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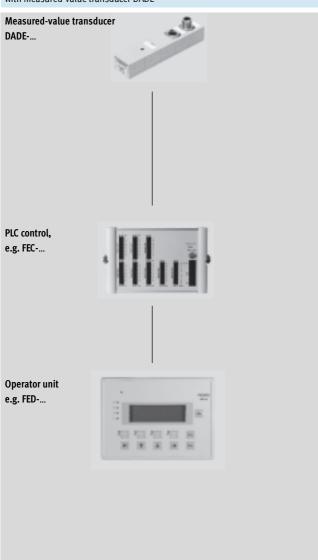


Components for positioning and measuring using the standard cylinder DDPC



Measuring





Positioning with end-position controller SPC11 or controller module CPX-CMAX/-CMPX

control valve MPYE-...

Proportional directional



End-position controller SPC11-INC



Proportional directional control valve VPWP-...



Sensor interface CASM-S-D3-R7

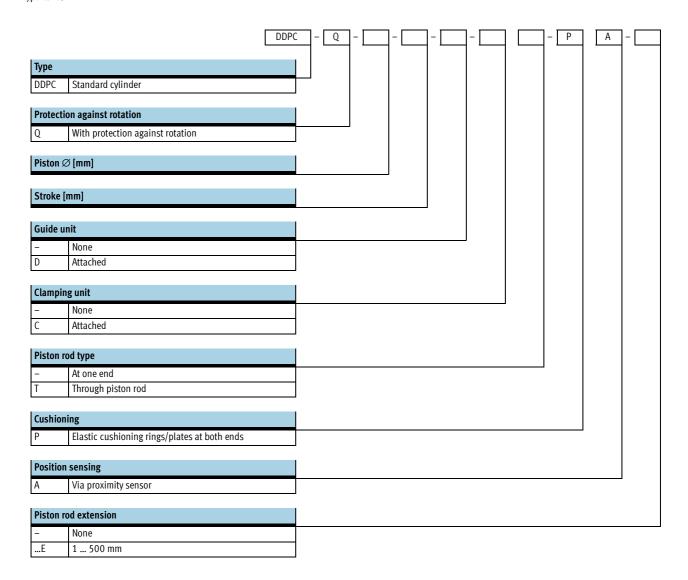


Controller module CPX-CMAX, CPX-CMPX



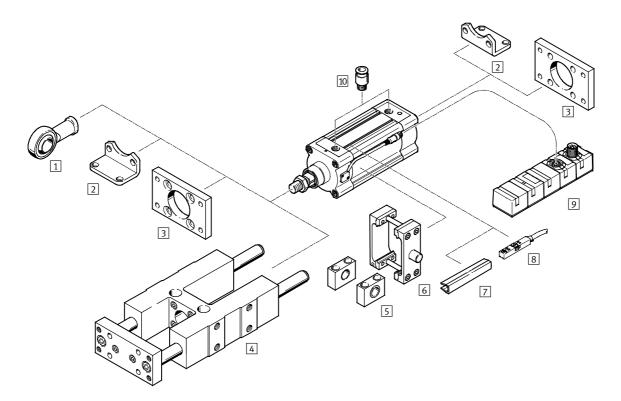


Type codes





Peripherals overview



- Note

If the drive DDPC is used without an end-position controller CPX-CMPX, SPC11 or axis controller CPX-CMAX, SPC200, e.g. as a measuring cylinder, then the standard accessories for the drive DNC can be used.

Standard cylinders DDPC, with measured-value transducer DADE Peripherals overview



Acce	ssories		
	Туре	Brief description	→ Page/Internet
1	Rod eye	With spherical bearing	ddpc
	SGS		
2	Foot mounting	For mounting the drive on the bearing and end caps	ddpc
	HNC		
3	Flange mounting	For mounting the drive on the bearing and end caps	ddpc
	FNC		
4	Guide unit ¹⁾	For protecting against rotation at high torque loads	12
	FENG-KF		
5	Trunnion support	For securing the trunnion mounting kit DAMT	ddpc
	LNZG		
6	Trunnion mounting kit	For swivelling movements of the drive	ddpc
	DAMT		
7	Slot cover	For protecting against contamination	ddpc
	ABP-5-S		
8	Proximity sensor	For additional sensing of the piston position, can be ordered optionally, only in conjunction	ddpc
	SME/SMT-8	with the order code A in the drive's modular product section	
9	Measured-value transducer	Converts the sensor signal of the cylinder in to a voltage signal of 0 10 V and/or a current	14
	DADE	signal of 4 20 mA	
10	Push-in fitting	For connecting outer toleranced compressed air tubing	quick star
	QS		

¹⁾ Guide unit FENG-KF must be attached to the piston rod in a way that eliminates backlash



Technical data

Function











General technical data								
Piston ∅		80	100					
Based on standard		ISO 15552						
Design		Piston						
		Piston rod						
		Profile barrel						
Mode of operation		Double-acting						
Guide ¹⁾		Guide rod with yoke, with ball bearing guide						
Protection against rotation		Square piston rod						
Mounting position		Any						
Type of mounting		Via accessories						
Cushioning		Elastic cushioning rings/plates at both ends						
Position sensing		Integrated displacement encoder						
		Via proximity sensor ²⁾						
Measuring principle (displacement encoder)		Encoder, contactless and relative measurement						
Pneumatic port		G3/8	G½					
Stroke								
DDPC	[mm]	10 2,000						
DDPCD	[mm]	100 500						
Extended piston rod	[mm]	1 500						

- 1) Guide unit FENG-KF can be ordered via the modular product system (feature D) and is supplied attached. The maximum stroke is restricted.
- 2) Not included in the scope of delivery, can be ordered as an option

Operating and environmental conditions							
Operating pressure [bar]	412						
Operating pressure ¹⁾ [bar]	4 8						
Operating medium ²⁾	Compressed air to ISO 8573-1:2010 [6:4:4]						
Note on operating/pilot medium	Lubricated operation not possible						
	Pressure dew point 10°C below ambient/medium temperature						
Ambient temperature ³⁾ [°C]	-20 +80						
Vibration resistance to DIN/IEC 68, Part 2 - 6	Severity level 2						
Continuous shock resistance to DIN/IEC 68, Part 2 - 82	Severity level 2						
CE marking (see declaration of conformity) ⁴⁾	To EU EMC Directive						
Corrosion resistance class CRC ⁵⁾	1						

- 1) Only applies to applications with end-position controller CPX-CMPX, SPC11 and axis controller CPX-CMAX, SPC200
- 2) The proportional directional control valve VPWP, MPYE requires these characteristic values
- Note operating range of proximity sensors
- For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com
 Support
 User documentation.

 If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.
- 5) Corrosion resistance class 1 according to Festo standard 940 070
 Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.



Forces [N] and impact energy [Nm]									
Piston ∅	80	100							
Theoretical force at 6 bar, advancing	3,016	4,712							
Theoretical force at 6 bar, retracting	2,721	4,418							
Impact energy at the end positions	1.8	2.5							

Permissible impact Impact - Note Permissible impact velocity velocity Maximum impact Impact These specifications represent the maximum values that can be energy achieved. Note the maximum m_{Intrinsic} Moving mass (drive) $m_{Load} \ = \frac{2 \ x \ E_{perm.}}{v^2} \ - \ m_{Intrinsic}$ Maximum permissible load: permissible impact energy. Moving payload

Electrical data – Displacement encoder							
Output signal		Analogue					
Linearity error							
Strokes up to 500 mm	[mm]	< ±0.08					
Strokes up to 1,000 mm	[mm]	< ±0.09					
Strokes above 1,000 mm	[mm]	< ±0.11					
Maximum travel speed	[m/s]	1.5					
Protection class		IP65					
CE marking (see declaration of conformity)		To EU EMC Directive ¹⁾					
Maximum permitted magnetic interference	[kA/m]	10					
field ²⁾							
Electrical connection		Cable with 8-pin plug, round design, M12					
Cable length	[m]	1.5					

- 1) For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com
 Support
 User documentation. If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.

 2) At a distance of 100 mm

Pin allocation for plug



Pin	Function	Colour
1	5V	Black
2	GND	Brown
3	sin+	Red
4	sin-	Orange
5	cos-	Green
6	COS+	Yellow
7	Screening	Screening
8	n.c.	-

Standard cylinders DDPC, with measured-value transducer DADE Technical data

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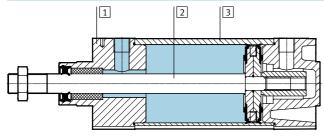
Subject to change – 2013/11

Weight [g]		
Piston \varnothing	80	100
DDPC		
Basic weight with 0 mm stroke	3,053	4,330
Additional weight per 10 mm stroke	87	95
Moving mass with 0 mm stroke	804	994
Additional weight per 10 mm stroke	31	31
	·	
DDPCT – through piston rod		
Basic weight with 0 mm stroke	3,537	5,019
Additional weight per 10 mm stroke	127	134
Moving mass with 0 mm stroke	1,247	1,467
Additional weight per 10 mm stroke	70	70
DDPCE – additional weight with piston rod	sutancian .	
Additional weight per 10 mm extension	31	31
DDPCC – additional weight with clamping un	t	
Additional weight	2,046	2,829
DDPCD – additional weight with guide unit		
Basic weight with 0 mm stroke	10,430	12,990
Additional weight per 10 mm stroke	80	80

Materials

8

Sectional view



Stan	dard cylinder						
1	Cover	Wrought aluminum alloy					
2	Piston rod	High-alloy steel					
3	Cylinder barrel	Wrought aluminum alloy					
-	Seals	Nitrile rubber, polyurethane					
	Note on materials	Free of copper and PTFE					
		RoHS-compliant					

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Technical data

Torques and lateral forces

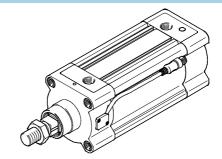
Max. torque for protection against rotation:

Dynamic $\leq 3 \text{ Nm}$ Static $\leq 5 \text{ Nm}$

An external guide unit FENG-KF is recommended with higher torque loads. The guide unit is supplied attached.

The permissible static and dynamic characteristic load values with and without attached guide

→ Internet: feng



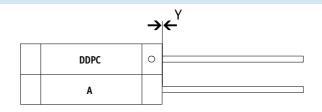
Mounting conditions

When mounting a drive A with magnet (for position sensing) next to a standard cylinder DDPC, the following conditions must be observed:

- X Minimum distance between the drives
- Y Offset between the drives on the bearing cap

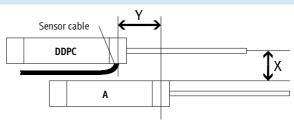
Parallel assembly

If the offset Y = 0 mm, the drives can be assembled directly next to one another.



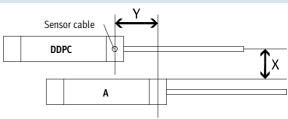
Off-set assembly, cable outlet between the drives

If the offset is Y > 0 mm and the cable outlet is between the drives, a distance of X > 70 mm must be observed.



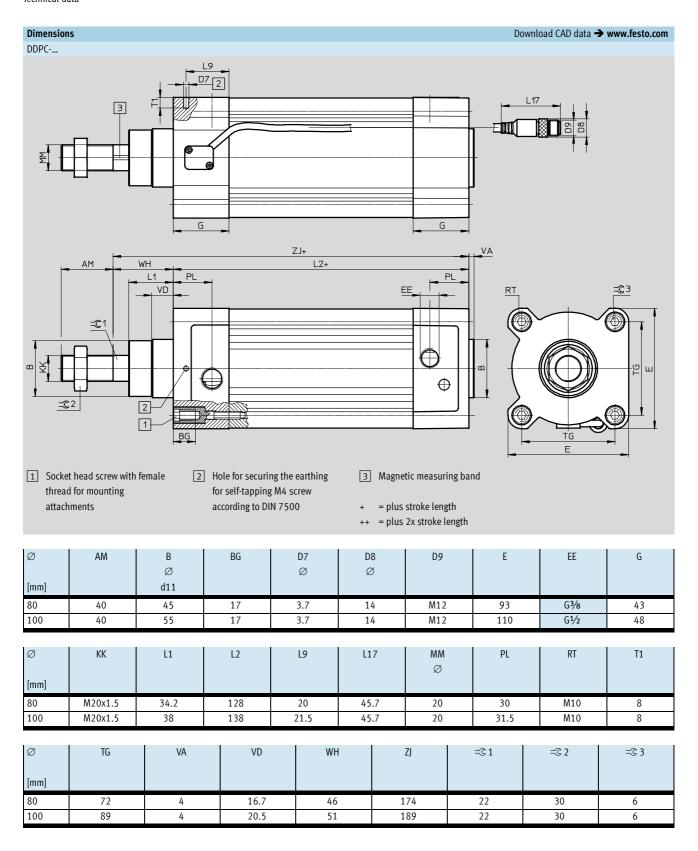
Off-set assembly, cable outlet upwards or downwards

If the offset is Y > 0 mm and the cable outlet is up or down, a distance of X > 60 mm must be observed.



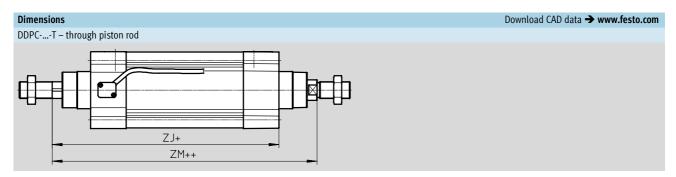
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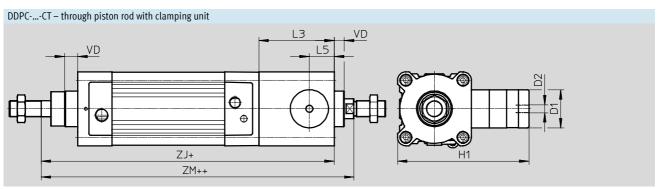
Technical data



Standard cylinders DDPC, with measured-value transducer DADE Technical data







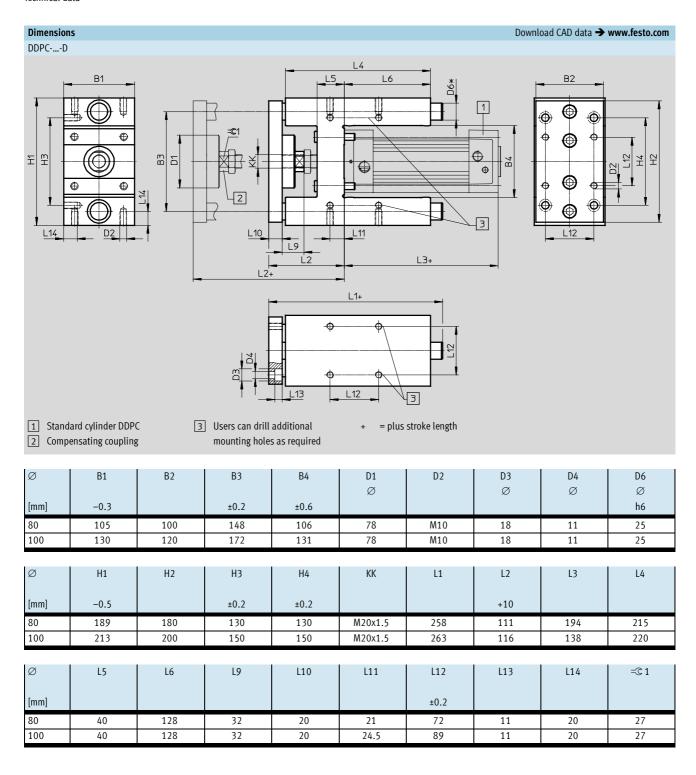


Ø	A2	D1	D2	H1	L3	L5
		Ø				
[mm]	max.	f9				
80	500	48	G1/8	165.5	95	31.5
100	500	48	G1/8	174	98	31

Ø	VD	WH	Z	J	ZM				
[mm]			DDPCT	DDPCCT	DDPCT	DDPCCT			
80	16.7	46	174	269	222	317			
100	20.5	51	189	287	240	338			



Technical data



Standard cylinders DDPC, with measured-value transducer DADE Ordering data – Modular products

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Or	dering table									
Pi	ston Ø		80	Condi- tions	Code		Enter code			
M	Module No.		1677705	1691433						
	Function		Standard cylinder with integrated displace	cement encoder		DDPC		DDPC		
	Protection against rotation		With protection against rotation			-Q		-Q		
	Piston Ø	[mm]	80	80 100						
	Stroke	[mm]	10 2,000							
0	Guide unit		None							
			Attached	Attached						
	Clamping unit		None							
			Attached	Attached						
	Piston rod type		At one end							
			Through piston rod		T					
M	Cushioning		Elastic cushioning rings/plates at both e	nds		-P		-P		
	Position sensing		For proximity sensor	ty sensor						
0	Piston rod extension		None							
		[mm]	1 500		E					

¹ C Only available with T

Transfer order	cod	e												
		DDPC	-	Q	_	_	-	-	-	-	P	Α	-	

Standard cylinders DDPC, with measured-value transducer DADETechnical data

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Measured-value transducer DADE-MVC-010 DADE-MVC-420

The measured-value transducer converts sensor signals from the standard cylinder DDPC into a voltage signal of 0 ... 10 V or a current signal of $4 \dots 20$ mA. These signals can be evaluated by a PLC with an appropriate signal input.



General technical data			
Type of mounting		Via through-hole	
Mounting position		Any	
Repetition accuracy in relation to	≤ 400	±0.1 mm	
effective stroke	≤ 750	±0.2 mm	
	≤ 1200	±0.3 mm	
	≤ 1600	±0.4 mm	
	≤ 2000	±0.5 mm	
Protection against short circuit		Yes	
Protection against incorrect polarity		Yes	
Diagnostic function		Display via LED	

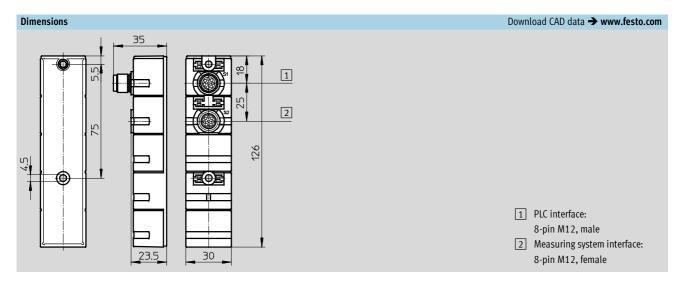
General electrical data			
Analogue output	[V]	0 10 (according to EN 61131-2)	
	[mA]	4 20 (according to EN 61131-2)	
Nominal operating voltage	[DC V]	24 ±25%	
Residual ripple	[%]	4 (at 50 Hz)	
Current consumption at nominal	[mA]	20 30	
operating voltage			
Switching logic at outputs		PNP	
Switching logic at inputs		PNP	
Debounce time at inputs	[ms]	3	
Linearity error FS		0.2%	

Operating and environmental conditions			
Ambient temperature [°C]	0 55		
Protection class	IP65		
Relative air humidity	95% non-condensing		
CE marking (see declaration of conformity)	To EU EMC Directive		
Corrosion resistance class CRC ¹⁾	1		
Product weight [g]	128		
Note on material for housing	Polybutylene terephthalate		

¹⁾ Corrosion resistance class 1 according to Festo standard 940 070 Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.

Standard cylinders DDPC, with measured-value transducer DADE Technical data



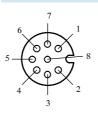


Pin allocation

PLC interface



Measuring system interface	Measuring	system	interface
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Pin	Function	Cable colour
1	24V	White
2	Analogue measurement signal	Brown
3	Reference output	Green
4	0 V measurement signal	Yellow
5	Reference input	Grey
6	Calibration input	Pink
7	Ready output	Blue
8	0 V power supply and inputs/ outputs	Red

Pin	Function
1	Ub
2	0 V
3	Signal sine +
4	Signal sine –
5	Signal cosine –
6	Signal cosine +
7	Screening / earth
8	-

Ordering data					
		Description	Part no.	Туре	
Measured-value transducer					
	With voltage signal	0 10 V	542 117	DADE-MVC-010	
	With current signal	4 20 mA	542 118	DADE-MVC-420	
Accessories Technical data → Internet: sim					
	Connecting cable	PLC connecting cable (length 2 m)	525 616	SIM-M12-8GD-2-PU	
		PLC connecting cable (length 5 m)	525 618	SIM-M12-8GD-5-PU	