Radial gripper HGRT-25-A-G2 Part number: 563909

Data sheet

| Feature | Value |
|---|--|
| Size | 25 |
| Max. interchangeability | 0.2 mm |
| Max. gripper jaw angular play ax, ay | 0.1 deg |
| Max. opening angle | 180 deg |
| Rotational symmetry | 0.2 mm |
| Pneumatic gripper repetition accuracy | 0.02 mm |
| Number of gripper jaws | 2 |
| Mounting position | Any |
| Mode of operation | Double-acting |
| Gripper function | Radial |
| Gripping force backup | During closing |
| Structural design | Positively driven motion sequence |
| Position sensing | For proximity sensor For inductive proximity sensors |
| Operating pressure | 4 bar8 bar |
| Max. operating frequency of pneumatic gripper | 3 Hz |
| Min. opening time at 6 bar | 443 ms |
| Min. closing time at 6 bar | 301 ms |
| Operating medium | Compressed air as per ISO 8573-1:2010 [7:4:4] |
| Information on operating and pilot media | Operation with oil lubrication possible (required for further use) |
| Corrosion resistance class (CRC) | 1 - Low corrosion stress |
| LABS (PWIS) conformity | VDMA24364-B1/B2-L |
| Ambient temperature | 5 °C60 °C |
| Mass moment of inertia | 2.33 kgcm ² |
| Maximum force on gripper jaw Fz, static | 180 N |
| Maximum torque on gripper jaw, My static | 10 Nm |
| Maximum torque on gripper jaw, Mz static | 1 Nm |
| Relubrication interval for guidance elements | 10 MioCyc |
| Product weight | 610 g |
| Type of mounting | With internal thread and centering sleeve |
| Pneumatic connection | M5 |
| Note on materials | RoHS-compliant |

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| Feature | Value |
|----------------------|---|
| Housing material | Wrought aluminum alloy, smooth-anodized |
| Gripper jaw material | Hardened steel |