



### Key features

### Features

### Compactness

- Small dimensions
- Full integration of all components for the controller and power section, including RS232 and CANopen interface
- Integrated brake chopper
- Integrated EMC filters
- Automatic actuation for a holding brake
- Complies with the current CE and EN standards without additional external measures (motor cable length of up to 15 m)

#### Bus protocols





# DeviceNet.

#### Safety functions

- The motor controller CMMS-ST supports the "safe torque off (STO)" safety function and, by providing a reliable time delay, also supports "safe stop 1 (SS1)" with protection against unexpected start-up in accordance with the requirements of EN 61800-5-2
- Protection against unexpected start-up
- Two-channel shutdown of the power stage
- Shorter response times in the event of an error

#### Servo mode

• Encoder option (closed loop), in other words no step losses, following errors are corrected

#### Motion control

- Can be operated as a torque, rotational speed or position controller
- Integrated positioning control
- Time-optimised (trapezoidal) or jerk-free (S-shaped) positioning
- Absolute and relative movements
- · Point-to-point positioning with and without motion path smoothing
- Position synchronisation
- Electronic gear unit
- 63 position sets
- 8 positioning profiles
- Wide range of homing methods

#### Input/output

- Freely programmable I/Os
- High-resolution 12-bit analogue input
- Jog/teach mode
- Easy connection to a higher-order controller via I/O or fieldbus
- Synchronous operation
- Master/slave mode

#### Interpolating multi-axis movement

• With a suitable controller, the CMMS-ST can perform path movements with interpolation via CANopen. To do this, the controller specifies setpoint position values in a fixed time pattern. In between, the servo position controller independently interpolates the data values between two interpolation points.

Integrated sequence control

· Linear and cyclical position

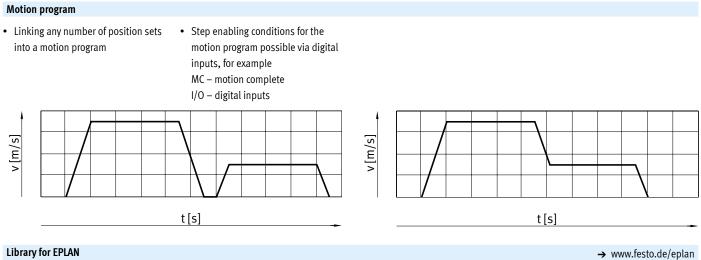
· Adjustable delay times

sequences

· Automatic sequence of position sets

without a higher-order controller

### Key features



#### Library for EPLAN



EPLAN macros for fast and reliable planning of electrical projects in combination with motor controllers, motors and cables. This enables a high level of planning reliability and standardisation of documentation without the need to create symbols, graphics and master data.

#### FHPP – Festo Handling and Positioning Profile Optimised data profile

Festo has developed an optimised data profile, the "Festo Handling and Positioning Profile (FHPP)", which is specifically tailored to handling and positioning applications.

With the FHPP data profile, Festo motor controllers can be controlled using a fieldbus interface via standardised control and status bytes.

The following are defined, among others:

- Operating modes
- I/O data structure
- Parameter objects
- Sequence control

Type codes

001	Series	0	04	Nominal input voltage	
CMMS	Motor controller, standard	7		48 V DC	
002	Motor type	0	05	Generation	
ST	Stepper motor ST	G	i2	2nd generation	
003	Nominal current				
C8	8 A				

Bus protocols

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# DeviceNet.



#### General technical data

Type of mounting		Screwed onto connection plate	
Operating mode		PWM MOSFET power output stage	
Mode of operation		Microstepping, > 4000 steps/rev	
Motor control		Sinusoidal current injection	
Cycle rate	[kHz]	Constant 50	
Rotor position sensor		Encoder	
Display		7-segment display	
Parameterisation interface		RS232 (9600 115,000 bits/s)	
Encoder interface input		As speed/position specification for the slave drive in synchronous mode	
		RS422	
Encoder interface output		Setpoint specification for downstream slave drive	
Braking resistor, integrated	[Ω]	17	
Pulse power of braking resistor	[kVA]	0.5	
Bus terminating resistor		Built in	
Impedance of setpoint input	[kΩ]	20	
Number of analogue outputs		1	
Operating range of analogue outputs	[V]	±10	
Characteristics of digital logic outputs		Freely configurable in some cases	
Number of analogue inputs		1	
Operating range of analogue inputs	[V]	±10	
Mains filter		Built in	
Product weight	[g]	900	

Technical data – Bus protocols/control					
Interfaces		I/O	CANopen	PROFIBUS DP	DeviceNet
Communication profile		-	DS301, FHPP	DP-V0/FHPP	FHPP
		-	DS301; DSP402	-	
Max. fieldbus transmission rate	[Mbps]	-	1	12	0.5
Interface	Built in			-	-
	Optional	-	-		•
				→ Page 10	→ Page 10

### Function blocks for PLC programming

Function blocks for PLC programming					
Programming software	Controller manufacturer	Interfaces			
		CANopen	PROFIBUS DP	DeviceNet	
CODESYS	Festo	•	•	•	
TwinCAT	Beckhoff	7			
	Other manufacturers	7			
RSLogix5000	Rockwell Automation	-	-		
STEP 7	Siemens	-		-	

#### Electrical data

Output connection data		
Output voltage range		0 V up to input voltage
Nominal current setting		Via software
Max. peak current duration	[s]	2
Max. DC link voltage	[V DC]	48
Output frequency	[Hz]	0 2000
Load supply		
Nominal voltage	[V DC]	2448
Nominal current	[A]	8
Peak current	[A]	12
Logic supply		
Nominal voltage	[V DC]	24 ±20%
Nominal current	[A]	0.2
Max. current of digital logic outputs	[mA]	100

#### Safety characteristics

Safety characteristics				
Safety function to EN 61800-5-2	Safe torque off (STO)			
Performance Level (PL) to EN ISO 13849-1	Category 3, Performance Level d			
Safety Integrity Level (SIL) to EN 61800-5-2, EN 62061,	SIL 2			
EN 61508				
MTTFd	STO/2521 years			
PFH	4.53 x 10 <sup>-8</sup>			
Certification	BIA			
Certificate issuing authority	BG MFS 09031			
CE marking (see declaration of conformity)	To EU EMC Directive <sup>1)</sup>			
	To EU Machinery Directive			

1) For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp  $\rightarrow$  Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

#### Operating and environmental conditions

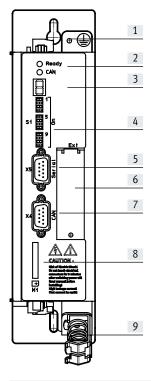
Operating and environmental conditions		
Digital logic outputs	Not galvanically isolated	
Logic inputs	Galvanically isolated	
Degree of protection	IP20	
Protective function	l <sup>2</sup> t monitoring	
	Current monitoring	
	Voltage failure detection	
	Following error monitoring	
	Temperature monitoring	
Pollution degree	2	
Ambient temperature [°	0+50	
Storage temperature [°	-25+70	
Relative humidity [%	0 90 (non-condensing)	
CE marking (see declaration of conformity)	To EU EMC Directive <sup>1)</sup>	
	To EU Machinery Directive	
Certification	c UL us - Listed (OL)	
	C-Tick	
Note on materials	RoHS-compliant	

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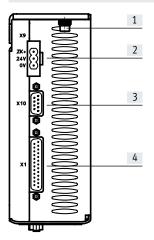
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### Datasheet

View of motor controller From the front

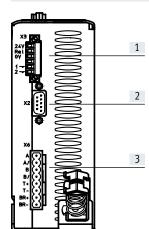


#### From above



### [1] Earthing screw

- [2] X9 power supply[3] X10 incremental encoder
- interface (bidirectional)
- [4] X1 I/O interface

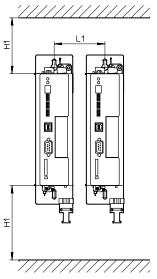


- [1] Earthing
- [2] Ready/bus LED
- [3] Status indication
- [4] Fieldbus settings and bootloader
- [5] X5 interface: RS232/RS485
- [6] X4 technology module slot
- [7] Interface: CAN bus
- [8] SD memory card
- [9] Shield connection

### From underneath

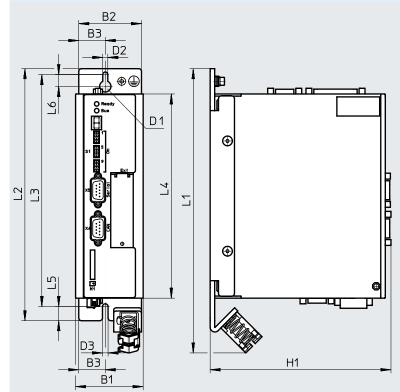
- [1] X3 safe standstill
- [2] X2 incremental encoder input for motor
- [3] X6 motor connection

### Installation clearance for motor controller



H1	L1
100	69

#### Dimensions



B1 B2 B3 D2 Η1 Туре D1 D3 Ø Ø Ø 24 10 4.5 5 CMMS-ST 60 56 161 L1 L2 L3 L4 L6 Туре L5 CMMS-ST 252 224 206.25 181 12.5 15.75

Download CAD data → <u>www.festo.com</u>

# Technical data and accessories

Ordering data					
	Description	Part no.	Туре		
	The plug assortment NEKM (→ page 11) is included in the scope of delivery of the motor controller.	572211	CMMS-ST-C8-7-G2		

#### Accessories

Ordering data – Plug-in cards						
	Description	Part no.	Туре			
	Interface module, for PROFIBUS interface	547450	CAMC-PB			
	Interface module, for DeviceNet interface	547451	CAMC-DN			
	Memory card, for data backup and firmware download	1436343	CAMC-M-S-F10-V1			

Ordering data – Connection op	tions from I/O interface to the controller			
	Description	Cable length [m]	Part no.	Туре
Control cable				
	For I/O interface to any controller	2.5	552254	NEBC-S1G25-K-2.5-N-LE26
	Recommended for analogue signals since the cable is shielded			
	For I/O interface to any controller	3.2	8001373	NEBC-S1G25-K-3.2-N-LE25
	Cannot be used if the incremental encoder interface (plug X10) is in use			
Connection block				
	Ensures simple and clear wiring. The connection to the motor controller is	-	8001371	NEFC-S1G25-C2W25-S7
	established via the connecting cable NEBC-S1G25-K			
Connecting cable				
	Connects the motor controller to the connection block	1.0	8001374	NEBC-S1G25-K-1.0-N-S1G25
		2.0	8001375	NEBC-S1G25-K-2.0-N-S1G25
		5.0	8001376	NEBC-S1G25-K-5.0-N-S1G25
Plug				
	25-pin Sub-D plug. Each wire can be individually assembled using screw	-	8001372	NEFC-S1G25-C2W25-S6
	terminals			

# Accessories

Ordering data – Cables and plugs						
	Description	Cable length [m]	Part no.	Туре		
Programming cable						
	-	2.0	160786	PS1-ZK11-NULLMODEM-2.0M		
Encoder plug						
	For incremental encoder interface	-	564264	NECC-A-S-S1G9-C2M		
			1			
Diug	•	• •				
Plug	For PROFIBUS interface	_	533780	FBS-SUB-9-WS-PB-K		
	For CANopen interface	-	533783	FBS-SUB-9-WS-CO-K		
		<u>  -</u>	199769	1535057995404		
Alter .	For DeviceNet interface	-	525635	FBSD-KL-2X5POL		

#### Ordering data – Assortment of plugs

5	Description	Part no.	Туре
	Comprising plug for power supply, motor connection and safety function	547452	NEKM-C-1
	<ul> <li>The plug assortment is included in the scope of delivery of the motor controller</li> </ul>		

#### Ordering data – Power supply units

	Description	Input voltage range [V AC]	Nominal output voltage [V DC]	Nominal output current [A]	Part no.	Туре
	Power supply for motor controller	100 240	24	5	8149580	CACN-3A-1-5-G2
				10	8149581	CACN-3A-1-10-G2
			48	5	8149583	CACN-3A-7-5-G2
				10	8149584	CACN-3A-7-10-G2
				20	8149585	CACN-11A-7-20-G2

### - 📲 - Note

If a common power supply unit is used to supply the power unit and the control unit, the voltage tolerances for supplying the control unit cannot be met at high braking energies. This can result in damage to the control unit. Always use separate power supplies to supply the power unit and the control unit.

# Accessories

Ordering data – Documentation <sup>1)</sup>								
	Language	Part no.	Туре					
		Festo Handli	ng and Positioning Profile (FHPP) for the motor controller family CMM					
	DE	555695	P.BE-CMM-FHPP-SW-DE					
	EN	555696	P.BE-CMM-FHPP-SW-EN					
	ES	555697	P.BE-CMM-FHPP-SW-ES					
	FR	555698	P.BE-CMM-FHPP-SW-FR					
	IT	555699	P.BE-CMM-FHPP-SW-IT					

1) User documentation in paper form is not included in the scope of delivery