Standard cylinders DNCI, with measuring transducer DADE

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Measuring transducer DADE

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Components for positioning and measuring using the standard cylinder DNCI





Measuring transducer





PLC controller e.g. FEC-...

→ Internet: fec



Display and control unit

e.g. FED-...

→ Internet: fed



with end-position controller SPC11 or axis controller SPC200

Proportional directional control valve

MPYE-...

→ Internet: mpye



Soft Stop

→ Internet: soft stop

Closed loop end-position controller

SPC11-INC



Positioning technology

→Internet:: spc

Axis interface SPC-AIF-INC



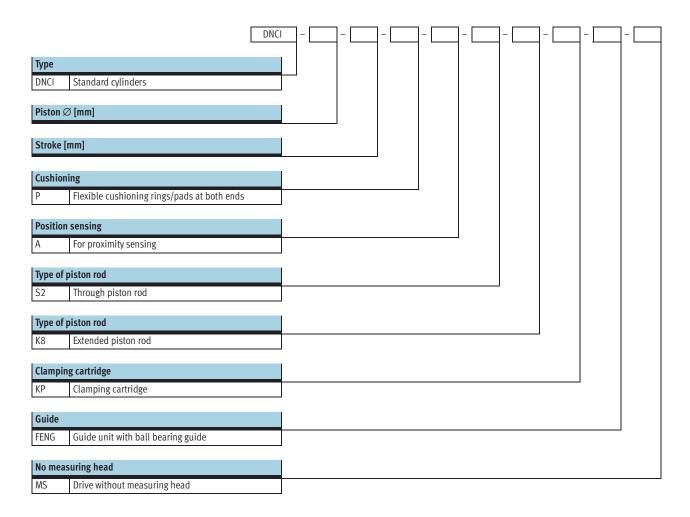
Axis controller SPC200



Standard cylinders DNCI, with measuring transducer DADE Type code

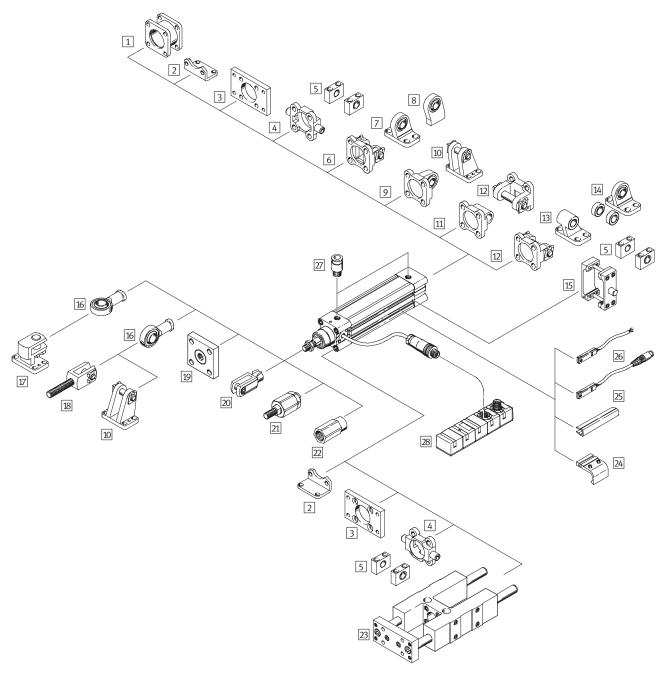


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Standard cylinders DNCI, with measuring transducer DADE Peripherals overview





Acce	Accessories									
	Туре	Brief description	→ Page/Internet							
1	Adapter kit ¹⁾ DPNC	For connecting two cylinders with identical piston \varnothing to form a multi-position cylinder	dpnc							
2	Foot mounting HNC	For mounting the drive on the bearing and end cap	hnc							
3	Flange mounting FNC	For mounting the drive on the bearing and end cap	fnc							
4	Trunnion mounting ZNCF/CRZNG	For swivelling movements of the drive on the bearing or end caps	pivot pin							
5	Trunnion support LNZG/CRLNZG	-	lnzg							

Standard cylinders DNCI, with measuring transducer DADE Peripherals overview



Acce	Cessories Prior description						
	Туре	Brief description	→ Page/Internet				
6	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap	snc				
	SNC						
7	Clevis foot mounting ¹⁾	With spherical bearing	lsng				
	LSNG						
8	Clevis foot mounting ¹⁾	Weld-on, with spherical bearing	lsnsg				
	LSNSG						
9	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap, with spherical bearing	sncs				
_	SNCS						
10	Clevis foot mounting ¹⁾	_	lbg				
	LBG						
11	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap	sncl				
	SNCL	Total streeting movements of the title of the cap	Silet				
12	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap	sncb				
12]	SNCB	To swiveling movements of the arrive of the end cap	31100				
13	Clevis foot mounting ¹⁾		lng				
D	LNG/CRLNG		ling				
47	Clevis foot mounting ¹⁾	With only original housing	lan				
14	LSN	With spherical bearing	lsn				
1		F 1 11 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1					
15	Trunnion mounting kit	For swivelling movements of the drive	zmcm				
	ZNCM						
16	Rod eye	With spherical bearing	sgs				
	SGS/CRSGS						
17	Right-angle clevis foot	-	lqg				
	LQG						
18	Rod clevis	With male thread	sga				
	SGA						
19	Coupling piece	For compensating radial deviations	ksg				
	KSG						
	Coupling piece	For cylinders with a non-rotating piston rod to compensate for radial deviations	ksz				
	KSZ						
20	Rod clevis	Permits a swivelling movement of the cylinder in one plane	sg				
	SG/CRSG						
21	Self-aligning rod coupler	For compensating radial and angular deviations	fk				
	FK						
22	Adapter	For a vacuum suction cup	ad				
_	AD	· ·					
23	Guide unit	For protecting standard cylinders from torsion at high torque loads	feng				
	FENG						
24	Mounting kit	For mounting proximity sensors SME/SMT-8 in combination with guide unit FENG	smb-8				
- 4	SMB-8-FENG		2				
25	Slot cover	To protect the sensor cable and keep dirt out of the sensor slots	abp				
ارے	ABP-5-S	To proceed the sensor custe and keep and out of the sensor stors	app				
26	Proximity sensor	Can be integrated in the cylinder profile barrel	proximity sensor				
20	SME/SMT-8	Can be integrated in the cylinder profite barret	proximity sensor				
27		For compositing company of air to bing with the conduction of the	autaleat-				
27	Push-in fitting	For connecting compressed air tubing with standard external diameters	quick star				
20	QS	Construction of the standard alice Buckley and the standard alice Buckley	14.6				
28	Measuring transducer	Converts sensor signals of the standard cylinder DNCI into one voltage signal of 0 10 V and/or	16				
	DADE-MVC	current signal of 0 20 mA					

Not with variants S2
 Guide unit FENG-KF must be attached to the piston rod such that backlash is eliminated

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Function







32 ... 63 mm



Stroke length 10 ... 2,000 mm



General technical data								
Piston ∅	32	40	50	63				
Constructional design		Piston						
		Piston rod						
		Profile barrel						
Mode of operation		Double-acting						
Cushioning		Flexible cushio	oning rings/pads at both	ends				
Position sensing		Integrated dis	Integrated displacement encoder					
		For proximity s	For proximity sensing ¹⁾					
Measuring principle (displacement enc	oder)	Digital						
Type of mounting		Foot mounting	Foot mounting					
Stroke	[mm]	10 2,000	10 2,000					
Torsion protection/Guide ³⁾		Guide rod with	Guide rod with yoke, with ball bearing guide					
Stroke	[mm]	100 500						
Piston rod extension	[mm]	1 500						
Pneumatic connection	G1/8	G1/4	G1/4	G3/8				
Electrical connection		Cable with 8-p	Cable with 8-pin plug, round type M12					
Cable length	1.5	1.5						

- Not included in the scope of delivery, can be ordered as an option
 Guide unit FENG-KF must be ordered as an option and will be supplied attached, the max. stroke is reduced

Forces [N] and impact energy [Nm]												
Piston \varnothing	32	40	50	63								
Theoretical force at 6 bar		483	754	1,178	1,870							
advancing	S2	415	633	990	1,682							
Theoretical force at 6 bar		415	633	990	1,682							
retracting	S2	415	633	990	1,682							
Impact energy at end positions		0.1	0.2	0.2	0.5							

Permissible impact velocity:

$$v_{\text{perm.}} = \sqrt{\frac{2 \times E_{\text{perm.}}}{m_{\text{dead}} + m_{\text{load}}}}$$

Permissible impact velocity v_{perm}. Max. impact energy E_{perm}. $\mathsf{m}_{\mathsf{dead}}$ Moving load (drive)

Moving work load



Note

These specifications represent the maximum values which can be reached. Note the maximum permitted impact energy.

Maximum permissible load:

$$m_{load} = \frac{2 \times E_{perm.}}{v^2} - m_{dead}$$



Operating and environmental conditions								
Operating pressure	[bar]	0.6 12						
Operating medium ²⁾		Compressed air, filtered and unlubricated, filter unit 5 µm						
Ambient temperature ³⁾	[°C]	-20 +80						
Vibration resistance		To DIN/IEC 68 Parts 2 – 6, severity level 2						
Continuous shock resistance		To DIN/IEC 68 Parts 2 – 82, severity level 2						
CE symbol (declaration of conformance)		In accordance with EU EMC Directive						
Protection class (displacement encoder)		IP65 to IEC 60 529						
Corrosion resistance class CRC ⁴⁾		1						

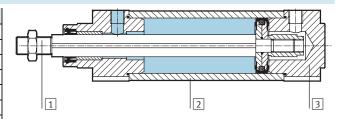
- The proportional directional control valve MPYE used requires the characteristic values
 Note operating range of proximity sensors
 Corrosion resistance class 1 according to Festo standard 940 070 Components requiring low corrosion resistance. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.

Piston Ø		32	40	50	63
		52	70	30	0,5
Basic drive DNCI					
	Product weight with 0 mm stroke	521	853	1,319	1,914
	Additional weight per 10 mm stroke	30	44	62	71
	Moving load with 0 mm stroke	95	175	316	383
	Additional weight per 10 mm stroke	8	14	23	23
<u> </u>					
Drive with through	piston rod DNCIS2				
	Product weight with 0 mm stroke	586	981	1,553	2,165
	Additional weight per 10 mm stroke	39	60	87	96
	Maring land with 0 mm strake	1.55	1//	207	264
,	Moving load with 0 mm stroke	155	164	297	364
	Additional weight per 10 mm stroke	17	30	48	48
Additional weight	with extended piston rod K8				
	Additional weight per 10 mm stroke	8	14	23	23
Additional weight	with clamping cartridge KP	-			
	Product weight	234	394	700	1,147
Additional waith	with avide weit FFNC				
Additional weight	with guide unit FENG	T	Ta a a a	T	T
	Product weight with 0 mm stroke	1,530	2,370	4,030	5,410
	Additional weight per 10 mm stroke	18	32	50	62

Materials

Sectional view

Stan	dard cylinders	
1	Piston rod	High-alloy steel
2	Cylinder barrel	Anodised aluminium
3	Bearing/end caps	Die-cast aluminium
-	Dynamic seals	Polyurethane TPE-U
-	Static seals	Nitrile rubber
-	Lubricant	Klüberplex BE31-102
Disp	lacement encoder	
-	Sensor housing	Polyacetate
-	Cable sheath	Polyurethane
-	Plug housing	Polybuteneterephthalate
-	Wall mounting plate	Polyacetate
-	Screws for mounting plate	Steel





Electrical data, displacement encoder	lectrical data, displacement encoder							
Linearity error ¹⁾	[mm]	±(0.07±0.02xL)						
Max. speed of travel	[m/s]	1.5						
Ambient temperature	[°C]	-20 +80						
Max. temperature coefficient	[ppm/°K]	30						
Protection class		IP65						
CE symbol (declaration of conformance)		In accordance with EU EMC Directive						
Max. permitted magnetic disruption field at	[kA/m]	10						
100 mm interval from the sensor ²⁾								
Electrical connection		Cable with 8-pin plug, round type M12						
Cable length	[m]	1.5						

¹⁾ Maximum deviation of the output signal from "best fit" line (characteristic curve with nominal gradient). L = Length of measuring system in meters
2) See also mounting conditions

Standard cylinders DNCI, with measuring transducer DADE

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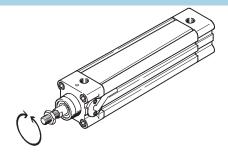
Technical data

Torques and lateral forces

The piston rod must not absorb any torque. We therefore recommend that an external guide FENG-KF be used with the drive DNCI. The guide unit is delivered installed.

The permissible static and dynamic characteristic load values with and without attached guide as well as with regard to the technical data of the variants (S2, S8, S9)

→ Internet: dnc



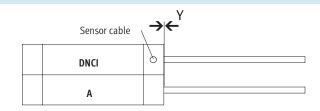
Mounting conditions

When mounting a drive A with magnet (for position sensing), in addition to a standard cylinder DNCI, the following conditions must be observed:

- X Minimum distance between the drives
- Y Offset between the drives on the bearing cap

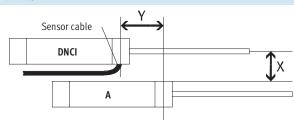
Parallel assembly

If the offset Y = 0 mm, the drives can be assembled directly next to one another.



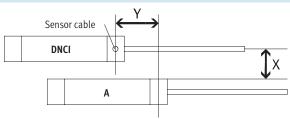
Offset assembly, cable outlet between the drives

If the offset Y > 0 mm and the cable outlet is between the drives, the distance from X > 70 mm must be observed.



Offset assembly, cable outlet upwards or downwards

If the offset Y > 0 mm and the cable outlet is up or down, the distance from X > 60 mm must be observed.

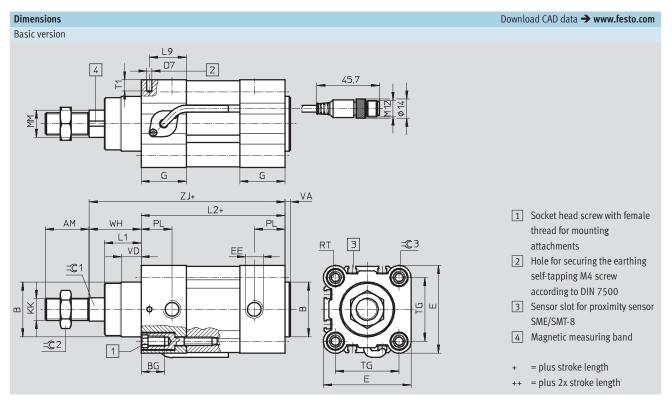


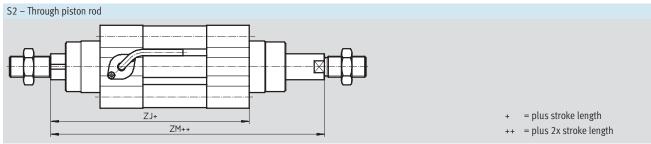
Pin assignment of plug, view of plug

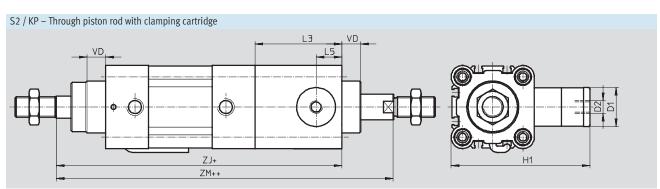
Pin	Function	Colour
1	5 V	black
2	GND	brown
3	sin+	red
4	sin-	orange
5	cos-	green
6	COS+	yellow
7	Screening	Screening
8	-	-

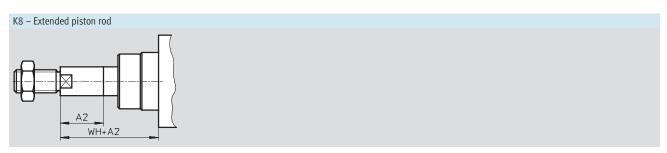








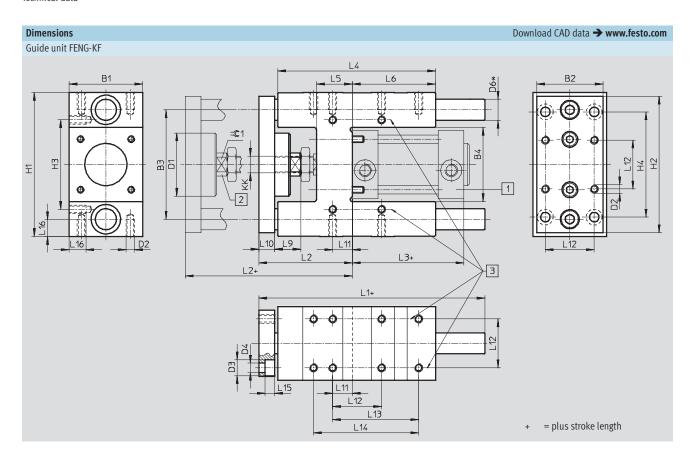






Ø [mm]	AM	A2 max.	B ∅ d11	BG	D1 ∅ f9	D2	D7 ∅	E	EE	G	H1
32	22	500	30	16	20	M5	3.7	45	G1/8	28	67
40	24	500	35	16	24	G1/8	3.7	54	G1/4	33	88
50	32	500	40	17	30	G1/8	3.7	64	G ¹ / ₄	33	107
63	32	500	45	17	38	G1/8	3.7	75	G3/8	40.5	123
Ø	KK	L1	L2	L3	L5	L9	MM Ø	PL	RT	T1	TG
[mm]							f8				
32	M10x1.25	18	94	45	14	22.5	12	15.6	M6	8	32.5
40	M12x1.25	21.3	105	53	16	27	16	14	M6	8	38
50	M16x1.5	26.8	106	67	20	27	20	14	M8	8	46.5
63	M16x1.5	27	121	76	24	33	20	17	M8	8	56.5
Ø	PI	VD	WH	Z	J	ZI	M	=©1	=©2	=3	2 3
[mm]					KP		KP				
32	4	10	26	120	165	148	193	10	16	6	5
40	4	10.8	30	135	188	167	220	13	18	ϵ	5
50	4	14.3	37	143	210	183	250	17	24	8	3
63	4	14.5	37	158	234	199	275	17	24	3	3







For \varnothing	B1	B2	В3	B4	D1	D2	D3	D4	D6	H1
					Ø		Ø	Ø	Ø	
[mm]	-0.3		±0.2	±0.3					h6	
32	50	45	74	50.5	44	M6	11	6.6	12	97 _{-0.4}
40	58	54	87	58.5	44	M6	11	6.6	16	115-0.4
50	70	63	104	70.5	60	M8	15	9	20	137 _{-0.5}
63	85	80	119	85.5	60	M8	15	9	20	152 _{-0.5}

For Ø	H2	Н3	H4	KK	L1	L2	L3	L4	L5	L6
[mm]		±0.2	±0.2							
32	90	61	78	M10x1.25	155	67+5	94	125	24	76
40	110	69	84	M12x1.25	170	75 ₊₅	105	140	28	81
50	130	85	100	M16x1	188	89+10	106	150	34	79
63	145	100	105	M16x1	220	89+10	121	182	34	111

For Ø	L9	L10	L11	L12	L13	L14	L15	L16	= ©1
[mm]				±0.2	±0.2	±0.2			
32	20	12	4.3	32.5	70.3	78	6.5	12	15
40	22	12	11	38	84	-	6.5	14	15
50	25	15	18.8	46.5	81.8	100	9	16	19
63	25	15	15.3	56.5	105	-	9	16	19

Standard cylinders DNCI, with measuring transducer DADE Ordering data – Modular products



	ry data							
Module No.	Function	Pist	on Ø	Stroke	Cushioning		Position sen	sing
	J							
535 411	DNCI	32		10 2,000	Р	A	P	
535 412		40						
535 413		50						
535 414		63						
Order								
example								
535 411	DNCI	- 32		- 100	– P	- 1	4	-
Ordering table		1	1	1	1		la i	l l
Piston Ø		32	40	50	63	Condi-	Code	Enter
						tions		code
Module No.		535 411	535 412	535 413	535 414			
Function		Standard cylind	er with integrated dis	placement encoder, non	rotating piston rod		DNCI	DNCI
Piston Ø	iston ∅ [mm] 32		40	50	63			
Stroke	[mm]	10 2,000	,					
Cushioning		Flexible cushion	ning rings/pads at bot	h ends			-P	-P
Position ser	sing	For proximity se	nsing				-A	-A

Transfer order cod	le									
	DNCI] -	_	- [-	-	P	-	Α] –

14

Standard cylinders DNCI, with measuring transducer DADE Ordering data – Modular products



Type of piston rod		Piston rod ex ront	tended at	Clamping	unit		Guide		Measuring hea	ad
S2		K8		КР			FENG		MS	
dering table				-] - [- [
ston Ø		32	40		50		63	Conditions		Enter code
Type of piston rod		Through pis	ton rod						-S2	
Piston rod extended	[mm]	1 500						2	K8	
Clamping unit		Clamping ca	ırtridge					3	-KP	
Guide		Guide unit v	vith ball bearin	g guide on the	guide on the sensor head side			4	-FENG	
Measuring head No measuring head									-MS	

2 K8	In combination with piston rod type S2, the piston rod is only extended at the front	3 K9	Only with piston rod type S2
	(the side facing the measuring head)	4 FFNG	Maximum stroke length 500 mm

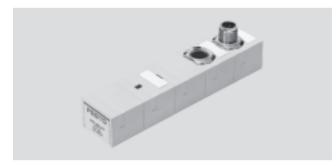
	Transfer order code							
-		-	-	-	-[-	-	



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Measuring transducer DADE-MVC-010 DADE-MVC-420

The transducer converts sensor signals of the DNCI standard cylinder into a voltage signal of 0 \dots 10 V or a current signal of 0 ... 20 mA. These signals can be evaluated by a PLC with an appropriate signal input.



General technical data					
Type of mounting		Via through holes			
Mounting position		Any			
Repetition accuracy in relation to	≤ 400	±0.1 mm			
effective stroke	≤ 750	±0.2 mm			
	≤ 1,200	±0.3 mm			
	≤ 1,600	±0.4 mm			
	≤ 2 , 000	±0.5 mm			
Protection against short circuit		Yes			
Protection against polarity reversal		Yes			
Diagnostic function		Display via LED			

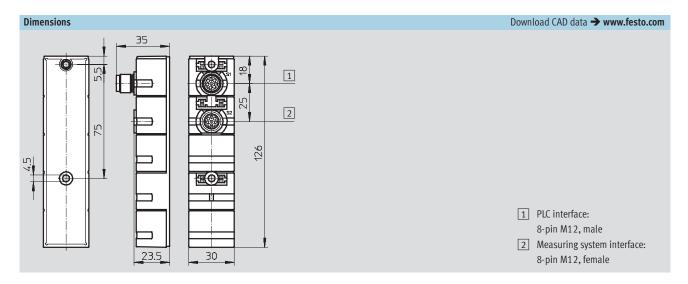
General electrical data		
Analogue output	[V]	0 10 (as per EN 61131-2)
	[mA]	0 20 (as per EN 61131-2)
Nominal operating voltage	[V DC]	24 ±25%
Residual ripple	[%]	4 (at 50 Hz)
Current consumption at nominal	[mA]	20 30
operating voltage		
Switching logic at outputs		PNP
Switching logic at inputs		PNP
Debounce time at inputs	[ms]	3
Linearity error FS		0,2%

Operating and environmental conditions						
Ambient temperature	[°C]	0 55				
Protection class		IP65				
Relative air humidity		95% non-condensing				
CE symbol (see conformity declaration)		As per EU EMC directive				
Corrosion resistance class CRC ¹⁾		1				
Product weight	[g]	128				
Note on material for housing		Polybutylene terephthalate				

¹⁾ Corrosion resistance class 1 as per Festo standard 940 070 Components requiring low corrosion resistance Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers



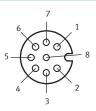
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Pin allocation

PLC interface





Pin	Function	Cable colour
1	24 V	white
2	Measured signal (analogue)	brown
3	Reference output	green
4	0 V measured signal	yellow
5	Reference input	grey
6	Calibration input	pink
7	Ready output	blue
8	0 V power supply and inputs/	red
	outputs	

Pin	Function
1	Ub
2	0 V
3	Signal sine +
4	Signal sine -
5	Signal cosine -
6	Signal cosine +
7	Screening / earth
8	-

Ordering data				
		Description	Part No.	Туре
Measuring transducer				
	With voltage signal	0 10 V	542 117	DADE-MVC-010
	With current signal	0 20 mA	542 118	DADE-MVC-420
Accessories Technical data → Internet: sim				
	Cable with socket	Connecting cable to PLC (length 2 m)	525 616	SIM-M12-8GD-2-PU
		Connecting cable to PLC (length 5 m)	525 618	SIM-M12-8GD-5-PU