



## **Data sheet**

Max. interchangeability 0.  Max. opening angle 18  Rotational symmetry 0.  Pneumatic gripper repetition accuracy 0.  Number of gripper jaws 2  Mounting position Ar  Mode of operation De	20.2 mm 180 deg 20.2 mm 20.1 mm 20.1 mm 20.2 Any 20.2 Double-acting 20.3 Radial 20.4 Radial 20.5 Radial 20.6 Radial 20.7 Radia
Max. opening angle 18 Rotational symmetry 0. Pneumatic gripper repetition accuracy 0. Number of gripper jaws 2 Mounting position Ar Mode of operation De	180 deg 0.2 mm 0.1 mm 2 Any Double-acting Radial During closing Positively driven motion sequence
Rotational symmetry 0. Pneumatic gripper repetition accuracy 0. Number of gripper jaws 2 Mounting position Ar Mode of operation De	2.2 mm 2.1 mm 2.2 Any Double-acting Radial During closing Positively driven motion sequence
Pneumatic gripper repetition accuracy  O. Number of gripper jaws  Mounting position  Ar  Mode of operation  Definition	2.1 mm 2.2 Any 2.2 Double-acting Radial During closing Positively driven motion sequence
Number of gripper jaws 2  Mounting position Ar  Mode of operation De	Any  Double-acting  Radial  During closing  Positively driven motion sequence
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Grinner function R:	Ouring closing Positively driven motion sequence
inper function	Positively driven motion sequence
Gripping force backup Do	,
Structural design Po	or proximity sensor
Position sensing Fo	
Operating pressure 4	4 bar8 bar
Max. operating frequency of pneumatic gripper 3	3 Hz
Min. opening time at 6 bar	131 ms
Min. closing time at 6 bar	38 ms
Operating medium Co	Compressed air as per ISO 8573-1:2010 [7:4:4]
nformation on operating and pilot media O	Operation with oil lubrication possible (required for further use)
Corrosion resistance class (CRC)	1 - Low corrosion stress
ABS (PWIS) conformity VI	/DMA24364-B2-L
Ex	Metals with more than 5% by mass of copper are excluded from use. Exception are printed circuit boards, cables, electrical connectors and soils
Ambient temperature 5	5 °C60 °C
Mass moment of inertia 1.	1.69 kgcm²
Maximum force on gripper jaw Fz, static	120 N
Maximum torque on gripper jaw, Mx static 6.	5.2 Nm
Maximum torque on gripper jaw, My static 6.	5.2 Nm
Maximum torque on gripper jaw, Mz static 6.	5.2 Nm
Product weight 49	490 g

Feature	Value
Type of mounting	With internal thread and centering sleeve Via through-hole and centering sleeve Optionally:
Pneumatic connection	G1/8
Note on materials	RoHS-compliant
Cover cap material	PA
Housing material	Wrought aluminum alloy, hard-anodized
Gripper jaw material	High-alloy steel