

## **Data sheet**

Feature	Value
Ambient temperature	-15 °C40 °C
Note on ambient temperature	Up to 80 °C with derating of -1.5% per degree Celsius
Max. installation height	4000 m
Information on max. installation height	with 1,000 m and longer only with derating of -1.0% per 100 m
Storage temperature	-20 °C70 °C
Relative air humidity	0 - 90 %
Conforms to standard	IEC 60034
Thermal class according to EN 60034-1	F
Max. winding temperature	155 ℃
Rating class according to EN 60034-1	S1
Temperature monitoring	Digital motor temperature transmission via EnDat® 2.2
Motor type as per EN 60034-7	IM B5 IM V1 IM V3
Mounting position	Any
Degree of protection	IP40 IP65
Note on degree of protection	IP40 for motor shaft without rotary shaft seal IP65 for motor shaft with rotary shaft seal IP67 for motor housing, incl. connection technology
Concentricity, coaxiality, axial runout according to DIN SPEC 42955	N
Balancing quality	G 2.5
Detent torque	<1.0% of peak torque
Bearing lifetime, under nominal conditions	20000 h
Featherkey shaft design	DIN 6885 A 5 x 5 x 22
Interface code, motor out	60P
Electrical connection 1, connection type	Hybrid plug
Electrical connection 1, connection technology	M23x1
Electrical connection 1, number of pins/wires	15
Contamination level	2
Note on materials	RoHS-compliant
Corrosion resistance class (CRC)	0 - No corrosion stress

Feature	Value
LABS (PWIS) conformity	VDMA24364 zone III
Vibration resistance	Transport application test with severity level 2 as per FN 942017-4 and EN 60068-2-6
Shock resistance	Shock test with severity level 2 as per FN 942017-5 and EN 60068-2-27
Certification	RCM compliance mark German Technical Control Board (TÜV) c UL us - Recognized (OL)
CE marking (see declaration of conformity)	As per EU EMC directive As per EU low voltage directive As per EU RoHS directive
UKCA marking (see declaration of conformity)	To UK instructions for EMC To UK RoHS instructions To UK instructions for electrical equipment
Certificate issuing authority	TÜV 968/INS 464.00/24 UL E342973
Nominal operating voltage DC	325 V680 V
Type of winding switch	Star inside
Number of pole pairs	5
Stall torque	0.64 Nm1.66 Nm
Nominal torque	0.56 Nm1.4 Nm
Peak torque	1.6 Nm5.6 Nm
Nominal rotary speed	3000 rpm
Max. rotational speed	6800 rpm15000 rpm
Angular acceleration	100000 rad/s <sup>2</sup>
Motor nominal power	180 W440 W
Continuous stall current	1.6 A3.8 A
Motor nominal current	1.4 A3.2 A
Peak current	5.4 A18.3 A
Motor constants	0.4 Nm/A0.45 Nm/A
Standstill torque constant	0.49 Nm/A0.53 Nm/A
Voltage constant, phase-to-phase	29.9 mVmin32 mVmin
Phase-phase winding resistance	2.68 Ohm11.7 Ohm
Winding inductance phase-phase	12 mH38 mH
Winding longitudinal inductivity Ld (phase)	5 mH15.5 mH
Cross inductivity Lq (phase)	6 mH19 mH
Electric time constant	2.1 ms3 ms
Thermal time constant	40 min44 min
Thermal resistance	1 K/W1.5 K/W
Measuring flange	250 x 250 x 15 mm, steel
Total output inertia moment	0.169 kgcm²0.49 kgcm²
Product weight	1180 g2230 g
Permissible axial shaft load	70 N
Permissible radial shaft load	350 N
Rotor position sensor	Absolute encoder, single-turn Absolute encoder, multi-turn Safety encoder, absolute multi-turn
Rotor position sensor interface	EnDat® 22
Rotor position sensor measuring principle	Inductive
Rotor position sensor resolution	18 bit19 bit
Brake holding torque	2.5 Nm
Brake DC operating voltage	24 V
Brake power consumption	11 W

Feature	Value
	1 Safety device Safety integrity level 3 See user documentation Reliable recording and transmission of single-turn position data Reliable recording and transmission of single-turn position data, only with additional software function in the servo drive Performance Level e, Category 3 See user documentation Reliable recording and transmission of single-turn position data Reliable recording and transmission of single-turn position data, only with additional software function in the servo drive
Brake mass moment of inertia	0.074 kgcm²
Switching cycles, holding brake	10 million idle actuations (without friction work!)
PFHd, subcomponent	15 x 10E-9, encoder
Duration of use Tm, subcomponent	20 years, rotor position sensor
MTTF, subcomponent	190 years, rotor position sensor