

Features

## General information

- Piston Ø 8, 12 and 18
- Stroke lengths of 100 ... 900 mm
- Two cushioning types selectable:
- Elastic cushioning

## Direct mounting

- via centering holes
- Extremely flat design
- Built-in precision guide
- High load capacity
- Adjustable end stops
- Versatile supply port options
- Suitable for multiple-axis applications with other mini slides

→ 1 / 3.1-99

**FESTO** 



- Finely-adjustable end stops over entire stroke range
- 2 Guide rail Highly accurate, rigid precision guide unit: stainless steel roller track pressed into aluminum

Interface for attachments. Highly adaptable, thanks to wide choice of mounting and attachment options

With rubber buffers or with shock absorbers. The cushioning elements are inserted into the slide and fixed.

- 6 Slot
  - for integrateable proximity sensors SME-/SMT-10

#### Design

#### The flat linear drive SLG

The height H remains the same even if the intermediate position module is used.



x Height (H) Piston  $\varnothing$ Width (B) 8 mm 53.5 x 15 mm 12 mm 64.5 x 18.5 mm 18 mm 85.5 x 25.5 mm

#### Mounting and assembly options

#### Drive

- 1 Through-holes
- 3 Locating hole for centering pin ZBS

### Slide

- 2 Threaded holes
- 3 Locating hole for centering pin ZBS



Features

### Intermediate positions - simple and inexpensive

- The intermediate position module can be used for advancing to one or more intermediate positions
- It is mounted parallel to the linear drive SLG via an additional mounting rail. This means that it can also be easily retrofitted.
- Fine adjustment of the intermediate position is effected via a stop screw with lock nut

#### In combination with linear drive SLG

- With two modules the same position can be approached from either direction
- The intermediate positions can be freely selected across the entire stroke range (observe minimum distances)
- The module's symmetry means that it can advance to its right or left once mounted
- It can be activated and sensed before the movement starts
- Integratable proximity switches in the module housing mean that the intermediate position (activated or initial position) can be sensed contactlessly
- Up to 4 modules can be ordered via the SLG modular product system

#### → 1 / 3.1-110

FESTO

The slide must be retracted once the intermediate position is reached. The stop on the module can then swivel back into its initial position



# - Note

The intermediate position module can also be used independently of the linear drive SLG. It is simply mounted on any even surface using mounting screws and locating pins and can then be used universally as an autonomous intermediate position module in numerous applications.

- Shock absorber retainer SLG-D The retainer accepts rubber buffers or shock absorbers and is attached to the slide of the SLG. The use of shock absorber YSRG (Accessories → 1 / 3.1-119) is recommended to ensure accurate positioning of stops and in the case of vertical assembly positions.
- 2 Intermediate position module SLG-Z

The stop with cushioning screw is retracted and extended by means of a 90° swivel motion based on a double-acting rotary drive (rack and pinion principle). The module is fastened to the mounting rail using screws and slot nuts.

#### 3 Mounting rail SLG-S

The rail is used for mounting the intermediate position modules. It can also accept the end stops of the linear drive SLG. The gear teeth on the rail and module permit rough preadjustment with respect to the drive part of the SLG.

Completely assembled with two intermediate positions



- 1 Linear drive SLG
- 2 Intermediate position module
- 3 Shock absorber retainer
- 4 Mounting rail
- 5 End stop



System elements and accessories					
	Туре	Brief description	→ Page		
1	Drives	Diverse possible combinations in handling and assembly technology	Volume 1		
2	Grippers	Diverse variation options in handling and assembly technology	Volume 1		
3	Adapters	For drive-drive and drive-gripper connections	Volume 5		
4	Basic components	Profiles and profile connections	Volume 5		
5	Proximity sensors	For position sensing	Volume 1		
6	Multi-pin plug distributor	For bundling individual cables to form a multi-pin cable	Volume 2		

3.1

# Linear drives SLG, flat design Peripherals overview



Туре	Brief description	→ Page
Linear drive	Drive without accessories	1/3.1-101
SLG		
Centering pin	For centering loads and attachments on the slide	1/3.1-119
ZBS		
Shock absorber retainer	For fastening the rubber buffers or shock absorbers in combination with the intermediate	1/3.1-117
SLG-D	position	
] Cushioning	Non-adjustable, elastic cushioning. Used only at low speeds	1/3.1-119
Р		
] Cushioning	Self-adjusting hydraulic shock absorber with return spring and linear cushioning	1/3.1-119
YSR	characteristic	
] Mounting rail	For fastening the intermediate position modules and end stops	1/3.1-118
SLG-S		
Intermediate position module	Fixed stop for the intermediate position	1/3.1-117
SLG-Z		
] One-way flow control valve	The small distance between the supply ports means that only certain one-way flow control	1/3.1-107
GRLA	valves can be used	
Proximity sensors	The proximity switches are fitted in the profile slot. The switches therefore do not project	1/3.1-120
SME-/SMT-10		

# Linear drives SLG, flat design Type codes



Data sheet





General technical data					
Piston $\varnothing$		8	12	18	
Stroke <sup>1)</sup>	[mm]	100 500	100 700	100 900	
Pneumatic connection		M3	·	M5	
Mode of operation		Double-acting			
Operating medium		Filtered compressed air, lubricated or u	nlubricated		
Constructional design		Rodless drive			
Cushioning		Not adjustable at either end			
→1/3.1-104		Self-adjusting at both ends			
Position sensing Via proximity sensors					
Type of mounting		Direct mounting			
Mounting position		Any			
Driver principle Slotted cylinder, me		Slotted cylinder, mechanically coupled	ted cylinder, mechanically coupled		
Guide	Guide rail with slide				
Max. speed	[m/s]	1		1.5	

1) Intermediate strokes are infinitely adjustable with stops.

Operating and environmental conditions					
Piston $\varnothing$		8	12	18	
Operating pressure	[bar]	2.5 8	2 8	1 8	
Ambient temperature <sup>1)</sup> [°C] –10 +60					

1) Note operating range of proximity switches.

Forces [N]				
Piston $\varnothing$	8	12	18	
Theoretical force at 6 bar	30	68	153	

Weights [g]				
Piston $\varnothing$	8	12	18	
Basic weight per 0 mm stroke with P cushioning	215	410	965	
Basic weight per 0 mm stroke with YSR cushioning	225	420	995	
Additional weight per 10mm stroke	11.5	17.5	29.5	
Moving load with P cushioning	80	160	440	
Moving load with YSR cushioning	90	170	470	

## Materials

Sectional view



Cylin	Cylinder				
1	Profile barrel	Anodized aluminum			
2	Guide	Stainless steel			
3	Slide	Stainless steel			
4	Stop sleeve	Anodized aluminum			
-	Seals	Polyurethane			
	Material note	Free of copper and PTFE			

3.1

Data sheet

## Characteristic load values

The forces and torques specified refer to the centre of the guide rail.



If the drive is subjected to several of the indicated forces and torques simultaneously, the following equations must be satisfied in addition to the indicated maximum loads:

$$\frac{Fy}{Fy_{max.}} + \frac{Fz}{Fz_{max.}} + \frac{Mx}{Mx_{max.}} + \frac{My}{My_{max.}} + \frac{Mz}{Mz_{max.}} \le 1$$

Torsional backlash [°] at the respective torques					
Piston $\varnothing$	8	12	18		
at Mx <sub>max.</sub>	±0.03	±0.04	±0.05		
at My <sub>max.</sub>	±0.005	±0.007	±0.007		
at Mz <sub>max.</sub>	±0.005	±0.007	±0.007		



Selection and ordering aid ProDrive www.festo.com/en/engineering

Data sheet

Maximum permissible piston speed v as a function of useful load m when the unit is operated horizontally As a function of operating pressure and end-position cushioning system

A linear drive SLG with YSR cushioning (YSRG shock absorbers) must be used in applications requiring very high repetition accuracy.



### Cushioning P



### YSR cushioning



Data sheet



### Flatness of the bearing surface

Contact surfaces which support the linear drive SLG should be no farther than 100 mm apart, or over its entire length and should be flat to within at

least 0.1 mm. The support surface for the load on the slide should be flat to within at least 0.05 mm.

Mechanically coupled **Rodless cylinders** 

3.1



Minimum clearances for li	near drives S	G to ferrite materials for reliable proxim	ity switch functioning	
		Slot 1Slot 2	Minimum clearances in mm	
		Slot	Х	У
🗆 চন্দ্র	SLG-8	1	5	-
		2	5	-
	SLG-12	1	6	-
		2	5	-
ЦĘЯ	SLG-18	1	5	-
_ <b>_</b> X		2	5	-
NFU 🗆	SLG-8	1	5	-
		2	10	-
<b>6</b>	SLG-12	1	5	-
		2	6	-
	SLG-18	1	5	-
		2	5	-
	SLG-8	1	7	-
		2	10	-
	SLG-12	1	10	-
@[		2	10	-
	SLG-18	1	5	-
		2	5	-
TUTU	SLG-8	1	14	-
		2	12	-
	SLG-12	1	16	-
		2	1	-
	SLG-18	1	2	-
		2	2	-
NTUT	SLG-8	1	7	-
		2	17	-
	SLG-12	1	1	-
		2	17	-
	SLG-18	1	1	-
		2	12	-
	SLG-8	1	11	17
ѷ҄҄҄҄Ӊ <b>ӏ҉ѽ</b> ӏӏӏ		2	15	17
	SLG-12	1	7	16
•••••		2	10	16
	SLG-18	1	5	12
_, , <b>_</b> _		2	5	12

Data sheet



In general		
The following spanner widths can be	SLG-8:	=© 5.5 8
used on the external surface and	SLG-12:	=© 5.5 8
front side:	SLG-18:	=© 810

#### Restrictions on the front sides

The threaded connectors protrude from the top or bottom of the profile with compressed air connections at both ends. The connector threads are too close to one another for the threaded fittings with compressed air connections at one end only.

For this reason, the following	SLG-8:	=C 8
spanner widths can only be used in	SLG-12:	=© 8
certain conditions:	SLG-18:	=© 10

3.1

Data sheet



Slide SLG-18



### 1 Supply port, external surface

2 Supply port, front side

- 3 Slot for proximity sensor SME-/SMT-10
- 4 Stop
- 5 Shock absorber YSR or rubber buffer (P cushioning)

# Linear drives SLG, flat design Data sheet

	B1	B2	B3	B4	B5	B6	B7	D1 <sup>1)</sup> Ø H7	D2 Ø	D3 <sup>1)</sup> Ø H7	D4	EE	H1	H2	H3	H4	H5	H6	H7
SLG-8	15	2.5	6.6	4.4	7.5	0.65	3.5	2	3.4	3	M4	M3	53.5	0.5	13	13.6	8.8	3.9	25
SLG-12	18.5	2.6	7.9	5.2	8.5	0.5	4.75	2	3.4	3	M4	M3	64.5	0.5	15.9	16.5	9.5	4.3	30
SLG-18	25.5	3.5	13.3	8	13.2	1.6	5.4	5	4.5	5	M5	M5	85.5	0.5	19.8	21.7	11.5	4.1	40
	H8	H9	n	L1	L2	L3	L4	L5	L6	L7	L8	L9 min.	L10	T1	T2 min.	T3	-©1	-©2	-©3
SLG-8-100 SLG-8-200			0	207 307		127 227													
SLG-8-200	4.4	31	2	407	43.5	327	10	5	10	20	62	20	2	2.5	4	4.5	5.5	1.5	1.5
SLG-8-400	7.7	51	2	507	-J.J	427	10	,	10	20	02	20	2	2.5	7	ч. <b>у</b>	5.5	1.5	1.5
SLG-8-500			4	607		527													
SLG-12-100			0	233		153													
SLG-12-200			1	333		253													
SLG-12-300			2	433		353													
SLG-12-400	5.25	36.7	3	533	56.5	453	10	5	10	20	80	36.5	2	2.5	4	4.5	7	2	2
SLG-12-500			4	633		553													
SLG-12-600			5	733		653													
SLG-12-700 SLG-18-100			6	833		753													
SLG-18-100 SLG-18-200			0	271 371		191 291													
SLG-18-300			2	471		391													
SLG-18-400	-		3	571		491													
SLG-18-500	8	48.5	4	671	75.5	591	12	6	13	24	105	29	3	3	5	6	8	2.5	2.5
SLG-18-600	1		5	771		691													
SLG-18-700	1		6	871		791													
SLG-18-800	1		7	971		891													
SLG-18-900			8	1071		991													

1) Locating hole for ZBS centering pins

FESTO



......

1.



General technical data										
Piston $\varnothing$		8	12		18					
Pneumatic connection		M3								
Mode of operation		Double-acting	Double-acting							
Operating medium		Filtered compressed air, lubricated	Filtered compressed air, lubricated or unlubricated							
Constructional design		Stop in the form of a semi-rotary d	evice in accordance with the r	rack and pinion pri	nciple					
Fine adjustment of the	[mm]	1.7								
intermediate position										
Cushioning <sup>1)</sup>		→1 / 3.1-104								
Position sensing		Via proximity sensors								
Type of mounting		Direct mounting								
Assembly position <sup>2)</sup>		Any								
Min. swivel time	[ms]	30			50					
at 6 bar										
Max. frequency	[1/s]	16			10					
at 6 bar										
Max. permissible impact	[m/s]	1			1.5					
velocity										
Max. perm. end-stop impact force <sup>3)</sup>	[N]	320			600					

1) The end position of the slide or another drive is not exactly defined when rubber buffers are used. Shock absorbers YSRG-... must be used for high repetition accuracy.

2) Shock absorbers YSRG-... must be used for high repetition accuracy as well as in non-horizontal movements.

With vertical installation (where the stop moves upwards), it must be ensured that no foreign objects enter the swivel range of the stop.

3) The max. stop force must act on the centre of the cushioning screw disk. Lateral forces on the cushioning screw are not permissible.

Operating and environmental conditions									
Piston $\varnothing$		8	12	18					
Operating pressure	[bar]	1 8							
Ambient temperature <sup>1)</sup>	[°C]	-10 +60							

Max. permissible energy in the intermediate position										
Piston $\varnothing$		8	12	18						
With P cushioning	[Nm]	0.1		0.6						
With YSR cushioning	[Nm]	1		3						



### Materials

Sectional view



### Intermediate position module

1 Housing	Hard anodized aluminum
2 Stop	Nickel plated steel
3 Cushioning screw	High-alloy steel
– Seals	Polyurethane

Mounting options on linear drive						
Piston Ø		8	12	2	18	
Through-holes for direct mounting with screws to DIN 912	Intermediate position module	ate position M2.5			M3	
	Shock absorber retainer	M4			M5	
	Mounting rail	M3			M4	
Centering pins	Intermediate position module	Ø 4H7			Ø 5H7	
	Shock absorber retainer	Ø 2H7			Ø 5H7	
	Mounting rail	Ø 3H7			Ø 5H7	

-- Note

The module's symmetric design makes it suitable for both approach directions.

## **FESTO**



Туре	B1	H10	L1
SLG-8-100			207
SLG-8-200		F	307
SLG-8-300	15	93.1	407
SLG-8-400		F	507
SLG-8-500		Γ	607
SLG-12-100			233
SLG-12-200			333
SLG-12-300		Γ	433
SLG-12-400	18.5	104.1	533
SLG-12-500			633
SLG-12-600		Γ	733
SLG-12-700			833
SLG-18-100			271
SLG-18-200			371
SLG-18-300			471
SLG-18-400			571
SLG-18-500	25.5	135.5	671
SLG-18-600		F	771
SLG-18-700			871
SLG-18-800		Γ	971
SLG-18-900			1071

Products 2004/2005 - Subject to change - 2003/10



Piston $\varnothing$	L3	1)	L4
	min.	max.	
8 <sup>2)</sup>	21	27	68
12	39	45	86
18	50	56.5	111

1) Depends on the fine adjustment

2) Due to the narrowness of the space L3 only the following threaded connectors can be used for the compressed air connections: 30 491 LCN-M3-PK-2-B

#### Two positions approached from the same direction





The space for 2 intermediate positions can be reduced to 0 mm by turning the second module by 90° in the same plane (→ 1 / 3.1-115).

Piston Ø	L5	L6 <sup>3)</sup>
	min.	
8	90	32
12	90	
18	97	

3) The space between the modules is such that the following threaded connectors can be used for the compressed air connections:

153 330 QSML-M3-3

153 332 QSML-M3-4

30 491 LCN-M3-PK-2-B

30 984 LCN-M3-PK-2

#### Space between end stop and intermediate position module



Piston Ø	11
	min.
8	20
12	
18	

Technical data – Intermediate position module SLG-Z

## FESTO



the intermediate position to ensure safe inward or outward swivelling of the stop ( $\rightarrow$  1 / 3.1-115).

Piston Ø	H1	L7		
		Cushioning P	YSR cushioning	
8	11	18	23	
12	11	18	23	
18	16	23	31	

### Maximum number of intermediate position modules on one mounting rail

The number of intermediate position modules that can be ordered via the linear drive SLG modular product system is restricted to max. 4. If additional intermediate positions are required, further modules can be ordered separately ( $\rightarrow$  1 / 3.1-117) and fitted in another mounting plane.

Ρ	iston Ø	Stroke length	n of the mount	ing rail [mm]						
		100	200	300	400	500	600	700	800	900
8		2		3	4		-	-	-	-
1	2						4		-	-
1	8								4	

## **FESTO**

Rodless cylinders Mechanically coupled



# Linear drives SLG, flat design Ordering data – Modular product system

M Mandatory	/ data									0 Options
Module No.	Drive function	Size		Stroke		Cushioning		Position sensing		Intermediate position
187 857	SLG	8		100 900		Р		A		Z1
187 855		12				YSR				Z2
187 853		18								Z3
										Z4
Ordering										
example		_								
187 853	SLG	- 18	-	800	-	Р	-	Α	-	Z4

Ordering table

0.	uering table							
Siz	ze		8	12	18	Condi- tions	Code	Enter code
М	Module No.		187 857	187 855	187 853			
	Drive function		Rodless linear drive unit				SLG	SLG
	Size	[mm]	8	12	18			
	Stroke	[mm]	100	100	100	1	-100	
			200	200	200	1	-200	
			300	300	300	2	-300	
			400	400	400		-400	
			500	500	500		-500	
			-	600	600		-600	
			-	700	700		-700	
			-	-	800		-800	
			-	-	900		-900	
	Cushioning		Flexible cushioning rings in	the end positions			-P	
			Shock absorbers in the end	positions			-YSR	
	Position sensing		Via proximity sensors				-A	-A
0	Intermediate position		1 intermediate position				-Z1	
			2 intermediate positions				-Z2	
			3 intermediate positions				-Z3	
			4 intermediate positions				-Z4	

1 100, 200 2 300 Max. 2 intermediate positions.

Max. 3 intermediate positions.



Accessories

### Intermediate position module SLG-Z





Dimensions and ordering data



1 Air connections on both sides 2 Slot for proximity sensor SME-/SMT-10

For $\varnothing$	B1	B2	D1	D2 Ø	D3 Ø	H1	H2	H3	HZ	4	H5	H6	H7	L1
				H7										+0.3
8,12	10.8	4.8	M3	4	8	26.6	16.2	4	6		9.5	3.5	36.6	55
18	15.6	4.8	M3	5	10	29.6	19.2	-	9.6	6	11.5	4.3	44.2	62
For $\varnothing$	L2	L3	L4	L6	L7	L8		L9		Weig	ghts	Part No.	Гуре	
	±0.1	±0.1	±0.02				mi	n.	max.	[g]				
8,12	50.5	40	36	10	24.4	9.2	5 2.	5	4.2	39.5	5	525 680	SLG-Z-8/12-	A
18	57.5	50	50	-	21.6	12	3.	.7	5.4	89.5	5	525 681	SLG-Z-18-A	

Shock absorber retainer SLG-D

Material: Hard anodized aluminum





1 Rubber buffer or shock absorber

Dimensions a	imensions and ordering data													
For Ø	B1	B2	D1 Ø H7/h8	D2	D3 Ø	H1	H2	H3 -0.1						
8 12	- 11.5	5	2	M4	<b>7.5</b> <sub>+0.05</sub>	10	5.4	4.1						
18	17	8	5	M5	10+0.02	15	7.5	7.75						

For $\varnothing$	H4	H5	L1	L2	L3	T1	Weights	Part No. Type
				±0.02			[g]	
8	2.25	4.8	62	20	2	26	17/27.5 <sup>2)</sup>	525 703 SLG-D-8 <sup>1)</sup>
12	2.25	4.0	80	20	ر	20	22.5/33 <sup>2)</sup>	525 704 SLG-D-12 <sup>1)</sup>
18	2	4.7	105	60	3	43	60/104 <sup>2)</sup>	525 705 SLG-D-18 <sup>1)</sup>

1) Shock absorber elements are not included in the scope of delivery

2) With P cushioning/with YSR cushioning

### Mounting rail SLG-S







Dimension	s and ordering	g data																		
For Ø	Stroke	B1	B2	B3	D1 Ø	D2 Ø	D3 Ø	H1	H2	H3	n	L1	L2	L3	Weights	Part No.	Туре			
	[mm]				H7										[g]					
8	100										0	207	127		73.5	525 682	SLG-S-8-100			
	200										1	307	227		109	525 683	SLG-S-8-200			
	300	39.6	32	3.4	3	3.4	6	4.8	3.5	0.9	2	407	327	43.5	144.5	525 684	SLG-S-8-300			
	400										3	507	427		180	525 685	SLG-S-8-400			
	500										4	607	527		215.5	525 686	SLG-S-8-500			
12	100										0	233	153		110.4	525 687	SLG-S-12-100			
	200										1	333	253		157.8	525 688	SLG-S-12-200			
	300	39.6 3									2	433	353		205.2	525 689	SLG-S-12-300			
	400		39.6	32	4.1	3	3.4	6	7.2	1.9	1.9	3	533	453	56.5	252.6	525 690	SLG-S-12-400		
	500								1							4	633	553		300
	600										5	733	653		347.4	525 692	SLG-S-12-600			
	700										6	833	753		394.8	525 693	SLG-S-12-700			
18	100										0	271	191		245.6	525 694	SLG-S-18-100			
	200										1	371	291		336.2	525 695	SLG-S-18-200			
	300										2	471	391		426.8	525 696	SLG-S-18-300			
	400										3	571	491		517.4	525 697	SLG-S-18-400			
	500	50	40	4.75	5	4.5	7.5	10.3	9	2.5	4	671	591	75.5	608	525 698	SLG-S-18-500			
	600										5	771	691		698.6	525 699	SLG-S-18-600			
	700										6	871	791		789.2	525 700	SLG-S-18-700			
	800										7	971	891		879.8	525 701	SLG-S-18-800			
	900										8	1071	991		970.4	525 702	SLG-S-18-900			

Rubber buffer SLG



Ordering data			
For $\varnothing$	Weights	Part No.	Туре
	[g]		
8,12	1.5	379 802	SLG-8/12
18	6	381 219	SLG-18

Shock absorber YSRG



Ordering data			
For $\varnothing$	Weights	Part No.	Туре
	[g]		
8,12	7	381 042	YSRG-5-5-C
18	27	384 581	YSRG-8-8-C

### Centering pin ZBS

Material: Stainless steel





Dimensions and	d ordering data					
For $\varnothing$	B1	D1	Weights	Part No.	Туре	PE <sup>1)</sup>
		Ø				
[mm]	-0.2	h8	[g]			
8,12	5	2	1	525 273	ZBS-2	10
18	5	5	1	150 928	ZBS-5	10

1) Packaging unit quantity

Core Range

### FESTO

	Mounting	Electrical cor	nnection	Swi	tch	Cable length	Connection	Part No.	Туре
	mounting			out		cubic tengin	direction	. are not	.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,
		Cables	M8 plu		put	[m]	uncenon		
) contact				0					
	Inserted from	3 wires	-	PN	)	2.5	In-line	525 915	SMT-10F-PS-24V-K2,5L-OE
a la	above	-	3-pin	PN		0.3	In-line	525 916	SMT-10F-PS-24V-K0,3L-M8D
			5 p			0.5	Lateral	526 675	SMT-10F-PS-24V-K0,3Q-M8D
0/-	Flush fitting	_	3-pin	PN	)	0.3	In-line	173 220	SMT-10-PS-SL-LED-24
	1 40011 114113	3 wires				2.5		173 218	SMT-10-PS-KL-LED-24
dering da	ata – Proximity sens	or for slot 10, n	nagnetic re	ed					Technical data 🗲 1 / 10.2
	Mounting	Electrical con	nnection			Cable length	Connection	Part No.	Туре
							direction		
		Cables		M8 plug		[m]			
contact									
R	Inserted from	-		3-pin		0.3	In-line	525 914	SME-10F-DS-24V-K0,3L-M8D
	above	3 wires		-		2.5	In-line	525 913	SME-10F-DS-24V-K2,5L-OE
		2 wires						526 672	SME-10F-ZS-24V-K2,5L-OE
N	Flush fitting	3 wires		-		0.3	In-line	173 212	SME-10-SL-LED-24
		-		3-pin		2.5		173 210	SME-10-KL-LED-24
dering da	ata – Plug sockets						_	_	Data sheets 🗲 1 / 10.2-1
	Mounting	Switch outpu	ut			Connection	Cable length	Part No.	Туре
		PNP		NPN			[m]		
aight plu	-	-				-	-		
	M8 union nut	-		_		3-pin	2.5	159 420	SIM-M8-3GD-2,5-PU
							5	159 421	SIM-M8-3GD-5-PU
مامما بماريب									
gled plug						2 min	2.5	150 (22	
	M8 union nut	-		-		3-pin	2.5	159 422	SIM-M8-3WD-2,5-PU
							5	159 423	SIM-M8-3WD-5-PU
6									
5	0 m a	antral							Tooknight data NV/
dering da	ta – One-way flow	control valves				Material		Part No.	Technical data → Volum Type

Metal design

3.1

Core Range

М3

M5

3

4

175 041 GRLA-M3-QS-3

193 138 GRLA-M5-QS-4-D