Three-point gripper HGDT-25-A Part number: 540859







Data sheet

| Feature | Value |
|--|--|
| Size | 25 |
| Stroke per gripper jaw | 3 mm |
| Max. interchangeability | 0.2 mm |
| Max. gripper jaw angular play ax, ay | 0.1 deg |
| Max. gripper jaw backlash Sz | 0.05 mm |
| Rotational symmetry | 0.2 mm |
| Pneumatic gripper repetition accuracy | 0.03 mm |
| Number of gripper jaws | 3 |
| Mounting position | Any |
| Mode of operation | Double-acting |
| Gripper function | 3-point |
| Structural design | Inclined plane Positively driven motion sequence |
| Position sensing | For proximity sensor |
| Gripping force per gripper jaw at 6 bar, opening | 246 N 82 N |
| Gripping force per gripper jaw at 6 bar, closing | 207 N 69 N |
| Operating pressure | 3 bar8 bar |
| Operating pressure for sealing air | 0 bar0.5 bar |
| Max. operating frequency of pneumatic gripper | 4 Hz |
| Min. opening time at 6 bar | 28 ms |
| Min. closing time at 6 bar | 25 ms |
| Operating medium | Compressed air as per ISO 8573-1:2010 [7:4:4] |
| Information on operating and pilot media | Operation with oil lubrication possible (required for further use) |
| Corrosion resistance class (CRC) | 2 - Moderate corrosion stress |
| LABS (PWIS) conformity | VDMA24364-B1/B2-L |
| Ambient temperature | 5 °C60 °C |
| Mass moment of inertia | 0.48 kgcm² |
| Maximum force on gripper jaw Fz, static | 350 N |
| Maximum torque on gripper jaw, Mx static | 7 Nm |
| Maximum torque on gripper jaw, My static | 10 Nm |

| Feature | Value |
|--|--|
| Maximum torque on gripper jaw, Mz static | 5 Nm |
| Relubrication interval for guidance elements | 5 MioCyc |
| Max. mass per external gripper finger | 10 g |
| Product weight | 185 g |
| Type of mounting | With through-hole and dowel pin With internal thread and dowel pin Optionally: |
| Sealing air pneumatic connection | M5 |
| Pneumatic connection | M5 |
| Cover cap material | High-alloy stainless steel |
| Housing material | Wrought aluminum alloy COMPCOTE-coated |
| Gripper jaw material | Hardened steel |