

Features

General information

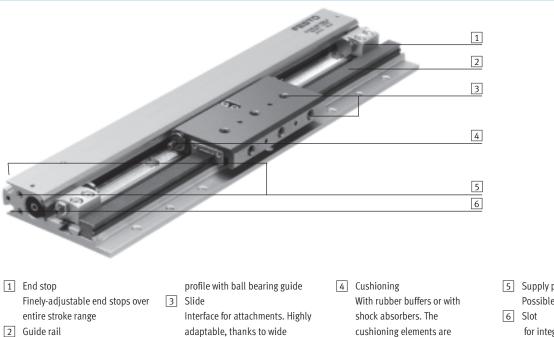
- Piston \emptyset 8, 12 and 18
- Stroke lengths of 100 ... 900 mm
- Two cushioning types selectable:
- Elastic cushioning
- Shock absorbers

The technology in detail

- Direct mounting via centering holes
- Extremely flat design
- Built-in precision guide
- Slide with polished surface
- High load capacity
- Adjustable end stops
- Versatile supply port options
- Suitable for multiple-axis applications with other mini slides

→ 5

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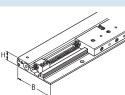


2 Guide rail

Highly accurate, rigid precision guide unit: stainless steel roller track pressed into aluminum

Design The flat linear drive SLG

The height H remains the same even if the intermediate position module is used.



choice of mounting and

attachment options

cushioning elements are

fixed.

 $\operatorname{Piston} \varnothing$

8 mm

12 mm

18 mm

inserted into the slide and

53.5

64.5

85.5

Width (B) x Height (H)

x 15 mm

x 18.5 mm

x 25.5 mm

5 Supply port

- Possible on three sides
- for integrateable proximity sensors SME-/SMT-10

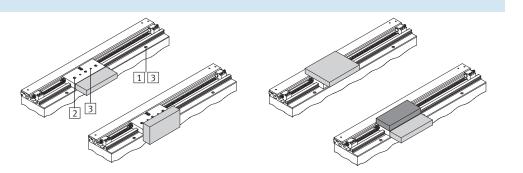
Mounting and assembly options

Drive

- 1 Through-holes
- 3 Locating hole for centering pin ZBS

Slide

- 2 Threaded holes
- 3 Locating hole
- for centering pin ZBS



Features

Intermediate positions - simple and inexpensive

- The intermediate position module can be used for advancing to one or more intermediate positions
- It is mounted parallel to the linear drive SLG via an additional mounting rail. This means that it can also be easily retrofitted.
- Fine adjustment of the intermediate position is effected via a stop screw with lock nut

In combination with linear drive SLG

SLG-D

The retainer accepts rubber

buffers or shock absorbers and

is attached to the slide of the

absorber YSRG (Accessories

sure accurate positioning of

→ 25) is recommended to en-

stops and in the case of vertical

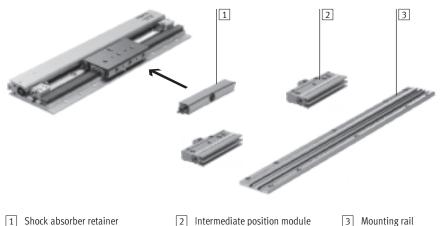
SLG. The use of shock

assembly positions.

- With two modules the same position can be approached from either direction
- The intermediate positions can be freely selected across the entire stroke range (observe minimum distances)
- The module's symmetry means that it can advance to its right or left once mounted
- It can be activated and sensed before the movement starts
- Integratable proximity switches in the module housing mean that the intermediate position (activated or initial position) can be sensed contactlessly
- Up to 4 modules can be ordered via the SLG modular product system
- → 16 • The slide must be retracted once the intermediate position is reached. The stop on the module

can then swivel back into its

initial position



2 Intermediate position module SLG-Z

The stop with cushioning screw is retracted and extended by means of a 90° swivel motion based on a double-acting rotary drive (rack and pinion principle). The module is fastened to the mounting rail using screws and slot nuts.

Completely assembled with two intermediate positions

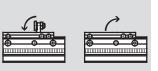


3 Mounting rail SLG-S

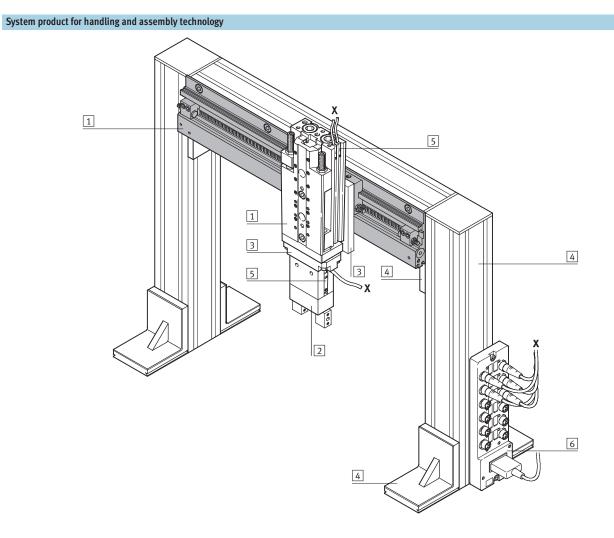
> The rail is used for mounting the intermediate position modules. It can also accept the end stops of the linear drive SLG. The gear teeth on the rail and module permit rough preadjustment with respect to the drive part of the SLG.

Note

The intermediate position module can also be used independently of the linear drive SLG. It is simply mounted on any even surface using mounting screws and locating pins and can then be used universally as an autonomous intermediate position module in numerous applications.

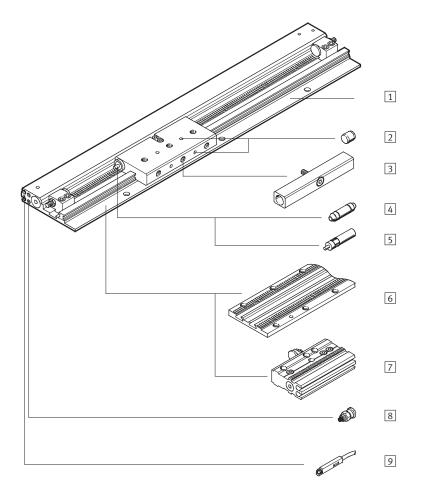


- 1 Linear drive SLG
- 2 Intermediate position module
- Shock absorber retainer 3
- 4 Mounting rail
- 5 End stop

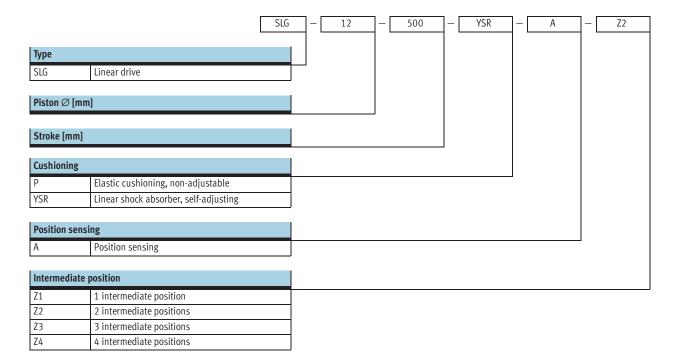


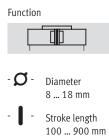
Syste	System elements and accessories				
	Туре	Brief description	→ Page/Internet		
1	Drives	Diverse possible combinations in handling and assembly technology	drive		
2	Grippers	Diverse variation options in handling and assembly technology	gripper		
3	Adapters	For drive-drive and drive-gripper connections	adapter kit		
4	Basic components	Profiles and profile connections	basic component		
5	Proximity sensors	For position sensing	proximity sensor		
6	Multi-pin plug distributor	For bundling individual cables to form a multi-pin cable	multi-pin plug distributor		

Linear drives SLG, flat design Peripherals overview



Varia	Variants and accessories					
	Туре	Brief description	→ Page/Internet			
1	Linear drive	Drive without accessories	7			
	SLG					
2	Centering pin	For centering loads and attachments on the slide	25			
	ZBS					
3	Shock absorber retainer	For fastening the rubber buffers or shock absorbers in combination	23			
	SLG-D	with the intermediate position				
4	Rubber buffer	Non-adjustable, elastic cushioning. Used only at low speeds	25			
	SLG					
5	Shock absorber	Self-adjusting hydraulic shock absorber with return spring and linear cushioning	25			
	YSRG	characteristic				
6	Mounting rail	For fastening the intermediate position modules and end stops	24			
	SLG-S					
7	Intermediate position module	Fixed stop for the intermediate position	23			
	SLG-Z					
8	One-way flow control valve	The small distance between the supply ports means that only certain one-way flow	26			
	GRLA	control valves can be used				
9	Proximity sensors	The proximity switches are fitted in the profile slot. The switches therefore do not project	26			
	SME-/SMT-10					







General technical data				
Piston \varnothing		8	12	18
Stroke ¹⁾	[mm]	100 500	100 700	100 900
Pneumatic connection		M3	•	M5
Mode of operation		Double-acting		
Operating medium		Filtered compressed air, lubricated or ur	lubricated	
Constructional design		Rodless drive		
Cushioning Flexible cushioning rings/plates at both ends				
→ 10	10 Self-adjusting at both ends			
Position sensing		For proximity sensing		
Type of mounting		Direct mounting		
Mounting position		Any		
Driver principle		Slotted cylinder, mechanically coupled		
Guide		Guide rail with slide		
Max. speed	[m/s]	1		1.5

1) Intermediate strokes are infinitely adjustable with stops.

Operating and environmental conditions						
Piston Ø		8	12	18		
Operating pressure	[bar]	2.5 8	2 8	1 8		
Ambient temperature ¹⁾	[°C]	-10 +60				

1) Note operating range of proximity switches.

Forces [N]						
Piston Ø	8	12	18			
Theoretical force at 6 bar	30	68	153			

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Neights [g]					
Piston \varnothing	8	12	18		
Basic weight per 0 mm stroke with P cushioning	215	410	965		
Basic weight per 0 mm stroke with YSR cushioning	225	420	995		
Additional weight per 10mm stroke	11.5	17.5	29.5		
Moving load with P cushioning	80	160	440		
Moving load with YSR cushioning	90	170	470		

Materials

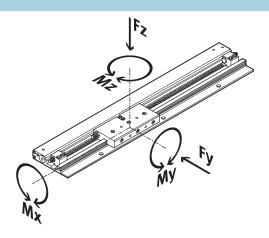
Sectional view

2	3		 4
	- \$ - \$ -	-	

Line	inear drives			
1	Profile barrel	Anodized aluminum		
2	Guide	High-alloy steel		
3	Slide	High-alloy steel		
4	Stop sleeve	Anodized aluminum		
-	Seals	Polyurethane		
	Material note	Free of copper, PTFE and silicone		

Characteristic load values

The forces and torques specified refer to the centre of the guide rail.



 $\frac{Fy}{Fy_{max.}} + \frac{Fz}{Fz_{max.}} + \frac{Mx}{Mx_{max.}} + \frac{My}{My_{max.}} + \frac{Mz}{Mz_{max.}} \leq 1$

If the drive is subjected to several of the indicated forces and torques simultaneously, the following equations must be satisfied in addition to the indicated maximum loads:

Permissible forces [N] and torques [Nm]					
Piston \varnothing		8	12	18	
Fy _{max.}	[N]	255	565	930	
Fz _{max.}	[N]	255	565	930	
Mx _{max} .	[Nm]	1	3	7	
My _{max.}	[Nm]	3.5	9	23	
Mz _{max.}	[Nm]	3.5	9	23	

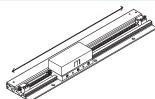
Torsional backlash [°] at the respective torques						
Piston \varnothing	8	12	18			
at Mx _{max} .	±0.03	±0.04	±0.05			
at My _{max.}	±0.005	±0.007	±0.007			
at Mz _{max} .	±0.005	±0.007	±0.007			

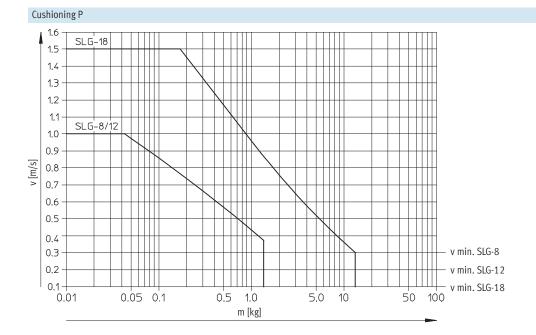
Note -Sizing software ProDrive →www.festo.com

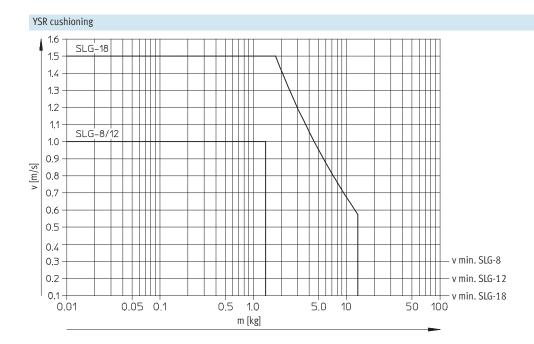
Maximum permissible piston speed v as a function of useful load m when the unit is operated horizontally

As a function of operating pressure and end-position cushioning system

A linear drive SLG with YSR cushioning (YSRG shock absorbers) must be used in applications requiring very high repetition accuracy.

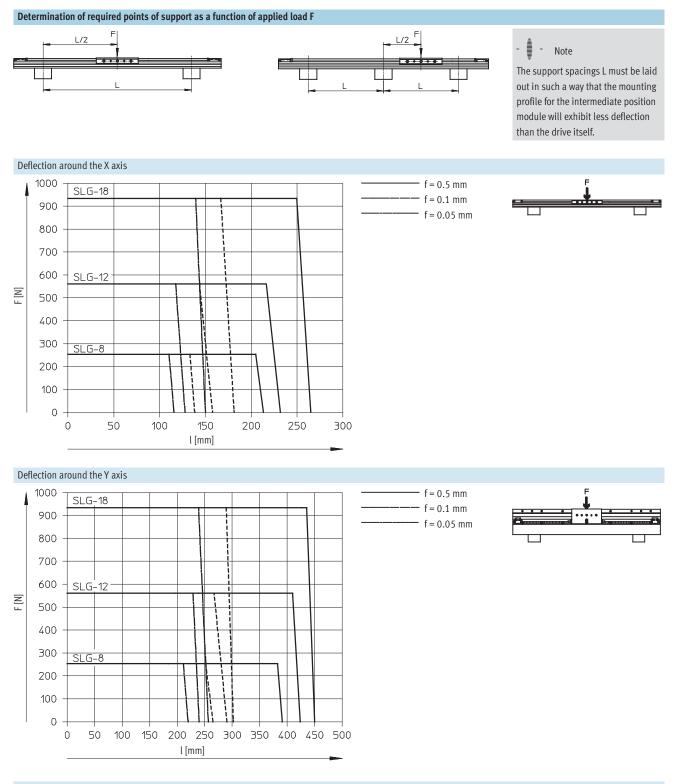






Technical data

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Flatness of the bearing surface

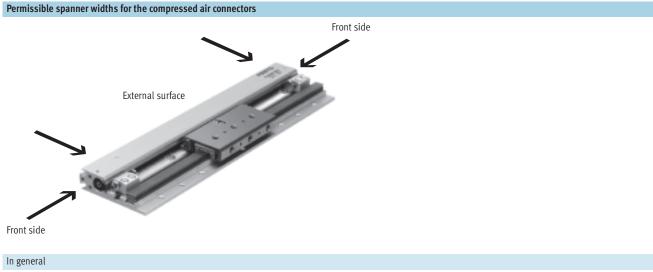
Contact surfaces which support the linear drive SLG should be no farther than 100 mm apart, or over its entire length and should be flat to within at least 0.1 mm. The support surface for the load on the slide should be flat to within at least 0.05 mm.

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Minimum clearances for lin	near drives Sl	G to ferrite materials for reliable proximi			
		Slot 1 Slot 2	Minimum clearances in mm		
			Х	у	
	SLG-8	1	5	-	
	010.40	2	5	-	
	SLG-12	1	6	-	
	<u>CIC 10</u>	2	5	-	
	SLG-18	1	5	-	
	616.0	2	5	-	
NT 1	SLG-8	1	5	-	
	010.40	2	10	-	
	SLG-12	1	5	-	
		2	6	-	
▏	SLG-18	1	5	-	
	01.0.5	2	5	-	
	SLG-8	1	7	-	
		2	10	-	
	SLG-12	1	10	-	
		2	10	-	
	SLG-18	1	5	-	
_= X =-		2	5	-	
J NTY	SLG-8	1	14	-	
		2	12	-	
On I	SLG-12	1	16	-	
		2	1	-	
	SLG-18	1	2	-	
		2	2	-	
NTY	SLG-8	1	7	-	
		2	17	-	
	SLG-12	1	1	-	
		2	17	-	
	SLG-18	1	1	-	
		2	12	-	
्राष्ट्रीय 🗆	SLG-8	1	11	17	
		2	15	17	
	SLG-12	1	7	16	
		2	10	16	
	SLG-18	1	5	12	
		2	5	12	

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Subject to change – 2011/06



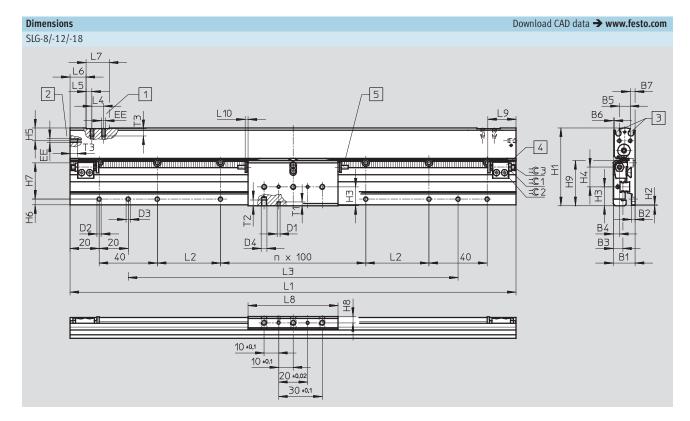
The following spanner widths can be	SLG-8:	=© 5.5 8
used on the external surface and	SLG-12:	=© 5.5 8
front side:	SLG-18:	=© 810

Restrictions on the front sides

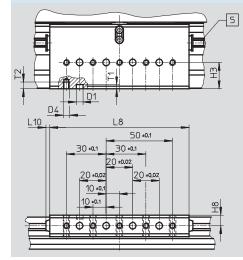
The threaded connectors protrude from the top or bottom of the profile with compressed air connections at both ends. The connector threads are too close to one another for the threaded fittings with compressed air connections at one end only.

For this reason, the following	SLG-8:	=C 8
spanner widths can only be used in	SLG-12:	=© 8
certain conditions:	SLG-18:	≕© 10





Slide SLG-18



- 1 Supply port, external surface
- 2 Supply port, front side
- 3 Slot for proximity sensor SME-/SMT-10
- 4 Stop

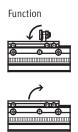
5 Shock absorber YSR or rubber

buffer (P cushioning)

	B1	B2	B3	B4	B5	B6	B7	D1 ¹⁾ Ø H7	D2 Ø	D3 ¹⁾ Ø H7	D4	EE	H1	H2	H3	H4	H5	H6	H7
SLG-8	15	2.5	6.6	4.4	7.5	0.65	3.5	2	3.4	3	M4	M3	53.5	0.5	13	13.6	8.8	3.9	25
SLG-12	18.5	2.6	7.9	5.2	8.5	0.5	4.75	2	3.4	3	M4	M3	64.5	0.5	15.9	16.5	9.5	4.3	30
SLG-18	25.5	3.5	13.3	8	13.2	1.6	5.4	5	4.5	5	M5	M5	85.5	0.5	19.8	21.7	11.5	4.1	40

	H8	H9	n	L1	L2	L3	L4	L5	L6	L7	L8	L9	L10	T1	T2	T3	=31	=©2	=©3
												min.			min.				
SLG-8-100			0	207		127													
SLG-8-200	1		1	307		227													
SLG-8-300	4.4	31	2	407	43.5	327	10	5	10	20	62	20	2	2.5	4	4.5	5.5	1.5	1.5
SLG-8-400			3	507		427													
SLG-8-500			4	607		527													
SLG-12-100			0	233		153													
SLG-12-200			1	333		253													
SLG-12-300			2	433		353													
SLG-12-400	5.25	36.7	3	533	56.5	453	10	5	10	20	80	36.5	2	2.5	4	4.5	7	2	2
SLG-12-500			4	633		553													
SLG-12-600			5	733		653													
SLG-12-700			6	833		753													
SLG-18-100			0	271		191													
SLG-18-200			1	371		291													
SLG-18-300			2	471		391													
SLG-18-400			3	571		491													
SLG-18-500	8	48.5	4	671	75.5	591	12	6	13	24	105	29	3	3	5	6	8	2.5	2.5
SLG-18-600			5	771		691													
SLG-18-700			6	871		791													
SLG-18-800			7	971		891													
SLG-18-900			8	1071		991													

1) Locating hole for ZBS centering pins





General technical data					
Piston \varnothing		8	12	18	
Pneumatic connection		M3			
Mode of operation		Double-acting			
Operating medium		Filtered compressed a	ir, lubricated or unlubricated		
Constructional design		Stop in the form of a s	semi-rotary device in accordance with	the rack and pinion principle	
Fine adjustment of the intermediate position	[mm]	1.7			
Cushioning ¹⁾		→10			
Position sensing		For proximity sensor			
Type of mounting		Direct mounting			
Assembly position ²⁾		Any			
Min. swivel time at 6 bar	[ms]	30		50	
Max. frequency at 6 bar	[1/s]	16		10	
Max. permissible impact velocity	[m/s]	1		1.5	
Max. perm. end-stop impact force ³⁾	[N]	320		600	

1) The end position of the slide or another drive is not exactly defined when rubber buffers are used. Shock absorbers YSRG-... must be used for high repetition accuracy.

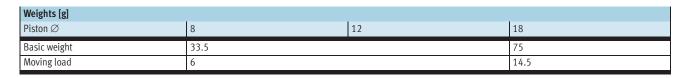
2) Shock absorbers YSRG-... must be used for high repetition accuracy as well as in non-horizontal movements.

With vertical installation (where the stop moves upwards), it must be ensured that no foreign objects enter the swivel range of the stop.

3) The max. stop force must act on the centre of the cushioning screw disk. Lateral forces on the cushioning screw are not permissible.

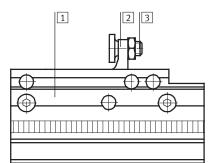
Operating and environmental conditions							
Piston Ø		8	12	18			
Operating pressure	[bar]	1 8					
Ambient temperature ¹⁾	[°C]	-10 +60					

Max. permissible energy in the intermediate position							
Piston Ø		8	12	18			
With P cushioning	[Nm]	0.1		0.6			
With YSR cushioning	[Nm]	1		3			



Materials

Sectional view

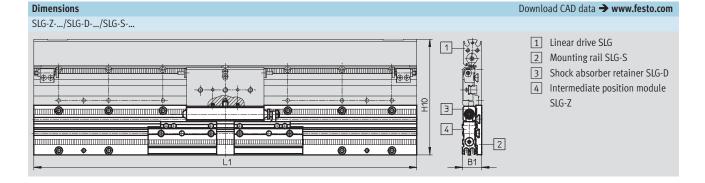


Intermediate position module

	1	
1	Housing	Hard anodized aluminum
2	Stop	Nickel plated steel
3	Cushioning screw	High-alloy steel
-	Seals	Polyurethane

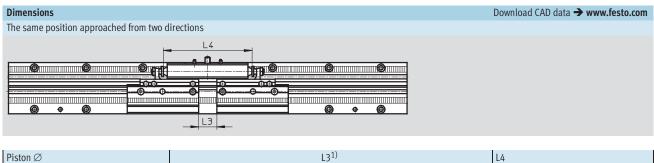
Mounting options on linear drive				
Piston Ø		8	12	18
Through-holes for direct mounting with screws to DIN 912	Intermediate position module	M2.5	M3	
	Shock absorber retainer	M4		M5
	Mounting rail	M3		M4
Centering pins	Intermediate position module	Ø 4H7		Ø 5H7
	Shock absorber retainer	Ø 2H7		Ø 5H7
	Mounting rail	Ø 3H7		Ø 5H7

-Note The module's symmetric design makes it suitable for both approach directions.



Туре	B1	H10	L1
SLG-8-100			207
SLG-8-200			307
SLG-8-300	15	93.1	407
SLG-8-400			507
SLG-8-500			607
SLG-12-100			233
SLG-12-200			333
SLG-12-300			433
SLG-12-400	18.5	104.1	533
SLG-12-500			633
SLG-12-600			733
SLG-12-700			833
SLG-18-100			271
SLG-18-200			371
SLG-18-300			471
SLG-18-400			571
SLG-18-500	25.5	135.5	671
SLG-18-600			771
SLG-18-700			871
SLG-18-800			971
SLG-18-900			1071

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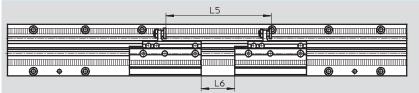


Piston Ø	L3	L4	
	min.	max.	
82)	21	27	68
12	39	45	86
18	50	56.5	111

1) Depends on the fine adjustment

2) Due to the narrowness of the space L3 only the following threaded connectors can be used for the compressed air connections: 30 491 LCN-M3-PK-2-B





Note

The space for 2 intermediate positions can be reduced to 0 mm by turning the second module by 90° in the same plane (\rightarrow 21).

Piston \varnothing	L5 min.	L6 ³⁾
8	90	32
12	90	
18	97	

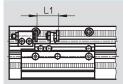
3) The space between the modules is such that the following threaded connectors can be used for the compressed air connections:

153 330 QSML-M3-3 153 332 QSML-M3-4

30 491 LCN-M3-PK-2-B

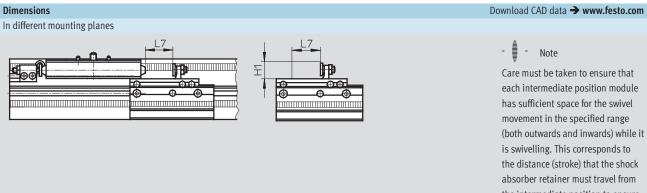
30 984 LCN-M3-PK-2

Space between end stop and intermediate position module



Piston \varnothing	L1
	min.
8	20
12	
18	

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 $\mathsf{Piston}\,\varnothing$ H1 L7 Cushioning P YSR cushioning 8 18 11 23 12 11 18 23 18 16 23 31

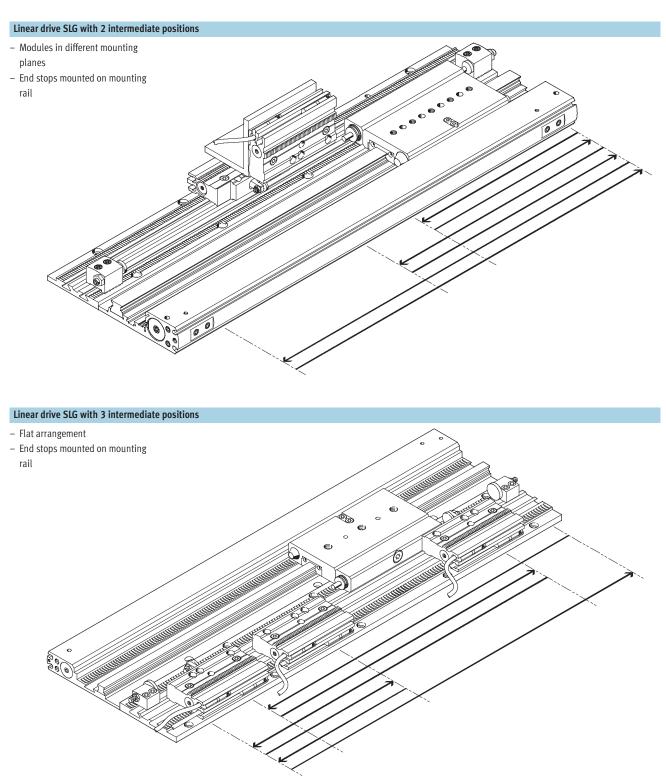
Maximum number of intermediate position modules on one mounting rail

The number of intermediate position modules that can be ordered via the linear drive SLG modular product system is restricted to max. 4.

If additional intermediate positions are required, further modules can be ordered separately (\rightarrow 23) and fitted in another mounting plane.

Piston Ø	Stroke length of the mounting rail [mm]								
	100	200	300	400	500	600	700	800	900
8	2		3	4		-	-	-	-
12						4		-	-
18								4	

each intermediate position module has sufficient space for the swivel movement in the specified range (both outwards and inwards) while it is swivelling. This corresponds to the distance (stroke) that the shock absorber retainer must travel from the intermediate position to ensure safe inward or outward swivelling of the stop (➔ 21).



Linear drives SLG, flat design Ordering data – Modular product system

3.1

M Mandatory	M Mandatory data												
Module No.	Drive function	Size		Stroke		Cushioning		Position sensing		Intermediate position			
187 857 187 855	SLG	8 12		100 900		P YSR		A		Z1 Z2			
187 853		18								Z3 Z4			
Ordering example 187 853	SLG	- 18	٦-	800	-	Р	_	A	_	Z4			

Ordering table

01	uering table							
Siz	ze		8	12	18	Condi- tions	Code	Enter code
Μ	Module No.		187 857	187 855	187 853			
	Drive function		Rodless linear drive unit				SLG	SLG
	Size	[mm]	8	12	18			
	Stroke	[mm]	100	100	100	1	-100	
			200	200	200	1	-200	
			300	300	300	2	-300	
			400	400	400		-400	
			500	500	500		-500	
			-	600	600		-600	
			-	700	700		-700	
			-	-	800		-800	
			-	-	900		-900	
	Cushioning		Flexible cushioning rings in t	he end positions			-P	
			Shock absorbers in the end p	ositions			-YSR	
	Position sensing		For proximity sensing				-A	-A
0	Intermediate position		1 intermediate position				-Z1	
			2 intermediate positions				-Z2	
		3 intermediate positions					-Z3	
			4 intermediate positions					

1 100, 200 Max. 2 intermediate positions.

2 300 Max. 3 intermediate positions.

Transfer order code SLG

→ Internet: www.festo.com/catalog/...

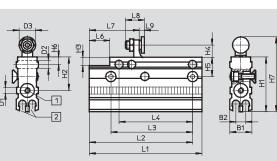
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Intermediate position module SLG-Z Technical data → 16



1 Air connections on both sides 2 Slot for proximity sensor SME-/SMT-10

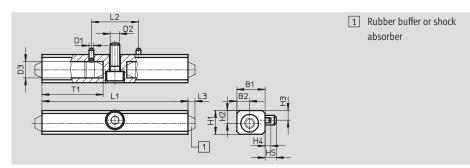
Dimensions and ordering data For Ø B1 B2 D1 D2 D3 H1 H2 H3 H4 H5 H6 H7 L1 Ø Ø H7 +0.3 8,12 10.8 4.8 М3 4 8 26.6 16.2 4 6 9.5 3.5 36.6 55 18 15.6 4.8 М3 5 29.6 19.2 9.6 11.5 4.3 44.2 62 10 _

For \varnothing	L2	L3	L4	L6	L7	L8	LS	9	Weights	Part No.	Туре
	±0.1	±0.1	±0.02				min.	max.	[g]		
8,12	50.5	40	36	10	24.4	9.25	2.5	4.2	39.5	525 680	SLG-Z-8/12-A
18	57.5	50	50	-	21.6	12	3.7	5.4	89.5	525 681	SLG-Z-18-A

Shock absorber retainer SLG-D

Material: Hard anodized aluminum





Dimensions an	Dimensions and ordering data												
For Ø	B1	B2	D1 Ø	D2	D3 Ø	H1	H2	H3					
			H7/h8					-0.1					
8 12	11.5	5	2	M4	7.5+0.05	10	5.4	4.1					
18	17	8	5	M5	10+0.02	15	7.5	7.75					

For \varnothing	H4	H5	L1	L2	L3	T1	Weights	Part No. Type	
				±0.02			[g]		
8	2.25	4.8	62	20	2	26	17/27.5 ²⁾	525 703 SLG-D-8 ¹⁾	
12	2.25	4.0	80	20	ر	20	22.5/33 ²⁾	525 704 SLG-D-12 ¹⁾	
18	2	4.7	105	60	3	43	60/104 ²⁾	525 705 SLG-D-18 ¹⁾	

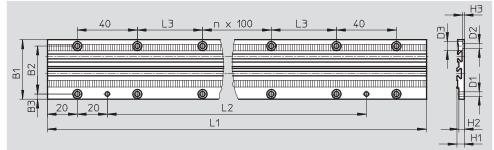
Shock absorber elements are not included in the scope of delivery
 With P cushioning/with YSR cushioning



Mounting rail SLG-S

Material: Hard anodized aluminum





Dimensions	imensions and ordering data																			
For Ø	Stroke	B1	B2	B3	D1 Ø	D2 Ø	D3 Ø	H1	H2	H3	n	L1	L2	L3	Weights	Part No.	Туре			
	[mm]				H7										[g]					
8	100										0	207	127		73.5	525 682	SLG-S-8-100			
	200										1	307	227		109	525 683	SLG-S-8-200			
	300	39.6	32	3.4	3	3.4	6	4.8	3.5	0.9	2	407	327	43.5	144.5	525 684	SLG-S-8-300			
	400										3	507	427		180	525 685	SLG-S-8-400			
	500										4	607	527		215.5	525 686	SLG-S-8-500			
12	100										0	233	153		110.4	525 687	SLG-S-12-100			
	200										1	333	253	56.5	56.5			157.8	525 688	SLG-S-12-200
	300										2	433	353			205.2	525 689	SLG-S-12-300		
	400	39.6	32	3.5	3	3.4	6	7.2	1.9	1.9	3	533	453			252.6	525 690	SLG-S-12-400		
	500										4	633	553			300	525 691	SLG-S-12-500		
	600										5	733	653			347.4	525 692	SLG-S-12-600		
	700										6	833	753		394.8	525 693	SLG-S-12-700			
18	100										0	271	191		245.6	525 694	SLG-S-18-100			
	200										1	371	291		336.2	525 695	SLG-S-18-200			
	300										2	471	391		426.8	525 696	SLG-S-18-300			
	400										3	571	491		517.4	525 697	SLG-S-18-400			
	500	50	40	4.75	5	4.5	7.5	10.3	9	2.5	4	671	591	75.5	608	525 698	SLG-S-18-500			
	600										5	771	691		698.6	525 699	SLG-S-18-600			
	700										6	871	791		789.2	525 700	SLG-S-18-700			
	800]									7	971	891]	879.8	525 701	SLG-S-18-800			
	900	<u> </u>									8	1071	991		970.4	525 702	SLG-S-18-900			

Rubber buffer SLG



Ordering data			
For \varnothing	Weights	Part No.	Туре
	[g]		
8,12	1.5	379 802	SLG-8/12
18	6	381 219	SLG-18

Shock absorber YSRG



Ordering data			
For \varnothing	Weights	Part No.	Туре
	[g]		
8,12	7	381 042	YSRG-5-5-C
18	27	384 581	YSRG-8-8-C

Centering pin ZBS

Material: Stainless steel





Dimensions and	Dimensions and ordering data											
For \varnothing	B1	D1	Weights	Part No. Type	PE ¹⁾							
		Ø										
[mm]	-0.2	h8	[g]									
8,12	5	2	1	525 273 ZBS-2	10							
18	5	5	1	150 928 ZBS-5	10							

1) Packaging unit quantity

Ordering data	- Proximity sensors for C-sl	ot, magneto-re	sistive			Technical data 🗲 Internet: smt
	Type of mounting	Switch output	Electrical connection, connection direction	Cable length [m]	Part No.	Туре
N/O contact						
\sim	Insertable in the slot from	PNP	Cable, 3-wire, in-line	2.5	525 915	SMT-10F-PS-24V-K2,5L-OE
a sal	above, flush with cylinder		Plug M8x1, 3-pin, in-line	0.3	525 916	SMT-10F-PS-24V-K0,3L-M8D
×	profile		Plug M8x1, 3-pin, lateral	0.3	526 675	SMT-10F-PS-24V-K0,3Q-M8D
D	Insertable in the slot	PNP	Plug M8x1, 3-pin, in-line	0.3	173 220	SMT-10-PS-SL-LED-24
	lengthwise		Cable, 3-wire, in-line	2.5	173 218	SMT-10-PS-KL-LED-24

Ordering data	- Proximity sensors for C-sl	ot, magnetic re	eed			Technical data 🗲 Internet: sme
	Type of mounting	Switch	Electrical connection,	Cable length	Part No.	Туре
		output	connection direction	[m]		
N/O contact						
A	Insertable in the slot from	Contacting	Plug M8x1, 3-pin, in-line	0.3	525 914	SME-10F-DS-24V-K0,3L-M8D
of el	above, flush with cylinder		Cable, 3-wire, in-line	2.5	525 913	SME-10F-DS-24V-K2,5L-OE
₩.	profile		Cable, 2-wire, in-line	2.5	526 672	SME-10F-ZS-24V-K2,5L-OE
<i>A</i>	Insertable in the slot	Contacting	Plug M8x1, 3-pin, in-line	0.3	173 212	SME-10-SL-LED-24
Carlos Carlos	lengthwise		Cable, 3-wire, in-line	2.5	173 210	SME-10-KL-LED-24

Ordering data	Technical data 🗲 Internet: nebu				
	Electrical connection, left	Electrical connection, right	Cable length	Part No.	Туре
			[m]		
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 333	NEBU-M8G3-K-2.5-LE3
			5	541 334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 338	NEBU-M8W3-K-2.5-LE3
			5	541 341	NEBU-M8W3-K-5-LE3

Ordering da	ita – One-way flow contro	Technical data 🗲 Internet: grla			
	Connection	Connection		Part No.	Туре
	Thread	For tubing OD			
	M3	3	Metal design	175 041	GRLA-M3-QS-3
	M5	4		193 138	GRLA-M5-QS-4-D

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