Linear modules HMP

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Key features

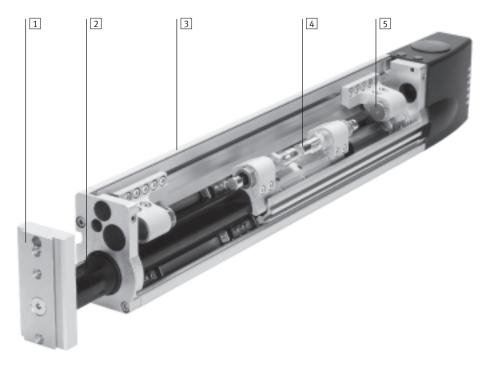
At a glance



- Sturdier
- Optimised end stop system
- Optimised intermediate position module
- Minimised susceptibility to wear
- One-way flow control valves that can be externally adjusted
- Integrated sensor strip

- Diameters of 16 ... 32 mm
- Stroke lengths of 50 ... 400 mm
- Extremely rigid basic profile
- Infinitely adjustable end stops
- Rotatable yoke plate
- Integrated clamping unit
- Precision backlash-free guide system
- Freely adjustable intermediate position
- Adjustable end-position cushioning

- Integrated sensors:
 - Sensor strip for proximity sensors for end-position sensing
 - Mounting slot for proximity sensors for position sensing
- Functional end cap:
 - Pneumatic interface
 - Electrical interface
- Highly flexible thanks to various mounting and assembly options:
 - Basic profile
 - Yoke plate
- Large selection of adapters for:
 - Drives
 - Grippers
- Innovative and user-friendly installation system



- 1 Yoke plate
 Can be turned to any angle from
 0 to 360°. The yoke plate cannot
 be turned if combined with the
 clamping unit. Drives and
 grippers can be mounted on the
 yoke plate by means of adapter
 kits (direct mounting or dovetail
 connections).
- 2 Guide system
 Extremely high rigidity thanks to
 the hardened steel guide barrel
 which is supported in pre-loaded
 and backlash-free recirculating
 ball bearing guides guaranteeing
 the utmost precision.
- 3 Basic profile

 Drives and basic components

 can be attached to the rigid light
 alloy profile using adapter,
 connector and component kits.
- [4] End-position cushioning.
 Extremely dynamic operation thanks to hydraulic shock absorbers which cushion the piston sleeve at the end positions.
- Any desired intermediate position can be set between minimum and maximum stroke (plus the strokes of the shock absorbers).

Key features

Wide choice of variants

End stop

The optimised end stop system is practically wear-free. Rough adjustment is performed by moving the stop into the profile groove. Fine adjustment is performed using compressed air via a rotatable sleeve.



Clamping unit

The pneumatically-powered clamping unit can be used to hold loads at any end position and with the module installed at any angle. In the case of a pressure drop or pressure failure, the clamping unit acts like an EMERGENCY STOP device. The clamping unit can be released by means of the manual override.



End cap

Connections can be made on the top and bottom of the end cap. Pneumatic tubing and electrical cables can be bundled and routed through the end cap via conduits.

Max. 6 proximity sensors can be connected to the integral terminal strip. The switching states of the proximity sensors are indicated via a display window in the end cap.



Intermediate position module

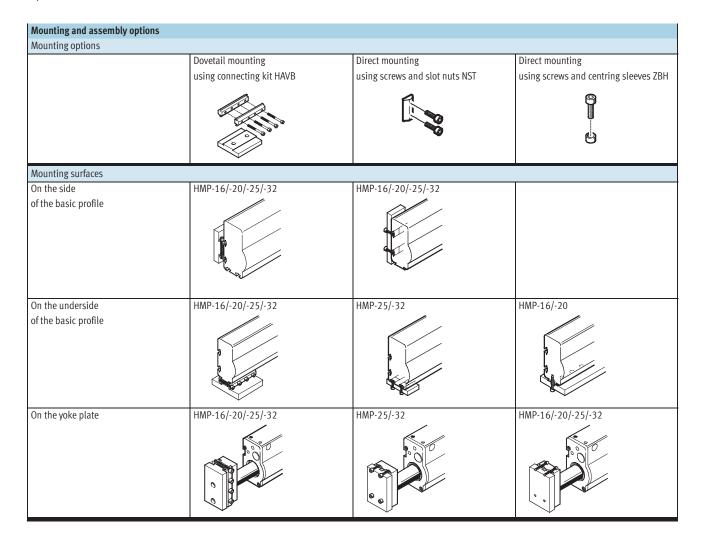
The intermediate position module permits advancing to an additional position between the two end positions. This is done by swivelling a lever into the traversing range of the moving stop on the guide tube.

The intermediate position can be activated during the advancing stroke or retracting stroke, depending on the type of design.

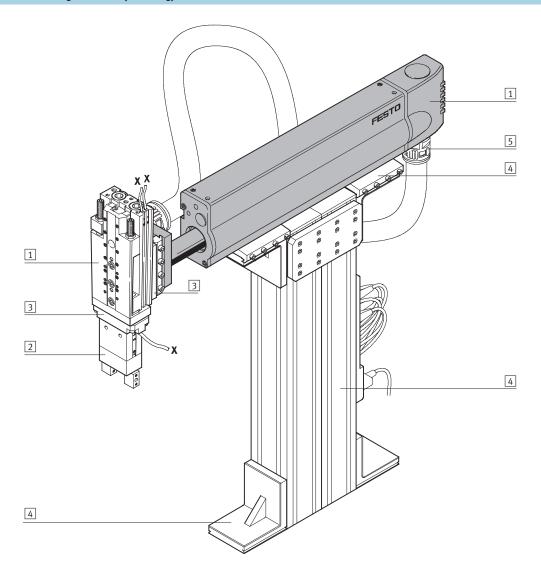
Multiple intermediate position modules can be installed on request.



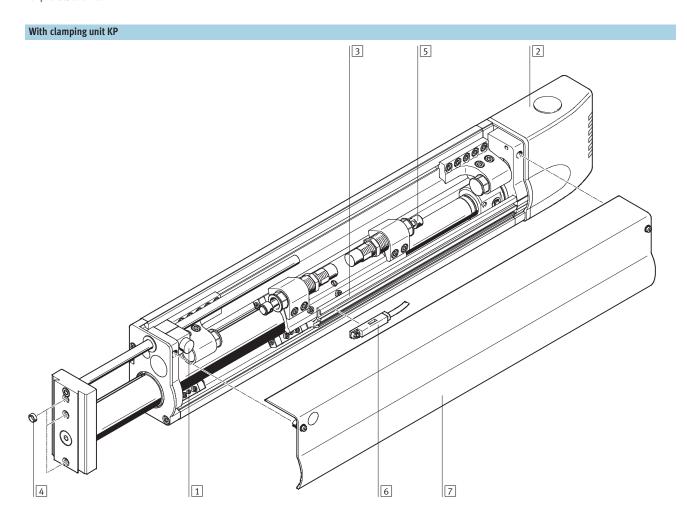
Key features



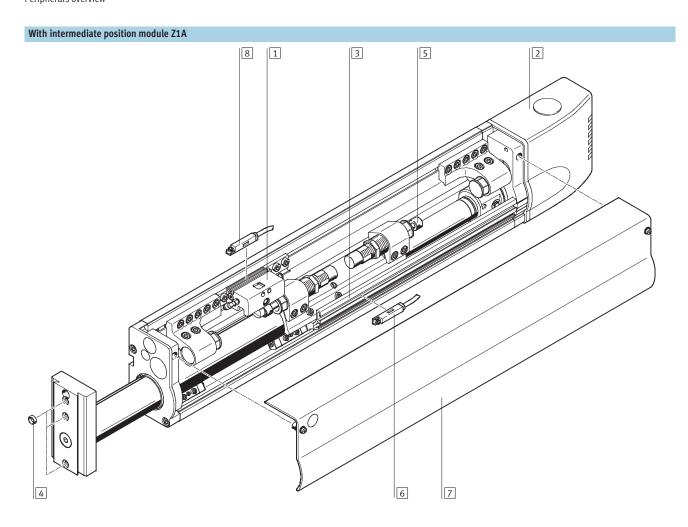
System product for handling and assembly technology



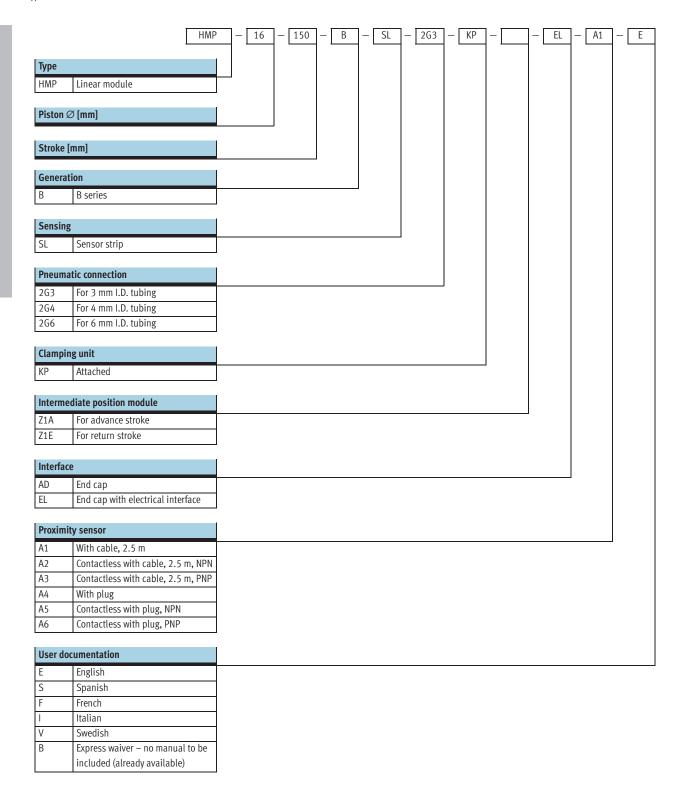
Syste	m elements and accessories		
		Brief description	→ Page/Internet
1	Drives	Wide range of combination options within handling and assembly technology	drive
2	Grippers	Wide range of optional variants within handling and assembly technology	gripper
3	Adapters	For drive/drive and drive/gripper combinations	adapter kit
4	Basic components	Profiles and profile combinations as well as profile/drive combinations	basic component
5	Installation components	For achieving a clear-cut, safe layout of electrical cables and tubing	installation component
-	Axes	Wide range of combination options within handling and assembly technology	axes
-	Motors	Servo and stepper motors, with or without gearing	motor

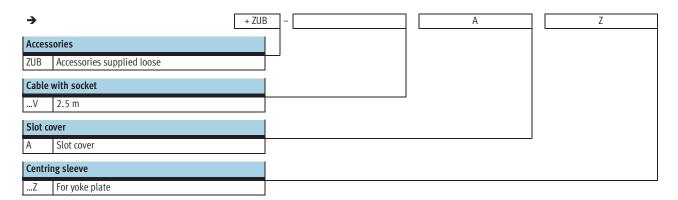


Acce	essories		
		Brief description	→ Page/Internet
1	Clamping unit KP	For holding loads in all mounting and end positions in the event of a drop in pressure	1 / 7.1-24
2	End cap AD/EL	The end cap (EL) houses an integrated electrical interface	1 / 7.1-24
3	Sensor strip SL	For mounting proximity sensors and flexible sensing of any desired end positions. Included in the scope of delivery of the linear module.	1 / 7.1-24
4	Centring sleeve Z	For centring loads and attachments on the yoke plate	26
5	Shock absorber	Included in the scope of delivery of the linear module	26
6	Proximity sensor A	For position sensing via the sensor strip	27
7	Housing cover	Included in the scope of delivery of the linear module	-
-	Cable with socket V	For proximity sensor	27
-	Slot cover A	For protecting the proximity sensor cable	26



Acce	essories		
		Brief description	→ Page/Internet
1	Intermediate position module	For approaching an intermediate position during the advance stroke. The intermediate position	18
	Z1A	module Z1E is used to approach an intermediate position during the return stroke.	
2	End cap	The end cap (EL) houses an integrated electrical interface	1 / 7.1-24
	AD/EL		
3	Sensor strip	For mounting proximity sensors and flexible sensing of any desired end positions. Included in	1 / 7.1-24
	SL	the scope of delivery of the linear module.	
4	Centring sleeve	For centring loads and attachments on the yoke plate	26
	Z		
5	Shock absorber	Included in the scope of delivery of the linear module	26
6	Proximity sensor	For position sensing via the sensor strip	27
_	A		
7	Housing cover	Included in the scope of delivery of the linear module	-
8	Proximity sensor	For sensing the position of the lever at the intermediate position module	28
	A	(intermediate position active/not active)	
-	Cable with socket	For proximity sensor	27
	V		
-	Slot cover	For protecting the proximity sensor cable	26
	A		



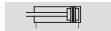


indling units

7.1

Technical data

Function Standard version



with clamping unit











General technical data							
Piston Ø			16	20	25	32	
System mode			Yoke				
Mode of operation			Double-acting				
Protection against torsion			Guide				
Connection type			Female thread				
Pneumatic connection, linear module	ę.		M5	G1/8	G1/8	G1/4	
Pneumatic connection, intermediate	position module		M3				
Assembly position			Any				
Effective stroke		[mm]	16 320	24 400	24 400	40 400	
Position sensing			For proximity sensing				
Max. repetition accuracy ¹⁾		[mm]	0.01				
Max. speed	advancing	[m/s]	0.8	1.1	1.1	1.2	
	returning	[m/s]	0.8	1.1	1.1	1.1	
Swivel time of lever at intermediate	advancing	[s]	0.04	0.04	0.04	0.072	
position module	returning	[s]	0.04	0.036	0.034	0.065	

 $^{1) \}quad \text{Variation of end position and intermediate position for 100 successive strokes under constant operating conditions} \\$

Operating and environmental conditions							
Piston \varnothing		16	20	25	32		
Operating pressure	[bar]	4 8	48				
Operating medium		Dried compressed air,	Dried compressed air, lubricated or unlubricated				
Ambient temperature ¹⁾	[°C]	0 +60					
Protection class to EN 60 529		IP 40	IP 40				
Noise level F _{LEQ}	[dB(A)]	62	65	68	69		
Corrosion resistance class CRC ²⁾		2		•			

¹⁾ Note operating range of proximity sensors

²⁾ Corrosion resistance class 2 according to Festo standard 940 070 Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Forces [N]				
Piston Ø	16	20	25	32
Theoretical force at 6 bar, advancing ¹⁾	121	188	295	483
Theoretical force at 6 bar, returning ¹⁾	104	158	247	415

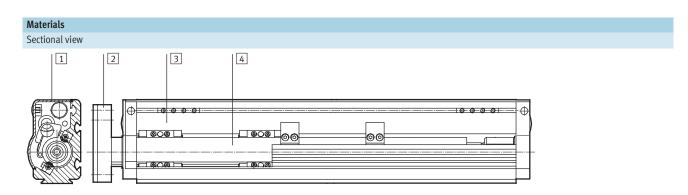
¹⁾ Theoretical values, please note: Degree of efficiency: approx. 90%

Linear modules HMP

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Technical data

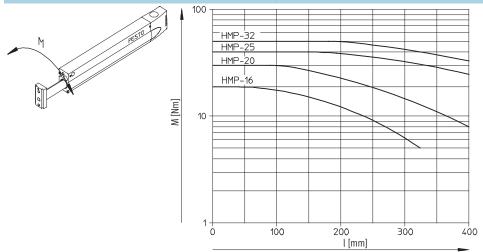
Weight [g]					
Piston Ø		16	20	25	32
Product weight	with 0 mm stroke	2100	4700	6300	10900
	per 10 mm stroke	88	110	150	200
Moving load	with 0 mm stroke	900	1500	2300	4000
	per 10 mm stroke	28	37	55	74
End cap	HMPAD	180	270	300	400
	HMPEL	210	300	330	430
Clamping unit HMPKP	50 mm	109	114	-	-
for effective stroke	100 mm	120	125	-	-
	150 mm	131	136	-	-
	200 mm	142	147	-	-
	250 mm	153	158	-	-
	320 mm	168	173	-	-
	400 mm	-	191	-	-
Intermediate position module	HMPZ1A/Z1E	165	206	227	321



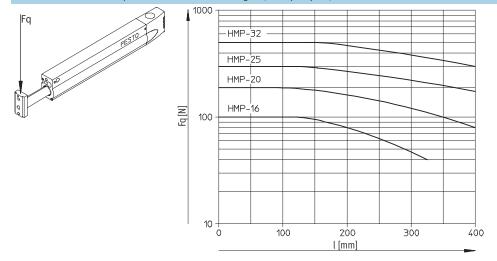
Line	inear module					
1	Housing cover	Anodised aluminium				
2	Yoke plate	Anodised aluminium				
3	Profile	Anodised aluminium				
4	Guide barrel	Tool steel				
_	Seals	Nitrile rubber, polyurethane				



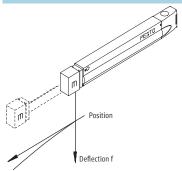
Permissible torque M as a function of the stroke length l (at the yoke plate)

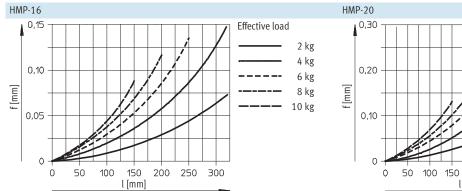


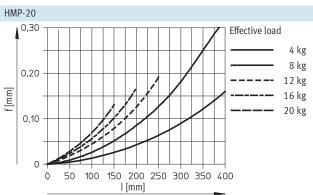
Permissible effective load Fq as a function of the stroke length I (at the yoke plate)

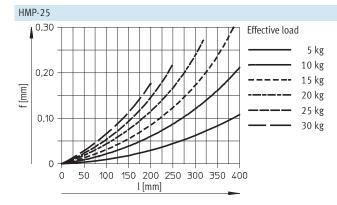


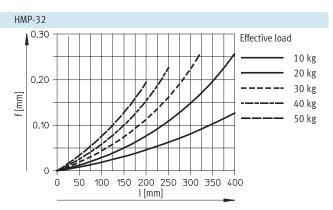
Deflection/deformation f as a function of the effective load m and the position l (stroke)









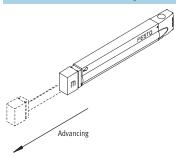


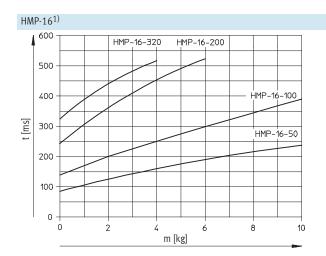
Technical data

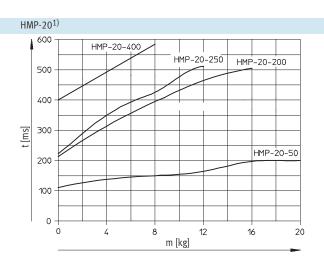
Max. permissible horizontal effective load at 6 bar

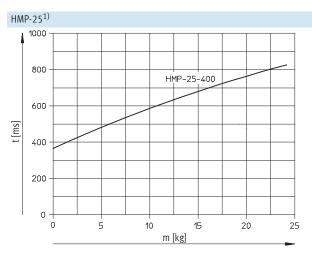
HMP-16: 10 kg HMP-20: 20 kg HMP-25: 30 kg HMP-32: 50 kg

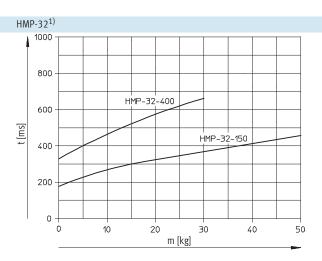
Permissible horizontal advancing time t as a function of the stroke length and the effective load m with optimum shock absorber stroke











¹⁾ Further nominal strokes in preparation

Linear modules HMP

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Technical data

Max. permissible horizontal effective load at 6 bar

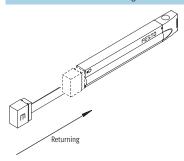
HMP-16: 10 kg

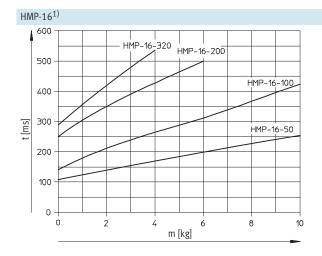
HMP-20: 20 kg

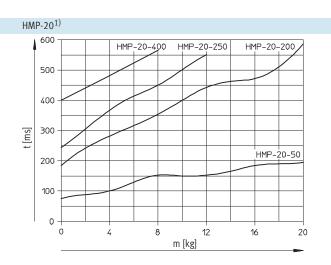
HMP-25: 30 kg

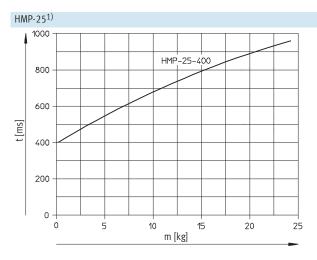
HMP-32: 50 kg

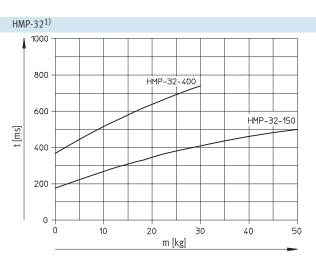
Permissible horizontal returning time t as a function of the stroke length and the effective load m with optimum shock absorber stroke











¹⁾ Further nominal strokes in preparation

Technical data

Max. permissible vertical effective load at 6 bar

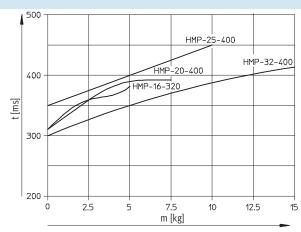
without clamping cartridge with clamping cartridge

HMP-16: 5 kg HMP-16: 4 kg HMP-20: 10 kg HMP-20: 7.5 kg

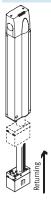
HMP-25: 15 kg HMP-32: 25 kg

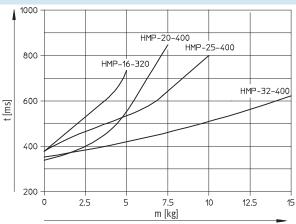
Permissible vertical advancing time t as a function of the stroke length and the effective load m with optimum shock absorber stroke $HMP-16/-20/-25/-32^{1)}$





Permissible vertical returning time t as a function of the stroke length and the effective load m with optimum shock absorber stroke HMP- $16/-20/-25/-32^{1)}$



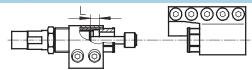


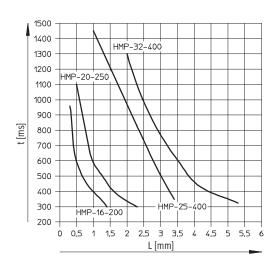
1) Further nominal strokes in preparation

Advancing/returning time t as a function of the optimum length L to which the shock absorber should be screwed out

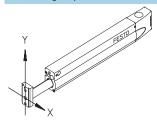
In order to obtain the shortest possible travel time with a linear module HMP, it is essential to adjust the shock absorbers to match the advancing/returning time t.

The optimum length L to which the shock absorbers should be screwed out is shown in the adjacent graph.



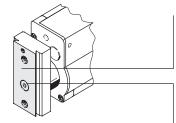


Determining the permissible effective load



As long as the centre of gravity of the effective load on the yoke plate lies within the outline of this plate, it is impossible to overload the linear module.



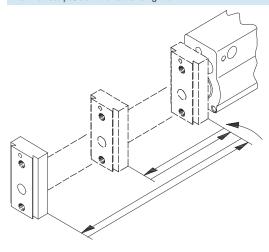


When dovetail mounting components are used, the centre of gravity should be within this area.

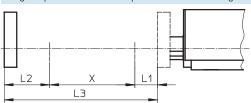
Recommended position of centre of gravity for low-vibration operation.

Intermediate position module Z1A/Z1E

Intermediate position with advancing with Z1A



Range for possible intermediate positions when advancing



L1 = Rear non-operational zone

L2 = Front non-operational zone

L3 = Effective stroke

X = Zone for possible

intermediate positions

X = L3 - L1 - L2

Non-operational zones [mm]				
Piston ∅	16	20	25	32
L1	33	42	42	55.5
L2	66	68.5	54.5	56

Calculation example

Given: Linear module

HMP-16-200-...-Z1A-...

To be found:

In which zone of the effective stroke are intermediate positions possible?

Calculation:

The piston ∅ of the linear module (16 mm) determines the following non-operational zones which do not permit intermediate positions:

L1 = 33 mm

L2 = 66 mm

X = L3 - L1 - L2 = 101 mm

This means:

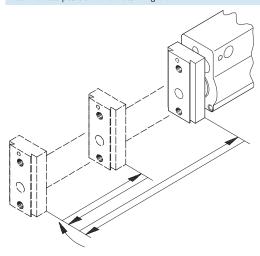
The lower limit of the effective stroke range for permissible intermediate positions is:

L1 = 33 mm

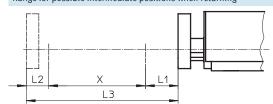
The upper limit of the effective stroke range for permissible intermediate positions is:

L1 + X = 134 mm

Intermediate position when returning with Z1E



Range for possible intermediate positions when returning



L1 = Rear non-operational zone

L2 = Front non-operational zone

L3 = Effective stroke

K = Zone for possible intermediate positions

X = L3 - L1 - L2

Non-operational zones [mm]								
Piston \varnothing	16	20	25	32				
L1	47.5	62	54.5	56				
L2	33	42	42	55.5				

Calculation example

Given: Linear module HMP-16-200-...-Z1E-... To be found:

In which zone of the effective stroke are intermediate positions possible?

Calculation:

The piston ∅ of the linear module (16 mm) determines the following non-operational zones which do not permit intermediate positions:

L1 = 47.5 mm

L2 = 33 mm

X = L3 - L1 - L2 = 119.5 mm

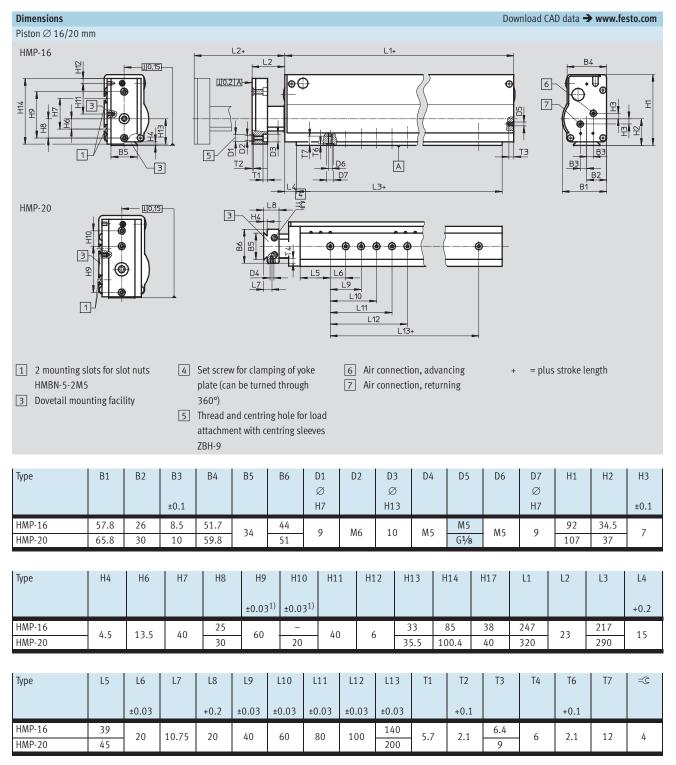
This means:

The lower limit of the effective stroke range for permissible intermediate positions is:

L1 = 47.5 mm

The upper limit of the effective stroke range for permissible intermediate positions is:

L1 + X = 167 mm

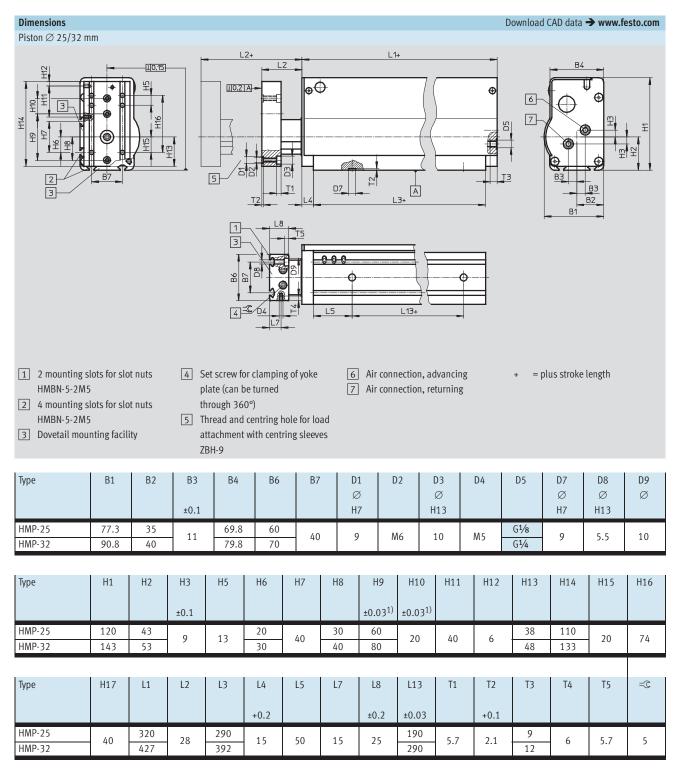


¹⁾ Tolerance specification applies to countersink D1; tolerance for thread D2: ±0.2

Linear modules HMP

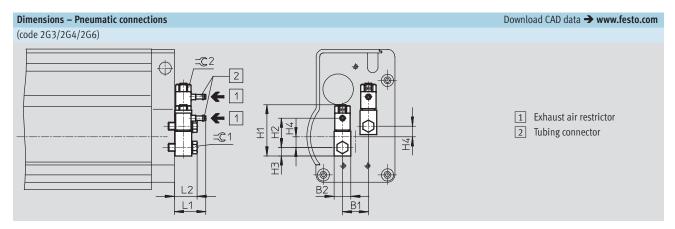
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Technical data

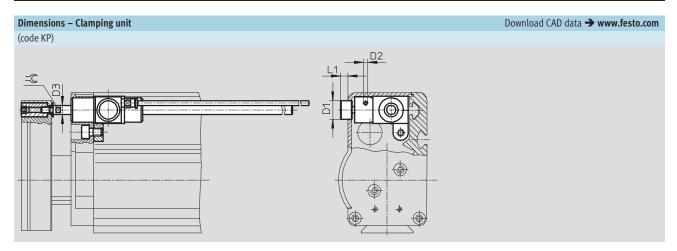


¹⁾ Tolerance specification applies to countersink D1; tolerance for thread D2: ± 0.2

Technical data



Туре	B1	B2	H1	H2	НЗ	H4	L1	L2	=©1	=©2
HMP-162G3	17	11	33.6	19	5.5	7	20.6 22.6	15	7	9
HMP-202G4 HMP-202G6	20	16	48.7	28.9 27.5	8	,	31.3 31.4	22.2	13	14
HMP-252G4 HMP-252G6	22	10	40.7	28.9 27.5	0	9	31.3 31.4	22.2	15	14
HMP-322G4 HMP-322G6		20	61.8	37.9 38.2	10	9	35.8 35.9	28.2	17	17



Туре	D1	D2	D3	L1	=©	Holding force	Effective load	
	Ø	1)	Ø				horizontal	vertical
						[N]	[kg]	[kg]
HMP-16	11 /	M3	6	5	5	100	10	4
HMP-20	11.4	CIVI	Ů Î	3.8			20	7.5

1) Air connection is supplied ready-fitted with QS connector QSM-M3-4



The clamping unit must only be operated when the rod is stationary (end position). Dynamic braking operations can result in severe damage to the clamping device.

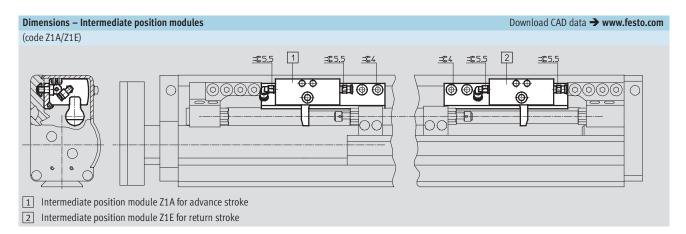
Precision positioning cannot be guaranteed with the clamping unit since slippage of approx. 1 – 2 mm can occur.

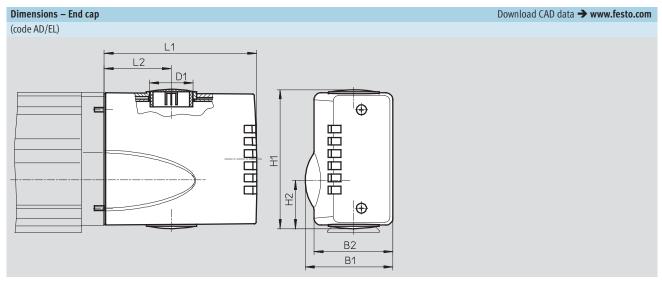
When using the linear module HMP-20 together with the clamping unit, the max. possible stroke is reduced by 12.5 mm.

Linear modules HMP

FESTO

Technical data





Туре	B1	B2	D1 ∅	H1	H2	L1	L2
HMP-16	57.4	51.2	28.5 (PG 21)	91.3	31.5	100	44
HMP-20	65.4	59.2		106.3	34.4		
HMP-25	76.9	69.2	37.2 (PG 29)	119	40.1	120	55
HMP-32	90.4	79.2		141.6	49.9		

Module No.	Function	Piston ∅	Stroke	Generation	Position sensing	Pneumatic connection
537 940	НМР	16	50	В	SL	2G3
537 941		20	100			2G4
537 942		25	150			2G6
537 943		32	200			
			250			
			320			
			400			
Ordering						
example						
537 940	НМР	- 16	- 150	- B	- SL	- 2G3

10	dering table								
Si	ze		16	20	25	32	Condi- tions	Code	Enter code
M	Module No.		537 940	537 941	537 942	537 943			
	Function		Linear module with ba	all bearing guide				HMP	HMP
	Piston Ø	[mm]	16	20	25	32			
	Stroke	[mm]	50	50	-	-		-50	
			100	100	100	100		-100	
			150	150	150	150		-150	
			200	200	200	200		-200	
			250	250	250	250		-250	
			320	320	320	320		-320	
			-	400	400	400		-400	
	Generation		B series					-B	-B
	Position sensing		Sensor strip					-SL	-SL
	Pneumatic connection		One-way flow control	-	-	-		-2G3	
			valve, 3 mm barbed						
			connector						
			One-way flow control	valve, 4 mm barbed co	nnector			-2G4	
•			-	One-way flow control	valve, 6 mm barbed	connector		-2G6	

Transfer order	cod	e								
		НМР	-	-] -	В	_	SL] -	

Ordering data – Modular products

Clamping unit	Intermedi- ate position	Interface	Proximity sensor set	User documentation	Acces- sories	Cable with socket	Slot cover	Centring sleeves
KP	Z1A	AD	A1	E	ZUB	V	A	Z
	Z1E	EL	A2	S				
			A3	F				
			A4	ı				
			A5	V				
			A6	В				
	- Z1A	- EL	- A1	- B	ZUB	- 2V		

Ordering table									
iize	16	20	25	32	Condi- tions	Code		Enter code	
Clamping unit	Attached		-	-	1	-KP			
Intermediate position	1 intermediate positi	on, advancing		·	2	-Z1A			
	1 intermediate positi	on, returning			2	-Z1E			
Interface	End cap	· · · · · · · · · · · · · · · · · · ·							
	End cap with electrica	cap with electrical interface							
Proximity sensor, assembled	Proximity sensor with	cable, 2.5 m		-A1					
	Proximity sensor, con	roximity sensor, contactless, NPN with cable, 2.5 m							
	Proximity sensor, con	Proximity sensor, contactless, PNP with cable, 2.5 m							
	Proximity sensor with	plug M8			3	-A4			
	Proximity sensor, con	tactless, NPN with p	plug M8		3	-A5			
	Proximity sensor, con	tactless, PNP with p	olug M8		3	-A6			
Alternative user documentation	User documentation,	English				-E			
(standard is German/English)	User documentation,	Spanish				-S			
	User documentation,	French				-F			
	User documentation,	Italian				-1			
	User documentation,					-V			
	Express waiver - no m		-B						
Accessories	Supplied separately					ZUB-		ZUB-	
Cable with socket, 2.5 m	1 10					V			
Slot cover	Slot cover					Α			
Centring sleeves (pack of 10)	10, 20, 30, 40, 50, 6	0, 20, 30, 40, 50, 60, 70, 80, 90							

1E.

2 **Z1A, Z1E** Min. stroke: 150 mm.

3 A4, A5, A6 Not with interface EL

Max. stroke: Piston \varnothing 16, 20, 25 mm: 200 mm Piston Ø 32 mm: 150 mm

Accessories

Ordering data						
	For piston \varnothing [mm]	Remarks	Order code	Part No.	Туре	PU ¹⁾
Centring sleeve ZBH					Technical data	→ Internet: zbh
6	16 32	For yoke plate	Z	150 927	ZBH-9	10
Slot cover ABP						
	16 32	For sensor strip every 0.5 m	A	151 681	ABP-5	2
Shock absorber YSRW	·		·	·	Technical data	➤ Internet: ysrw
	16 20		_	191 194 191 196	YSRW-8-14 YSRW-12-20	1
	25 32			191 196 191 197	YSRW-12-20 YSRW-16-26	

¹⁾ Packaging unit quantity

Accessories

Ordering data	- Proximity sensors for T-slot, magneto-	esistive				Technical data → Internet: smt
	Type of mounting	Switch output	Electrical connection	Cable length [m]	Part No.	Туре
N/O contact		<u>'</u>				
	Insertable in the slot from above, flush	PNP	Cable, 3-wire	2.5	543 867	SMT-8M-PS-24V-K-2,5-0E
A DE TO	with cylinder profile		Plug M8x1, 3-pin	0.3	543 866	SMT-8M-PS-24V-K-0,3-M8D
			Plug M12x1, 3-pin	0.3	543 869	SMT-8M-PS-24V-K-0,3-M12
		NPN	Cable, 3-wire	2.5	543 870	SMT-8M-NS-24V-K-2,5-0E
			Plug M8x1, 3-pin	0.3	543 871	SMT-8M-NS-24V-K-0,3-M8D
NS .	Insertable in the slot lengthwise, flush	PNP	Cable, 3-wire	2.5	175 436	SMT-8-PS-K-LED-24-B
	with the cylinder profile		Plug M8x1, 3-pin	0.3	175 484	SMT-8-PS-S-LED-24-B
N/C contact						
N/C COMMUNIC	Insertable in the slot from above, flush with cylinder profile	PNP	Cable, 3-wire	7.5	543 873	SMT-8M-PO-24V-K7,5-OE

Ordering data	- Proximity sensors for T-slot, magnetic r	eed				Technical data → Internet: sme
	Type of mounting	Switch	Electrical connection	Cable length	Part No.	Туре
		output		[m]		
N/O contact						
	Insertable in the slot from above, flush	Contacting	Cable, 3-wire	2.5	543 862	SME-8M-DS-24V-K-2,5-OE
	with cylinder profile			5.0	543 863	SME-8M-DS-24V-K-5,0-OE
			Cable, 3-wire	2.5	543 872	SME-8M-ZS-24V-K-2,5-OE
			Plug M8x1, 3-pin	0.3	543 861	SME-8M-DS-24V-K-0,3-M8D
	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	2.5	150 855	SME-8-K-LED-24
	with the cylinder profile		Plug M8x1, 3-pin	0.3	150 857	SME-8-S-LED-24
N/C contact						
	Insertable in the slot lengthwise, flush with the cylinder profile	Contacting	Cable, 3-wire	7.5	160 251	SME-8-O-K-LED-24
W	with the cylinder profile					

Accessories

Ordering data	– Proximity sensors for C-sl	ot, magneto-re	sistive			Technical data → Internet: smt
	Type of mounting	Switch output	Electrical connection, Cable length Part No. connection [m]		Туре	
N/O contact						
	Insertable in the slot from	PNP	Cable, 3-wire, in-line	2.5	525 915	SMT-10F-PS-24V-K2,5L-OE
	above, flush with cylinder		Plug M8x1, 3-pin, in-line	0.3	525 916	SMT-10F-PS-24V-K0,3L-M8D
	profile		Plug M8x1, 3-pin, lateral	0.3	526 675	SMT-10F-PS-24V-K0,3Q-M8D
	Insertable in the slot	PNP	Plug M8x1, 3-pin, in-line	0.3	173 220	SMT-10-PS-SL-LED-24
(Total	lengthwise		Cable, 3-wire, in-line	2.5	173 218	SMT-10-PS-KL-LED-24

Ordering data	– Proximity sensors for C-sl	ot, magnetic r	eed			Technical data → Internet: sme
	Type of mounting	Switch output	Electrical connection, connection direction	Cable length [m]	Part No.	Туре
N/O contact						
	Insertable in the slot from	Contacting	Plug M8x1, 3-pin, in-line	0.3	525 914	SME-10F-DS-24V-K0,3L-M8D
	above, flush with cylinder		Cable, 3-wire, in-line	2.5	525 913	SME-10F-DS-24V-K2,5L-OE
	profile		Cable, 2-wire, in-line	2.5	526 672	SME-10F-ZS-24V-K2,5L-0E
	Insertable in the slot	Contacting	Plug M8x1, 3-pin, in-line	0.3	173 212	SME-10-SL-LED-24
On the second	lengthwise		Cable, 3-wire, in-line	2.5	173 210	SME-10-KL-LED-24

Ordering data – Connecting cables					Technical data → Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 333	NEBU-M8G3-K-2.5-LE3
			5	541 334	NEBU-M8G3-K-5-LE3
	Straight socket, M12x1, 5-pin	Cable, open end, 3-wire	2.5	541 363	NEBU-M12G5-K-2.5-LE3
			5	541 364	NEBU-M12G5-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 338	NEBU-M8W3-K-2.5-LE3
			5	541 341	NEBU-M8W3-K-5-LE3
	Angled socket, M12x1, 5-pin	Cable, open end, 3-wire	2.5	541 367	NEBU-M12W5-K-2.5-LE3
			5	541 370	NEBU-M12W5-K-5-LE3

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