

Mini slides SLTE, electric

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Mini slides SLTE, electric

Key features

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Range of applications

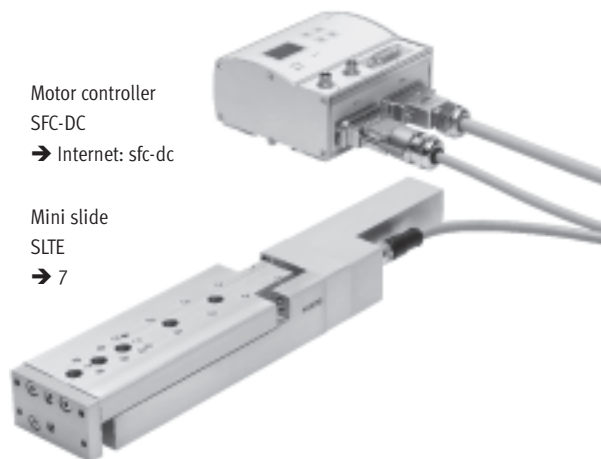
The electric mini slide SLTE is ideal for use in automation applications where controlled end-position cushioning (gentle stopping), constant travel speed and positioning capability are important factors.

The SLTE has the same interfaces on the yoke, slide and underneath the housing as the pneumatic SLT. It is also fully compatible with the modular handling and assembly system and SLT adapter kits.

Special features

- Precise and rigid guide
- Freely positionable
- Fast positioning times
- Through-holes from above and below
- Sensors can be integrated
- Gentle starting and stopping
- Working loads up to 4 kg
- Constant travel speeds of 2 ... 200 mm/s

Everything from a single source



The mini slide SLTE and motor controller SFC form one unit.

- Thanks to the protection class IP54, the SFC can be mounted close to the SLTE, either:
 - with centre supports
 - on an H-rail
- Only one cable required between SLTE and SFC
- Motor controller SFC available with or without control panel
- Easy control with
 - I/O interface
 - Profibus
 - CANopen
 - DeviceNet

Parameterisation possible via

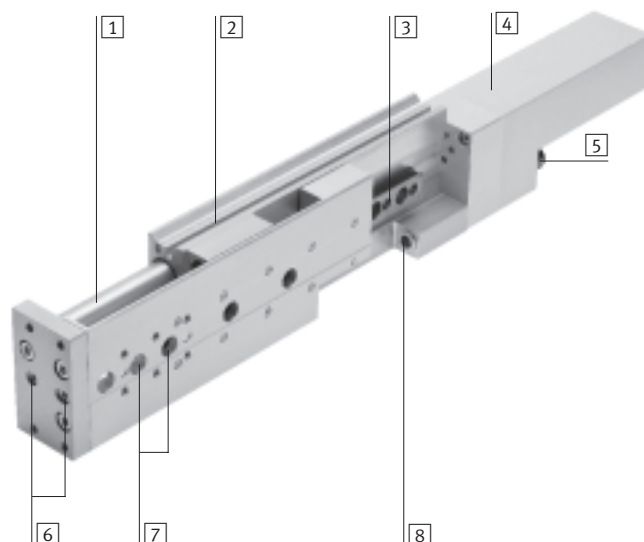
- Control panel:
 - Suitable for simple position sequences
- Configuration package FCT (Festo configuration tool):
 - Parameterisation via RS 232 interface
 - Windows-based PC user interface (Festo configuration tool)



CANopen

DeviceNet

The technology in detail



- 1 Drive rod
- 2 Slot for reference switch
- 3 Roller bearing guide
- 4 Drive assembly consisting of DC motor with displacement encoder
- 5 Electrical connection
- 6 Threaded holes and through-holes with centring hole for attaching the working load
- 7 Threaded holes and through-holes with centring hole for attaching the SLTE
- 8 Fixed stop with integrated rubber buffer

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Key features

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Comparison between electric mini slide SLTE and pneumatic mini slide SLT

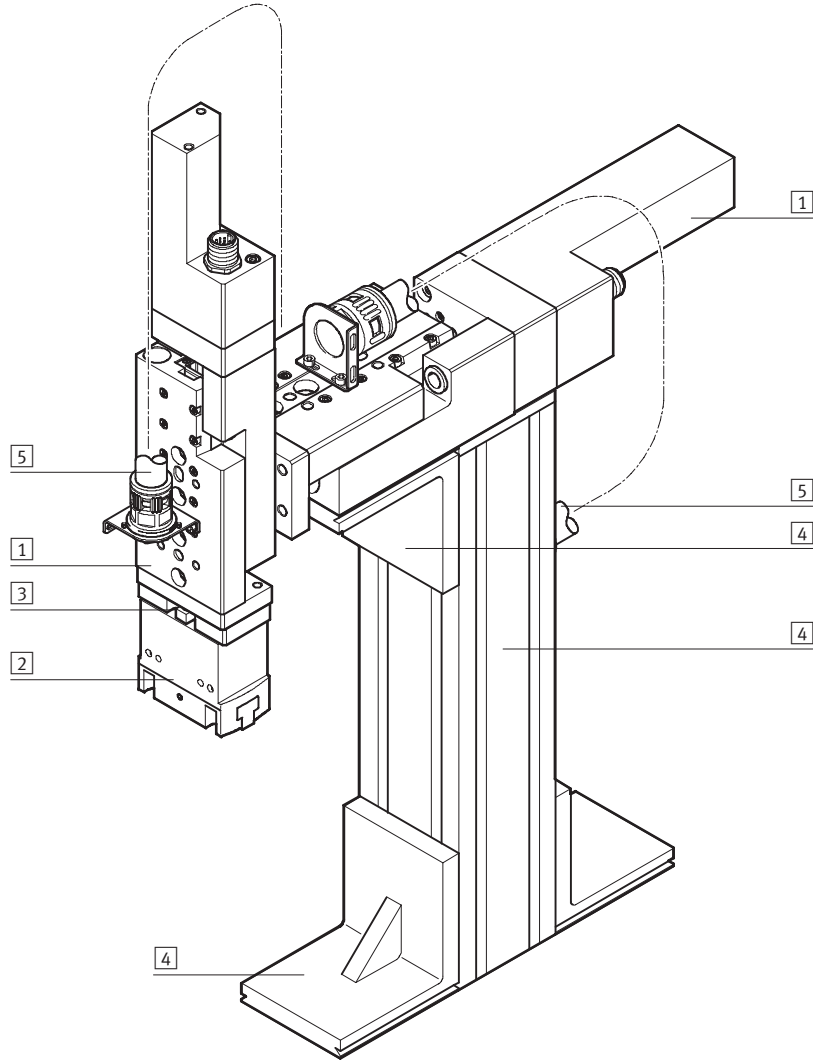
	Electrical: SLTE	Pneumatic: SLT												
Advantages														
	- Gentle starting and stopping - Constant and precise speed (2 ... 200 mm/s) - Flexible positioning without mechanical devices - Programmable drive profile	- High feed force - High speed - Fast positioning time - Compact length												
Guide														
- Preloaded, backlash-free, precise and rigid ball bearing cage guide - High torque and load absorption	Guide rail for slide Ball bearing Guide rail on drive body													
Dimensions														
Identical width and height dimensions <table><tr><td>Type</td><td>Width (W)</td><td>x</td><td>Height (H)</td></tr><tr><td>SLT(E)-10</td><td>50</td><td>x</td><td>30 mm</td></tr><tr><td>SLT(E)-16</td><td>66</td><td>x</td><td>40 mm</td></tr></table>	Type	Width (W)	x	Height (H)	SLT(E)-10	50	x	30 mm	SLT(E)-16	66	x	40 mm		
Type	Width (W)	x	Height (H)											
SLT(E)-10	50	x	30 mm											
SLT(E)-16	66	x	40 mm											
Interfaces														
Identical mounting and attachment options 1 Attachment surfaces: Direct mounting using threaded holes and through-holes 2 Mounting surfaces: Direct mounting of loads and devices (e.g. SLT: semi-rotary drives and grippers) via threaded holes in the slide and the yoke plate														
Technical data														
Piston Ø	[mm]	10, 16	6 ... 25											
Stroke	[mm]	50 ... 150	10 ... 200											
Max. speed	[m/s]	0.2	0.8											
Repetition accuracy at end positions	[mm]	±0.1	±0.02											
Intermediate positions		Any	None											

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System product for handling and assembly technology



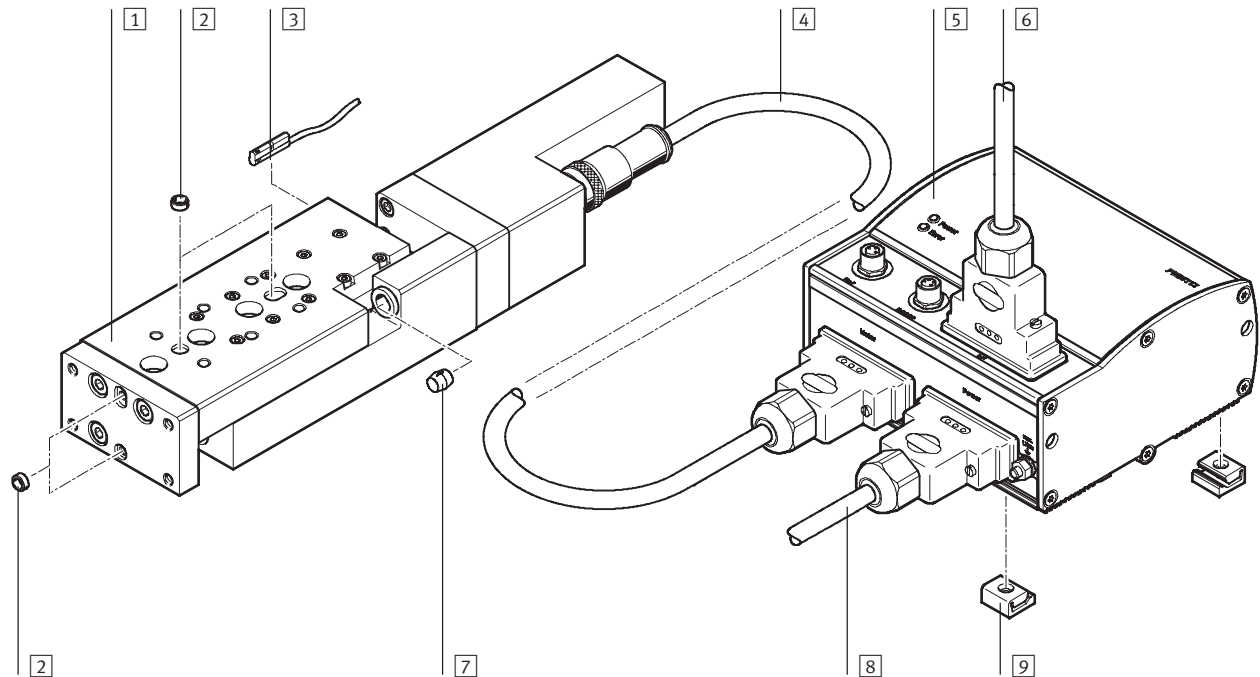
System elements and accessories		
	Brief description	→ Page/Internet
1 Axes	Wide range of combinations possible within handling and assembly technology	axes
2 Grippers	Wide range of variations possible within handling and assembly technology	gripper
3 Adapters	For drive/drive and drive/gripper combinations	adapter kit
4 Basic mounting components	Profiles and profile connectors as well as profile/drive connectors	basic component
5 Installation components	For manageable and secure guidance of electrical cables and tubing	installation component
– Drive units	Wide range of combinations possible within handling and assembly technology	drive

Mini slides SLTE, electric

Peripherals overview

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Size 10/16



Accessories		Brief description	→ Page/Internet
1	Mini slide SLTE	Electromechanical linear axis with lead screw spindle	7
2	Centring pin/sleeve ZBS/ZBH	– For centring loads and attachment components – Centring sleeves included in scope of delivery	15
3	Proximity sensor SME/SMT-10	For referencing mini slide or for sensing slide position	15
4	Motor cable KMTR	Connecting cable between motor and motor controller	kmtr
5	Motor controller SFC	For parameterising and positioning mini slide	sfc-dc
6	Control cable KES	For I/O connection to any controller	kes
6	Plug FBS, FBA	For fieldbus interface	plug
7	Buffer	Buffer included in scope of delivery	–
8	Supply cable KPWR	Power supply cable; load and logic power supplies are isolated	kpwr
9	Centre supports MUP	– For mounting motor controller – Motor controller can also be mounted on H-rail	mup

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Type codes

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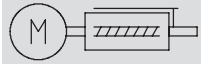
		SLTE	–	16	–	80	–	LS	–	G04
Type										
SLTE	Mini slide									
Size										
Stroke [mm]										
Drive spindle/pitch										
LS	Lead screw									
Gearing type										
G04	Gear unit ratio $i = 4.4$									

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Technical data

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Function



- - Size
10 and 16
- - Stroke length
50 ... 150 mm



General technical data			
Size		10	16
Constructional design		Electromechanical linear axis with lead screw	
Guide		With ball bearings	
Type of mounting		Via through-holes	
		Via female thread	
		Via female thread and centring sleeve	
Stroke		[mm] 50, 80	50, 80, 100, 150
Stroke reserve per end position	with rubber buffer at both ends	[mm] 0.5	0.6
	with rubber buffer at one end	[mm] 1.2	1.25
Assembly position		Any	
Lead screw pitch		[mm] 5	7.5
Min. travel speed		[mm/s] 2	
Max. acceleration		[m/s ²] 2.5	
Repetition accuracy		[mm] ±0.1	
Reversing backlash		[mm] < 0.1	

Electrical data for motor			
Size		10	16
System resolution of encoder		512 (pulses per rotation)	1,000 (pulses per rotation)
Nominal operating voltage		[V DC] 24	
Output		[W] 4.5	18

Operating and environmental conditions			
Size		10	16
Ambient temperature		[°C] 0 ... +40	
Protection class		IP40	
Fast transients		To EN61000-4-4	
Max. noise level ¹⁾		[dB A] < 50	< 55
CE symbol (declaration of conformity)		In accordance with EU EMC directive	

1) At maximum permissible speed

Weight [g]						
Size		10		16		
Stroke		50	80	50	80	100 150
Product weight		574	737	1,185	1,465	1,714 2,196
Moving load		163	235	296	415	519 729

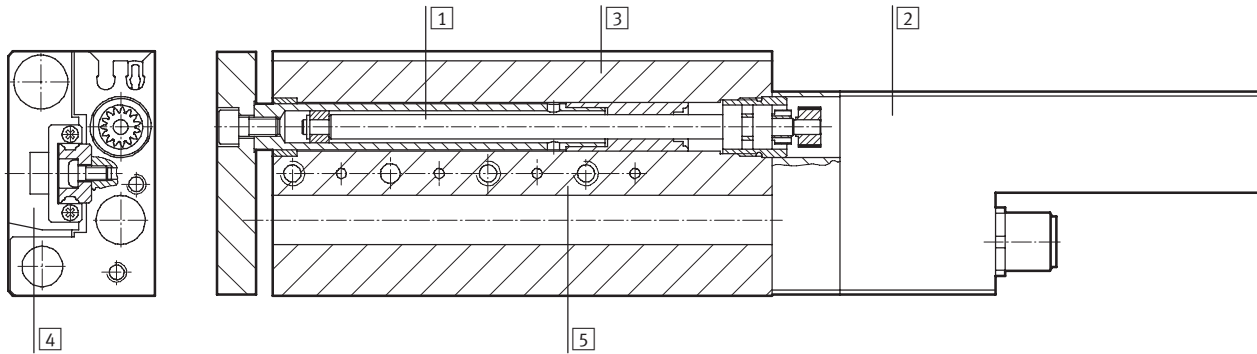
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Technical data

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Materials

Sectional view



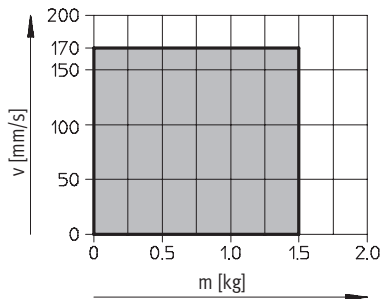
Mini slide

1	Lead screw	High-alloy steel
2	Motor housing	Wrought aluminium alloy, anodised
3	Housing	Wrought aluminium alloy, anodised
4	Slide	Wrought aluminium alloy, anodised
5	Guide	Tempered steel
-	Seals	Thermoplastic rubber, nitrile rubber

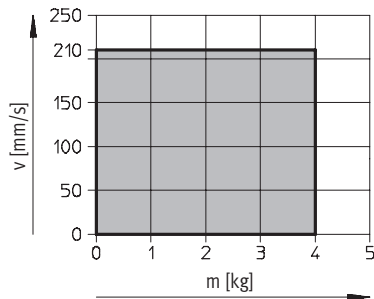
Travel speed v as a function of applied load m

Horizontal mounting position

SLTE-10

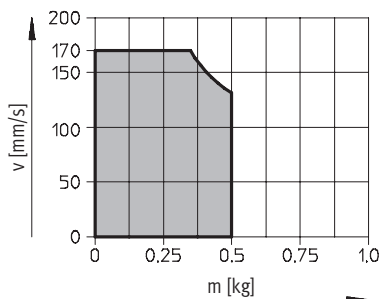


SLTE-16

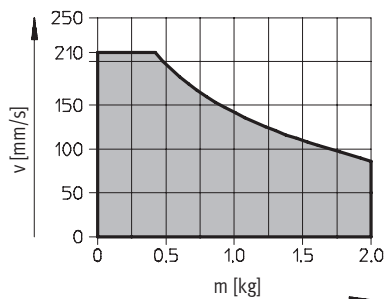


Vertical mounting position

SLTE-10



SLTE-16



Permissible operating range

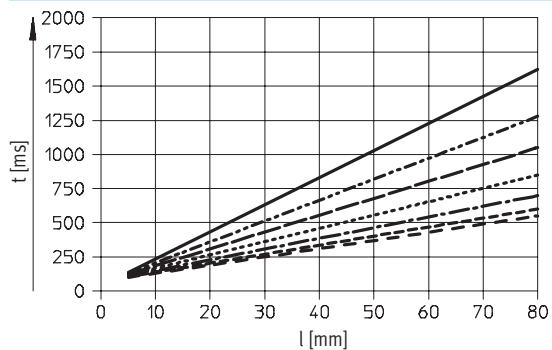
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Technical data

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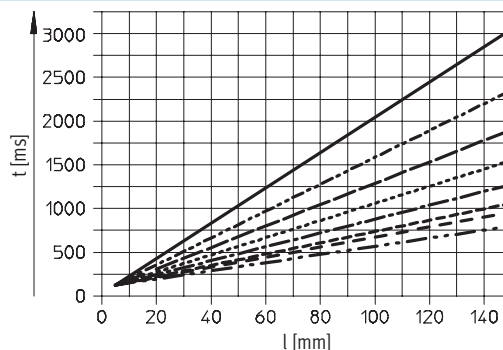
Positioning time t as a function of stroke l

SLTE-10



$v = 50 \text{ mm/s}$
 $v = 65 \text{ mm/s}$
 $v = 80 \text{ mm/s}$
 $v = 100 \text{ mm/s}$
 $v = 125 \text{ mm/s}$
 $v = 150 \text{ mm/s}$
 $v = 170 \text{ mm/s}$

SLTE-16

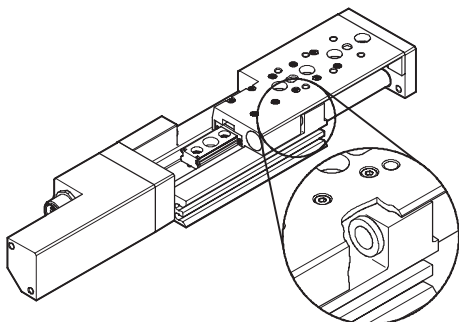


$v = 50 \text{ mm/s}$
 $v = 65 \text{ mm/s}$
 $v = 80 \text{ mm/s}$
 $v = 100 \text{ mm/s}$
 $v = 125 \text{ mm/s}$
 $v = 150 \text{ mm/s}$
 $v = 170 \text{ mm/s}$
 $v = 210 \text{ mm/s}$

Reference travel

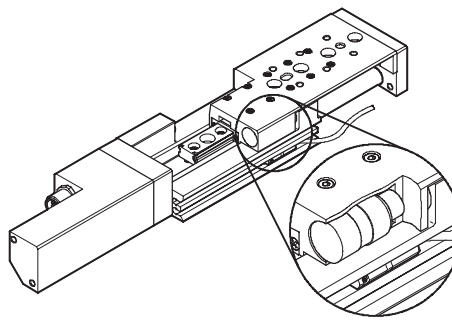
to fixed stop

- Positive fixed stop
 - To front stop bush (extended)
- Negative fixed stop
 - To rear stop bush (retracted)



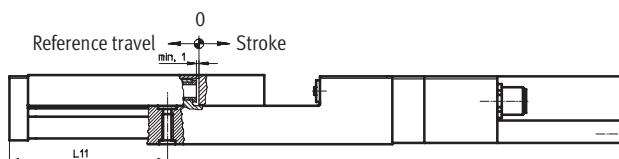
to proximity sensor

- Position freely selectable

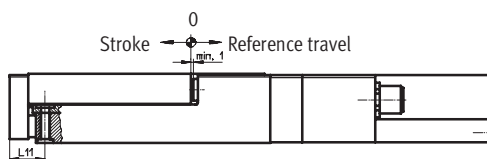


The following applies for reference travel to a fixed stop:

Positive fixed stop



Negative fixed stop



Size	Stroke	L11	
		Positive fixed stop	Negative fixed stop
10	50	67.4 ^{+1.1}	15.6 ^{-1.1}
	80	97.0 ^{+1.1}	15.2 ^{-1.1}
16	50	74.9 ^{+1.1}	23.1 ^{-1.1}
	80	104.1 ^{+1.1}	22.3 ^{-1.1}
	100	124.6 ^{+1.1}	22.8 ^{-1.1}
	150	173.3 ^{+1.1}	21.5 ^{-1.1}

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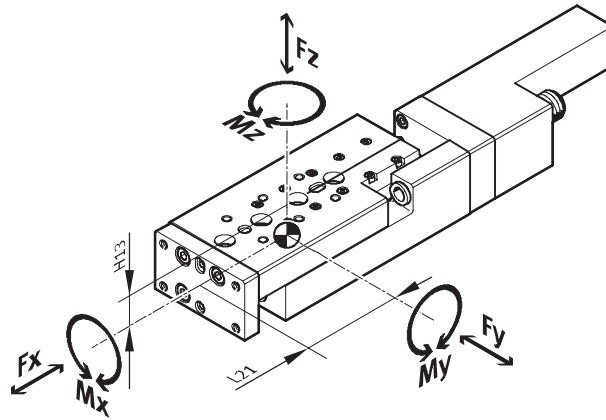
Technical data

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Dynamic characteristic load values

Torques are indicated with reference to the centre of the guide.

They must not be exceeded in the dynamic range. Special attention must be paid to the cushioning phase.



If the drive is subjected to more than two of the indicated forces and torques simultaneously, the following equation must be satisfied in addition to the indicated maximum loads:

$$\frac{|F_{y1}|}{F_{y\max.}} + \frac{|F_{z1}|}{F_{z\max.}} + \frac{|M_{x1}|}{M_{x\max.}} + \frac{|M_{y1}|}{M_{y\max.}} + \frac{|M_{z1}|}{M_{z\max.}} \leq 1$$

Position of the guide centre



+ plus stroke length

Permissible forces and torques						Geometric characteristics	
Size	Stroke	F _y max [N]	F _z max [N]	M _x max, M _y max [Nm]	M _z max [Nm]	H13 [mm]	L21 [mm]
10							
	50	390	390	3.1	1.4	13	33.5
	80	410	410	4.3	1.5		41
16							
	50	510	510	4.6	2.8	16	35
	80	520	520	6.0	2.8		41.5
	100	600	600	9.1	3.2		51.5
	150	660	960	12.6	3.5		66.5

-  - Note

Sizing software
PositioningDrives
→ www.festo.com

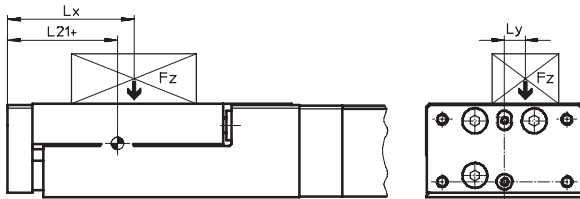
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Calculation example

Given:



Mini slide = SLTE-10
 Stroke length = 80 mm
 Lever arm L_x = 50 mm
 Lever arm L_y = 30 mm
 Weight F_z = 0.8 kg
 Acceleration a = 0 m/s²

To be found:

F_y , F_z , M_x , M_y , M_z
 and verification of function with
 combined load

Solution:

$L_{21} = 41$ mm from table

$F_y = 0$ N

$F_z = m \times g$
 $= 0.8 \text{ kg} \times 9.81 \text{ m/s}^2 = 7.848 \text{ N}$

$M_x = m \times g \times L_y$
 $= 0.8 \text{ kg} \times 9.81 \text{ m/s}^2 \times 30 \text{ mm} = 0.236 \text{ Nm}$

$M_y = m \times g \times [(L_{21} + \text{stroke}) - L_x]$
 $= 0.8 \text{ kg} \times 9.81 \text{ m/s}^2 [(41 \text{ mm} + 80 \text{ mm}) - 50 \text{ mm}] = 0.557 \text{ Nm}$

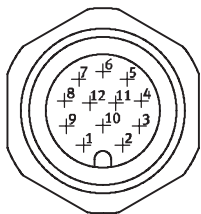
$M_z = 0$ Nm

Combined load:

$$\frac{|F_y|}{F_{y_{\max}}} + \frac{|F_z|}{F_{z_{\max}}} + \frac{|M_x|}{M_{x_{\max}}} + \frac{|M_y|}{M_{y_{\max}}} + \frac{|M_z|}{M_{z_{\max}}}$$

$$= 0 + \frac{7.848 \text{ N}}{410 \text{ N}} + \frac{0.2366 \text{ Nm}}{4.3 \text{ Nm}} + \frac{0.557 \text{ Nm}}{1.5 \text{ Nm}} + 0 = 0.445 \leq 1$$

Pin allocation of connection plug



Plug M12		
Pin	Connection	Function
1	Motor +	Motor conductor
2	Motor -	Motor conductor
3	A	Encoder signal RS 485
4	A/	Encoder signal RS 485
5	B	Encoder signal RS 485
6	B/	Encoder signal RS 485
7	I	Encoder signal RS 485
8	I/	Encoder signal RS 485
9	+5 V DC	Signal supply
10	0 V	Signal ground
11	-	-
12	-	-

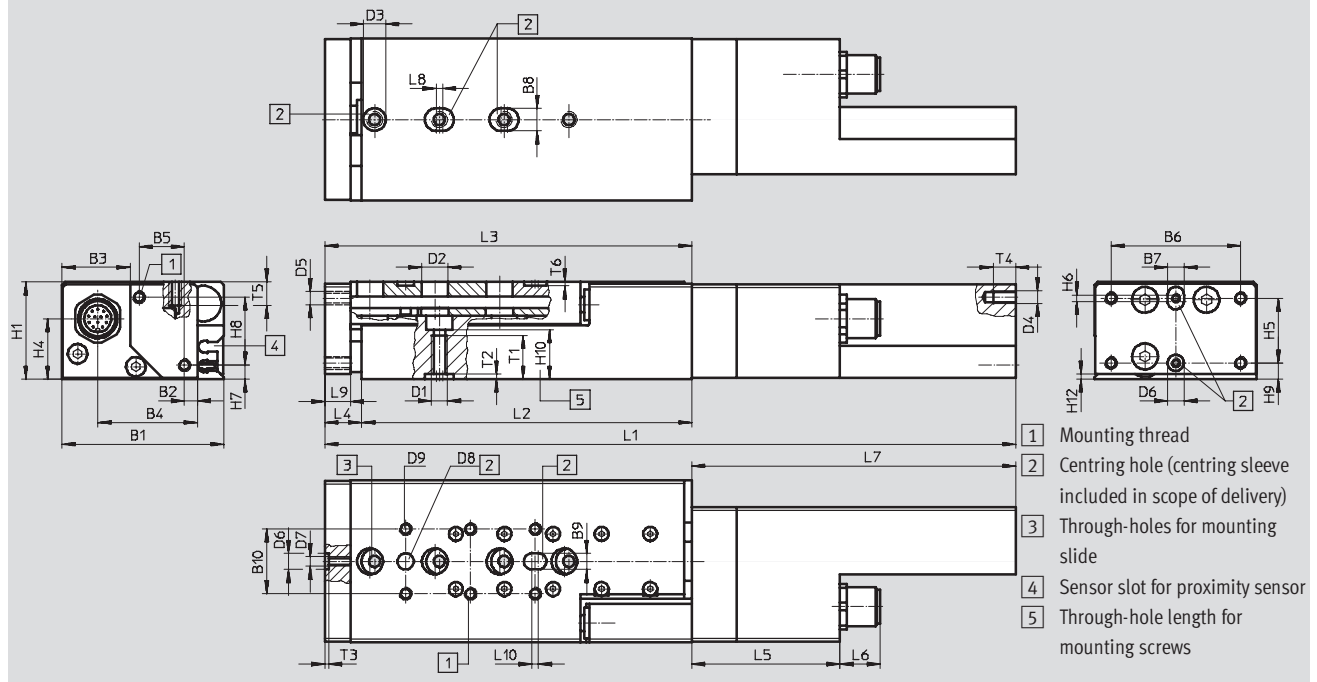
Mini slides SLTE, electric

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Dimensions

Download CAD data → www.festo.com



Size	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	D1	D2	D3	D4
		±0.3	±0.3				H7	H7	H7			Ø	Ø	
10	50	30.8	20.8	4	14	40	5	5	5	20	M5	8	7	M4
16	66	45.7	24.3	4.2	25	55	7	9	5	20	M6	10	9	M4

Size	D5	D6	D7	D8	D9	H1	H4	H5	H6	H7	H8	H9	H10	H12
		Ø		Ø										
10	M4	5	M3	5	M4	30	18.4	20	2	4	21	5	15	1.5
16	M5	7	M4	5	M5	40	25.8	20	2	4.5	30	13	20	1.5

Size	Stroke [mm]	L1 ±1.5		L2	L3 ±1		L4 ±1	
		1)	2)		1)	2)	1)	2)
10	50	212	213	102	112	113	10	11.1
	80	262	263	152	162	163	9.6	10.7
16	50	262.5	263.5	100	112.5	113.5	12.5	13.5
	80	307.5	308.5	146	158	159	11.7	12.7
	100	349	350	187	199.5	200.5	12.2	13.2
	150	430.5	431.5	270	281	282	11	12

Size	L5	L6	L7	L8	L9	L10	T1	T2	T3	T4	T5	T6
	±0.5											
10	45.8	12.5	100	2	8	2	12	1.5	1.2	7	8	1.2
16	56.3	12.5	149.7	2	10	1	16	2.1	1.5	7	7	1.2

- 1) End position at fixed stop
2) End position at rubber buffer

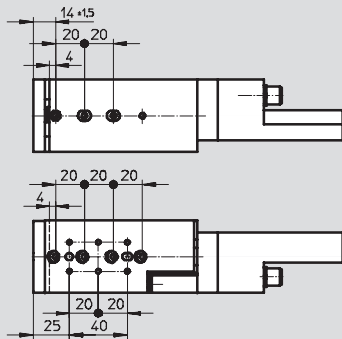
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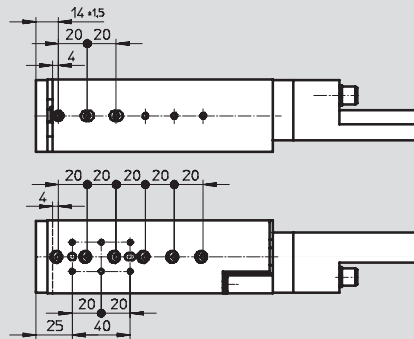
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Hole pattern for mounting thread and centring holes

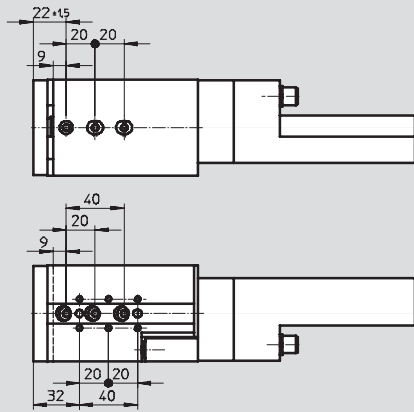
SLTE-10-50



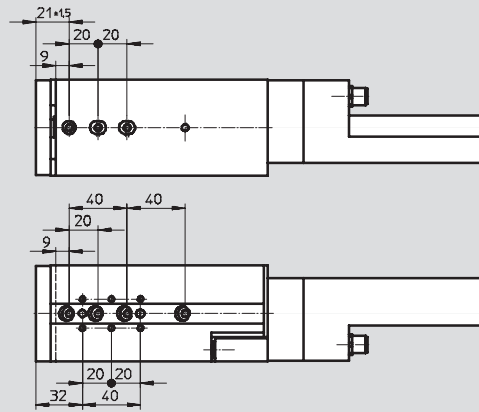
SLTE-10-80



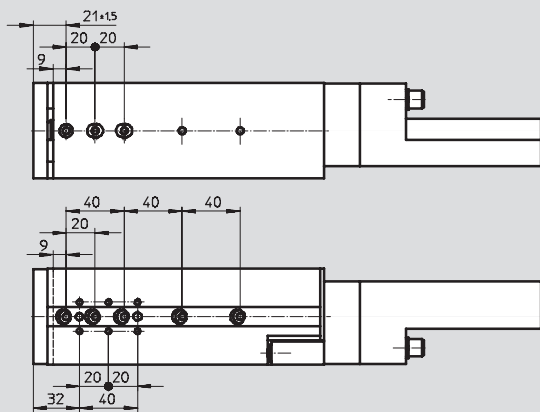
SLTE-16-50



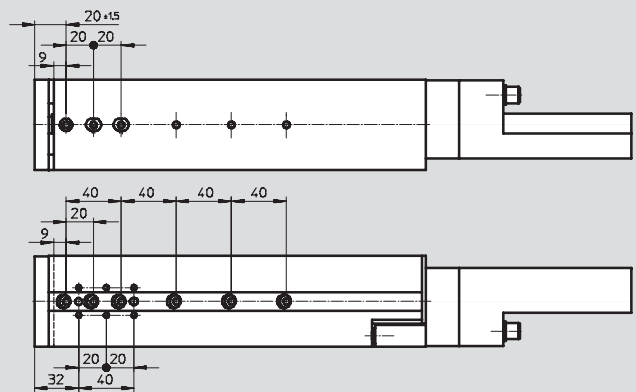
SLTE-16-80



SLTE-16-100



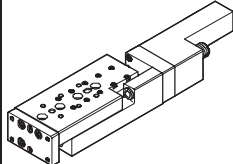
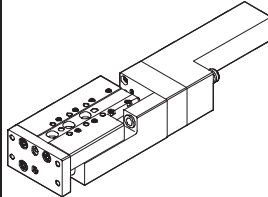
SLTE-16-150



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Ordering data			
Size	Brief description	Part No.	Type
10			
	Mini slide	537 447	SLTE-10-50-LS-G04
		537 449	SLTE-10-80-LS-G04
16			
	Mini slide	537 459	SLTE-16-50-LS-G04
		537 461	SLTE-16-80-LS-G04
		537 463	SLTE-16-100-LS-G04
		537 465	SLTE-16-150-LS-G04

Mini slides SLTE, electric

Accessories

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Ordering data – Centring sleeves ¹⁾				Technical data → Internet: zbh	
Size		10		16	
		Part No.	Type	Part No.	Type
	Housing	186 717	ZBH-7	150 927	ZBH-9
	Slide	189 652	ZBH-5	189 652	ZBH-5
	Yoke	189 652	ZBH-5	186 717	ZBH-7

1) Scope of delivery: 10 per pack

Ordering data – Proximity sensors for C-slot, magneto-resistive					Technical data → Internet: smt	
	Type of mounting	Switch output	Electrical connection, connection direction	Cable length [m]	Part No.	Type
N/O contact						
	Insertable in the slot from above, flush with cylinder profile	PNP	Cable, 3-wire, in-line	2.5	525 915	SMT-10F-PS-24V-K2,5L-OE
			Plug M8x1, 3-pin, in-line	0.3	525 916	SMT-10F-PS-24V-K0,3L-M8D
			Plug M8x1, 3-pin, lateral	0.3	526 675	SMT-10F-PS-24V-K0,3Q-M8D
	Insertable in the slot lengthwise	PNP	Plug M8x1, 3-pin, in-line	0.3	173 220	SMT-10-PS-SL-LED-24
			Cable, 3-wire, in-line	2.5	173 218	SMT-10-PS-KL-LED-24

Ordering data – Proximity sensors for C-slot, magnetic reed					Technical data → Internet: sme	
	Type of mounting	Switch output	Electrical connection, connection direction	Cable length [m]	Part No.	Type
N/O contact						
	Insertable in the slot from above, flush with cylinder profile	Contacting	Plug M8x1, 3-pin, in-line	0.3	525 914	SME-10F-DS-24V-K0,3L-M8D
			Cable, 3-wire, in-line	2.5	525 913	SME-10F-DS-24V-K2,5L-OE
			Cable, 2-wire, in-line	2.5	526 672	SME-10F-ZS-24V-K2,5L-OE
	Insertable in the slot lengthwise	Contacting	Plug M8x1, 3-pin, in-line	0.3	173 212	SME-10-SL-LED-24
			Cable, 3-wire, in-line	2.5	173 210	SME-10-KL-LED-24

Ordering data – Connecting cables				Technical data → Internet: nebu	
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 333	NEBU-M8G3-K-2.5-LE3
			5	541 334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 338	NEBU-M8W3-K-2.5-LE3
			5	541 341	NEBU-M8W3-K-5-LE3