



Data sheet

Max. interchangeability Max. gripper jaw angular play ax, ay Max. gripper jaw backlash Sz Rotational symmetry Pneumatic gripper repetition accuracy Number of gripper jaws Actuator system Mounting position Mode of operation Gripper function	2 mm 0.2 mm 0 deg 0 mm 0.2 mm 0.2 mm
Max. interchangeability Max. gripper jaw angular play ax, ay 0 Max. gripper jaw backlash Sz 0 Rotational symmetry 0 Pneumatic gripper repetition accuracy Number of gripper jaws 2 Actuator system Mounting position Mode of operation Gripper function	0.2 mm 0 deg 0 mm 0.2 mm 0.02 mm
Max. gripper jaw angular play ax, ay Max. gripper jaw backlash Sz Rotational symmetry Pneumatic gripper repetition accuracy Number of gripper jaws Actuator system Mounting position Mode of operation Gripper function O O O O O O O O O O O O O	O deg O mm O.2 mm O.02 mm
Max. gripper jaw backlash Sz Rotational symmetry O. Pneumatic gripper repetition accuracy Number of gripper jaws Actuator system Mounting position Mode of operation Gripper function O Rotational Symmetry O O O O O O O O O O O O O	0 mm 0.2 mm 0.02 mm
Rotational symmetry 0. Pneumatic gripper repetition accuracy 0. Number of gripper jaws 2 Actuator system Price Mounting position Armode of operation Dripper function Price Gripper	0.2 mm 0.02 mm
Pneumatic gripper repetition accuracy Number of gripper jaws 2 Actuator system Mounting position Mode of operation Gripper function Diagram Page 100 Page 200 Page 200	D.02 mm
Number of gripper jaws 2 Actuator system Promotion Armonic Mode of operation Dripper function Promotion Pr	2
Actuator system Production And Mode of operation Drapper function Production	
Mounting position And Mode of operation Gripper function Page 19 19 19 19 19 19 19 19 19 19 19 19 19	
Mode of operation Digripper function Page 1971	Pneumatic
Gripper function Pa	Any
The second secon	Double-acting
	Parallel
Gripping force backup W	Nithout
Le Si	Connection direction at side Lever Standard mounting type for gripper fingers Positively driven motion sequence
Guide Ba	Ball guide
Position sensing Fo	For proximity sensor
e) pl	Metals with copper, zinc or nickel by mass as main constituent are excluded from use. Exceptions are nickel in steel, chemically nickel- plated surfaces, printed circuit boards, cables, electrical plug connectors and coils.
1.	0.15 MPa0.8 MPa 1.5 bar8 bar 21.75 psi116 psi
Max. operating frequency of pneumatic gripper 3	3 Hz
Min. opening time at 6 bar 9	9 ms
Min. closing time at 6 bar 1	11 ms
Operating medium Co	Compressed air as per ISO 8573-1:2010 [7:4:4]
Information on operating and pilot media O	compressed an as per 150 657 5-1:2010 [7:4:4]
Corrosion resistance class (CRC) 0	Operation with oil lubrication possible (required for further use)
LABS (PWIS) conformity	

Feature	Value
Suitability for the production of Li-ion batteries	Product corresponds to Festo's internal product definition for use in battery production: Metals with more than 1% by mass of copper, zinc or nickel are excluded from use. The exceptions are nickel in steel, chemically nickel-plated surfaces, circuit boards, cables, electrical plug connectors and coils
Ambient temperature	-10 °C60 °C
Gripping force per gripper jaw at 6 bar, opening	14.6 N 7.3 N
Gripping force per gripper jaw at 6 bar, closing	11 N 5.5 N
Mass moment of inertia	0.011 kgcm²
Maximum force on gripper jaw Fz, static	22 N
Maximum torque on gripper jaw, Mx static	0.24 Nm
Maximum torque on gripper jaw, My static	0.11 Nm
Maximum torque on gripper jaw, Mz static	0.11 Nm
Product weight	25 g
Type of mounting	Direct mounting via through-hole Direct fastening via thread Optionally:
Pneumatic connection	M3
Note on materials	RoHS-compliant
Housing material	Aluminum, anodized
Gripper jaw material	High-alloy stainless steel