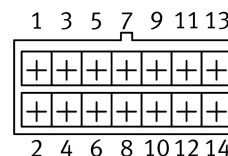
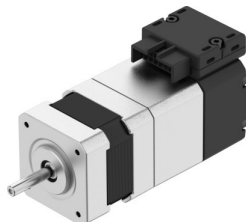


Stepper motor EMMB-ST-42-S-SMB

Part number: 8156130

FESTO



Data sheet

Feature	Value
Ambient temperature	0 °C...40 °C
Note on ambient temperature	up to 80°C with derating -2%/°C
Max. installation height	4000 m
Information on max. installation height	with 1,000 m and longer only with derating of -1.0% per 100 m
Storage temperature	-20 °C...70 °C
Relative air humidity	0 - 90 % Non-condensing
Conforms to standard	IEC 60034
Thermal class according to EN 60034-1	B
Max. winding temperature	130 °C
Rating class according to EN 60034-1	S1
Temperature monitoring	Dig. motor temp. via BiSS-C
Motor type as per EN 60034-7	IM B5 IM V1 IM V3
Mounting position	Any
Degree of protection	IP20
Note on degree of protection	IP40 for motor shaft without rotary shaft seal
Interface code, motor out	42A
Electrical connection 1, connection type	Hybrid plug
Electrical connection 1, connection technology	Connection diagram L5
Electrical connection 1, number of pins/wires	14
Note on materials	RoHS-compliant
Corrosion resistance class (CRC)	0 - No corrosion stress
LABS (PWIS) conformity	VDMA24364 zone III
Vibration resistance	Transport application test with severity level 2 as per FN 942017-4 and EN 60068-2-6
Shock resistance	Shock test with severity level 2 as per FN 942017-5 and EN 60068-2-27
Certification	RCM compliance mark
CE marking (see declaration of conformity)	As per EU EMC directive As per EU RoHS directive
UKCA marking (see declaration of conformity)	To UK instructions for EMC To UK RoHS instructions

Feature	Value
Nominal operating voltage DC	48 V
Number of pole pairs	50
Motor holding torque	250 Nm
Nominal torque	240 Nm
Peak torque	250 Nm
Nominal rotary speed	600 rpm
Max. rotational speed	2700 rpm
Max. mechanical speed	9000 rpm
Step angle with full step	1.8 deg
Step angle tolerance	±5%
Motor nominal power	17 W
Continuous stall current	2 A
Motor nominal current	1800 A
Peak current	2 A
Motor constants	133 Nm/A
Voltage constant, phase	12100 mVmin
Phase winding resistance	2100 Ohm
Winding inductance phase	3 mH
Winding longitudinal inductivity Ld (phase)	1600 mH
Cross inductivity Lq (phase)	3 mH
Electric time constant	1400 ms
Thermal time constant	22 min
Thermal resistance	3500 K/W
Measuring flange	200 x 200 x 15 mm, steel
Total output inertia moment	0.043 kgcm ²
Product weight	520 g
Permissible axial shaft load	10 N
Permissible radial shaft load	28 N
Rotor position sensor	Absolute encoder, multi-turn
Rotor position sensor for manufacturer designation	KCD-BC33B-1617-JP4F-GRQ-009
Rotor position encoder for absolutely detectable revolutions	65536
Rotor position sensor interface	BiSS-C
Rotor position sensor measuring principle	Magnetic
Rotor position encoder for DC operating voltage	5 V
Rotor position encoder for DC operating voltage range	4500 V...5500 V
Rotor position encoder, sinusoidal/cosinusoidal periods per revolution	2
Rotor position encoder for positional values per revolution	131072
Rotor position sensor resolution	17 bit
Rotor position encoder system accuracy angle measurement	-310 arcsec...310 arcsec
Brake holding torque	630 Nm
Brake DC operating voltage	24 V
Brake current consumption	340 A
Brake power consumption	8200 W
Brake coil resistance	70900 Ohm
Brake coil inductivity	146 mH
Brake separation time	28 ms
Brake closing time	41 ms
DC brake response delay	8 ms
Max. brake no-load speed	9000 rpm
Max. brake friction work	1500 J
	1
Brake mass moment of inertia	0.006 kgcm ²
Switching cycles, holding brake	10 million idle actuations (without friction work!)

Feature	Value
MTTF, subcomponent	20 years, rotor position encoder