



Key features

At a glance

General information

The compact and cost-optimised angle gripper consists of a two-part mirror-symmetrical housing made of die-cast zinc. The force generated by the linear motion of the piston is translated into the gripper jaw movement via a pneumatic piston, which acts directly on the gripper jaws installed in the housing by means of a moment compensator in accordance with the rack and pinion principle. To ensure a low-backlash plain-bearing guide for the gripper jaws, appropriate guide elements are fitted in the housing and pretensioned by means of socket head screws.

- Double-acting gripper
- Internal fixed flow control, does away with the need for external flow control in 90% of applications
- High force with minimal volume
- Suitable for external and internal gripping
- Opening angle of 30°, 80°
- Wide range of options for mounting on drives

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- Repetition accuracy of 0.05 mm
- Slot for proximity sensor SME/SMT-10

Note

Sizing software for gripper selection → www.festo.com



Angle grippers HGWC Peripherals overview and type codes



System product for handling and assembly technology



Accessories						
	Туре	Brief description	→ Page/Internet			
1	Centring sleeve	For centring when attaching gripper fingers	12			
	ZBH	• 4 included in the scope of delivery of the gripper				
2	One-way flow control valve	For regulating speed	grla			
	GRLA					
3	Push-in fitting	For connecting compressed air tubing with standard O.D.	quick star			
	QS					
4	Proximity sensor	For sensing the piston position	12			
	SME/SMT-10					
5	Centring sleeve	For centring when attaching to a drive or plate	12			
	ZBH	• 2 included in the scope of delivery of the gripper				
6	-	Drive/gripper connections	adapter kit			

Type codes HGWC 12 40 А Туре HGWC Angle gripper Size Opening angle per gripper jaw 15° 15 40 40° Position sensing

A Via proximity sensor	A	Via proximity sensor
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Function Double-acting HGWC-...-A



-N-

-T-

12,16,20 mm Opening angle 30° and 80°

Size



General technical data						
Size		12	16		20	
Design		Rack and pinion				
		Force-guided motion sequence				
Mode of operation		Double-acting				
Gripper function		Angle				
Number of gripper jaws		2				
Max. opening angle	[°]	30,80				
Pneumatic connection		M5				
Repetition accuracy ¹⁾	[mm]	≤ 0.05				
Max. interchangeability	[mm]	≤ 0.2				
Max. gripper jaw backlash ²⁾	[mm]	≤ 0.1				
Max. gripper jaw angular backlash ³⁾	[°]	≤ 0.5				
Max. operating frequency	[Hz]	≤ 4				
Rotational symmetry	[mm]	≤Ø0.2				
Position sensing		Via proximity sensor				
Type of mounting		Via female thread and centring sleeve				
Mounting position		Any				
Product weight	[g]	200	350		700	

1) End-position drift under constant operating conditions with 100 consecutive strokes in the direction of movement of the gripper jaws

Perpendicular to the direction of motion of the gripper jaws
 Pretensioned, backlash-free ball bearing guide

Operating and environmental conditions					
Operating pressure [bar]		2 8			
Operating medium		Filtered compressed air, lubricated or unlubricated			
Ambient temperature ¹⁾ [°C]		+5 +60			
Corrosion resistance class CRC ²⁾		2			

1) Note operating range of proximity sensors

2) Corrosion resistance class 2 according to Festo standard 940 070

Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Angle grippers HGWC Technical data



Angl	Angle gripper				
1	1 Gripper jaw Die-cast zinc, painted				
2	Housing	Die-cast zinc, painted			
3	Piston	Polyamide			
4	Distance sleeve	Polyurethane			
-	Seals	Polyurethane, nitrile rubber			
-	Note on materials	Free of copper, PTFE and silicone			
		RoHS-compliant			

Total gripping torque at 6 bar



Size	12	2	16	20
Opening [N	Ncm] 22	2	72	144
Closing [N	Vcm] 22	2	72	144

Static characteristic load values at the gripper jaws



The indicated permissible forces and torques apply to a single gripper jaw. The indicated values include the lever arm, additional applied loads caused by the workpiece or external gripper fingers, as well as forces which occur

during movement. The zero co-ordinate line (gripper jaw guide) must be taken into consideration for the calculation of torques.

Size		12	16	20
Max. permissible force Fz	[N]	40	60	80
Max. permissible torque M _x	[Nm]	2.5	4	8
Max. permissible torque My	[Nm]	0.6	1	1.9
Max. permissible torque M _z	[Nm]	2	3.2	6.7

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Mass moment of inertia



Mass moment of inertia [kgm²x10⁻⁴] of the angle gripper in relation to the central axis with no load.

Size		12	16	20
HGWCA	[kgm ² x10 ⁻⁴]	0.52	1.35	4.31

Opening and closing times [ms] at 6 bar



The indicated opening and closing times [ms] have been measured at room temperature and an operating pressure of 6 bar with vertically mounted gripper and without additional gripper fingers.

The grippers must be throttled for greater applied loads. Opening and closing times must then be adjusted accordingly.

Size	12-15	12-40	16-15	16-40	20-15	20-40	
Without external gripper fingers							
HGWCA	Opening	50	70	50	85	50	90
	Closing	35	50	35	70	35	75

Angle grippers HGWC Technical data

Gripping force $F_{\mbox{Grip}}$ per gripper jaw as a function of operating pressure and lever arm x

Gripping forces as a function of the operating pressure and the lever arm can be determined for the size using the following graph.









Angle grippers HGWC Technical data

Туре	B1	B2	B3	B4	B5	B6	D1	D2	D3	D4	D5
			+0.05	+0.25	+0.5	+0.1			+0.05	F10/b7	
	E 7	50	12	0.05	+0.5	11	12	M2	0.02 E	7	E 2
HGWC-12	70	63	12	2.5	4	11	12	M/	7	7	5.3
HGWC-20	86	79	20	38	6	14	12	M4 M5	9	9	6.4
		, ,							2	-	,
Type	D6	D7	D8	EE	H1	H2	H3	H4	H5	H6	H7
21							-		-		
					±0.5					±0.2	
HGWC-12	M4	4.8	2.6	M5	43.2	20.7	18.2	35.2	6.9	17	12.5
HGWC-16	M5	5.8	3.2	M5	54.2	26.2	21.2	44.7	8.2	21	15.7
HGWC-20	M6	8.1	4.4	M5	68.2	32.7	27	55.7	10.2	26.5	19.5
Туре	H8	H10	L1	L2	L3	L4 ¹⁾	L5	L6	L7 ¹⁾	T:	1
								+0.25			
			±0.2		±0.1			-0.05		mi	n.
HGWC-12	7.5	9.2	27.5	25.5	6	33	42	12	20	4.	5
HGWC-16	9	10.7	33	30	9	40	51	15	24	5	, ,
HGWC-20	12	13.7	45	38	12	50	65	21	33	5	5
Туре	T2	T3	T4	T5	T6	T7	T8	T9	W1	W2	W3
			+0.4	+0.1							
		±0.1	-0.3	-0.3	min.	+0.2		+0.1	±2	±3	
HGWC-12-15	22	17	3.1	13	6	17	0.5	13	15°	1º	90°
HGWC-12-40	2.2	1.7	5.1	1.9	0	1.7	0.5	1.9	40°	1	70
HGWC-16-15	2.7	1.8	3.8	1.2	7	3	0.3	1.6	15°	1°	90°
HGWC-16-40						-			40°	_	
HGWC-20-15	3.2	2.3	5.2	1.7	9	3.5	0.5	2.1	15°	1°	90°
HGWC-20-40					-				40°	-	

1) Tolerance for centring hole ±0.03 Tolerance for thread ±0.2

Ordering data			
	Size	Opening angle	Double-acting
		[°]	Part No. Type
	12	30	565135 HGWC-12-15-A
		80	565141 HGWC-12-40-A
	16	30	565137 HGWC-16-15-A
		80	565143 HGWC-16-40-A
	20	30	565139 HGWC-20-15-A
		80	565145 HGWC-20-40-A

Adapter kit HAPG	Material: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant	Note The kit includes the individual mounting interface as well as the
		necessary mounting material.
Permissible drive/grippe	er combinations with adapter kit	Download CAD Data 🗲 www.festo.com/us/cad

Complitation	Drive	Gripper			Adapter Kit			
	Size Size		Mounting option			Part No.	Туре	
DGSL/HGWC	DGSL	HGWC			DHAA, HA	PG		
	12, 16	12				529018	HAPG-58	
	20, 25	16			2	191267	HAPG-49	
	20,25	20	•			191269	HAPG-51	
SIT/HGWC	SIT	HGWC			DHAA HA	PG		
	10	12	-		Dinugina	542670	HAPG-100	
	16	12	-		-	529018	HAPG-58	
	16	16	-		-	542666	HAPG-101	
AND STATE OF THE STATE	20	16	-		2	191267	HAPG-49	
	20	20	-		-	542667	HAPG-102	
	25	20	-		1	191269	HAPG-51	
		1	-			1		
HMP/HGWC	HMP	HGWC			DHAA, HA	PG		
ll ll	16	16		-	2	191263	HAPG-45	
	20, 25	20		-	2	191264	HAPG-46	
DRQD/HGWC	.							
	DRQD	HGWC			DHAA, HA	PG		
	12,16	12			_	542671	HAPG-SD2-41	
	16, 20	16			2	542668	HAPG-SD2-42	
A A A A A A A A A A A A A A A A A A A	20	20			_	542669	HAPG-SD2-43	
	25	20		•		542758	HAPG-SD2-44	

1) Corrosion resistance class 2 according to Festo standard 940 070

Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Angle grippers HGWC

Adapter kit HAPG, HMSV Material: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant Permissible drive/gripper combinations with adapter kit Download CAD Data → www.festo.com/us/cad Combination Drive Gripper Adapter kit Size Size Mounting option CRC¹⁾ Part No. Î

HGWC

16

20

HSP/HGWC	HSP
·	16
	25

HSW/HGWC	HSW	HGWC			DHAA, HAP	G		
×.	12	16		-		191901	HAPG-55	
			_	-	2	540882	HAPG-71-B	
	16	16		_		191901	HAPG-55	
			-	-		540882	HAPG-71-B	
			•					
FCCA /UCNIC	ECCA	HCWC						

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LUSA/IIUWC	LUSA	IIGWC		DHAA, HAFG, HIVISV			
6/7	50	12				560017	HMSV-61
			-	-		529018	HAPG-58
a series of the	60	16	_			560018	HMSV-62
a state			-	-	2	191267	HAPG-49
	60	20	_		1	560018	HMSV-62
			-	-		191269	HAPG-51
ERMB/HGWC	ERMB	HGWC			DHAA, HAP	G	
	20	16				542668	HAPG-SD2-42
	20 20	16 20	•		2	542668 542669	HAPG-SD2-42 HAPG-SD2-43
	20 20 25	16 20 20	•		2	542668 542669 542758	HAPG-SD2-42 HAPG-SD2-43 HAPG-SD2-44

1) Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Туре

HAPG-55

HAPG-55

HAPG-71-B

HAPG-72-B

DHAA, HAPG

2

191901

540882

191901

540883

The kit includes the individual mounting interface as well as the necessary mounting material.

Ordering data	- Centring sleeves		Technical data 🗲 Intern	et: zbh			
	For size	Part No.	Туре	PU ¹⁾			
	[mm]						
<u>í</u>	For attachment to a drive or on a plate						
S	12,16	186717	ZBH-7	10			
	20	150927	ZBH-9	10			
	For attaching gripper fingers						
	12	189652	ZBH-5	10			
	16	186717	ZBH-7	10			
	20	150927	ZBH-9	10			

1) Packaging unit

Ordering data - Proximity sensors for C-slot, in-line connecting cable

	Assembly	Electrical connection		Cable length	Part No.	Туре	
		Cable	Plug M8	[m]			
A Contraction of the second se	N/O contact, magneto-resistive Technical data → Int						
a second	Insertable in slot	3-wire	-	2.5	551373	SMT-10M-PS-24V-E-2,5-L-OE	
-	from above	-	3-pin	0.3	551375	SMT-10M-PS-24V-E-0,3-L-M8D	
	N/O contact, magn	etic reed				Technical data 🗲 Internet: sme	
	Insertable in slot	3-wire	-	2.5	173210	SME-10-KL-LED-24	
	lengthwise	-	3-pin	0.3	173212	SME-10-SL-LED-24	

Ordering data – Proximity sensors for C-slot, lateral connecting cable

	Assembly	Electrical connection		Cable length	Part No.	Туре
		Cable	Plug M8	[m]		
N/O contact, magneto-resistive						Technical data 🗲 Internet: smt
5	Insertable in slot	3-wire	-	2.5	551374	SMT-10M-PS-24V-E-2,5-Q-OE
CT . B	from above	-	3-pin	0.3	551376	SMT-10M-PS-24V-E-0,3-Q-M8D
	N/O contact, magn	contact, magnetic reed				Technical data 🗲 Internet: sme
	Insertable in slot	3-wire	-	2.5	173211	SME-10-KQ-LED-24
	lengthwise	-	3-pin	0.3	173213	SME-10-SQ-LED-24

Ordering data	– Proximity sensor	rs for C-slot, short design				
	Assembly	Electrical connection		Cable length	Part No.	Туре
		Cable	Plug M8	[m]		
A	N/O contact, magn	neto-resistive	Technical data 🗲 Internet: smt			
ji	Insertable in slot	3-wire	-	2.5	547862	SMT-10G-PS-24V-E-2,5Q-OE
P	lengthwise	-	3-pin	0.3	547863	SMT-10G-PS-24V-E-0,3Q-M8D
B ^o						
1 al						

Ordering data	Drdering data – Connecting cables Technical data → Internet: nebu								
	Electrical connection, left	Electrical connection, right	Cable length	Part No.	Туре				
			[m]						
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3				
Contraction of the second seco			5	541334	NEBU-M8G3-K-5-LE3				
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3				
S			5	541341	NEBU-M8W3-K-5-LE3				

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Festo North America

Festo Regional Contact Center

5300 Explorer Drive Mississauga, Ontario L4W 5G4 Canada

USA Customers:

For ordering assistance, Call: 1.800.99.FESTO (1.800.993.3786) Fax: 1.800.96.FESTO (1.800.963.3786) Email: customer.service@us.festo.com For technical support, Call: 1.866.GO.FESTO (1.866.463.3786) Fax: 1.800.96.FESTO (1.800.963.3786)

Email: product.support@us.festo.com Canadian Customers:

 Call:
 1.877.GO.FESTO (1.877.463.3786)
 Fax:
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 Email:
 festo.canada@ca.festo.com
 Fax:
 festo.canada@ca.festo.com

USA Headquarters

Festo Corporation 395 Moreland Road P.O. Box 18023 Hauppauge, NY 11788, USA www.festo.com/us

USA Sales Offices

Appleton North 922 Tower View Drive, Suite N Greenville, WI 54942, USA

Boston 120 Presidential Way, Suite 330 Woburn, MA 01801, USA

Chicago 1441 East Business Center Drive Mt. Prospect, IL 60056, USA Dallas

1825 Lakeway Drive, Suite 600 Lewisville, TX 75057, USA

Detroit – Automotive Engineering Center 2601 Cambridge Court, Suite 320 Auburn Hills, MI 48326, USA

New York 395 Moreland Road Hauppauge, NY 11788, USA Silicon Valley

4935 Southfront Road, Suite F Livermore, CA 94550, USA

Central USA

Festo Corporation 1441 East Business Center Drive Mt. Prospect, IL 60056, USA Phone: 1.847.759.2600 Fax: 1.847.768.9480



United States



USA Headquarters, East: Festo Corp., 395 Moreland Road, Hauppauge, NY 11788 Phone: 1.631.435.0800; Fax: 1.631.435.8026; Email: info@festo-usa.com www.festo.com/us

Canada



Headquarters: Festo Inc., 5300 Explorer Drive, Mississauga, Ontario L4W 5G4 Phone: 1.905.624.9000; Fax: 1.905.624.9001; Email: festo.canada@ca.festo.com www.festo.ca

Mexico



Headquarters: Festo Pneumatic, S.A., Av. Ceylán 3, Col. Tequesquinahuac, 54020 Tlalnepantla, Edo. de México Phone: 011 52 [55] 53 21 66 00; Fax: 011 52 [55] 53 21 66 65; Email: Festo.mexico@mx.festo.com www.festo.com/mx

 Western USA

 Festo Corporation

 4935 Southfront Road,

 Suite F

 Livermore, CA 94550, USA

 Phone:
 1.925.371.1099

 Fax:
 1.925.245.1286

Festo Worldwide

Argentina Australia Austria Belarus Belgium Brazil Bulgaria Canada Chile China Colombia Croatia Czech Republic Denmark Estonia Finland France Germany Great Britain Greece Hong Kong Hungary India Indonesia Iran Ireland Israel Italy Japan Latvia Lithuania Malaysia Mexico Netherlands New Zealand Norway Peru Philippines Poland Romania Russia Serbia Singapore Slovakia Slovenia South Africa South Korea Spain Sweden Switzerland Taiwan Thailand Turkey Ukraine United States Venezuela

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