

Motor controller SFC-LAC-VD-10-E-H0-IO

Part number: 540038

FESTO

for assignment of parameters and positioning of the linear module HME.
Products to be discontinued. Available until 2011.



Data sheet

| Feature | Value |
|--|--|
| Controller operating mode | adaptive status controller |
| Mains filter | Integrated |
| Protective function | I ² t monitoring Current monitoring Voltage failure detection Drag error monitoring Software end-position detection |
| Rotor position sensor | Encoder |
| Digital logic output characteristics | Electrically isolated |
| Max. current, digital logic outputs | 500 mA |
| Max. intermediate circuit voltage, DC | 48 V |
| Nominal controller power | 480 VA |
| Nominal DC voltage, logic power supply | 24 V |
| Nominal voltage, load supply DC | 48 V |
| Nominal current, load supply | 10 A |
| Nominal current, logic supply | 0.5 A |
| Parameters configuring interface | Parameters configuration and commissioning RS232 (38400 Baud) |
| Peak power | 960 VA |
| Peak current, load supply | 20 A |
| Peak current, logic supply | 0.8 A |
| Effective peak current per phase | 15 A |
| Permissible range, load supply | +5 % / -10 % |
| Permissible range, logic voltage | ± 10 % |
| CE mark (see declaration of conformity) | to EU directive for EMC |
| Storage temperature | -20 ... 60 °C |
| Shock resistance | Following DIN EN 60068-2-27 |
| Protection class | IP54 |
| Vibration resistance | Following DIN EN 60068-2-6 |
| Ambient temperature | 0 ... 40 °C |
| Authorisation | C-Tick |
| Product weight | 1,200 g |
| Number of 24 V DC digital logic outputs | 4 |
| Number of digital logic inputs | 8 |
| Process interface | I/O coupling For 32 traversing records |
| Logic input working range | 24 V |
| Encoder interface input, characteristics | CAN-Bus |
| Logic input characteristics | Electrically isolated |
| Mounting type | with top-hat rail with wall/surface fixing |
| Materials note | Contains PWIS substances |