistons move the gripper jaws directly and without loss of force
- Reliable
 - A pinion that synchronises the movement of both gripper jaws ensures controlled, precise and centred gripping
 - The space-saving design of the parallel gripper jaws permits a long guide length for the gripper jaws
- Sturdy
 - The T-slot in combination with a long guide length allows the gripper jaws to withstand high forces and torques
- Flexible range of applications
 - Double-acting gripper suitable for external and internal gripping.
 - Versatile mounting options and compressed air connections
 - Opening stroke can be adjusted to optimise time



- | | |
|----------------------|----------------------|
| 1 Gripper jaw | 3 Piston with magnet |
| 2 Synchronising gear | 4 Driver |

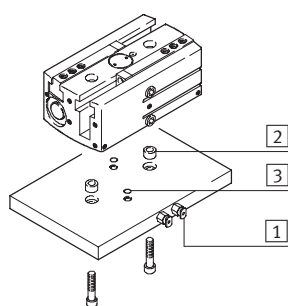
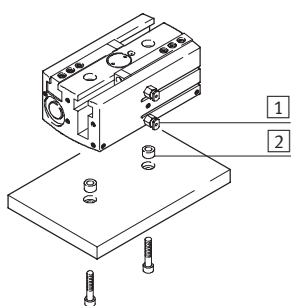


Gripper selection software
www.festo.com/en/engineering

Versatile compressed air connections

Direct
from the front

Via adapter plate
from underneath

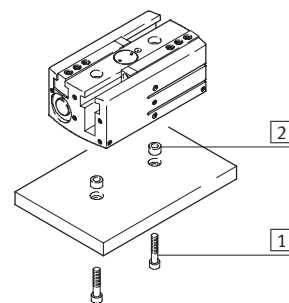
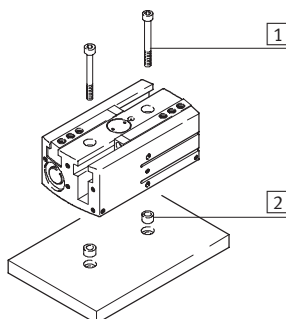


- | |
|------------------------------|
| 1 Compressed air connections |
| 2 Centring sleeves |
| 3 O-rings |

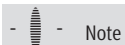
Mounting options

Direct mounting
from above

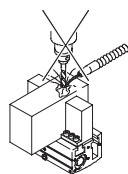
from underneath



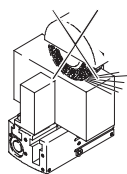
- | |
|--------------------|
| 1 Mounting screws |
| 2 Centring sleeves |



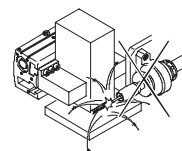
Grippers are not designed for the following or similar applications:



- Aggressive media
- Machining



- Grinding dust



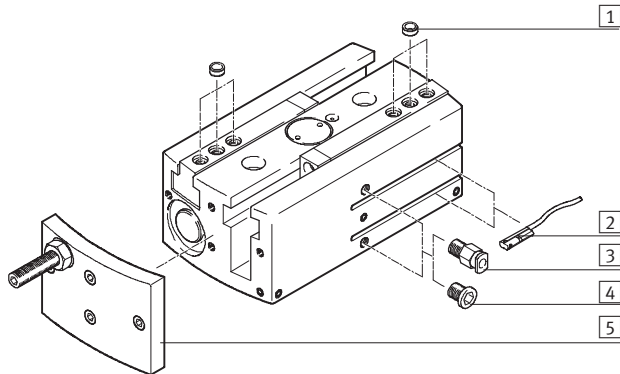
- Welding spatter

Parallel grippers HGPL, robust, with long stroke

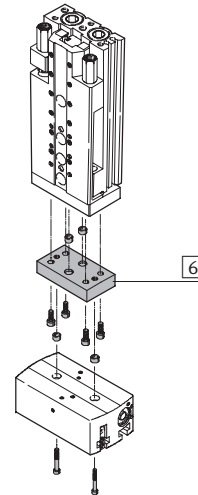
Peripherals overview and type codes

FESTO

Peripherals overview



System product for handling and assembly technology



Accessories			
Type	Brief description		→ Page
1 Centring sleeve ZBH	For centring when attaching gripper fingers		1 / 7.0-32
2 Proximity sensor SME/SMT-10	For sensing the piston position		1 / 7.0-33
3 Push-in fitting QS	For connecting compressed air tubing with standard external diameters		Volume 3
4 Blanking plug B	For sealing compressed air connections when using air connections at the front		1 / 7.0-32
5 Stroke reducing plate HGPL-HR...	For reducing the opening stroke		1 / 7.0-31
6 –	Drive/gripper connections		Volume 5
– Unmachined gripper finger BUB-HGPL	Unmachined part specially matched to the gripper jaws for custom building of gripper fingers		1 / 7.0-32

Type codes

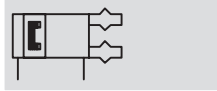
		HGPL	–	14	–	40	–	A
Type								
HGPL	Parallel gripper							
Size								
Stroke [mm]								
Position sensing								
A	For proximity sensing							

Parallel grippers HGPL, robust, with long stroke

Technical data

FESTO

Function
Double-acting
HGPL-...-A



www.festo.com/en/
Spare_parts_service
Wearing parts kits
→ 1 / 7.0-30



Ø - Size
14 ... 40 mm
- Stroke
80 ... 160 mm

General technical data							
Size		14		25		40	
Design		Synchronised pneumatic pistons					
		Guided motion sequence					
Mode of operation		Double-acting					
Gripper function		Parallel					
Number of gripper jaws		2					
Max. applied load per external gripper finger ¹⁾	[N]	0.8		2.5		4.2	
Stroke per gripper jaw	[mm]	40	80	40	80	40	80
Pneumatic connection		M5					
Repetition accuracy ²⁾	[mm]	< 0.03					
Max. interchangeability	[mm]	< 0.2					
Max. gripper jaw backlash ³⁾	[mm]	< 0.05					
Max. operating frequency	[Hz]	< 1					
Rotational symmetry	[mm]	< Ø 0.2					
Position sensing		For proximity sensing					
Type of mounting		Via through-holes and centring sleeves					
		With female thread and centring sleeves					
Fitting position		Any					

- 1) Valid for unthrottled operation
2) End-position drift under constant conditions of use with 100 consecutive strokes in the direction of movement of the gripper jaws
3) In the direction of the gripper jaw movement

Operating and environmental conditions	
Operating pressure [bar]	3 ... 8
Operating medium	Filtered compressed air, lubricated or unlubricated
Ambient temperature ¹⁾ [°C]	+5 ... +60
Corrosion resistance class CRC ²⁾	2

- 1) Note operating range of proximity sensors
2) Corrosion resistance class 2 according to Festo standard 940 070
Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Weight [g]			
Size	14	25	40
Stroke per gripper jaw			
40 mm	440	1400	3300
80 mm	720	2200	4800

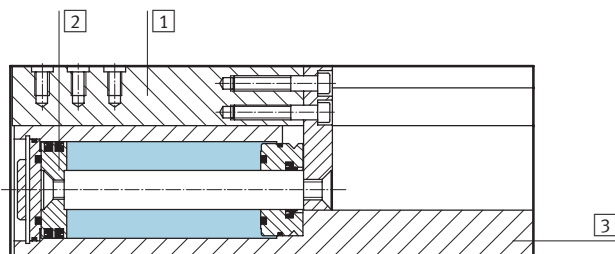
Parallel grippers HGPL, robust, with long stroke

FESTO

Technical data

Materials

Sectional view



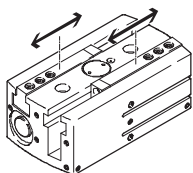
Parallel gripper

1	Gripper jaw	Hardened steel, CitroX-coated
2	Piston	High-alloy steel
3	Housing	Wrought aluminium alloy with CompCote
–	Seals	Nitrile rubber, polyurethane
Note on materials		Free of copper, PTFE and silicone

Handling units

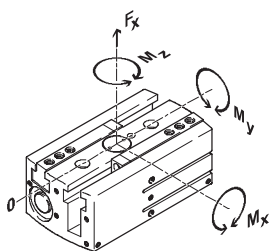
7.0

Gripping force [N] at 6 bar



Size	Stroke	14	25	40
Gripping force per gripper jaw				
Opening	40 mm	60	180	440
	80 mm	64	205	520
Closing	40 mm	80	240	550
	80 mm	80	255	605
Total gripping force				
Opening	40 mm	120	360	880
	80 mm	128	410	1040
Closing	40 mm	160	480	1100
	80 mm	160	510	1210

Characteristic load values at the gripper jaws



The indicated permissible forces and torques refer to a single gripper jaw. The indicated values include the lever arm, additional applied loads caused

by the workpiece or external gripper fingers, as well as forces which occur during movement. The zero coordinate line (gripper finger guide slot) must be

taken into consideration for the calculation of torques.

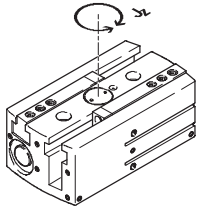
Size		14	25	40
Max. permissible force F_z	[N]	500	1500	2500
Max. permissible torque M_x	[Nm]	35	100	125
Max. permissible torque M_y	[Nm]	35	60	80
Max. permissible torque M_z	[Nm]	35	70	100

Parallel grippers HGPL, robust, with long stroke

Technical data

FESTO

Mass moment of inertia [kgm²x10⁻⁴]



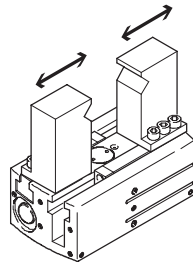
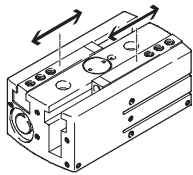
Mass moment of inertia [kgm²x10⁻⁴]
for parallel grippers in relation to the
central axis with no load.

Size		14	25	40
Stroke per gripper jaw	40 mm	4.69	18.88	66.83
	80 mm	21.93	78.7	198.87

Opening and closing times [ms] at 6 bar

without external gripper fingers

with external gripper fingers



The indicated opening and closing
times [ms] have been measured at
room temperature and at 6 bar oper-
ating pressure with horizontally
mounted additional gripper fingers.

The grippers must be throttled for
greater applied loads. Opening and
closing times must then be adjusted
correspondingly.

Size		14	25	40
without external gripper fingers – opening				
Stroke per gripper finger	40 mm	104	194	238
	80 mm	234	360	414
without external gripper fingers – closing				
Stroke per gripper finger	40 mm	86	192	205
	80 mm	217	366	438
with external gripper fingers as a function of applied load				
Stroke per gripper finger	40 mm			
Applied load	1 N	108	–	–
	2 N	136	–	–
	3 N	167	210	–
	4 N	192	243	–
	5 N	–	272	260
	6 N	–	–	284
	8 N	–	–	328
with external gripper fingers as a function of applied load				
Stroke per gripper finger	80 mm			
Applied load	1 N	243	–	–
	2 N	343	–	–
	3 N	420	401	–
	4 N	485	463	–
	5 N	–	518	478
	6 N	–	–	524
	8 N	–	–	604

Parallel grippers HGPL, robust, with long stroke

Technical data

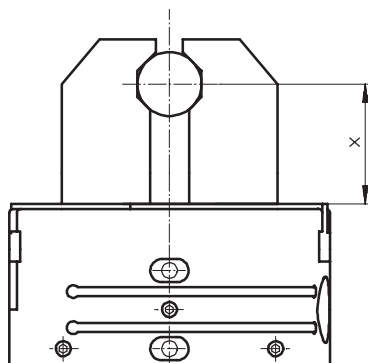
FESTO

Handling units

7.0

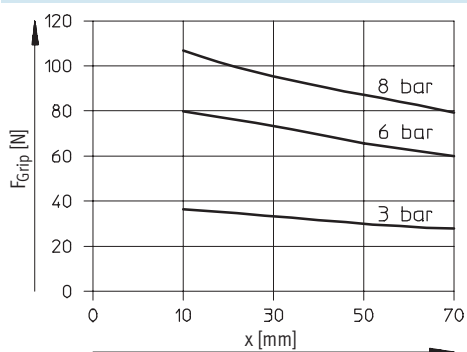
Gripping force F_{Grip} per gripper jaw as a function of operating pressure and lever arm x

Gripping forces related to operating pressure and lever arm can be determined for the various sizes using the following graphs.

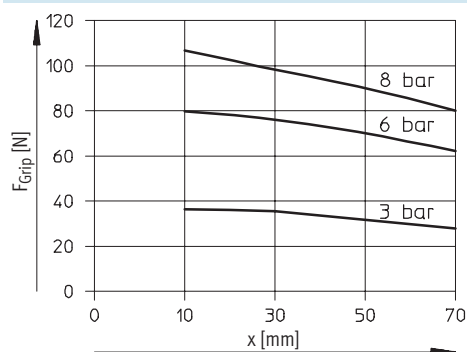


As external gripper: Closing operation

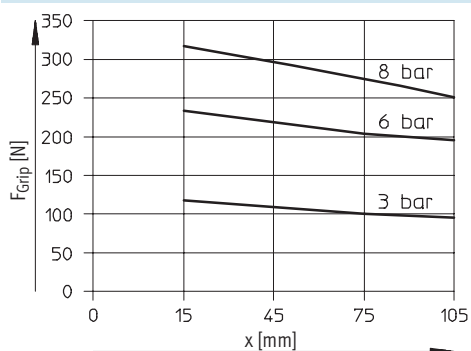
HGPL-14-40-A



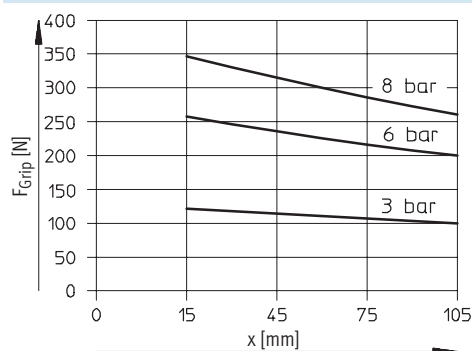
HGPL-14-80-A



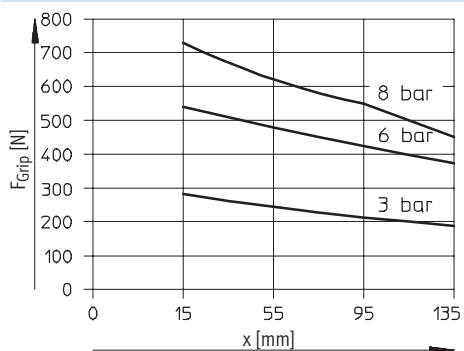
HGPL-25-40-A



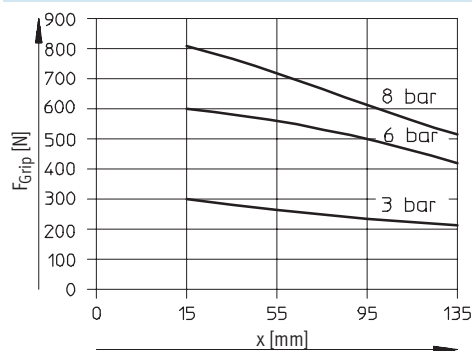
HGPL-25-80-A



HGPL-40-40-A



HGPL-40-80-A



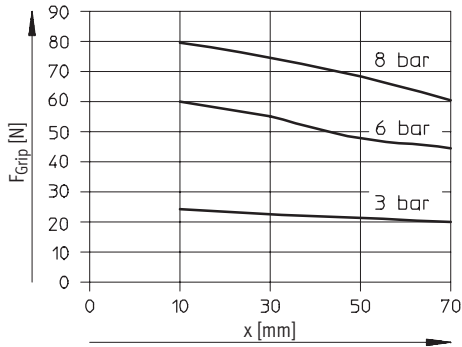
Parallel grippers HGPL, robust, with long stroke

Technical data

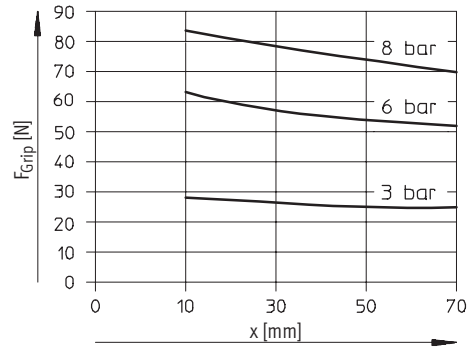
FESTO

Gripping force F_{Grip} per gripper jaw as a function of operating pressure and lever arm x
As internal gripper: Opening operation

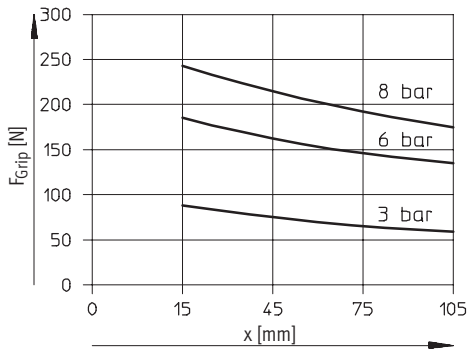
HGPL-14-40-A



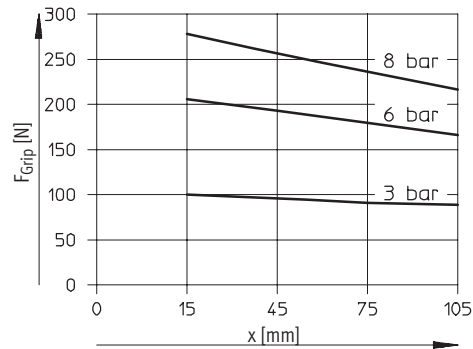
HGPL-14-80-A



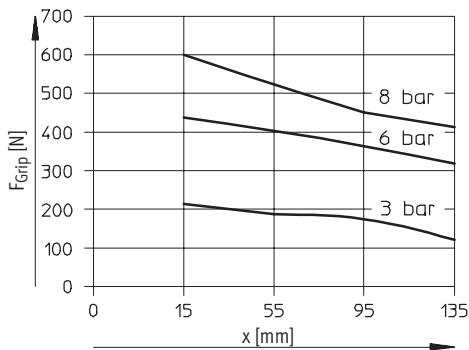
HGPL-25-40-A



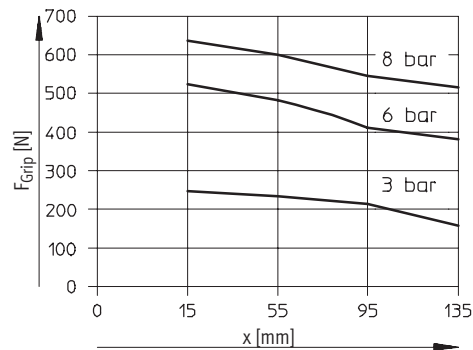
HGPL-25-80-A



HGPL-40-40-A



HGPL-40-80-A



Parallel grippers HGPL, robust, with long stroke

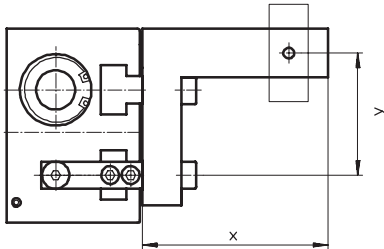
Technical data

FESTO

Handling units

7.0

Gripping force F_{Grip} per gripper jaw as a function of lever arm x and eccentricity y



Gripping forces at 6 bar dependent upon eccentric application of force and the maximum permissible off-centre point of force application can be determined for the various sizes using the following graphs.

Calculation example

Given:

Lever arm $x = 32 \text{ mm}$

Eccentricity $y = 22 \text{ mm}$

To be found:

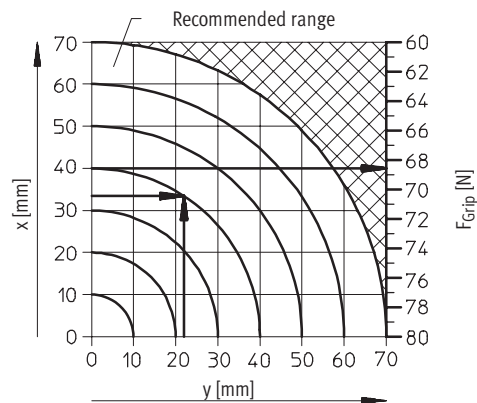
Gripping force at 6 bar

Procedure:

- Determine the intersection xy between lever arm x and eccentricity y in the graph for HGPL-14-40-A
- Draw an arc (with centre at origin) through intersection xy
- Determine the intersection between the arc and the X axis
- Read the gripping force

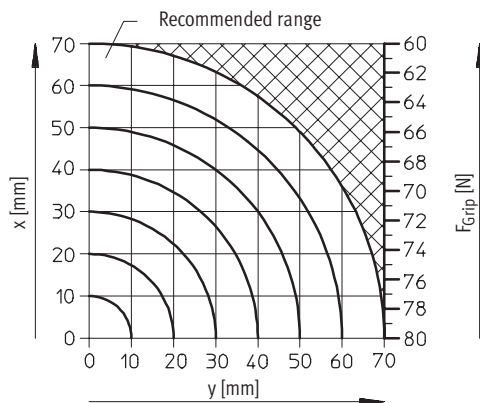
Result:

Gripping force = approx. 68.3 N

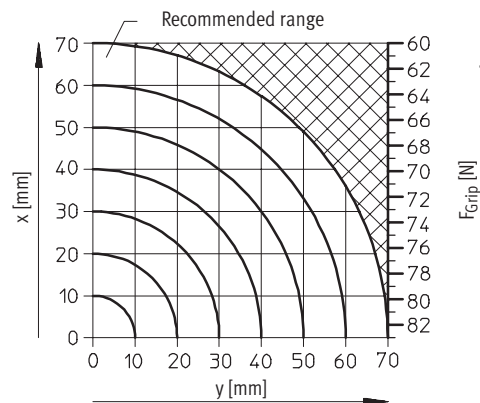


As external gripper: Closing operation

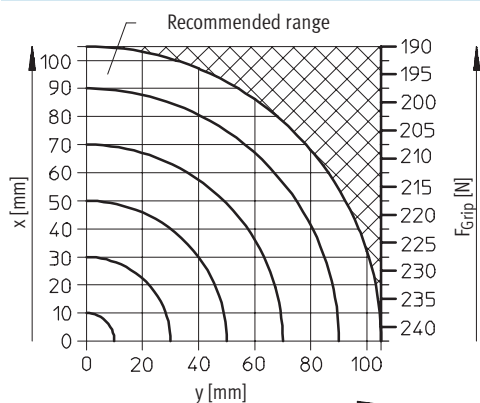
HGPL-14-40-A



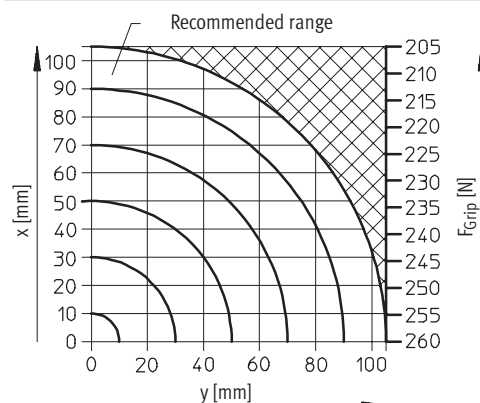
HGPL-14-80-A



HGPL-25-40-A



HGPL-25-80-A



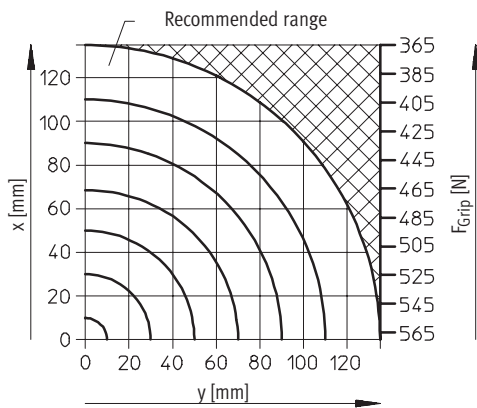
Parallel grippers HGPL, robust, with long stroke

Technical data

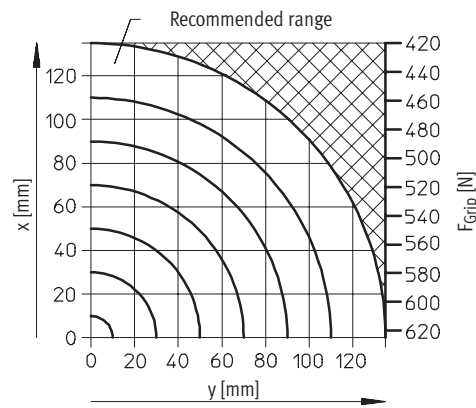
FESTO

Gripping force F_{Grip} per gripper jaw as a function of lever arm x and eccentricity y

HGPL-40-40-A

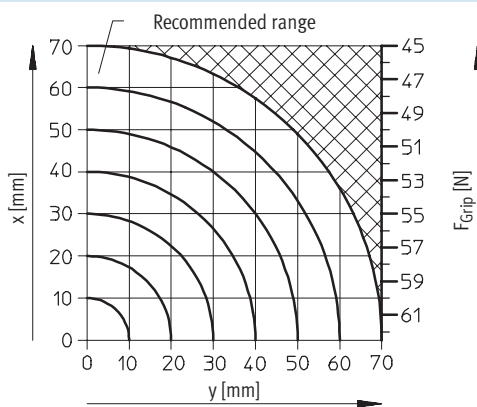


HGPL-40-80-A

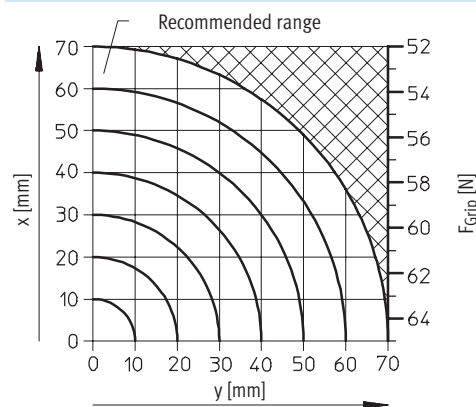


As internal gripper: Closing operation

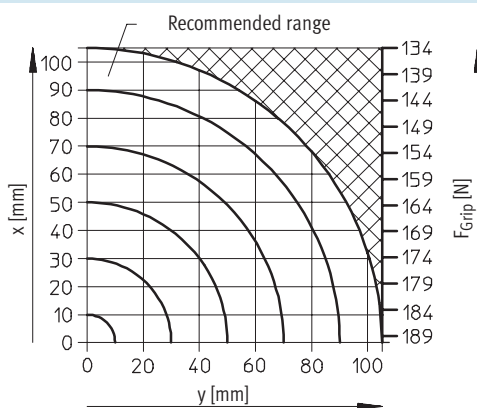
HGPL-14-40-A



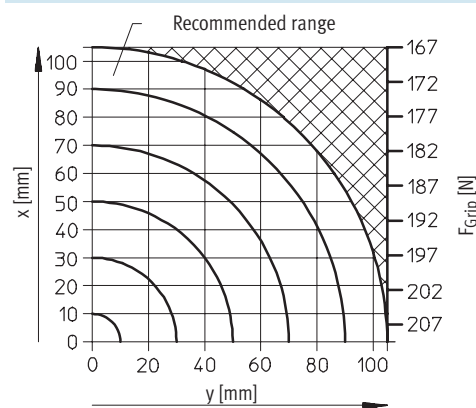
HGPL-14-80-A



HGPL-25-40-A



HGPL-25-80-A



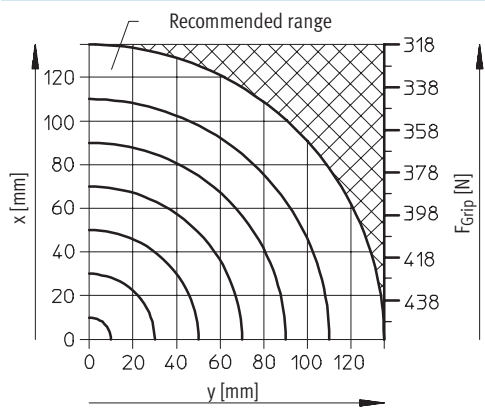
Parallel grippers HGPL, robust, with long stroke

Technical data

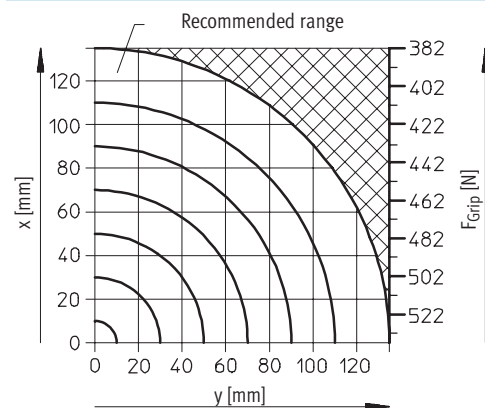


Gripping force F_{Grip} per gripper jaw as a function of lever arm x and eccentricity y

HGPL-40-40-A



HGPL-40-80-A



Handling units

7.0

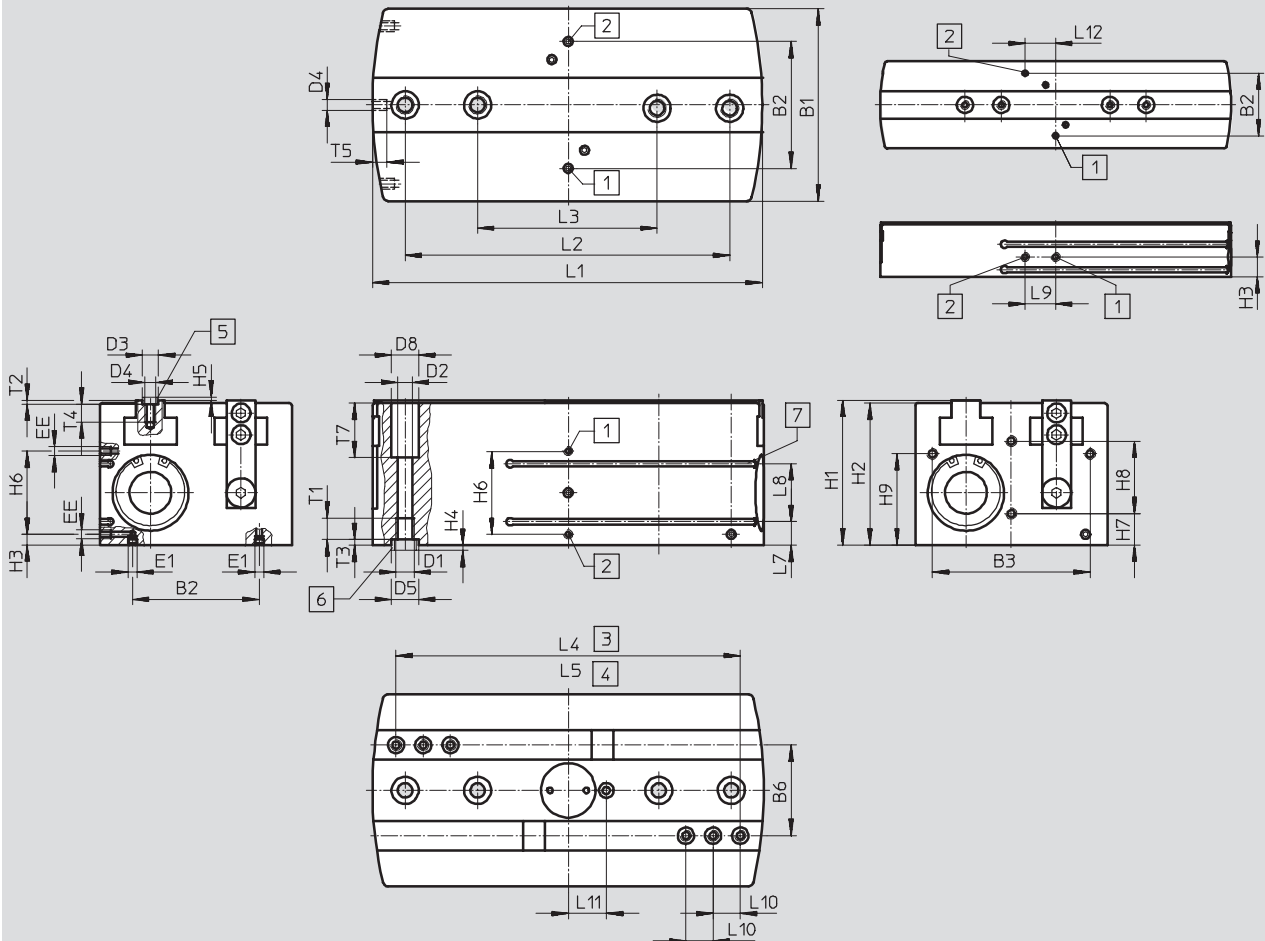
Technical data

Dimensions

Handling units

7.0

Size 14/25



- | | | | | | | | |
|---|--|---|--|---|--|---|--|
| 1 | Compressed air connection opening, either on the side or bottom (bottom connection sealed on delivery) | 2 | Compressed air connection closing, either on the side or bottom (bottom connection sealed on delivery) | 3 | Gripper jaw open | 6 | Centring sleeves ZBH (2 included in scope of delivery) |
| | | | | 4 | Gripper jaw closed | | |
| | | | | 5 | Centring sleeves ZBH (4 included in scope of delivery) | 7 | Slot for proximity sensor SME/SMT-10 |

Parallel grippers HGPL, robust, with long stroke

Technical data

FESTO

Type	B1 ±0.05	B2 ±0.1	B3 ±0.1	B6 ±0.01	D1	D2 ∅ +0.1	D3 ∅ H8/h7	D4	D5 ∅ H8/h7	D8 ∅ H13	EE	E1
HGPL-14-40	48	34.5	37	22	M5	4.2	5	M3	9	7.4	M5	M3
HGPL-14-80												
HGPL-25-40	80	60	65	38	M6	5.1	7	M5	9	10	M5	M5
HGPL-25-80												
HGPL-40-40	106	70	87	50	M10	8.5	9	M6	15	15	M5	M5
HGPL-40-80												

Type	H1	H2 ±0.1	H3 ±0.1	H4 -0.3	H5 -0.3	H6 ±0.1	H7 ±0.1	H8 ±0.1	H9 ±0.1	L1 ±0.1	L2 ±0.02 ¹⁾ ±0.1 ²⁾	L3 ±0.02 ¹⁾ ±0.1 ²⁾	L4 ±0.5
HGPL-14-40	30	29	11	1.9	1.2	-	10	12	18	113.6	-	60	102
HGPL-14-80										193.6	100	60	182
HGPL-25-40	50	49	18	1.9	1.4	-	18	20	30	126	-	60	104
HGPL-25-80										206	100	60	184
HGPL-40-40	80	78.5	6	2.9	1.9	46	17.5	40	50.5	136	-	100	110
HGPL-40-80										216	180	100	190

Type	L5 ±0.5	L7 ±0.1	L8 ±0.1	L9 ±0.2	L10 ±0.02 ¹⁾ ±0.1 ²⁾	L11 ±0.5	L12 ±0.1	T1 min.	T2 +0.1	T3 +0.1	T4 min.	T5 min.	T7 +0.1
HGPL-14-40	22	4	14	16.8	8	9	16.8	12	1.3	2.1	5	6	10
HGPL-14-80	22												
HGPL-25-40	24	11	14	20	10	17.5	20	12	1.6	2.1	8	7	17
HGPL-25-80	24												
HGPL-40-40	30	13	32	-	15	21	-	15	2.1	3.1	10	8	30
HGPL-40-80	30												

- 1) For centring
2) For through-hole

Handling units

7.0

Parallel grippers HGPL, robust, with long stroke

Technical data

FESTO

Handling units

7.0

Ordering data			
Size [mm]	Stroke [mm]	Double-acting without compression spring	
		Part No.	Type
14			
	40	535 852	HGPL-14-40-A
	80	535 853	HGPL-14-80-A
25			
	40	535 854	HGPL-25-40-A
	80	535 855	HGPL-25-80-A
40			
	40	535 856	HGPL-40-40-A
	80	535 857	HGPL-40-80-A

Ordering data – Wearing parts kits			
Size [mm]		Part No.	Type
14		701 585	HGPL-14
25		701 586	HGPL-25
40		701 587	HGPL-40

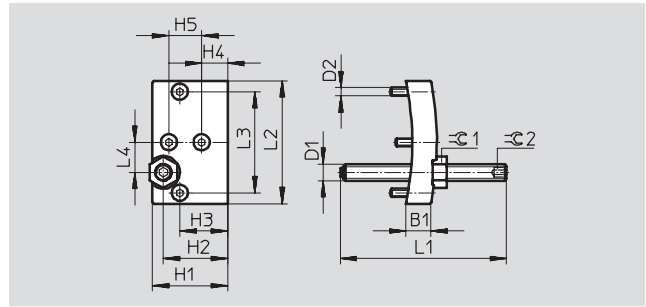
Parallel grippers HGPL, robust, with long stroke

Accessories

FESTO

Stroke reducing plate HGPL-HR

Material:
Aluminium
Free of copper, PTFE and silicone



Dimensions and ordering data								
For size	B1	D1	D2	H1	H2	H3	H4	H5
[mm]	±0.1			±0.1	±0.1	±0.1	±0.1	±0.1
14	9	M6	M3	27.5	23.5	17.5	9.5	12
25	12	M8	M5	47.5	37.5	29.5	17.5	20
40	18	M12	M6	77	63	50	17	40

For size	L1	L2	L3	L4	≈C1	≈C2	Weight	Part No.	Type
[mm]	±1	±0.1	±0.1	±0.1			[g]		
14	61	45	37	11	10	3	45	539 092	HGPL-HR-14
25	61	77	65	19	13	4	150	539 093	HGPL-HR-25
40	61	103	87	25	19	6	455	539 094	HGPL-HR-40

Handling units

7.0

Parallel grippers HGPL, robust, with long stroke

Accessories

FESTO

Unmachined gripper finger

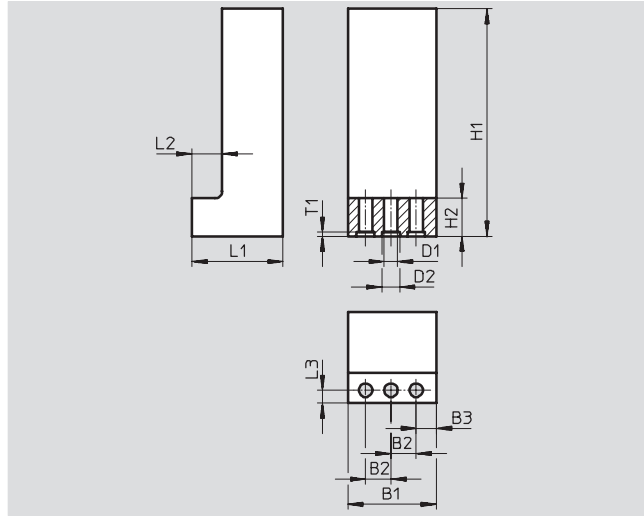
BUB-HGPL

(Scope of delivery: 2 pcs.)

Material:

Aluminium

Free of copper, PTFE and silicone



Dimensions and ordering data							
For size	B1	B2	B3	D1 Ø	D2 Ø	H1 Ø	H2
[mm]	±0.1	+0.02		+0.1	H8	±0.1	
14	25	8	4	3.2	5	80	11
25	35	10	8	5.3	7	120	15
40	50	15	10	6.4	9	150	18

For size	L1	L2	L3	T1	Weight per unmachined gripper finger [g]	Part No.	Type
[mm]	±0.1	+0.1	+0.1	+0.1			
14	20.5	8	3.3	1.3	75	537 316	BUB-HGPL-14
25	36	12	5	1.6	295	537 317	BUB-HGPL-25
40	49.5	16.5	8	2.1	720	537 318	BUB-HGPL-40

Ordering data					
	For size [mm]	Weight [g]	Part No.	Type	PU ¹⁾
Centring sleeve for the gripper jaws ZBH					
			Technical data → 1 / 10.1-3		
	14	1	189 652	ZBH-5	10
	25	1	186 717	ZBH-7	10
	40	1	150 927	ZBH-9	10
Centring sleeve for the gripper ZBH					
			Technical data → 1 / 10.1-3		
	14	1	189 652	ZBH-9	10
	25				
	40	3	191 409	ZBH-15	10
Blanking plug B					
			Technical data → Volume 4		
	14 (at front)	0.6	30 979	B-M3-S9	10
	14, 25, 40	1	174 308	B-M5-B	10

1) Packaging unit quantity

Parallel grippers HGPL, robust, with long stroke

FESTO

Accessories

Ordering data – Proximity sensors for C-slot, magneto-resistive								Technical data➔ 1 / 10.2-57	
	Assembly	Switch output	Electrical connection		Cable length [m]	Connection direction	Part No.	Type	
			Cable	Plug M8					
NO contact									
	Insertable from above	PNP	3-core	–	2.5	In-line	525 915	SMT-10F-PS-24V-K2,5L-OE	
			–	3-pin	0.3	In-line	525 916	SMT-10F-PS-24V-K0,3L-M8D	
						Lateral	526 675	SMT-10F-PS-24V-K0,3Q-M8D	
	Insertable from end	PNP	–	3-pin	0.3	In-line	173 220	SMT-10-PS-SL-LED-24	
			3-core	–	2.5		173 218	SMT-10-PS-KL-LED-24	

Ordering data – Proximity sensors for C-slot, magnetic reed							Technical data➔ 1 / 10.2-60	
	Assembly	Electrical connection		Cable length [m]	Connection direction	Part No.	Type	
		Cable	Plug M8					
NO contact								
	Insertable from above	–	3-pin	0.3	In-line	525 914	SME-10F-DS-24V-K0,3L-M8D	
		3-core	–	2.5	In-line	525 913	SME-10F-DS-24V-K2,5L-OE	
		2-core				526 672	SME-10F-ZS-24V-K2,5L-OE	
	Insertable from end	–	3-pin	0.3	In-line	173 212	SME-10-SL-LED-24	
		3-core	–	2.5		173 210	SME-10-KL-LED-24	

Ordering data – Plug sockets with cable							Technical data➔ 1 / 10.2-114	
	Assembly	Switch output		Connection	Cable length [m]	Part No.	Type	
		PNP	NPN					
Straight socket								
	Union nut M8			3-pin	2.5	159 420	SIM-M8-3GD-2,5-PU	
					5	159 421	SIM-M8-3GD-5-PU	
Angled socket								
	Union nut M8			3-pin	2.5	159 422	SIM-M8-3WD-2,5-PU	
					5	159 423	SIM-M8-3WD-5-PU	

Handling units

7.0

