



Cylinders with displacement encoder Product range overview

Function	Туре	Brief description
Drives	Rodless	
	DDLI	 Without guide With contactless displacement encoder Based on linear drive DGC-K Supply ports optionally on end face or front System product for handling and assembly technology
	DGCI	 With guide With contactless displacement encoder Based on linear drive DGC Supply ports optionally on end face or front System product for handling and assembly technology
	DGPI/DGPIL	Do not use for new projects! • With or without guide • With contactless displacement encoder, integrated • Wide range of options for mounting on drives • System product for handling and assembly technology
	DGP/DGPL	Do not use for new projects! • With or without guide • With potentiometer or contactless displacement encoder, attached • With clamping unit • Wide range of options for mounting on drives
	With piston rod	
	DNCI	 With contactless displacement encoder Various piston rod variants Standards-based cylinder to ISO 15552 DIN VDMA
	DDPC	 With contactless displacement encoder Various piston rod variants Standards-based cylinder to ISO 15552 DIN VIENA
	DNC/DSBC	 With attached potentiometer MLO-LWG Various piston rod variants Standards-based cylinder to ISO 15552 DIN VDMA
	30	
Swivel module	Swivel module DSMI	 Based on swivel module DSM Integrated rotary encoder Compact design Wide range of mounting options

Cylinders with displacement encoder Product range overview

$\textbf{Piston}\varnothing$	Stroke/swivel angle	Suitable					
		For positioning v		For end-position		For use as a measuring	
	[mm/°]	CPX-CMAX	SPC200	CPX-CMPX	SPC11	cylinder	
Rodless							
25, 32	100; 160; 225; 300; 360;						
	450; 500; 600; 750; 850;						
	1,000; 1,250; 1,500;						
	1,750; 2,000	•	•	•	•	•	
	-,, -, -, -,						
40.25.22	400 4(0 225 200 2(0						
18, 25, 32,	100; 160; 225; 300; 360;						
40,63	450; 500; 600; 750; 850;						
	1,000; 1,250; 1,500;						
	1,750; 2,000	-	-	-	-	-	
25, 32, 40,	225; 300; 360; 450; 500;						
50,63	600; 750; 1,000; 1,250;						
	1,500; 1,750; 2,000		_				
	_,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	-	-	-		-	
25, 32, 40,	225; 300; 360; 450; 500;						
50,63	600; 750; 1,000; 1,250;						
	1,500; 1,750; 2,000	-	•	-	•	•	
With piston r		1					
32, 40, 50,	10 2,000						
63	10 2,000					_	
03		-	-	-	-	•	
	100 750						
		•	•	•	•	-	
80,100	10 2,000						
		-	-	-	-	•	
	100 750						
			•	•		-	
32,40,50,	100, 150, 225, 300, 360,						
63,80	450, 600, 750						
		_	_	_	_	_	
			•	•	•	•	
Swivel modu		1					
25,40,63	270						
						•	
			_				

Key features

Servopneumatic drive technology

Positioning and Soft Stop applications as an integral component of the valve terminal CPX – the modular peripheral system for decentralised automation tasks.

The modular design means that valves, digital inputs and outputs, positioning modules and end-position controllers, as appropriate to the application, can be combined in almost any way on the CPX terminal.

Advantages:

- Pneumatics and electrics control and positioning on one platform
- Innovative positioning technology piston rod drives, rodless drives, rotary drives
- Actuation via fieldbus
- Remote maintenance, remote diagnostics, web server, SMS and e-mail alert are all possible via TCP/IP
- Modules can be quickly exchanged and expanded without altering the wiring

Axis controller CPX-CMAX



Free choice:

Position and force control, directly actuated or selected from one of 64 configurable position sets. If you are looking for something more: the configurable function for switching to the next set enables simple functional sequences to be realised in the axis controller CPX-CMAX.

All stations are recognised as the auto-identification function identifies each station with its device data on the controller CPX-CMAX.

Also included:

The functional scope of the controller CPX-CMAX includes actuation of a brake or clamping unit via the proportional directional control valve VPWP.

Up to 8 modules (max. 8 axes) can be operated in parallel and independently of each other. Commissioning via FCT (Festo configuration software) or via fieldbus: no programming, only configuration.

Technical data → Internet: cpx-cmax

- Advantages:
- Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
- You program the system in your PLC environment

Key features

End-position controller CPX-CMPX



Fast travel between the mechanical end stops of the cylinder, stopping gently and without impact in the end position.

Fast commissioning via control panel, fieldbus or handheld unit. Improved downtime control. Actuation of a brake or clamping unit via the proportional directional control valve VPWP is an integral part of the controller CMPX. Depending on the fieldbus chosen, up to 9 end-position controllers can be actuated on the CPX terminal. All system data can be read and written via the fieldbus, including, for example, the mid positions.

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Technical data → Internet: cpx-cmpx

Advantages:

- Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
- Up to 30% faster cycle rates
 Significantly reduced system vibration
- Improved work ergonomics thanks to significantly reduced noise level
- The extended diagnostics help to reduce the service time for the machine

Technical data → Internet: vpwp

Advantages:

- Easy installation and fast commissioning
- Reduction of system downtimes thanks to the new diagnostic options
- With switching output for actuating a brake/clamping unit

Proportional directional control valve VPWP



The 5/3-way proportional directional control valve for applications with Soft Stop and pneumatic positioning. Fully digitalised – with integrated pressure sensors, with new diagnostic functions. In sizes 4, 6, 8 and 10. Flow rate of 350, 700, 1,400 and 2,000 l/min. With switching output for actuating a brake. Coloured supply ports.

Pre-assembled cables guarantee faultless and fast connection with the controllers CPX-CMPX and CPX-CMAX.

Measuring module CPX-CMIX



Fully digital data acquisition and transmission means pneumatic cylinders can be used as sensors. With very high repetition accuracy and incorporating both analogue and digital measuring sensors. Suitable for the linear drive DGCI with displacement encoder for measuring absolute values, for the piston rod drive DNCI/DDPC with incremental displacement encoder or even for a potentiometer of the type MLO.

Technical data → Internet: cpx-cmix

- Advantages: • All process steps can be docu-
- mented, which improves quality
- An adjustable contact force (via pressure regulator) increases the precision of the "displacement sensor"
- With displacement encoders for measuring absolute values, the actual position is immediately available after the system is switched on

Drive options

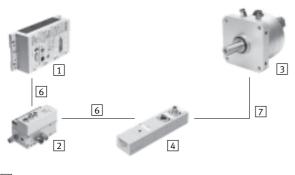
System with linear drive DDLI, DGCI Technical data → Internet: dgci Pneumatic rodless linear drive Advantages: with displacement encoder, with • Complete drive unit 6 or without recirculating ball DDLI for easy connection to bearing guide customer's guide system 3 • Displacement encoder with abso-• Excellent running characteristics • For fast and accurate positioning lute and contactless measuring • Identical design to pneumatic down to ±0.2 mm (only with axis linear drive DGC controller CPX-CMAX) 1 Controller module CPX-CMPX or CPX-CMAX • Diameter: 18 ... 40 and 63 mm 2 Proportional directional control valve VPWP • Stroke: 100 ... 2,000 mm in fixed 3 Linear drive DDLI, DGCI with displacement encoder lengths 6 Connecting cable KVI-CP-3-... • Range of applications: Soft Stop and pneumatic positioning • Loads from 1 ... 180 kg • No sensor interface required System with linear drive DGPI, DGPIL or displacement encoder MME-MTS Technical data → Internet: dgpi Pneumatic rodless linear drive Advantages: with displacement encoder, with • Complete drive unit 6 9 or without recirculating ball • DGPI for easy connection to bearing guide customer's guide system 3 • Displacement encoder with abso- Excellent running characteristics lute and contactless measuring • For fast and accurate positioning • Diameter: 25 ... 63 mm down to ±0.2 mm (only with axis • Stroke: 225 ... 2,000 mm in fixed controller CPX-CMAX) 1 Controller module CPX-CMPX or CPX-CMAX lengths 2 Proportional directional control valve VPWP • Range of applications: Soft Stop 3 Linear drive DGPI, DGPIL with displacement encoder and pneumatic positioning Connecting cable KVI-CP-3-... • Loads from 2 ... 180 kg 6 9 NEBP-M16W6-K-2-M9W5 • No sensor interface required System with standard cylinder DNCI, DDPC Technical data → Internet: dnci • Standard cylinder with integrated Advantages: displacement encoder, conforms • Compact drive unit to DIN ISO 6432, VDMA 24 562, Can be used universally NF E 49 003.1 and Uni 10 290 • Also with guide unit • Displacement encoder with For fast and accurate positioning down to ±0.5 mm (only with axis contactless and incremental measuring controller CPX-CMAX) 6 • Diameter: 32 ... 100 mm • Stroke: 100 ... 750 mm 5 • Range of applications: Soft Stop and pneumatic positioning • Loads from 3 ... 450 kg and a 1 Controller module CPX-CMPX or CPX-CMAX matching sensor interface 2 Proportional directional control valve VPWP CASM-S-D3-R7 3 Standard cylinder DNCI, DDPC with displacement encoder • Pre-assembled cables guarantee 5 Sensor interface CASM-S-D3-R7 faultless and fast electrical 6 Connecting cable KVI-CP-3-... connection

Subject to change – 2013/06

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Drive options

System with swivel module DSMI



- 1 Controller module CPX-CMPX or CPX-CMAX
- 2 Proportional directional control valve VPWP
- 3 Swivel module DSMI with displacement encoder
- 4 Sensor interface CASM-S-D2-R3
- 6 Connecting cable KVI-CP-3-...
- 7 Connecting cable NEBC-P1W4-K-0,3-N-M12G5

System with potentiometer

- 1 Controller module CPX-CMPX or CPX-CMAX
- 2 Proportional directional control valve VPWP
- 4 Sensor interface CASM-S-D2-R3
- 6 Connecting cable KVI-CP-3-...
- 7 Connecting cable NEBC-P1W4-K-0,3-N-M12G5
- 8 Connecting cable NEBC-A1W3-K-0,4-N-M12G5

- Swivel module DSMI with integrated displacement encoder
- Identical design to pneumatic swivel module DSM
- Absolute displacement encoder on basis of potentiometer
- Swivel range from 0 ... 270°
- Size: 25, 40, 63
- Max. torque: 5 ... 40 Nm
 Range of applications: Soft Stop and pneumatic positioning
- Mass moments of inertia from 15 ... 6,000 kgcm² and a matching sensor interface CASM-S-D2-R3
- Pre-assembled cables guarantee faultless and fast connection with the proportional directional control valve VPWP

Technical data → Internet: dsmi

Advantages:

- Complete drive unit, compact, can be used immediately
- High angular acceleration
- With adjustable fixed stops
- For fast and accurate positioning down to ±0.2° (only with axis controller CPX-CMAX)

Attachable potentiometers with absolute measurement, with high degree of protection

- With connecting rod or moment compensator
- Measuring range: 100 ... 2,000 mm
- Pre-assembled cables guarantee faultless and fast connection with the sensor interface CASM
- Range of applications: Soft Stop and pneumatic positioning with cylinder Ø 25 ... 80 mm,
 e.g. DNC or DSBC
- Loads from 1 ... 300 kg

Technical data 🗲 Internet: casm

Advantages:

- Easy installation and fast commissioning
- Cost-effective
- Can also be used in harsh environmental conditions
- Variety of drives: CPX-CMPX and CPX-CMAX also support cylinders with external displacement encoder

Cylinders with displacement encoder Drive options

Syster	System components for Soft Stop systems with end-position controller CPX-CMPX									
3		Linear drive		Standard cylinder	Swivel module	Displacement enco	oder	→ Page/		
		DDLI/DGCI	DGPI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	Internet		
1	End-position controller			-				стрх		
	CPX-CMPX	-	-	-	-	-	-	стрх		
2	Prop. directional control valve							VDWD		
	VPWP	-	-	-	-	-	-	vpwp		
4	Sensor interface	_	_	_			_	casm		
	CASM-S-D2-R3				-	-		casin		
5	Sensor interface	_	_		_	_	_	casm		
	CASM-S-D3-R7			-				cusin		
6	Connecting cable							kvi		
	KVI-CP-3	_	_	-	-	_	_	NV1		
7	Connecting cable	_	_	_		■ / -	_	nebc		
	NEBC-P1W4				-	- /		Hebc		
8	Connecting cable	_	_	_	_	- /	_	nebc		
	NEBC-A1W3					, –		nebe		
9	Connecting cable	_		_	-	_		nebp		
	NEBP-M16W6		_					heep		

Syste	System components for pneumatic positioning systems with axis controller CPX-CMAX									
3	3 Linear drive			Standard cylinder	Swivel module	Displacement enco	oder	→ Page/		
		DDLI/DGCI	DGPI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	Internet		
1	Axis controller		-	-	-			cmax		
	CPX-CMAX	-	-	-	-	-	-	CIIIdX		
2	Prop. directional control valve			-		-		vpwp		
	VPWP	-	-	-	-	-	-	vhwh		
4	Sensor interface	_	_	-			_	casm		
	CASM-S-D2-R3				-	-		cusiii		
5	Sensor interface	-	_	-	-	-	-	casm		
	CASM-S-D3-R7							645.III		
6	Connecting cable			-				kvi		
	KVI-CP-3	_	_	—	_	_	_	KVI		
7	Connecting cable	_	_	_		■ / -	_	nebc		
	NEBC-P1W4				-	-7		nebe		
8	Connecting cable	_	_	_	_	- / ■	_	nebc		
	NEBC-A1W3					7 -		liebe		
9	Connecting cable	_		_	_	-		nebp		
	NEBP-M16W6		_				_	heep		

System components for measur	ing cylinders with me	asuring module (PX-CMIX				
	Linear drive		Standard cylinder	Swivel module	Displacement en	coder	→ Page/
	DDLI/DGCI	DGPI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	Internet
Measuring module		_	_	_	_		amily
CPX-CMIX-M1-1	-	-	-	-	-	-	cmix
Sensor interface				-		_	cocm
CASM-S-D2-R3	-	-	-	-	-	-	casm
Sensor interface	_	_		_	_	_	casm
CASM-S-D3-R7	_	_	-	_	_	_	Casili
Connecting cable	(■)	(■)		-		(■)	kvi
KVI-CP-3	(=)	(=)	-	-	-	(-)	KVI
Connecting cable	_	_	_	-	■ / -	_	nebc
NEBC-P1W4				-	- /		nebe
Connecting cable	_				- / ■	_	nebc
NEBC-A1W3	_	_	_	_	-/-	_	nebt
Connecting cable	_		_	_	_		nebp
NEBP-M16W6		-				-	nenh

Overview

Individual components for positioning With axis controller SPC200 With end-position controller SPC11 → Internet: spc200 → Internet: spc11 1 6 5 4 7 2 2 1 Axis controller SPC200 2 Proportional directional control 2 Proportional directional control valve MPYE valve MPYE 3 Standard cylinder DNCI, DDPC 4 Axis interface SPC-AIF-INC 3 Standard cylinder DNCI, DDPC 6 Connecting cable 5 End-position controller KSPC-AIF-... SPC11-INC 3 3 7 Connecting cable 7 Connecting cable KMPYE-AIF-... KMPYE-AIF-... Individual components for use as a measuring cylinder With measuring module CPX-CMIX With measured-value transducer DADE → Internet: cmix → Internet: dade 4 1 5 2 6

- 1 Measuring module CPX-CMIX
- Sensor interface 2 CASM-S-D3-R7

3

3 Standard cylinder DNCI, DDPC

→ Internet: www.festo.com/catalogue/...

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3 Standard cylinder DNCI, DDPC

4 Operator unit FED

DADE

5

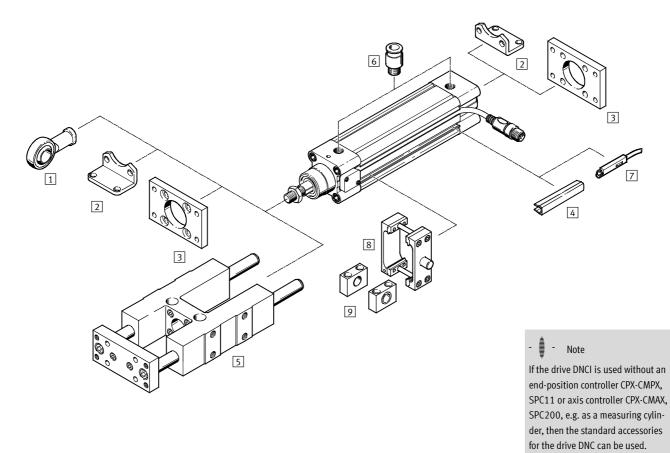
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PLC controller FEC

6 Measured-value transducer

		DNCI]-	-	- P	– A]-[-	-	-
Туре											
DNCI	Standard cylinder										
D : 1 (
Piston Ø	Ø [mm]										
Stroke [mm]										
Cushion	ing										
Р	Elastic cushioning rings/pads at both ends					J					
Position	sensing										
А	Via proximity sensor						_]				
Piston r	od type										
S2	Through piston rod										
Piston r	od turo										
K8	Extended piston rod										
110]									
Clampin	ig unit										
KP	Attached								4		
Guide											
FENG	Guide unit with recirculating ball bearing guid	do									
TENG	Guide unit with recirculating balt bearing gui	ue									
Measur	ed-value transducer										
MU	Output 0 10 V										
MI	Output 4 20 mA										
No mea	suring head										
MS	Drive without measuring head										

Peripherals overview



Acce	ssories		
	Туре	Brief description	→ Page/Internet
1	Rod eye	With spherical bearing	25
	SGS		
2	Foot mounting	For mounting the drive on the bearing and end cap	24
	HNC		
3	Flange mounting	For mounting the drive on the bearing and end cap	25
	FNC		
4	Slot cover	For protecting against the ingress of dirt	27
	ABP-5-S		
5	Guide unit ¹⁾	For protecting against rotation at high torque loads	22
	FENG-KF		
6	Push-in fitting	For connecting compressed air tubing with standard O.D.	27
	QS		
7	Proximity sensor	For additional sensing of the piston position, can be ordered optionally, only in combination	proximity sensor
	SME/SMT-8	with the order code A in the modular products section for the drive	
8	Trunnion mounting kit	For swivelling movements of the drive	26
	DAMT		
9	Trunnion support	For securing the trunnion mounting kit DAMT	26
	LNZG		

1) Guide unit FENG-KF must be attached to the piston rod in a way that eliminates backlash

Technical data

Function

Stroke length
 10 ... 2,000 mm

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General technical data							
Piston \varnothing	32	40	50	63			
Based on standard	ISO 15552						
Design	Piston						
	Piston rod						
	Profile barrel						
Mode of operation	Double-acting						
Guide ¹⁾	Guide rod with yoke, with	ball bearing guide					
Mounting position	Any						
Type of mounting	Via accessories						
Cushioning	Elastic cushioning rings/pads at both ends						
Position sensing	Integrated displacement encoder						
	Via proximity sensor ²⁾						
Measuring principle (displacement encoder)	Encoder, contactless and relative measurement						
Pneumatic connection	G1⁄8	G1⁄4	G1⁄4	G3⁄/8			
Stroke							
DNCI ³⁾ [mm]	10 2,000						
DNCIFENG [mm]	100 500						
Extended piston rod [mm]	1 500						

Guide unit FENG-KF can be ordered via the modular product system (feature FENG) and is supplied attached. The maximum stroke is restricted
 Not included in the scope of delivery, can be ordered as an option

3) Can only be used without restriction as a positioning drive in the range from 100 ... 750 mm.

Note stroke reduction in combination with CPX-CMAX, SPC200

Technical data

Operating and environmental conditions						
Operating pressure [bar]	0.6 12					
Operating pressure ¹⁾ [bar]	48					
Operating medium ²⁾	Compressed air according to ISO 8573-1:2010 [6:4:4]					
Note about the operating/pilot medium	Lubricated operation not possible					
	Pressure dew point 10 °C below ambient/medium temperature					
Ambient temperature ³⁾ [°C]	-20 +80					
Vibration resistance to DIN/IEC 68, Part 2-6	Severity level 2					
Continuous shock resistance to DIN/IEC 68, Part 2-82	Severity level 2					
CE marking (see declaration of conformity) ⁴⁾	To EU EMC Directive					
Corrosion resistance class CRC ⁵⁾	1					

Only applies to applications with end-position controller CPX-CMPX, SPC11 and axis controller CPX-CMAX, SPC200
 The proportional directional control valve VPWP, MPYE requires these characteristic values
 Note operating range of proximity sensors
 For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com → Support → User documentation.

If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary. 5) Corrosion resistance class 1 according to Festo standard 940 070

Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.

Forces [N] and impact energy [Nm]					
Piston Ø		32	40	50	63
Theoretical force at 6 bar,		483	754	1,178	1,870
advancing	S2	415	633	990	1,682
Theoretical force at 6 bar,		415	633	990	1,682
retracting	S2	415	633	990	1,682
Impact energy in the end positions		0.1	0.2	0.2	0.5

$$v_{perm.} = \sqrt{\frac{2 \text{ x } \text{E}_{perm.}}{\text{m}_{dead} + \text{m}_{load}}}$$

Permissible impact velocity v_{perm}. Max. impact energy Eperm. Moving mass (drive) m_{dead} Moving effective load mload

- Note

These specifications represent the maximum values that can be achieved. Note the maximum permissible impact energy.

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Maximum permissible load:

 $m_{load} = \frac{2 \times E_{perm.}}{v^2} - m_{dead}$

Technical data

Positioning characteristics with axis contr	oller CPX-CMA	X, SPC200						
Piston \varnothing		32	40	50	63			
Stroke	[mm]	100 750						
Mounting position		Any						
Resolution	[mm]	0.01						
Repetition accuracy	[mm]	≤ ±0.5						
Minimum load, horizontal	[kg]	3	5	8	12			
Maximum load, horizontal	[kg]	45	75	120	180			
Minimum load, vertical ¹⁾	[kg]	3	5	8	12			
Maximum load, vertical ¹⁾	[kg]	15	25	40	60			
Minimum travel speed	[m/s]	0.05	•	•				
Maximum travel speed	[m/s]	1.5						
Typical positioning time, long stroke ²⁾	[s]	0.45/0.70	0.50/0.75	0.65/0.80	0.55/0.75			
Typical positioning time, short stroke ³⁾	[S]	0.35/0.55	0.40/0.55	0.45/0.60	0.40/0.55			
Minimum positioning stroke ⁴⁾	[%]	≤ 3	•	•				
Stroke reduction ⁵⁾	roke reduction ⁵⁾ [mm]			10 15				
Recommended proportional directional con	trol valve	•		•				
For CPX-CMAX		→ 27	→ 27					
For SPC200	PC200 → 28							

1) Only in combination with an external guide

At 6 bar, horizontal mounting position, DNCI-XX-500, 400 mm travel at min./max. load 2)

At 6 bar, horizontal mounting position, DNCI-XX-500, 100 mm travel at min./max. load 3)

4) In relation to the maximum stroke of the drive, but never more than 20 mm
5) The stroke reduction must be maintained on each side of the drive, the max. positionable stroke is therefore: stroke – 2x stroke reduction

Force control characteristics with axis controller CPX-CMAX									
Piston \varnothing		32	40	50	63				
Stroke	[mm]	100 750							
Mounting position		Any							
Maximum controllable force ¹⁾	[N]	435/375	680/570	1,060/890	1,685/1,515				
Typical friction forces ²⁾	[N]	30	40	70	70				
Repetition accuracy of pressure control ³⁾⁴⁾	[%]	< ±2							

1) Advancing/retracting at 6 bar

2)

These values can fluctuate greatly from cylinder to cylinder and are not guaranteed. These friction forces must also be taken into consideration when using an external guide or when the cylinder is moving other components subject to friction

This value defines the repetition accuracy with which the internal differential pressure in the cylinder is controlled and refers to the maximum controllable force (the internal differential pressure corresponds to the 3) prescribed force setpoint value)

4) The effective force at the workpiece and its accuracy depends largely on the friction in the system as well as the repetition accuracy of the internal control system. Note that friction forces always work against the direction of movement of the piston. The following formula can be used as a rule of thumb for the force F at the workpiece:

 $F = F_{setpoint} \pm F_{friction forces} \pm repetition accuracy of pressure control$

Positioning characteristics with Soft S	Stop end-position (controller CPX-CMP	X, SPC11					
Piston \varnothing		32	40	50	63			
Stroke	[mm]	100 750						
Mounting position		Any	Any					
Repetition accuracy ¹⁾	[mm]	±2	±2					
Minimum load, horizontal	[kg]	3	5	8	12			
Maximum load, horizontal	[kg]	45	75	120	180			
Minimum load, vertical ²⁾	[kg]	3	5	8	12			
Maximum load, vertical ²⁾	[kg]	15	25	40	60			
Travel time		➔ Soft Stop siz	ing software: 🗲 www.fest	0.com				
Recommended proportional directiona	l control valve	•						
For CPX-CMPX		→ 27						
For SPC11		→ 28						

1) One intermediate position. The accuracy in the end positions depends solely on the stability of the end stops

2) Only in combination with an external guide

Electrical data – Displacement encoder	ilectrical data – Displacement encoder							
Output signal		Analogue						
Linearity error								
Strokes up to 500 mm	[mm]	< ±0.08						
Strokes up to 1,000 mm	[mm]	< ±0.09						
Strokes above 1,000 mm	[mm]	<±0.11						
Maximum travel speed	[m/s]	1.5						
Protection class		IP65						
CE marking (see declaration of conformity)		To EU EMC Directive ¹⁾						
Maximum permitted magnetic interference	[kA/m]	10						
field ²⁾								
Electrical connection		Cable with 8-pin plug, round type M12						
Cable length	[m]	1.5						

For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com → Support → User documentation. If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.
 At a distance of 100 mm

Pin allocation for plug



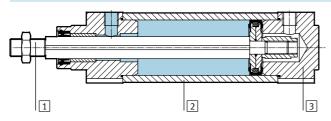
Pin	Function	Colour
1	5 V	Black
2	GND	Brown
3	sin+	Red
4	sin-	Orange
5	COS-	Green
6	COS+	Yellow
7	Screening	Screened
8	n.c.	-

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Weight [g]					
Piston \varnothing		32	40	50	63
DNCI					
	Product weight with 0 mm stroke	521	853	1,319	1,914
	Additional weight per 10 mm stroke	30	44	62	71
1	Moving load with 0 mm stroke	95	175	316	383
	Additional weight per 10 mm stroke	8	14	23	23
DNCIS2 -	Through piston rod				
	Product weight with 0 mm stroke	586	981	1,553	2,165
	Additional weight per 10 mm stroke	39	60	87	96
	Moving load with 0 mm stroke	155	164	297	364
	Additional weight per 10 mm stroke	17	30	48	48
DNCIK8 –	Additional weight with piston rod extension			<u>.</u>	
	Additional weight per 10 mm stroke	8	14	23	23
DNCIKP –	Additional weight with clamping unit				
	Product weight	234	394	700	1,147
DNCIFENG	6 – Additional weight with guide unit				
	Product weight with 0 mm stroke	1,530	2,370	4,030	5,410
	Additional weight per 10 mm stroke	18	32	50	62

Materials

Sectional view



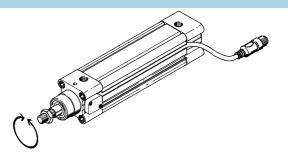
Standard cylinder

Stanuaru cyffiluer	
1 Piston rod	High-alloy steel
2 Cylinder barrel	Anodised aluminium
3 Bearing/end caps	Die-cast aluminium
 Dynamic seals 	Polyurethane TPE-U
- Static seals	Nitrile rubber
Note on materials	RoHS-compliant
	·
Displacement encoder	
 Sensor housing 	Polyacetal
 Cable sheath 	Polyurethane
 Plug housing 	Polybutylene terephthalate
 Mounting plate 	Polyacetal
 Screws for mounting plate 	Steel

Technical data

Torques and lateral forces

The piston rod must not absorb any torque. We therefore recommend that an external guide FENG-KF be used with the drive DNCI. The guide unit is supplied attached. The permissible static and dynamic characteristic load values with and without attached guide as well as with regard to the technical data of the variants (S2, S8, S9) → Internet: dnc



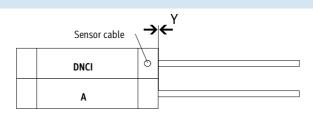
Mounting conditions

When mounting a drive A with magnet (for position sensing) next to a standard cylinder DNCI, the following conditions must be observed:

- X Minimum distance between the drives
- Y Offset between the drives on the bearing cap

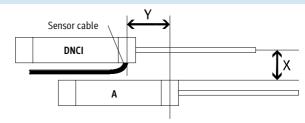
Parallel assembly

If the offset Y = 0 mm, the drives can be assembled directly next to one another.



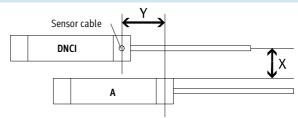
Offset assembly, cable outlet between the drives

If the offset is Y > 0 mm and the cable outlet is between the drives, a distance of X > 70 mm must be observed.



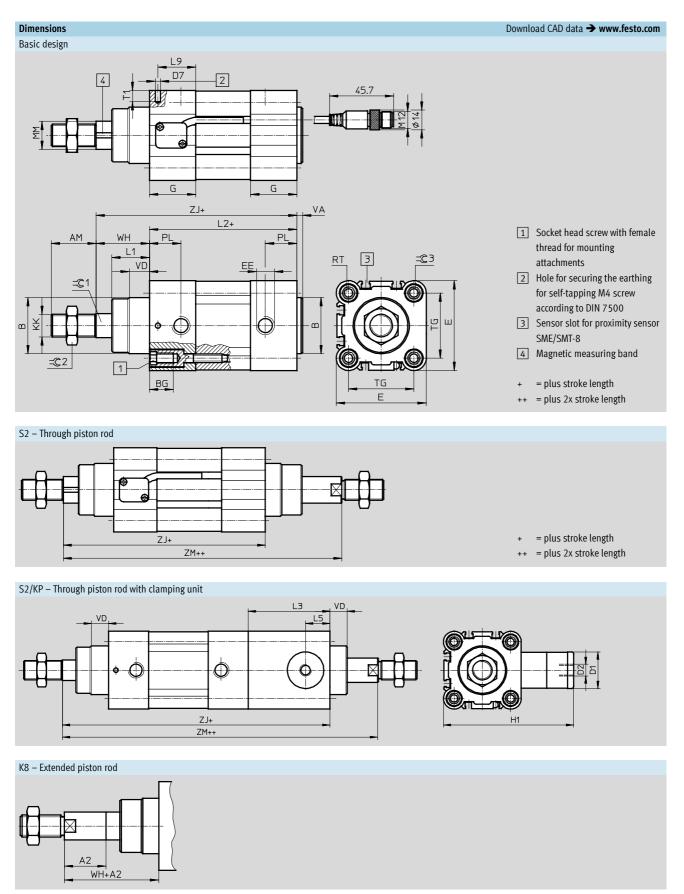
Offset assembly, cable outlet upwards or downwards

If the offset is Y > 0 mm and the cable outlet is up or down, a distance of X > 60 mm must be observed.

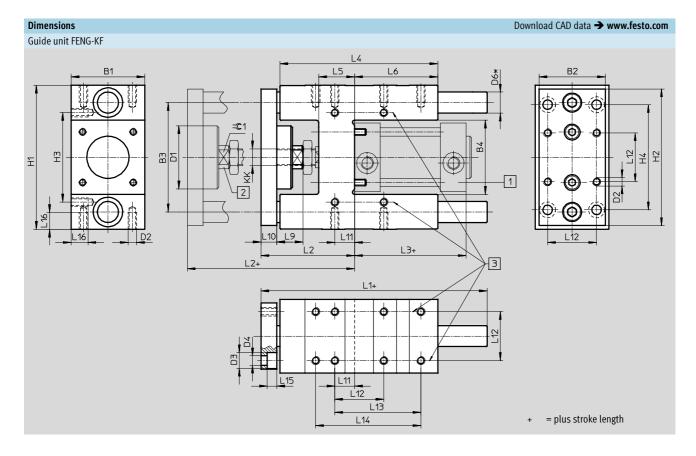


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Technical data



Ø	AM	A2	В	BG	D1	D2	D7	E	EE	G	H1	
		max.	Ø		Ø		Ø					
[mm]			d11		f9							
32	22	500	30	16	20	M5	3.7	45	G1⁄8	28	67	
40	24	500	35	16	24	G1⁄8	3.7	54	G1⁄4	33	88	
50	32	500	40	17	30	G1⁄8	3.7	64	G1⁄4	33	107	
63	32	500	45	17	38	G1⁄8	3.7	75	G3⁄/8	40.5	123	
Ø	KK	L1	L2	L3	L5	L9	MM	PL	RT	T1	TG	
							Ø					
[mm]							f8					
32	M10x1.25	18	94	45	14	22.5	12	15.6	M6	8	32.5	
40	M12x1.25	21.3	105	53	16	27	16	14	M6	8	38	
50	M16x1.5	26.8	106	67	20	27	20	14	M8	8	46.5	
63	M16x1.5	27	121	76	24	33	20	17	M8	8	56.5	
Ø	VA	VD	WH	Z	J	ZI	N	=©1	=©2	=0	3	
[mm]					KP		KP					
32	4	10	26	120	165	148	193	10	16	6		
40	4	10.8	30	135	188	167	220	13	18	6		
50	4	14.3	37	143	210	183	250	17	24	8	8	
63	4	14.5	37	158	234	199	275	17	24	8		



For Ø	B1	B2	B3	B4	D1 Ø	D2	D3 Ø	D4 Ø	D6 Ø	H1
[mm]	-0.3		±0.2	±0.3	Q		Ø	Q	b6	
32	50	45	74	50.5	44	M6	11	6.6	12	97 _{-0.4}
40	58	54	87	58.5	44	M6	11	6.6	16	115 _{-0.4}
50	70	63	104	70.5	60	M8	15	9	20	137 _{-0.5}
63	85	80	119	85.5	60	M8	15	9	20	152 _{-0.5}
For Ø	H2	H3	H4	КК	L1	L2	L3	L4	L5	L6
[mm]		±0.2	±0.2							
32	90	61	78	M10x1.25	155	67+5	94	125	24	76
40	110	69	84	M12x1.25	170	75 ₊₅	105	140	28	81
50	130	85	100	M16x1	188	89 ₊₁₀	106	150	34	79
63	145	100	105	M16x1	220	89+10	121	182	34	111
For Ø	L9	L10	L11	L12	L13	L14	L15	L16	=0	<u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u></u>
[mm]				±0.2	±0.2	±0.2				
32	20	12	4.3	32.5	70.3	78	6.5	12	1	5
40	22	12	11	38	84	-	6.5	14	1	5
50	25	15	18.8	46.5	81.8	100	9	16	1	9
63	25	15	15.3	56.5	105	_	9	16	1	9

0	dering table									
Pi	ston Ø		32	40	50	63	Condi-	Code		Enter
							tions			code
M	Module No.	Module No. 535411 535412 535413 535414								
	Function Standard cylinder with integrated displacement encoder, non-rotating piston rod							DNCI		DNCI
	Piston Ø	[mm]	32	40	50	63				
	Stroke	[mm]	10 2,000				1			
	Stroke	[mm]	10 2,000							
	Cushioning		Elastic cushioning rin	lastic cushioning rings/pads at both ends						-P
1	Position sensing Via proximity sensor							-A		-A

1 Stroke Can only be used without restriction as a positioning drive in the range from 100 ... 750 mm

Standard cylinders DNCI, with integrated displacement encoder Ordering data – Modular products

Transfer order code DNCI – P – A _

→ Internet: www.festo.com/catalogue/...

-

In combination with piston rod type S2, the piston rod is only extended at the front

Ordering data – Modular products

Or	dering table							
Pis	ston Ø	32	40	50	63	Condi-	Code	Enter
						tions		code
0	Piston rod type	Through piston rod				-\$2		
	Piston rod extended at [mm]	1 500		2	K8			
	front							
	Clamping unit	Attached				3	-KP	
	Guide	Guide unit with ball b	earing guide on the se	nsor head side		4	-FENG	
	Measured-value transducer	Output 0 10 V					-MU	
	Output 4 20 mA						-MI	
	Measuring head	No measuring head	5	-MS				

3 KP

4 FENG

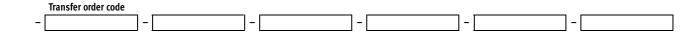
Can only be combined with piston rod type S2

Maximum stroke length 500 mm

2 **K8**

- ■ - Note
 5 The standard cylinder can be ordered without a measuring head for repairs (→ code MS). The existing measuring head can be installed in the new standard cylinder (→ operating instructions for DNCI).

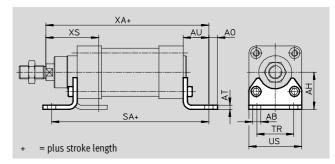
(slide closest to the measuring head)



Foot mounting HNC

Material: Galvanised steel Free of copper and PTFE





Dimensions a	Dimensions and ordering data											
For \varnothing	AB	AH	AO	AT	AU	SA						
	Ø											
[mm]						Basic cylinder	КР					
32	7	32	6.5	4	24	142	187					
40	10	36	9	4	28	161	214					
50	10	45	9.5	5	32	170	237					
63	10	50	12.5	5	32	185	261					

For \varnothing	TR	US	ХА		XS	CRC ¹⁾	Weight	Part No. Type
			Basic cylinder KP					
[mm]							[g]	
32	32	45	144	189	45	2	144	174369 HNC-32
40	36	54	163	216	53	2	193	174370 HNC-40
50	45	64	175	242	62	2	353	174371 HNC-50
63	50	75	190	266	63	2	436	174372 HNC-63

1)

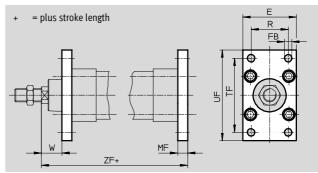
Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Accessories

Flange mounting FNC

Material: FNC: Galvanised steel Free of copper and PTFE RoHS-compliant





Dimensions a	Dimensions and ordering data												
For \varnothing	E	FB	MF	R	TF	UF	W	ZF		CRC ¹⁾	Weight	Part No.	Туре
		Ø						Basic	KP				
[mm]		H13						cylinder			[g]		
32	45	7	10	32	64	80	16	130	175	1	221	174376	FNC-32
40	54	9	10	36	72	90	20	145	198	1	291	174377	FNC-40
50	65	9	12	45	90	110	25	155	222	1	536	174378	FNC-50
63	75	9	12	50	100	120	25	170	246	1	679	174379	FNC-63

1) Corrosion resistance class 1 according to Festo standard 940 070

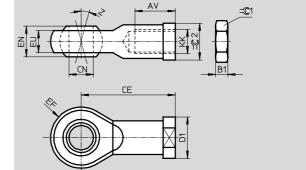
Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.

Rod eye SGS

Scope of delivery: 1 rod eye, 1 hex nut to DIN 439

Material: Galvanised steel RoHS-compliant





Dimensions and ordering data

For \varnothing	AV	B1	CE	CN	D1	EF	EN	Z	=©1	=©2	CRC ¹⁾	Weight	Part No.	Туре
				Ø	Ø									
[mm]				H7		±0.5		[°]				[g]		
M10x1.25	20 -2	5	43	10	19	14	14	13	17	17	2	70	9261	SGS-M10x1,25
M12x1.25	22 -2	6	50	12	22	16	16	13	19	19	2	105	9262	SGS-M12x1,25
M16x1.5	28 -2	8	64	16	27	21	21	15	24	22	2	210	9263	SGS-M16x1,5

1) Corrosion resistance class 2 according to Festo standard 940 070

Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

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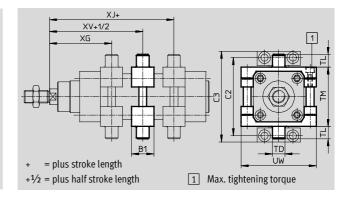
Accessories

Trunnion mounting kit DAMT

The mounting kit can be attached at any position along the profile barrel of the cylinder.

Material: Galvanised steel Free of copper and PTFE RoHS-compliant





Dimensions a	and ordering data	1							
For \varnothing	B1	C2	C3	TD	TL	TM	UW	X	Ĵ
				Ø				Basic cylinder	KP
[mm]				e9					
32	30	71	86	12	12	50	65	66.1	111.1
40	32	87	105	16	16	63	75	75.6	128.6
50	34	99	117	16	16	75	95	83.6	150.6
63	41	116	136	20	20	90	105	93.1	169.1

For \varnothing	X	J	X	V	Max. tightening torque	CRC ¹⁾	Weight	Part No. Type
	Basic	KP	Basic	KP				
[mm]	cylinder		cylinder		[Nm]		[g]	
32	79.9	124.9	73	118	4+1	1	224	2213233 DAMT-V1-32-A
40	89.4	142.4	82.5	135.5	8+1	1	396	2214899 DAMT-V1-40-A
50	96.4	163.4	90	157	8+2	1	616	2214909 DAMT-V1-50-A
63	101.9	177.9	97.5	173.5	18+2	1	931	2214971 DAMT-V1-63-A

1) Corrosion resistance class 1 according to Festo standard 940 070

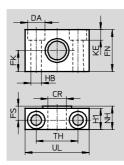
Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.

Trunnion support LNZG

Materials:

Trunnion support: Anodised aluminium Plain bearing: Plastic Free of copper and PTFE RoHS-compliant





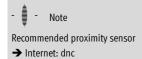
Dimensions a	Dimensions and ordering data														
For \varnothing	CR	DA	FK	FN	FS	H1	HB	KE	NH	TH	UL	CRC ¹⁾	Weight	Part No.	Туре
	Ø	Ø	Ø				Ø								
[mm]	D11	H13	±0.1				H13			±0.2			[g]		
32	12	11	15	30	10.5	15	6.6	6.8	18	32	46	2	90	32959	LNZG-32
40,50	16	15	18	36	12	18	9	9	21	36	55	2	140	32960	LNZG-40/50
63	20	18	20	40	13	20	11	11	23	42	65	2	190	32961	LNZG-63/80

1) Corrosion resistance class 2 according to Festo standard 940 070

Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Ordering data					
	For \varnothing	Comment	Part No.	Туре	PU ¹⁾
Slot cover				Technical data 🗲 Interne	et: abp
	32, 40, 50, 63	Every 0.5 m	151680	ABP-5-S	2

1) Packaging unit



Ordering data – Proportional directional control valves and push-in fittings

oracing auta rroportionat ar	rectional control va	wes and pash in m					
	For \varnothing	Stroke	Proportio	nal directional control valve	Push-in fi	tting for DNCI	
			Technical	data 🗲 Internet: vpwp	Technical	data 🗲 Internet: quick star	
	[mm]	[mm]	Part No.	Туре	Part No.	Туре	PU ¹⁾
^	For applications	with axis controller (CPX-CMAX				
	32	50 150	550170	VPWP-4-L-5-Q6-10-E	186096	QS-G1⁄8-6	10
		151 400	550170	VPWP-4-L-5-Q8-10-E	186098	QS-G1⁄8-8	
		> 401	550171	VPWP-6-L-5-Q8-10-E	186098	QS-G1⁄8-8	
	40	50 250	550170	VPWP-4-L-5-Q8-10-E	186099	QS-G1⁄4-8	
PC 2 Colee		> 251	550171	VPWP-6-L-5-Q8-10-E	186099	QS-G1⁄4-8	
	50	50 180	550170	VPWP-4-L-5-Q8-10-E	186099	QS-G1⁄4-8	
*		181 600	550171	VPWP-6-L-5-Q8-10-E	186099	QS-G1⁄4-8	
		> 601	550172	VPWP-8-L-5-Q10-10-E	186101	QS-G¼-10	
	63	50 100	550170	VPWP-4-L-5-Q8-10-E	186100	QS-G3⁄8-8	
		101 350	550171	VPWP-6-L-5-Q8-10-E	186102	QS-G¾-10	
		> 351	550172	VPWP-8-L-5-Q10-10-E	186102	QS-G¾-10	

1) Packaging unit

Ordering data – Proportional di	rectional control va	lves and push-in fit	ngs	
	For Ø	Stroke ¹⁾	Proportional directional control valve Push-in fitting for DNCI	
			Technical data → Internet: vpwp Technical data → Internet: quick star	
	[mm]	[mm]	Part No. Type Part No. Type	PU ²⁾
<u> </u>	For applications	with Soft Stop end-p	sition controller CPX-CMPX, horizontal	
	32	100 400	550170 VPWP-4-L-5-Q8-10-E 186098 QS-G ¹ /8-8	10
		401 500	550171 VPWP-6-L-5-Q8-10-E 186098 QS-G ¹ /8-8	
	40	100 250	550170 VPWP-4-L-5-Q8-10-E 186099 QS-G ¹ /4-8	
		251 500	550171 VPWP-6-L-5-Q8-10-E 186099 QS-G ¹ / ₄ -8	
DO CO CO CO	50	100 250	550170 VPWP-4-L-5-Q8-10-E 186099 QS-G ¹ /4-8	
		251 400	550171 VPWP-6-L-5-Q8-10-E 186099 QS-G ¹ /4-8	
, ·		500	550172 VPWP-8-L-5-Q10-10-E 186101 QS-G ¹ / ₄ -10	
	63	100 160	550170 VPWP-4-L-5-Q8-10-E 186100 QS-G¾-8	
		161 320	550171 VPWP-6-L-5-Q8-10-E 186100 QS-G¾-8	
		321 500	550172 VPWP-8-L-5-Q10-10-E 186102 QS-G¾-10	

Other stroke lengths on request
 Packaging unit

.

Ordering data – Proportional d	irectional control va	lves and push-in fitting	gs		
	For \varnothing	Stroke	Proportional directional control va	Ive Push-in fitting for DNCI	
			Technical data → Internet: mpye	Technical data → Internet: quick st	ar
	[mm]	[mm]	Part No. Type	Part No. Type	PU ¹⁾
	For applicati	ons with axis controller	SPC200		
	32	50 150	154200 MPYE-5-M5-010-B	186096 QS-G ¹ /8-6	10
		151 400	151692 MPYE-5-1/8-LF-010-B	186098 QS-G ¹ /8-8	
		> 401	151693 MPYE-5-1/8-HF-010-B	186098 QS-G ¹ ⁄8-8	
∇	40	50 300	151692 MPYE-5-1/8-LF-010-B	186099 QS-G ¹ / ₄ -8	
		> 301	151693 MPYE-5-1/8-HF-010-B	186099 QS-G ¹ /4-8	
	50	50 200	151692 MPYE-5-1/8-LF-010-B	186099 QS-G ¹ / ₄ -8	
		201 900	151693 MPYE-5-1/8-HF-010-B	186099 QS-G ¹ /4-8	
		> 901	151694 MPYE-5-1⁄4-010-B	186101 QS-G ¹ /4-10	
	63	50 300	151693 MPYE-5-1/8-HF-010-B	186100 QS-G¾-8	
		301 1,000	151694 MPYE-5-1⁄4-010-B	186102 QS-G¾-10	
		> 1,001	151695 MPYE-5-3/8-010-B	186102 QS-G¾-10	

1) Packaging unit

Ordering data - Proportional directional control valves and push-in fittings

	For Ø	Stroke ¹⁾	Proportion	nal directional control valve	Push-in fi	tting for DNCI	
			Technical	data 🗲 Internet: mpye	Technical	ck star	
	[mm]	[mm]	Part No.	Туре	Part No.	Туре	PU ²⁾
	For applicati	ons with Soft Stop end	-position cont	roller SPC11, horizontal			
0	32	100 400	151692	MPYE-5-1/8-LF-010-B	186098	QS-G1⁄8-8	10
		401 500	151693	MPYE-5-1/8-HF-010-B	186098	QS-G1⁄8-8	
e la	40	100 250	151692	MPYE-5-1/8-LF-010-B	186099	QS-G¼-8	
		251 500	151693	MPYE-5-1/8-HF-010-B	186099	QS-G1⁄4-8	
	50	100 250	151692	MPYE-5-1/8-LF-010-B	186099	QS-G1⁄4-8	
		251 400	151693	MPYE-5-1/8-HF-010-B	186099	QS-G¼-8	
		500	151694	MPYE-5-1/4-010-B	186101	QS-G¼-10	
	63	100 160	151692	MPYE-5-1/8-LF-010-B	186100	QS-G¾-8	
		161 320	151693	MPYE-5-1/8-HF-010-B	186100	QS-G¾-8	
		321 500	151694	MPYE-5-1/4-010-B	186102	QS-G¾-10	

Other stroke lengths on request
 Packaging unit