FESTO



Characteristics

At a glance

General

- · Heavy-duty, precision T-slot guide for gripper jaws
- High gripping forces with compact dimensions
- Options for centring the gripper jaws
- · Max. repetition accuracy
- Gripping force backup
- Internal fixed flow control
- · Wide range of adaptation options on the drives
- Sensor technology:
 - Adaptable position sensor for the small gripper sizes
 - Integratable proximity switches for the medium and large gripper sizes

Flexible range of applications

- Can be used as a double-acting and single-acting gripper
- Compression spring for supporting or backing up the gripping forces
- · Suitable for external and internal gripping

The technology in detail



- Gripper jaws [1]
- Reversing lever [2]
- Piston with magnet

→ www.festo.com

Note Engineering software Gripper selection

Position sensing/force control

With position transmitter SMAT-8M



Analogue position feedback possible

• Analogue output 0 ... 10 V

With proportional-pressure regulator VPPM



Infinite adjustment of the gripping force possible

- Setpoint value input
 - 0 ... 10 V
 - 4 ... 20 mA

With proximity switch SMT-8G



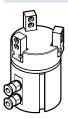
Detecting multiple positions:

- Open
- Closed
- Workpiece gripped

Key features

Compressed air supply ports

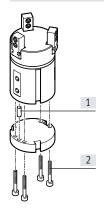
From the side

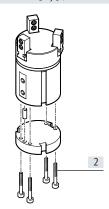


Mounting options

Size 16

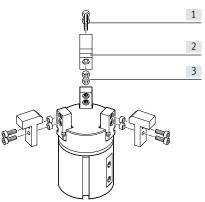
Size 32, 50





- [1] Centring pin
- [2] Retaining screws

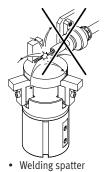
Mounting options for external gripper fingers



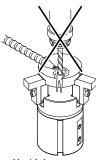


Note

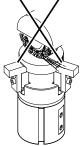
These grippers are not designed for the following or similar applications:



- [1] Retaining screws
- [2] Gripper finger
- [3] Centring sleeves



- Machining
- Aggressive media

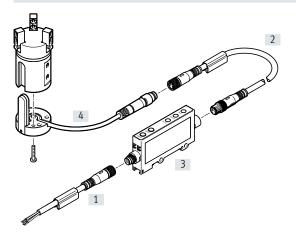


Grinding dust

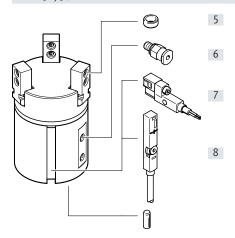
Peripherals overview

Peripherals overview

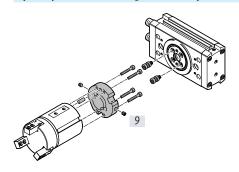
DHDS-16



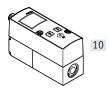
DHDS-32, 50



System product for handling and assembly technology



Proportional-pressure regulator VPPM



Access	sories			
	Туре	Size	Description	→ Page/Internet
[1]	Connecting cable NEBU	16	Connection between signal converter and controller	16
[2]	Connecting cable NEBU	16	Connection between position sensor and signal converter	16
[3]	Signal converter SVE4	16	For evaluating signals for position sensor SMH-S1	16
[4]	Position sensor SMH-S1	16	Adaptable and integratable sensor technology, for sensing the piston position	16
[5]	Centring sleeve ZBH	16 50	For centring the gripper fingers on the gripper jaws Gentring sleeves included in the scope of delivery of the gripper	16
[6]	Push-in fitting QS	16 50	For connecting tubing with standard outside diameters	qs
[7]	Proximity switch SMT-8G	32, 50	For sensing the piston position Proximity switch does not project past the housing at the bottom	17
[8]	Position transmitter SMAT-8M	32, 50	Continuously senses the position of the piston. It has an analogue output and an output signal relative to the piston position.	17
[9]	Adapter kit DHAA. HMSV, HAPG, HMVA	16 50	Connecting plate between drive and gripper	14
[10]	Proportional-pressure regulator VPPM	16 50	For infinite adjustment of the gripping force	vppm

Type codes

001	Series	
DHDS	Three-point gripper	
002	Size	
16	16	
32	32	
50	50	

003	Position sensing	
Α	For proximity sensor	
004	Gripping force backup	
	None	
NC	N/O contact	

Data sheet

Function
Double-acting
DHDS-...-A



- **G** -

Size

16 ... 50 mm



Stroke 2.5 ... 6 mm



www.festo.com

Function – Variant
Single-acting or with closing gripping
force backup
DHDS-...-NC





General technical data	General technical data					
Size		16	32		50	
Design		Lever	Lever			
		Guided motion sequence	Guided motion sequence			
Mode of operation		Double-acting				
Gripper function		3-point				
Gripping force backup		NC	NC		NC	
Number of gripper jaws		3				
Max. load per gripper finger ¹⁾	[g]	50	150		250	
Stroke per gripper jaw	[mm]	2.5	3.9		6	
Pneumatic connection		M3	M5		G1/8	
Repetition accuracy ²⁾	[mm]	≤ 0.04				
Max. interchangeability	[mm]	≤±0.2				
Max. operating frequency	[Hz]	≤ 4				
Rotational symmetry	[mm]	< Ø 0.2				
Position sensing		Via position sensor Via proximity switch, position transmitter				
Type of mounting		With female thread and dowel	pin			
Mounting position		Any				

- 1) Applies to unthrottled operation
- $2) \quad \text{Under constant exposure to operating conditions, end-position drift occurs, concentric to the central shaft, at 100 consecutive strokes} \\$

Operating and environmental conditions						
Min. operating pressure	Min. operating pressure					
DHDSA	[bar]	2				
DHDSA-NC	[bar]	4				
Max. operating pressure	[bar]	8				
Operating medium		Compressed air to ISO 8573-1:2010 [7:4:4]				
Note on operating/pilot medium		Lubricated operation possible (in which case lubricated operation will always be required)				
Ambient temperature ¹⁾	[°C]	+5 +60				
Corrosion resistance CRC ²⁾		1				

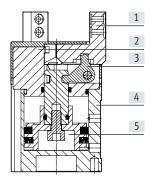
- 1) Note operating range of proximity switches
- 2) Corrosion resistance class CRC 1 to Festo standard FN 940070

 Low corrosion stress. Dry internal application or transport and storage protection. Also applies to parts behind covers, in the non-visible interior area, and parts which are covered in the application (e. g. drive trunnions).

Weight [g]			
Size	16	32	50
DHDSA	96	276	920
DHDSA-NC	99	281	932

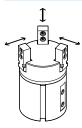
Materials

Sectional view



[1]	Gripper jaws	High-alloy stainless steel
[2]	Cover cap	Polyamide
[3]	Reversing lever	Hardened sintered steel
[4]	Housing	Hard anodised wrought aluminium alloy
[5]	Piston	Polyacetal
-	Note on materials	Free of copper and PTFE
		RoHS-compliant

Gripping force [N] at 6 bar



Size		16	32	50
Gripping force per gripper jaw				
DHDSA	Opening	40	135	280
	Closing	29	115	250
Total gripping force				
DHDSA	Opening	120	405	840
	Closing	87	345	750

Characteristic load values at the gripper jaws

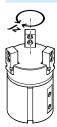


The indicated permissible forces and torques apply to a single gripper jaw. They include the lever arm, additional weight forces created by the workpiece or external gripper fingers and acceleration forces during movement.

The zero coordinate line (gripper-jaw point of rotation) must be taken into consideration for the calculation of torques.

Size		16	32	50
Max. permissible force F _z	[N]	50	150	250
Max. permissible torque M _x	[Nm]	2	9	24
Max. permissible torque M _y	[Nm]	2	9	24
Max. permissible torque M _z	[Nm]	2	9	24

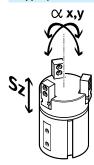
Mass moment of inertia [kgcm²]



Mass moment of inertia of the threepoint gripper in relation to the central axis, without external gripper fingers, without load.

Size	16	32	50
DHDS	0.14	0.79	6.10
DHDSNC	0.14	0.82	6.18

Gripper jaw backlash



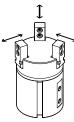
The plain-bearing guide used in the grippers means that there is backlash between the gripper jaws and the housing. The backlash values entered in the table have been calculated in accordance with the traditional accumulative tolerance method.

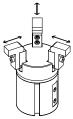
Size		16	32	50
Max. gripper jaw backlash Sz	[mm]	≤ 0.02		
Max. gripper jaw angular backlash ax, ay	[°]	≤ 0.5	≤ 0.2	

Opening and closing times [ms] at 6 bar

Without external gripper fingers

With external gripper fingers



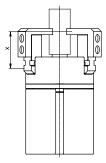


The opening and closing times [ms] were measured at room temperature at an operating pressure of 6 bar with the gripper horizontally mounted and without additional gripper fingers. The grippers must be throttled for larger loads [g]. Opening and closing times must then be adjusted accordingly.

Size		16	32	50
Without external gripper finge	ers			
DHDSA	Opening	26	44	62
	Closing	42	51	55
DHDSA-NC	Opening	31	55	73
	Closing	34	47	50
With external gripper fingers (as a function of load per grip	per finger)		
DHDS	100 g	100	-	-
	200 g	-	100	-
	300 g	-	200	100
	400 g	-	-	200
	500 g	-	-	300

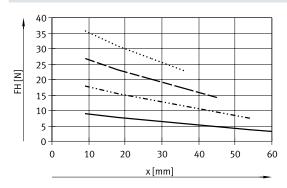
Gripping force F_H per gripper jaw as a function of operating pressure and lever arm x

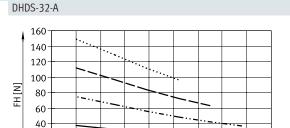
The gripping forces as a function of the operating pressure and lever arm can be determined from the following graphs.



External gripping (closing)

DHDS-16-A



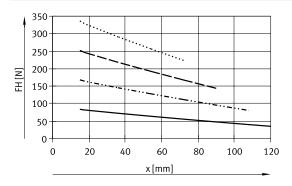


50

x [mm]

70

DHDS-50-A





20

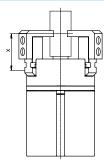
0 -

10 20

Data sheet

Gripping force F_H per gripper jaw as a function of operating pressure and lever arm \boldsymbol{x}

The gripping forces as a function of the operating pressure and lever arm can be determined from the following graphs.



- Note

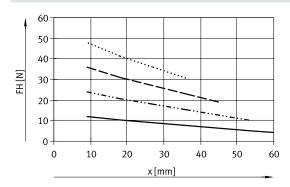
Engineering software

Gripper selection

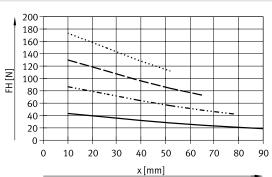
→ www.festo.com

Internal gripping (opening)

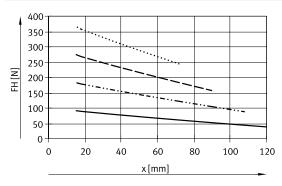
DHDS-16-A



DHDS-32-A



DHDS-50-A

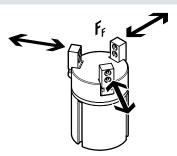


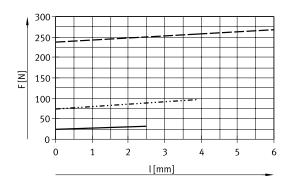


Spring force F_F as a function of size and gripper jaw stroke l

Gripping force backup for DHDS-...-NC

The spring forces F_F as a function of the gripper jaw stroke can be determined from the following graph.





DHDS-16-A-NC
DHDS-32-A-NC
DHDS-50-A-NC

Spring force F_F as a function of size, gripper jaw stroke l and lever arm x per gripper finger

The lever arm x must be taken into consideration when determining the actual spring force F_{Rotal} .

The formulae for calculating the spring force are provided in the table below.

Gripping force backup	Size	F _{Ftotal} per gripper finger
NC	16	-0.1* x+0.33* F _F
	32	-0.2* x+0.33* F _F
	50	-0.3* x+0.33* F _F

Determining the actual gripping forces F_{Gr} for DHDS-...-NC as a function of application per gripper finger

Depending on requirement, the three-point grippers with integrated spring, type DHDS-...-NC (closing gripping force backup), can be used as:

In order to calculate the available gripping forces F_{Gr} (per gripper finger), the gripping force F_{H} and spring force F_{Ftotal} must be combined accordingly.

- single-acting grippers
- grippers with supplementary gripping force and
- grippers with gripping force backup

Application forces per gripper finger

Single-acting

Supplementary gripping force

Gripping force backup

• Gripping with spring force: $F_{Gr} = F_{Ftotal}$

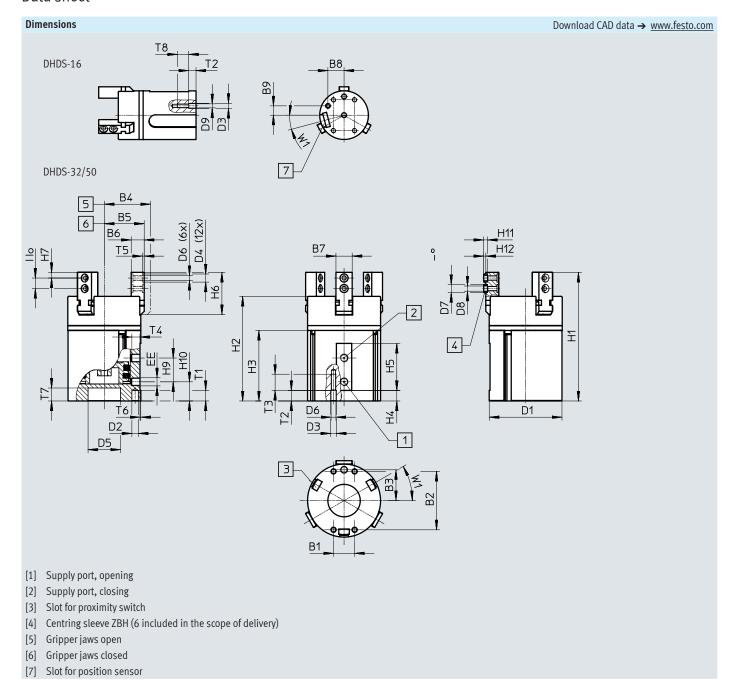
Gripping with pressure and spring force:

• Gripping with spring force: $F_{Gr} = F_{Ftotal}$

Gripping with pressure force:

 $F_{Gr} = F_H + F_{Ftotal}$

 $F_{Gr} = F_{H} - F_{Ftotal}$



Size	B1	B2	B3	B4		B5	B6	B7	B8	B9
[mm]			±0.02	±0.	5	±0.5	-0.02/-0.05	-0.02	-0.1	-0.1
16	13	19	11.5	20		17.5	7	6	9.96	5.75
32	13	36	19	28.	5	24.6	8	10	-	-
50	25	54	30	43		37	12	14	-	-
Size	D1	D2	D3	D4		D5	D6	D7	D8	D9
3126	ø	ø	ø	ø		Ø	50	ø	ø	D)
[mm]	,	H8	H8	H8		+0.05/+0.02		h7	, v	
16	30	3	3.2	5		-	M3	5	3.2	M2.5
32	45	4	3.5	5		20	M3	5	3.2	-
50	70	5	6	7		30	M5	7	5.3	-
Size	EE	H1	H2	Н3	H4	H:	5 H6	H7	H8 ¹⁾	Н9
[mm]										
16	M3	60	47.9	32.6	4.5	24	4 21.	5 3	6	12
32	M5	78	63.2	42.2	5.2	25	9 26	3.5	6.5	14.7
50	G1/8	107.5	86.5	56	6.7	4(0 37	5	10	22
Size	H10	T1	T2	T3	T4	T!	5 T6	Т7	Т8	W1
[mm]		min.	min.	+1	-0.5	5 +0.	.1 ±0.	2	±1	
16	11	4.5	4.5	8	4	1.	2 1	-	7	15°
32	10.5	6.5	6.5	10	4	1.	1 0.5	5 8	-	30°
50	16	7	7	18	6	1.	6 1	9	-	30°

¹⁾ Tolerance for centring hole ± 0.02 mm; tolerance for thread ± 0.1 mm

Ordering data				
Size	Double-acting		Single-acting or	with gripping force backup
	without compres	ssion spring	closing	
[mm]	Part no.	Туре	Part no.	Туре
16	1259491	DHDS-16-A	1259492	DHDS-16-A-NC
32	1259493	DHDS-32-A	1259494	DHDS-32-A-NC
50	1259495	DHDS-50-A	1259496	DHDS-50-A-NC

Accessories

Adapter kit DHAA, HAPG, HMSV, HMVA Material: Wrought aluminium alloy Free of copper and PTFE ROHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper co Combination		Crinner	Adamtari	,i+	Download CAD data → www.festo.co
CONTRIBUTION	Actuator	Gripper	Adapter l KBK ¹⁾		T
	Size	Size	KRK ₂	Part no.	Туре
DRRD/DHDS	DRRD	DHDS	DHAA	!	
	12	16	2	2823512	DHAA-G-Q11-12-B4-16
	16	16		2136626	DHAA-G-Q11-16-B4-16
	16	32		2151381	DHAA-G-Q11-16-B4-32
	20	32		2136339	DHAA-G-Q11-20-B4-32
	25	32		1471583	DHAA-G-Q11-25-B4-32
	25	50		1731165	DHAA-G-Q11-25-B4-50
	32	50		1907040	DHAA-G-Q11-32-B4-50
	35	50		2135899	DHAA-G-Q11-35-B4-50
SP/DHDS	HSP	DHDS	HAPG		
	16	16	2	192705	HAPG-36-S1
	•			540882	HAPG-71-B
	25	16		192705	HAPG-36-S1
				540883	HAPG-72-B
	<i>δ</i>				
ISW/DHDS	HSW	DHDS	HAPG		
SC SC	<u>16</u>	16	2	192705	HAPG-36-S1
				540882	HAPG-71-B

¹⁾ Corrosion resistance class CRC 2 to Festo standard FN 940070 Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment.

²⁾ For DGEA-... only

Accessories

Adapter kit DHAA, HAPG Material:

Wrought aluminium alloy Free of copper and PTFE RoHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

ombination	Actuator	Gripper	Adapter k	it	
	Size	Size	KBK ¹⁾	Part no.	Туре
DSM/DHDS	DSM	DHDS	HAPG		
	8, 10	16	2	187569	HAPG-35
	25	32		163272	HAPG-23
DSMHD/DHDS	DSMHD	DHDS	DHAA		
	12	16	2	8072232	DHAA-G-R3-12-B19-16
	16	16		8079175	DHAA-G-R3-16-B19-16
	16	32		8079191	DHAA-G-R3-16-B19-32
	25	32		8079196	DHAA-G-R3-25-B19-32
	25	50		8079199	DHAA-G-R3-25-B19-50
	32	50		8079210	DHAA-G-R3-32-B19-50
		·			
RMB/DHDS	ERMB	DHDS	HAPG		
	20	32	2	184481	HAPG-SD2-5
	25	50		184484	HAPG-SD2-8
	32	50		184487	HAPG-SD2-11
ERMO/DHDS	ERMO	DHDS	DHAA		
<u> </u>	12	16	2	8072232	DHAA-G-R3-12-B19-16
	16	16		8079175	DHAA-G-R3-16-B19-16
	16	32		8079191	DHAA-G-R3-16-B19-32
~ Me 1100 1100	25	32		8079196	DHAA-G-R3-25-B19-32
	25	50		8079199	DHAA-G-R3-25-B19-50
	32	50		8079210	DHAA-G-R3-32-B19-50
	32				
			1		
EHMB/DHDS	ЕНМВ	DHDS	HAPG	40//07	HADC CD2 44
		DHDS 50 50	HAPG 2	184487 526026	HAPG-SD2-11 HAPG-SD2-20

¹⁾ Corrosion resistance class CRC 2 to Festo standard FN 940070

Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment.

Accessories

Ordering data						
	For size	Comment	Weight	Part no.	Туре	PU ¹⁾
	[mm]		[g]			
				-		
Centring sleeve 2	ZBH				Data sheets → Inter	net: zbh
Centring sleeve 2	ZBH 16, 32	For centring the gripper fingers on the gripper jaws	1	189652	Data sheets → Inter ZBH-5	net: zbh 10

1) Packaging unit

Ordering data				
Туре	For size	1,,	Part no.	Туре
		[g]		
Position sensor SMH-S1				Data sheets → Internet: smh-s1
	16	30	175713	SMH-S1-HGD16

Signal converter SVE4 for position sensor SMH-S1

- Converts analogue signals into switching points
- Switching function freely programmable with teach-in
- Threshold value, hysteresis or window comparator

Ordering data							
Туре	For size	Input connection	Output connection	Switching output	Weight [g]	Part no.	Туре
Signal converter	SVE4						Data sheets → Internet: sve4
	16	Socket M8x1,	Plug M8x1,	2x PNP	19	544216	SVE4-HS-R-HM8-2P-M8
\$ 353		4-pin	4-pin	2x NPN		544219	SVE4-HS-R-HM8-2N-M8

Ordering data	– Connecting cables				Data sheets → Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Туре
Connection be	tween position sensor and signal conver	rter			
60 M	Straight socket, M8x1, 4-pin	Straight plug M8x1, 4-pin	2.5	554035	NEBU-M8G4-K-2.5-M8G4
Connection be	tween signal converter and controller			,	·
	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4
500 P			5	541343	NEBU-M8G4-K-5-LE4
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4
			5	541345	NEBU-M8W4-K-5-LE4

Accessories

Proximity sw	vitch for size 32, 50					
Ordering dat	ta – Proximity switch for T-slot, mag	neto-resistive				Data sheets → Internet: smt
ı	Type of mounting	Electrical connection, outlet direction of connection	Switching output	Cable length [m]	Part no.	Туре
N/O contact						
A	Inserted in the slot lengthwise	Cable, 3-wire, crosswise	PNP	2.5	547859	SMT-8G-PS-24V-E-2,5Q-OE
		Plug M8x1, 3-pin, crosswise		0.3	547860	SMT-8G-PS-24V-E-0,3Q-M8D
		Cable, 3-wire, crosswise	NPN	2.5	8065028	SMT-8G-NS-24V-E-2,5Q-OE
		Plug M8x1, 3-pin, crosswise		0.3	8065027	SMT-8G-NS-24V-E-0,3Q-M8D
Ordering dat	ta – Connecting cables					
	1					Data sheets → Internet: nebu
	Electrical connection, left	Electrical connection, right		Cable length	Part no.	Data sheets → Internet: nebu Type
	Straight socket, M8x1, 3-pin	Electrical connection, right Cable, open end, 3-wire		Cable length [m]	Part no. 541333	
	·	, ,		[m]		Туре
	·	, ,		[m] 2.5	541333	Type NEBU-M8G3-K-2.5-LE3

Position transmitter

The position transmitter continuously senses the position of the piston.

It has an analogue output and an output signal relative to the piston position.

Ordering data -	– Position trar	smitter for T-sl	ot				Dat	ta sheets → Internet: position transmitter
	For size	Position measuring range	Analogue output [V]	Type of mounting	Electrical connection	Cable length [m]	Part no.	Туре
	32, 50	0 40	0 10	Inserted in the slot from above	Plug M8x1, 4-pin, in-line	0.3	553744	SMAT-8M-U-E-0,3-M8D
Ordering data -	– Connecting o	ables						Data sheets → Internet: nebu
Ordering data -		cables		Electrical connection, rig	ht	Cable length	Part no.	Data sheets → Internet: nebu
	Electrical co			Electrical connection, rig			Part no.	1
Ordering data -	Electrical co	nnection, left				[m]		Туре
	Electrical co	nnection, left	1			[m] 2.5	541342	Type NEBU-M8G4-K-2.5-LE4

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