# Swivel modules DSMI-B, with integrated angular displacement encoder





# Product range overview

| Function             | Туре              | Description  |
|----------------------|-------------------|--|
|                      |                   |  |
| Drives               | Rodless           |  |
|                      | DDLI              | Without guide     With displacement encoder for contactless measurement     Based on linear drive DGC-K     Supply ports on the end face   |
|                      | 74                | System product for handling and assembly technology  |
|                      | DGCI              | With guide With displacement encoder for contactless measurement Based on linear drive DGC Supply ports optionally on the end face or at the front System product for handling and assembly technology |
|                      | With piston rod   |  |
|                      | DNCI              | With displacement encoder for contactless measurement     Range of piston rod variants     Standards-based cylinder to ISO 15552   |
|                      | DDPC              | With displacement encoder for contactless measurement  |
|                      | 1                 | <ul> <li>Range of piston rod variants</li> <li>Standards-based cylinder to ISO 15552</li> </ul>  |
|                      | DNC/DSBC          | With attached potentiometer MLO-LWG  |
|                      | S                 | <ul> <li>Range of piston rod variants</li> <li>Standards-based cylinder to ISO 15552</li> </ul>  |
| C                    | Comit materials   | <u>'</u>   |
| Semi-rotary<br>drive | Semi-rotary drive | Based on semi-rotary drive DSM     Integrated rotary potentiometer     Compact design     Wide range of mounting options   |

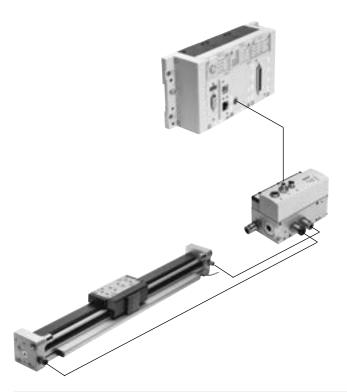
# Product range overview

| Piston Ø              | Stroke/swivel angle  | Suitable             |                          |                         |   |
|-----------------------|--|----------------------|--------------------------|-------------------------|---|
|                       |  | For positioning with | For end-position control | As a measuring cylinder |   |
|                       | [mm/°]   | CPX-CMAX             | CPX-CMPX                 | SPC11                   |   |
| Rodless               |  |                      |                          |                         |   |
| 25, 32, 40, 63        | 100, 160, 225, 300, 360, 450, 500, 600, 750, 850, 1000, 1250, 1500, 1750, 2000 | •                    | •                        | •                       | • |
| 18, 25, 32, 40, 63    | 100, 160, 225, 300, 360, 450, 500, 600, 750, 850, 1000, 1250, 1500, 1750, 2000 | •                    | •                        | •                       | • |
| With piston rod       |  |                      |                          |                         |   |
| 32, 40, 50, 63        | 10 2000  | -                    | -                        | -                       | • |
|                       | 100 750  | •                    | •                        | •                       | - |
| 80, 100               | 10 2000  | -                    | -                        | -                       | • |
|                       | 100 750  | •                    | •                        | •                       | - |
| 32, 40, 50, 63,<br>80 | 100, 150, 225, 300, 360, 450, 600, 750   | •                    | •                        | •                       | • |
| Semi-rotary driv      |  |                      |                          |                         |   |
| 40                    | 270  | •                    | •                        | •                       | • |
|                       |  |                      |                          |                         |   |

# Key features

#### Servo-pneumatic drive technology

Positioning and Soft Stop applications as an integral component of the valve terminal CPX – the modular peripheral system for decentralised automation tasks. The modular design means that valves, digital inputs and outputs, positioning modules and end-position controllers, as appropriate for the application, can be combined in almost any way on the CPX terminal.



#### Advantages:

- Pneumatics and electrics control and positioning on one platform
- Innovative positioning technology piston rod drives, rodless drives, rotary drives
- · Actuation via fieldbus
- Remote maintenance, remote diagnostics, web server, SMS and e-mail alerts are all possible via TCP/IP
- · Modules can be quickly exchanged and expanded without altering the wiring

#### Axis controller CPX-CMAX



#### Free choice:

Position and force control, directly actuated or selected from one of 128 configurable position sets.

If you are looking for something more: The configurable record sequencing function enables simple functional sequences to be realised with the axis controller CPX-CMAX.

Everything is recognisable: the auto-identification function identifies each participant with its device data on the controller CPX-CMAX.

#### Also included:

Actuation of a brake or clamping unit via the proportional directional control valve VPWP is also part of the scope of performance of the controller CPX-CMAX.

Up to 8 modules (max. 8 axes) can be operated in parallel and independently of each other.

Commissioning via FCT (Festo configuration software) or via fieldbus: no programming, only configuration.

- · Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
- You program the system in your PLC environment

# Key features

#### End-position controllers CPX-CMPX



Fast travel between the mechanical end stops of the cylinder, stopping gently and without impact in the end position.

Fast commissioning via control panel, fieldbus or handheld unit.
Improved control of standstills.
Actuation of a brake or clamping unit via the proportional directional control valve VPWP is an integral part of the controller CMPX.

Depending on the fieldbus chosen, up to 9 end-position controllers can be actuated on the CPX terminal.

All system data can be read and written via the fieldbus, including, for example, the mid-positions.

#### Datasheets → Internet: cpx-cmpx

#### Advantages:

- · Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- · Cost-effective
  - Up to 30% faster cycle rates
  - Significantly reduced system vibration
- Improved work ergonomics thanks to significantly reduced noise level
- The extended diagnostics help to reduce the service time of the machine

#### Proportional directional control valve VPWP



The 5/3-way proportional directional control valve for applications with Soft Stop and pneumatic positioning. Fully digitalised – with integrated pressure sensors, with new diagnostic functions.

In sizes 4, 6, 8 and 10. Flow rates of 350, 700, 1400 and 2000 l/min. With switching output for controlling a brake.

Colour-coded supply ports.

Pre-assembled cables guarantee error-free and fast connection to the controllers CPX-CMPX and CPX-CMAX.

#### Datasheets → Internet: vpwp

- Advantages:
- Easy installation and fast commissioning
- Reduction of system downtimes thanks to the new diagnostic options
- With switching output for controlling a brake/clamping unit

#### Measuring module CPX-CMIX



Fully digital data acquisition and transmission means that pneumatic cylinders can be used as sensors. With very high repetition accuracy and incorporating both analogue and digital measuring sensors.

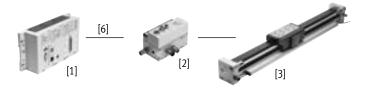
Suitable for the linear drive DGCI with displacement encoder for measuring absolute values, for the piston rod drive DNCI/DDPC with incremental displacement encoder or even for a potentiometer type MLO.

### Datasheets → Internet: cpx-cmix

- All process steps can be documented, which improves quality
- An adjustable contact force (via pressure regulator) increases the precision of the "displacement sensor"
- With displacement encoders for measuring absolute values, the actual position is immediately available after the system is switched on

# **Drive options**

#### System with linear drive DDLI, DGCI



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [3] Linear drive DDLI, DGCI with displacement encoder
- [6] Connecting cable KVI-CP-3-...

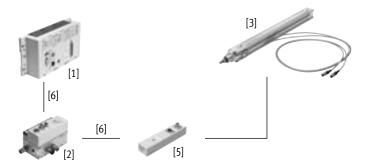
- Pneumatic rodless linear drive with displacement encoder, with or without recirculating ball bearing guide
- Displacement encoder with absolute and contactless measurement
- · Diameter:
  - With DGCI: 18 ... 63 mm
  - With DDLI: 25 ... 63 mm
- Stroke: 100 ... 2000 mm in fixed lengths
- Application areas: Soft Stop and pneumatic positioning
- Loads from 1 ... 180 kg
- · No sensor interface required

#### Datasheets → Internet: ddli or dgci

#### Advantages:

- · Complete drive unit
- DDLI for easy connection to customer's guide system
- Excellent running characteristics
- For fast and accurate positioning up to ±0.2 mm (only with axis controller CPX-CMAX)

#### System with standards-based cylinder DNCI, DDPC



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [3] Standards-based cylinder DNCI, DDPC with displacement encoder
- [5] Sensor interface CASM-S-D3-R7
- [6] Connecting cable KVI-CP-3-...

# Standards-based cylinder with integrated displacement encoder, conforms to DIN ISO 6432, VDMA 24 562, NF E 49 003.1 and Uni 10 290

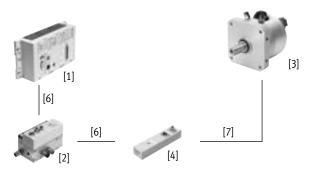
- Displacement encoder with contactless and incremental measurement
- Diameter: 32 ... 100 mm
- Stroke: 100 ... 750 mm
- Application areas: Soft Stop and pneumatic positioning
- Loads from 3 ... 450 kg and the corresponding sensor interface CASM-S-D3-R7
- Pre-assembled cables guarantee error-free and fast electrical connection

### Datasheets → Internet: dnci

- · Compact drive unit
- · Universal applications
- · Also with guide unit
- For fast and accurate positioning up to ±0.5 mm (only with axis controller CPX-CMAX)

# **Drive options**

#### System with semi-rotary drive DSMI



- [1] Controller module CPX-CMPX or CPX-CMAX
- Proportional directional control valve VPWP
- Semi-rotary drive DSMI with displacement encoder
- Sensor interface CASM-S-D2-R3
- [6] Connecting cable KVI-CP-3-...
- Connecting cable NEBC-P1W4-K-0.3-N-M12G5

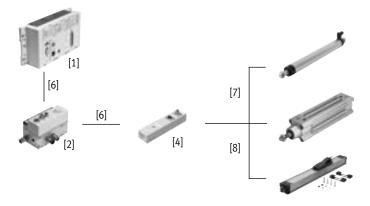
- · Swivel drive DSMI with integrated displacement encoder
- Identical design to pneumatic semi-rotary drive DSM
- Absolute displacement encoder based on a potentiometer
- Swivel range from 0 ... 270°
- Size: 40
- Max. torque: 20 Nm
- Application areas: Soft Stop and pneumatic positioning
- Mass moments of inertia of 60 ... 1200 kgcm<sup>2</sup> and the corresponding sensor interface CASM-S-D2-R3
- · Pre-assembled cables guarantee error-free and fast connection to the proportional directional control valve VPWP

#### Datasheets → Internet: dsmi

#### Advantages:

- Complete drive unit, compact, can be used immediately
- High angular acceleration
- · With adjustable fixed stops
- · For fast and accurate positioning down to ±0.2° (only with axis controller CPX-CMAX)

#### System with potentiometer



- [1] Controller module CPX-CMPX or CPX-CMAX
- Proportional directional control valve VPWP
- Sensor interface CASM-S-D2-R3 [4]
- [6] Connecting cable KVI-CP-3-...
- Connecting cable NEBC-P1W4-K-0.3-N-M12G5
- Connecting cable NEBC-A1W3-K-0.4-N-M12G5

- · Attachable potentiometers with absolute measurement, with high degree of protection
- With connecting rod or moment compensator
- Measuring range: Connecting rod: 100 ... 750 mm Moment compensator: 225 ... 2000 mm
- Pre-assembled cables guarantee error-free and fast connection to the sensor interface CASM
- · Application areas: Soft Stop and pneumatic positioning with cylinder diameters of 25 ... 80 mm
- Loads from 1 ... 300 kg

#### Datasheets → Internet: casm

- · Easy installation and fast commissioning
- · Cost-effective
- Can also be used in harsh operating conditions
- · Variety of drives: CPX-CMPX and CPX-CMAX also support cylinders with external displacement encoder

# Drive options

| System components for Soft Stop sys         | stems with end-posi | tion controller CPX-CMPX |                   |                     |         |                     |
|---|---------------------|--------------------------|-------------------|---------------------|---------|---------------------|
|   | Linear drive        | Standards-based cylinder | Semi-rotary drive | Displacement encode | er      | → Page/<br>Internet |
|   | DDLI/DGCI           | DNCI, DDPC               | DSMI              | MLO-LWG/-TLF        | MME-MTS |                     |
| End-position controller<br>CPX-CMPX         | •                   | •                        | •                 | •                   | •       | cmpx                |
| Proportional directional control valve VPWP | -                   | •                        | •                 | •                   | •       | vpwp                |
| Sensor interface<br>CASM-S-D2-R3            | -                   | -                        | •                 | •                   | -       | casm                |
| Sensor interface<br>CASM-S-D3-R7            | -                   |                          | -                 | -                   | -       | casm                |
| Connecting cable KVI-CP-3                   |                     | •                        | •                 |                     | •       | kvi                 |
| Connecting cable<br>NEBC-P1W4               | -                   | -                        | •                 | ■/-                 | -       | nebc                |
| Connecting cable<br>NEBC-A1W3               | _                   | -                        | -                 | -/ <b>■</b>         | -       | nebc                |
| Connecting cable<br>NEBP-M16W6              | -                   | -                        | -                 | -                   | •       | vpwp                |

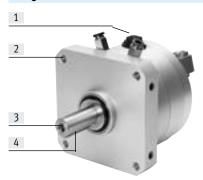
| System components for pneumatic positioning systems with axis controller CPX-CMAX |              |                               |                   |                      |         |                     |
|---|--------------|-------------------------------|-------------------|----------------------|---------|---------------------|
|   | Linear drive | Standards-based cylin-<br>der | Semi-rotary drive | Displacement encoder |         | → Page/<br>Internet |
|   | DDLI/DGCI    | DNCI, DDPC                    | DSMI              | MLO-LWG/-TLF         | MME-MTS |                     |
| Axis controller<br>CPX-CMAX   | •            | •                             | •                 | •                    | -       | cmax                |
| Proportional directional control valve VPWP                                       | •            | •                             | •                 | •                    | •       | vpwp                |
| Sensor interface<br>CASM-S-D2-R3  | _            | _                             | •                 | •                    | _       | casm                |
| Sensor interface<br>CASM-S-D3-R7  | -            | •                             | -                 | -                    | -       | casm                |
| Connecting cable KVI-CP-3   | •            | •                             | •                 | •                    | •       | kvi                 |
| Connecting cable NEBC-P1W4  | -            | -                             |                   | ■/-                  | -       | nebc                |
| Connecting cable NEBC-A1W3  | -            | _                             | _                 | <b>-/■</b>           | _       | nebc                |
| Connecting cable NEBP-M16W6   | _            | _                             | -                 | _                    | •       | vpwp                |

|                                   | Linear drive | Standards-based cylinder | Semi-rotary drive | Displacement encoder |         | → Page/<br>Internet |
|-----------------------------------|--------------|--------------------------|-------------------|----------------------|---------|---------------------|
|                                   | DDLI/DGCI    | DNCI, DDPC               | DSMI              | MLO-LWG/-TLF         | MME-MTS |                     |
| Measuring module<br>CPX-CMIX-M1-1 | •            | •                        | •                 | •                    | •       | cmix                |
| Sensor interface<br>CASM-S-D2-R3  | -            | -                        | •                 | •                    | -       | casm                |
| Sensor interface<br>CASM-S-D3-R7  | -            | •                        | -                 | -                    | -       | casm                |
| Connecting cable<br>KVI-CP-3      | (■)¹)        | •                        | •                 | •                    | (■)     | kvi                 |
| Connecting cable<br>NEBC-P1W4     | -            | -                        | •                 | ■/-                  | -       | nebc                |
| Connecting cable<br>NEBC-A1W3     | -            | -                        | -                 | -/=                  | -       | nebc                |
| Connecting cable<br>NEBP-M16W6    | -            | -                        | -                 | -                    | •       | vpwp                |

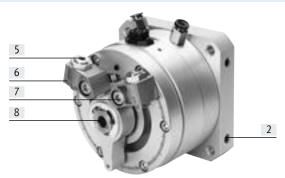
<sup>1)</sup> As an extension

# Key features

#### At a glance

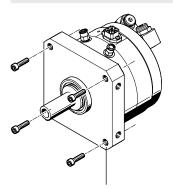


- [1] Connector plug for displacement encoder
- [2] Wide range of integrated mounting options
- [3] Option for mounting on the drive shaft by the customer
- [4] Feather key
- [5] Fixed stop with precision adjustment of the swivel angle
- [6] Sensor bracket for mounting proximity switch, for contactless position sensing

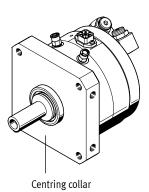


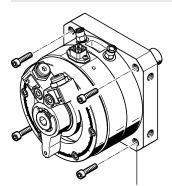
- [7] Fixed stop can be set at any point within the swivel angle
- [8] Manual operation via internal hexagon socket in the drive shaft. A female thread is already integrated for attaching an additional drive shaft by the customer.

#### **Mounting options**

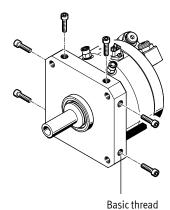


Threaded through-hole





Threaded through-hole



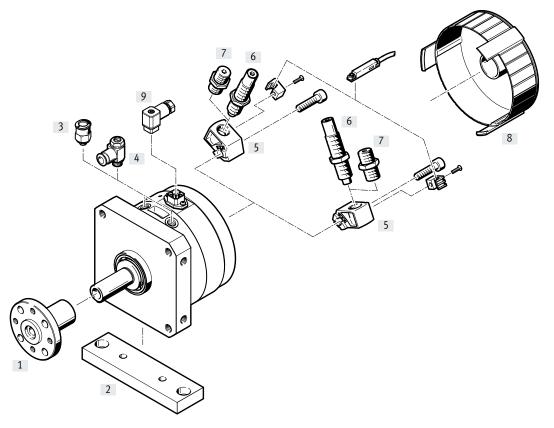
# Swivel modules DSMI-B, with integrated angular displacement encoder

# Type codes

| 001  | Series   |  |
|------|--|--|
| DSMI | Semi-rotary drive with displacement encoder, double-acting |  |
|      |  |  |
| 002  | Size [mm]  |  |
| 25   | 25   |  |
| 40   | 40   |  |

| 003 | Nominal swivel angle [°] | Nominal swivel angle [º] |  |  |  |
|-----|--------------------------|--------------------------|--|--|--|
| 270 | 270                      |                          |  |  |  |
| 004 | Position sensing         |                          |  |  |  |
| Α   | For proximity sensor     |                          |  |  |  |
| 005 | Variant                  |                          |  |  |  |
| В   | B-series                 |                          |  |  |  |

# Peripherals overview



| Δ | cc | eς | s٨ | ri | eς |
|---|----|----|----|----|----|

| Acces | ssories                    |   |                 |
|-------|----------------------------|---|-----------------|
|       |                            | Description   | → Page/Internet |
| [1]   | Push-on flange<br>FWSR     | For mounting attachments  | 17              |
| [2]   | Mounting plate<br>HSM      | Adapter plate for mounting the drive                                  | 17              |
| [3]   | Push-in fitting            | For connecting tubing with standard O.D.                              | qs              |
|       | QS                         | (push-in fittings are included in the scope of delivery of the drive) |                 |
| [4]   | One-way flow control valve | For regulating speed  | 19              |
|       | GRLA                       | (is recommended when using the DSMI as a measuring cylinder)          |                 |
| [5]   | Cushioning mount           | For elastic cushioning components                                     | 18              |
|       | DSM-B                      | For shock absorbers   |                 |
|       |                            | As a mechanical stop in Soft Stop applications                        |                 |
| [6]   | Shock absorber             | Self-adjusting shock absorbers with fixed stop                        | 18              |
|       | DYSC                       | (is recommended when using the DSMI as a measuring cylinder)          |                 |
| [7]   | Cushioning kit             | Elastic cushioning components with fixed stop                         | 18              |
|       | DSMP-B                     |   |                 |
| [8]   | Cover cap                  | Reduces the risk of injury in the swivel range of the stop lever      | 18              |
|       | AKM                        |   |                 |
| [9]   | Plug socket                | For connecting the displacement encoder                               | 19              |
|       | SD                         |   |                 |

# Swivel modules DSMI-B, with integrated angular displacement encoder

# Datasheet

- **Ø** - Size

Torque 20 Nm



### General technical data

| ocherut technicut data                             |       |  |  |
|--|-------|--|--|
| Size   |       | 40   |  |
| Design   |       | Vane   |  |
|  |       | Drive shaft, fitted with ball bearings         |  |
| Operating mode                                     |       | Double-acting                                  |  |
| Type of mounting                                   |       | Via female thread                              |  |
| Position sensing                                   |       | Via integrated angular displacement encoder    |  |
|  |       | Via proximity sensor <sup>1)</sup>             |  |
| Measuring principle (angular displacement encoder) |       | Analogue with conductive plastic potentiometer |  |
| Min. travel speed                                  | [°/s] | 50   |  |
| Max. travel speed                                  | [°/s] | 2 000  |  |
| Max. swivel angle <sup>2)</sup>                    | [°]   | 272  |  |
| Setting range of swivel angle                      | [°]   | 0 270  |  |
| Pneumatic connection                               |       | G1/8   |  |
| Push-in fitting used                               |       | QS-G1/8-8-I                                    |  |
| Compressed air tubing O.D.                         | [mm]  | 8  |  |

- 1) Not included in the scope of delivery, can be ordered as an option
- 2) Note stroke reduction in combination with axis controller CPX-CMAX

#### Operating and environmental conditions

| Size   |       | 40  |
|--|-------|---|
| Operating pressure                                       | [bar] | 210   |
| Operating pressure <sup>1)</sup>                         | [bar] | 48  |
| Operating medium <sup>2)</sup>                           |       | Compressed air to ISO 8573-1:2010 [6:4:4]                 |
| Note on the operating/pilot medium                       |       | Lubricated operation not possible                         |
|  |       | Pressure dew point 10 °C below ambient/medium temperature |
| Ambient temperature <sup>3)</sup>                        | [°C]  | -10 +60   |
| Vibration resistance to DIN/IEC 68, Part 2-6             |       | Severity level 2  |
| Continuous shock resistance to DIN/IEC 68, Part 2 - 82   |       | Severity level 2  |
| CE marking (see declaration of conformity) <sup>4)</sup> |       | To EU EMC Directive                                       |
| Corrosion resistance class CRC <sup>5)</sup>             |       | 1   |

- 1) Only applies to applications with end-position controller CPX-CMPX, SPC11 and axis controller CPX-CMAX
- $2) \quad \text{The proportional directional control valve VPWP, MPYE used requires these characteristic values} \\$
- 3) Note operating range of proximity switches
- 4) For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp  $\rightarrow$  Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

5) Corrosion resistance class CRC 1 to Festo standard FN 940070

Low corrosion stress. Dry internal application or transport and storage protection. Also applies to parts behind covers, in the non-visible interior area, or parts that are covered in the application (e.g. drive trunnions).

| 141. | •  | 1  |
|------|----|----|
| WP   | Ισ | nī |
|      |    |    |

| - 1  | weight |     |      |  |  |
|------|--------|-----|------|--|--|
| Size |        |     | 40   |  |  |
|      | DSMI   | [g] | 3950 |  |  |

### Torque [Nm]

| Size                 | 40 |  |  |
|----------------------|----|--|--|
| Torque <sup>1)</sup> | 20 |  |  |

1) Theoretical values, calculated at 6 bar

#### Permissible forces on the drive shaft

| Size                                |      | 40  |
|-------------------------------------|------|-----|
| Max. radial force                   | [N]  | 350 |
| Max. axial force                    | [N]  | 120 |
| Max. swivel frequency <sup>1)</sup> | [Hz] | 2   |

1) At max. permissible mass moment of inertia, operating pressure of 6 bar and a swivel angle of  $270^{\rm o}$ 



Note

Additional technical data

→ Internet: dsm

| D1411       | characteristics |           |            | CDV CMAY |
|-------------|-----------------|-----------|------------|----------|
| POSITIONING | cnaracteristics | with axis | controller | CPX-CMAX |

| Positioning characteristics with axis controller CPX-CMAX |                     |                         |  |  |  |  |  |  |
|---|---------------------|-------------------------|--|--|--|--|--|--|
| Size  |                     | 40                      |  |  |  |  |  |  |
| Mounting position   |                     | Any                     |  |  |  |  |  |  |
| Resolution  | [°]                 | 0.1                     |  |  |  |  |  |  |
| Repetition accuracy                                       | [°]                 | ≤ ±0.3                  |  |  |  |  |  |  |
| Min. mass moment of inertia,                              | [kgm <sup>2</sup> ] | $60 \times 10^{-4}$     |  |  |  |  |  |  |
| horizontal <sup>1)</sup>                                  |                     |                         |  |  |  |  |  |  |
| Max. mass moment of inertia,                              | [kgm <sup>2</sup> ] | 1200 x 10 <sup>-4</sup> |  |  |  |  |  |  |
| horizontal <sup>1)</sup>                                  |                     |                         |  |  |  |  |  |  |
| Min. mass moment of inertia,                              | [kgm <sup>2</sup> ] | $60 \times 10^{-4}$     |  |  |  |  |  |  |
| vertical <sup>2)</sup>                                    |                     |                         |  |  |  |  |  |  |
| Max. mass moment of inertia,                              | [kgm <sup>2</sup> ] | 1200 x 10 <sup>-4</sup> |  |  |  |  |  |  |
| vertical <sup>2)</sup>                                    |                     |                         |  |  |  |  |  |  |
| Min. travel speed   | [°/s]               | 50                      |  |  |  |  |  |  |
| Max. travel speed   | [°/s]               | 2000                    |  |  |  |  |  |  |
| Typical positioning time, long stroke <sup>3)</sup>       | [s]                 | 0.30/0.55               |  |  |  |  |  |  |
| Typical positioning time, short stroke <sup>4)</sup>      | [s]                 | 0.25/0.25               |  |  |  |  |  |  |
| Min. positioning stroke                                   | [°]                 | 5                       |  |  |  |  |  |  |
| Max. swivel stroke <sup>5)</sup>                          | [°]                 | 260                     |  |  |  |  |  |  |
| Recommended proportional directional control valve        |                     |                         |  |  |  |  |  |  |
| For CPX-CMAX  |                     | VPWP-4-L-5-Q8-10-E-F    |  |  |  |  |  |  |

- $1) \qquad \text{Must not change during the movement, but may be outside the centre of gravity} \\$
- 2) Must not change during the movement, must act at the centre of gravity  $% \left( 1\right) =\left( 1\right) \left( 1\right)$
- 3) At 6 bar, vertical mounting position, 260° positioning angle at min./max. mass moment of inertia
- 4) At 6 bar, vertical mounting position,  $15^{\circ}$  positioning angle at min./max. mass moment of inertia
- 5) A stroke reduction of  $5^{\circ}$  on both sides must be observed

#### Positioning characteristics with Soft Stop end-position controller CPX-CMPX, SPC11

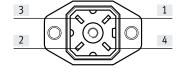
| Size  |                     | 40                        |
|---|---------------------|---------------------------|
| Mounting position                                     |                     | Horizontal                |
| End-position repetition accuracy <sup>1)</sup>        | [°]                 | <±0.2                     |
| Intermediate-position repetition accuracy             | [°]                 | ±2                        |
| Cushioning <sup>2)</sup>                              |                     | Electronically controlled |
| Min. mass moment of inertia, horizontal <sup>3)</sup> | [kgm <sup>2</sup> ] | $60 \times 10^{-4}$       |
| Max. mass moment of inertia, horizontal <sup>3)</sup> | [kgm <sup>2</sup> ] | 1200 x 10 <sup>-4</sup>   |
| Min. swivel stroke                                    | [°]                 | 15                        |
| Recommended proportional directional control valve    |                     |                           |
| For CPX-CMPX  |                     | VPWP-4-L-5-Q8-10-E-F      |
| For SPC11   |                     | MPYE-5-1/8-LF-010-B       |

- 1) When using the DSMI stops
- 2) The cushioning pad on the stop lever must be removed for applications with Soft Stop. The stop lever must not swivel to the end stop at too great a speed as this could damage the swivel module
- 3) Must not change during the movement, but may be outside the centre of gravity

| Electrical data – Displacement encoder    | •                                 |        |                                   |  |  |  |  |  |  |
|---|-----------------------------------|--------|-----------------------------------|--|--|--|--|--|--|
| Size                                      |                                   |        | 40                                |  |  |  |  |  |  |
| Output signal                             |                                   |        | Analogue                          |  |  |  |  |  |  |
| Linearity error <sup>1)</sup>             |                                   | [%]    | < ±0.25                           |  |  |  |  |  |  |
| Power supply <sup>2)</sup>                |                                   | [V DC] | 10                                |  |  |  |  |  |  |
| Max. current consumption                  |                                   | [mA]   | 4                                 |  |  |  |  |  |  |
| Wiper current                             | Recommended                       | [μΑ]   | <1                                |  |  |  |  |  |  |
|   | Maximum <sup>3)</sup>             | [mA]   | 10                                |  |  |  |  |  |  |
| Connection resistance                     | Connection resistance $[k\Omega]$ |        | 5                                 |  |  |  |  |  |  |
| Connection resistance tolerance [%]       |                                   | [%]    | ±20                               |  |  |  |  |  |  |
| Degree of protection                      |                                   |        | IP65                              |  |  |  |  |  |  |
| CE marking (see declaration of conformity | )                                 |        | To EU EMC Directive <sup>4)</sup> |  |  |  |  |  |  |
| Electrical connection                     |                                   |        | 4-pin plug, ☐ 16, DIN 45 322      |  |  |  |  |  |  |

- 1) In relation to max. swivel angle
- 2) Stabilised power supply is recommended, max. 42 V DC permissible
- 3) Only permissible in the short term in the event of a fault
- 4) For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp → Certificates.
  If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

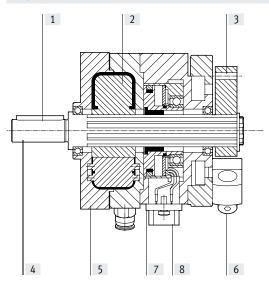
### Pin allocation for the plug



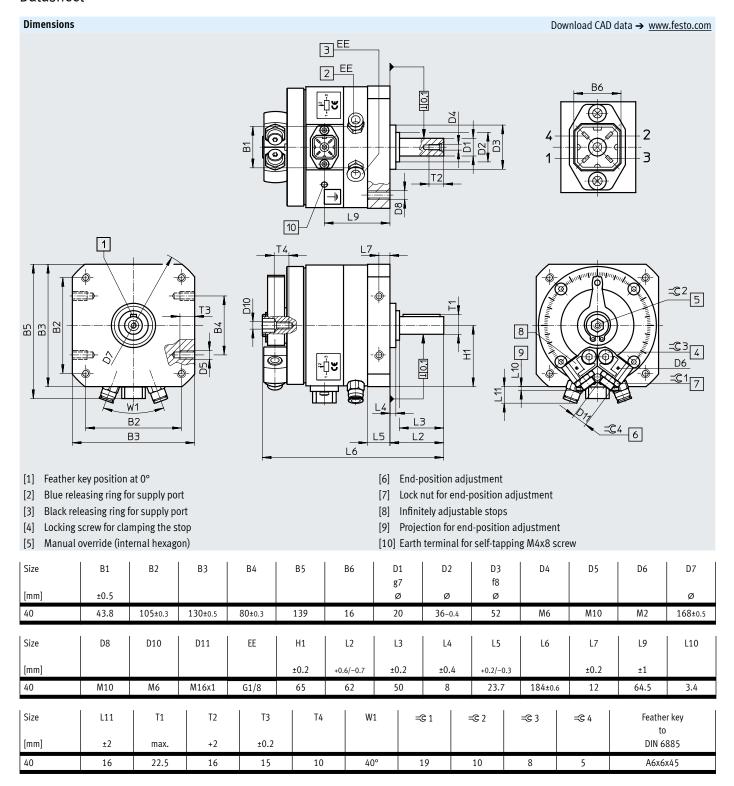
| Pin | Function | ınction      |  |  |  |  |  |  |  |  |
|-----|----------|--------------|--|--|--|--|--|--|--|--|
| 1   | 24 V     | Power supply |  |  |  |  |  |  |  |  |
| 2   | Sig      | Signal       |  |  |  |  |  |  |  |  |
| 3   | 0 V      | GND          |  |  |  |  |  |  |  |  |
| 4   | PE       | Shield       |  |  |  |  |  |  |  |  |

# Materials

Sectional view



| Cylino   | ler/displacement encoder |                                  |  |  |  |  |  |  |  |  |
|----------|--------------------------|----------------------------------|--|--|--|--|--|--|--|--|
| Cylin    | ders                     |                                  |  |  |  |  |  |  |  |  |
| [1]      | Feather key              | Steel                            |  |  |  |  |  |  |  |  |
| [2]      | Vane                     | Glass fibre-reinforced plastic   |  |  |  |  |  |  |  |  |
| [3]      | Stop lever               | Anodised wrought aluminium alloy |  |  |  |  |  |  |  |  |
| [4]      | Drive shaft              | Nickel-plated steel              |  |  |  |  |  |  |  |  |
| [5]      | Housing                  | Anodised wrought aluminium alloy |  |  |  |  |  |  |  |  |
| [6]      | Fixed stop/screw         | Steel                            |  |  |  |  |  |  |  |  |
|          | Note on materials        | Free of copper and PTFE          |  |  |  |  |  |  |  |  |
|          |                          | RoHS-compliant                   |  |  |  |  |  |  |  |  |
| Dienl    | Displacement encoder     |                                  |  |  |  |  |  |  |  |  |
| <u> </u> |                          | la                               |  |  |  |  |  |  |  |  |
| [7]      | Coupling                 | Polyurethane                     |  |  |  |  |  |  |  |  |
| [8]      | Housing                  | Anodised aluminium               |  |  |  |  |  |  |  |  |



# Accessories

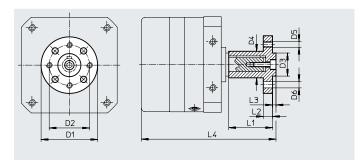
#### 

#### Accessories

#### Push-on flange FWSR

Material: Anodised aluminium Free of copper and PTFE



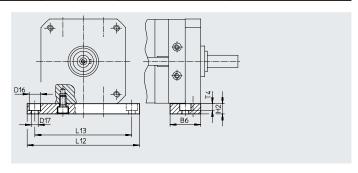


|   | Dimensions and ordering data |    |     |     |     |     |     |    |     |     |       |        |          |         |
|---|------------------------------|----|-----|-----|-----|-----|-----|----|-----|-----|-------|--------|----------|---------|
|   | For size                     | B5 | D11 | D12 | D13 | D14 | D15 | L9 | L10 | L11 | L12   | Weight | Part no. | Туре    |
|   |                              |    |     | Ø   | Ø   | Ø   | Ø   |    |     |     |       |        |          |         |
|   | [mm]                         |    |     | H13 | g7  |     |     |    |     |     |       | [g]    |          |         |
| ľ | 40                           | 54 | M8  | 9   | 36  | 70  | 38  | 60 | 11  | 5   | 186.5 | 240    | 14656    | FWSR-40 |

# Mounting plate HSM

Material: Anodised aluminium Free of copper and PTFE





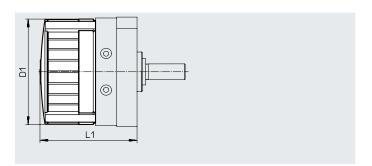
| Dimensions and or | Dimensions and ordering data |     |     |    |     |     |    |        |          |        |  |  |
|-------------------|------------------------------|-----|-----|----|-----|-----|----|--------|----------|--------|--|--|
| For size          | B6                           | D16 | D17 | H2 | L12 | L13 | T4 | Weight | Part no. | Туре   |  |  |
|                   |                              | Ø   | Ø   |    |     |     |    |        |          |        |  |  |
| [mm]              |                              |     |     |    |     |     |    | [g]    |          |        |  |  |
| 40                | 45                           | 18  | 11  | 20 | 180 | 155 | 11 | 459    | 165575   | HSM-40 |  |  |

# Accessories

# Cover cap AKM

Material: Polyamide





| Dimensions and ordering data |     |           |          |        |  |  |  |  |  |  |  |
|------------------------------|-----|-----------|----------|--------|--|--|--|--|--|--|--|
| For size                     | D1  | L1        | Part no. | Туре   |  |  |  |  |  |  |  |
| [mm]                         | Ø   |           |          |        |  |  |  |  |  |  |  |
| 40                           | 130 | 135.5±1.5 | 549198   | AKM-40 |  |  |  |  |  |  |  |

| Ordering data    |          |   |          |                |                  |
|------------------|----------|---|----------|----------------|------------------|
|                  | For size | Description   | Part no. | Туре           | PU <sup>1)</sup> |
| Cushioning mount |          |   |          |                | ,                |
|                  | 40       | For elastic cushioning components     For shock absorbers | 547904   | DSM-40-B       | 2                |
| Cushioning kit   | 40       | For cushioning mount DSMIB                                | 550660   | DSM-40-P-B     | 2                |
| Shock absorber   |          |   |          |                | <u></u>          |
|                  | 40       | For cushioning mount DSMIB                                | 548014   | DYSC-12-12-Y1F | 1                |

<sup>1)</sup> Packaging unit.

# Accessories

| Ordering data – One-way flow co  | ntrol valves    |                      |                      |              |          | Datasheets → Internet: grla |
|----------------------------------|-----------------|----------------------|----------------------|--------------|----------|-----------------------------|
|                                  | For size        | Connection<br>Thread | For tubing O.D.      | Material     | Part no. | Туре                        |
| For exhaust air                  |                 |                      |                      |              |          |                             |
|                                  | 40              | G1/8                 | 3                    | Metal design | 193142   | GRLA-1/8-QS-3-D             |
|                                  |                 |                      | 4                    |              | 193143   | GRLA-1/8-QS-4-D             |
|                                  |                 |                      | 6                    |              | 193144   | GRLA-1/8-QS-6-D             |
|                                  |                 |                      | 8                    |              | 193145   | GRLA-1/8-QS-8-D             |
| Ordering data – Connecting cable | Description     |                      |                      |              | Part no. | Туре                        |
|                                  | Between sensor  | interface CASM and   | displacement encoder |              | 549293   | NEBC-P1W4-K-0.3-N-M12G5     |
| Ordering data – Plug sockets     | Description     |                      |                      |              | Part no. | Туре                        |
|                                  | For displacemen | t encoder connectio  | n                    |              | 194332   | SD-4-WD-7                   |