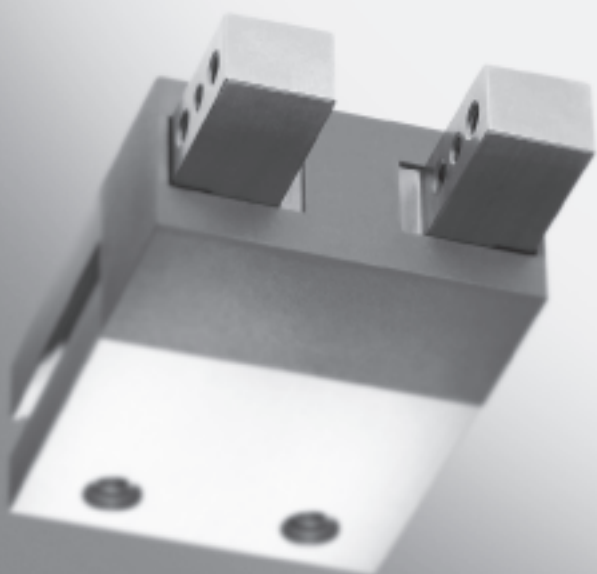


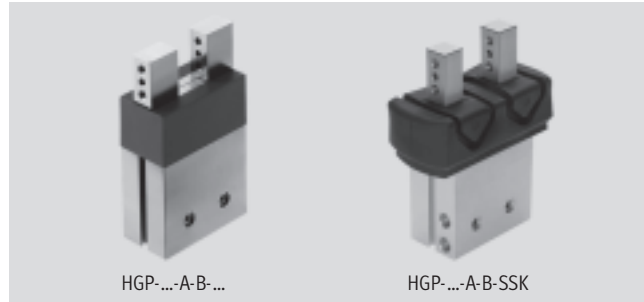


- Economical and versatile
- Self-centring
- Variable gripping action

Parallel grippers HGP

Key features

FESTO



At a glance

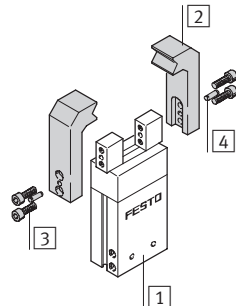
- Double-acting piston drive
- Self-centring
- Variable gripping action:
 - External/internal gripping
- Versatility thanks to externally adaptable gripper fingers
- Wide range of options for mounting on drive units
- High gripping force and compact size
- Max. repetition accuracy
- Gripping force retention
- Internal fixed flow control
- With protective dust cap for use in dusty environments (protection class IP54)
- Sensor technology:
 - Adaptable proximity sensors on the small grippers
 - Integral proximity sensors for medium and large grippers



Gripper selection software
www.festo.com/en/engineering

Mounting options for external gripper fingers (customer-specific)

- 1 Parallel gripper
- 2 External gripper fingers
- 3 Mounting screws
- 4 Centring pins



With protective dust cap

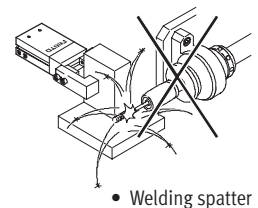
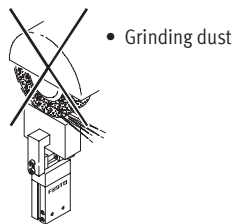
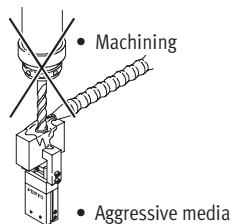
The sizes 16 and 25 can be adapted for use in dusty environments. They fulfil the requirements for protection class IP54.

The technical data corresponds to the data for parallel gripper HGP without protective dust cap.



-  Note

Grippers should always be used with exhaust air flow control. They are not suitable for the following, or for similar applications:



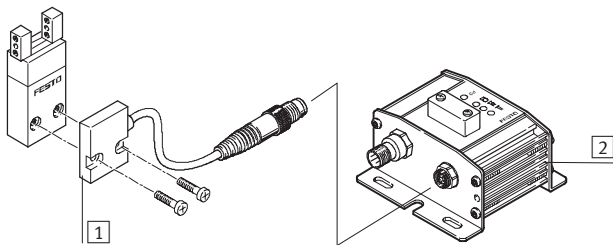
Parallel grippers HGP

Peripherals overview and type codes

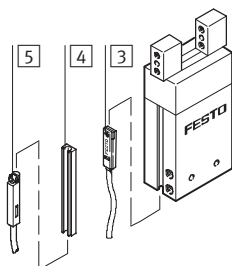
FESTO

Peripherals overview

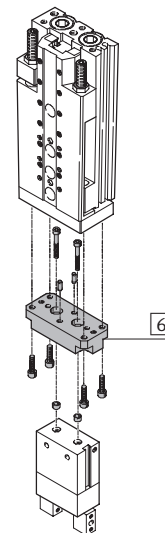
HGP-06



HGP-10 ... 35



System product for handling and assembly technology



Accessories			
Type	Brief description		→ Page
1 Position sensor SMH-S1	Adaptable and integratable sensor technology, for sensing the piston position		1 / 7.5-13
2 Evaluation unit SMH-AE1	For position sensor SMH-S1		1 / 7.5-13
3 Proximity sensor SME/SMT-8	For sensing the piston position		1 / 7.5-14
4 Bondable sensor rail HGP-SL	Allows the use of proximity sensors SME/SMT-10		1 / 7.5-13
5 Proximity sensor SME/SMT-10	For sensing the piston position		1 / 7.5-15
6 –	Drive/gripper connections		Volume 5

Type codes

		HGP	–	16	–	A	–	B	–	G1	–	SSK
Type												
HGP	Parallel gripper											
Size												
Position sensing												
A	For proximity sensing											
Generation												
B	B series											
Gripping force retention												
G1	Open											
G2	Closed											
Protective dust cap												
SSK	Protective dust cap											

Parallel grippers HGP

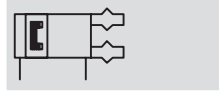
Technical data

FESTO

Function

Double-acting

HGP-06-A, HGP-...-A-B



Ø - Size
6 ... 35 mm

- | - Stroke
4 ... 25 mm

Variants

- With gripping force retention...
... open HGP-...-G1
... closed HGP-...-G2
- With protective dust cap

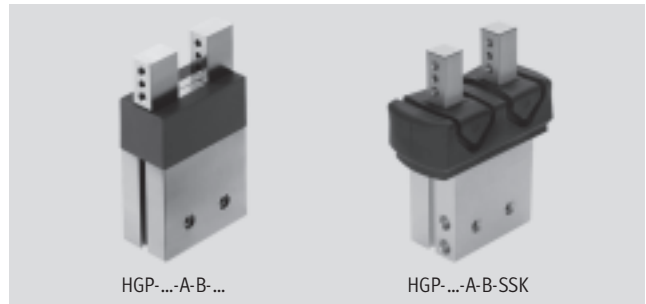


www.festo.com/en/

Spare_parts_service

Wearing parts kits

➔ 1 / 7.5-12



General technical data							
Size	6	10	16	20	25	35	
Design	Wedge-shaped	Lever mechanism					
Mode of operation	Double-acting						
Gripper function	Parallel						
Number of gripper jaws	2						
Max. applied load per external gripper finger ¹⁾	[N]	0.1	0.2	0.4	0.6	0.8	1.2
Stroke per gripper jaw	[mm]	2	3	5	6.5	7.5	12.5
Pneumatic connection	M3			M5	G3/8		
Repetition accuracy ²⁾	[mm]	≤ 0.04					
Max. interchangeability	[mm]	0.2					
Max. operating frequency	[Hz]	4					
Position sensing	For proximity sensing						
Type of mounting	With female thread and centring sleeve						
	–	Via through-holes and centring sleeve					

1) Valid for unthrottled operation

2) End position drift under constant conditions of use with 100 consecutive strokes in the direction of movement of the gripper jaws

Operating and environmental conditions							
Size		6	10	16	20	25	35
Min. operating pressure	HGP-...-A/-B	[bar]	2				
	HGP-...-G...	[bar]	5				
Max. operating pressure		[bar]	8				
Operating medium			Filtered compressed air, lubricated or unlubricated				
Ambient temperature			[°C] +5 ... +60				
Corrosion resistance class CRC ¹⁾			2	1			

1) Corrosion resistance class 1 according to Festo standard 940 070

Components requiring low corrosion resistance. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.

Corrosion resistance class 2 according to Festo standard 940 070

Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Weights [g]						
Size	6	10	16	20	25	35
HGP-...-A	18	75	194	396	725	1 369
HGP-...-G1	-	76	197	402	737	1 387
HGP-...-G2	-	76	197	402	737	1 387
With protective dust cap						
HGP-...-SSK	-	-	197	-	737	-

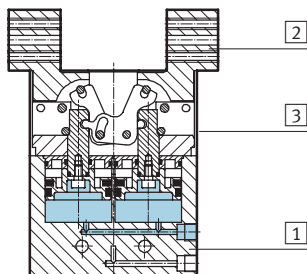
Parallel grippers HGP

Technical data

FESTO

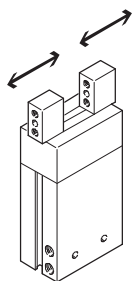
Materials

Sectional view



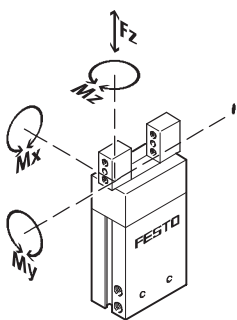
Parallel gripper	6	10	16	20	25	35
1 Body	Nickel-plated aluminium	Hard anodised aluminium				
2 Gripper jaw	Nickel-plated steel	High-alloy steel				
3 Cover cap	Polyamide					
– Protective dust cap SSK	–		Thermoplastic vulcanizate	–	Thermoplastic vulcanizate	–
– Note on materials	Copper, PTFE and silicone-free					

Gripping force [N] at 6 bar



Size	6	10	16	20	25	35
Gripping force per gripper jaw						
Opening	10	22	70	120	185	375
Closing	10	17	80	115	170	350
Total gripping force						
Opening	20	44	140	240	370	750
Closing	20	34	160	230	340	700

Characteristic load values per gripper jaw



The indicated permissible forces and torques apply to a single gripper jaw. The indicated values include the lever arm, additional applied loads caused

by the workpiece or external gripper fingers, as well as forces which occur during movement.

The zero co-ordinate line (gripper jaw guide) must be taken into consideration for the calculation of torques.

Size		6	10	16	20	25	35
Max. permissible force F_Z	[N]	14	25	90	150	240	380
Max. permissible torque M_X	[Nm]	0.1	0.5	3.3	6	11	25
Max. permissible torque M_Y	[Nm]	0.1	0.5	3.3	6	11	25
Max. permissible torque M_Z	[Nm]	0.1	0.5	3.3	6	11	25

Handling units
Parallel grippers

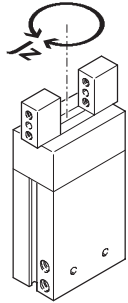
7.5

Parallel grippers HGP

Technical data

FESTO

Mass moment of inertia [kgm²x10⁻⁴]



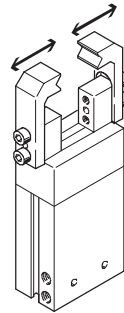
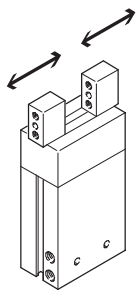
Mass moment of inertia [kgm²x10⁻⁴]
for parallel grippers in relation to the
central axis, without external gripper
fingers, without load.

Size	6	10	16	20	25	35
HGP-...-A	0.01	0.08	0.47	1.49	3.83	12.70
HGP-...-G1	–	0.08	0.47	1.52	3.92	12.83
HGP-...-G2	–	0.08	0.47	1.49	3.84	12.73

Opening and closing times [ms] at 6 bar

without external gripper fingers

with external gripper fingers



The indicated opening and closing
times [ms] have been measured at
room temperature and 6 bar operating
pressure without external gripper
fingers.

The grippers must be throttled for
greater applied loads. Opening and
closing times must then be adjusted
accordingly.

Size		6	10	16	20	25	35
Without external gripper fingers							
HGP-...-A	Opening	5	22	44	32	47	77
	Closing	5	31	60	44	50	77
HGP-...-G1	Opening	–	17	39	30	39	71
	Closing	–	29	62	48	60	82
HGP-...-G2	Opening	–	33	66	39	62	90
	Closing	–	29	44	42	49	72
With external gripper fingers (as a function of applied load)							
HGP	0.06 N	5	–	–	–	–	–
	0.08 N	10	–	–	–	–	–
	0.10 N	20	–	–	–	–	–
	0.20 N	50	–	–	–	–	–
	0.50 N	–	100	–	–	–	–
	1.00 N	–	200	100	–	–	–
	1.25 N	–	–	–	100	–	–
	1.50 N	–	300	200	–	100	–
	1.75 N	–	–	–	200	–	–
	2.00 N	–	–	300	–	200	100
	2.50 N	–	–	–	300	–	–
	3.00 N	–	–	–	–	300	200
	4.00 N	–	–	–	–	–	300

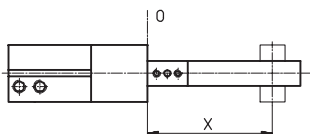
Parallel grippers HGP

Technical data

FESTO

Gripping force F_{Grip} per gripper jaw as a function of operating pressure and lever arm x

External and internal gripping (closing and opening)

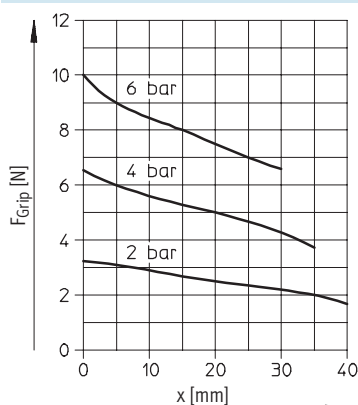


Gripping forces can be determined with the following diagrams for the various sizes in relation to operating

pressure and lever arm (distance from the zero co-ordinate line shown

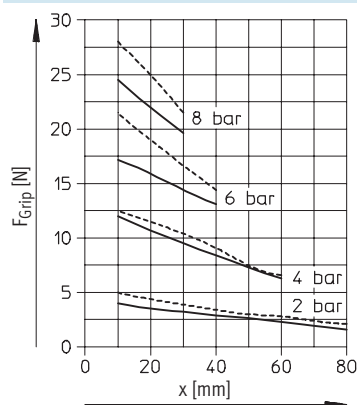
opposite to the pressure point at which the fingers grip the workpiece).

HGP-06-A¹⁾

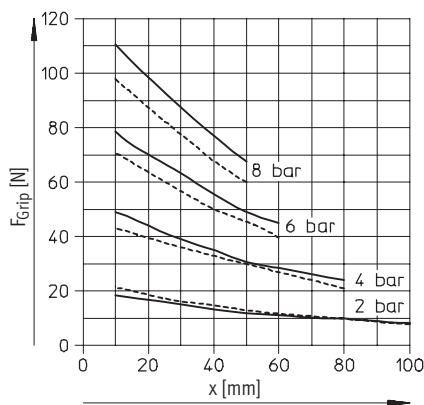


1) Due to the design, the opening and closing gripping forces for HGP-06-A are identical

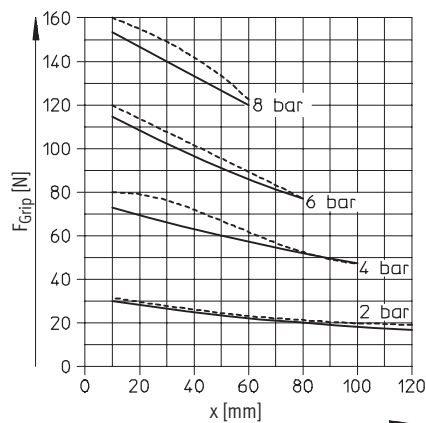
HGP-10-A-B



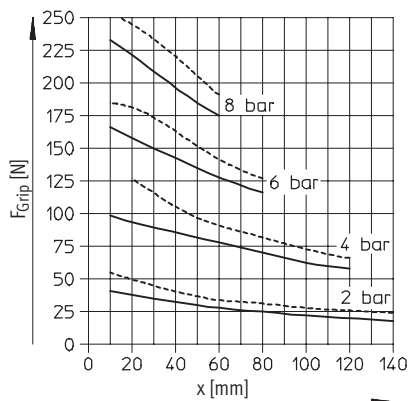
HGP-16-A-B



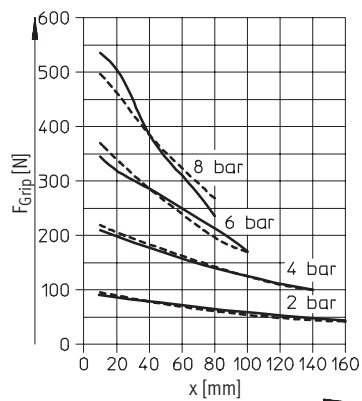
HGP-20-A-B



HGP-25-A-B



HGP-35-A-B



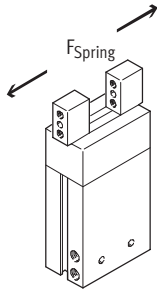
— Closing
- - - Opening

Parallel grippers HGP

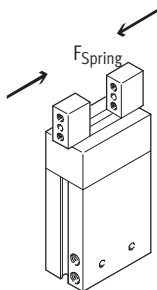
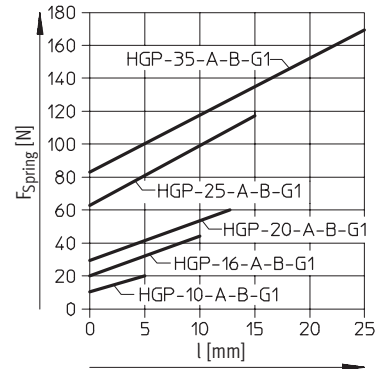
Technical data

FESTO

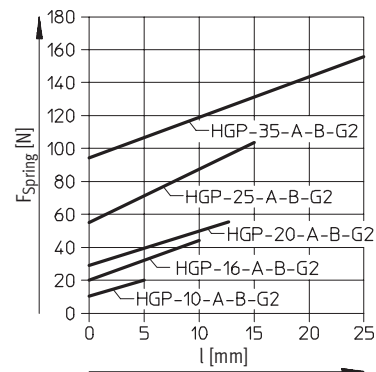
Spring force F_{Spring} as a function of the gripper size and overall stroke length l



Gripper retention force, opening:
the spring forces F_{Spring} of the parallel gripper HGP-...-G1 can be determined from the following graphs.



Gripper retention force, closing:
the spring forces F_{Spring} of the parallel gripper HGP-...-G2 can be determined from the following graphs.



Determination of actual gripping forces for parallel grippers HGP-...-G1 and HGP-...-G2 depending upon the application

The parallel grippers with integrated spring can be used as:

- single-acting grippers
- grippers with supplementary gripping force and
- grippers with gripping force retention

In order to calculate available gripping forces F_{Gr} (per gripper jaw), the gripping force F_{Grip} and spring

force (F_{Spring}) must be combined accordingly.

Application

The resulting gripping force F_{Gr} , conditional on the application, depends on the gripping action (external/internal gripping) and the gripper design (with/without spring return). The spring force is supplemented in accordance with the design and gripping action.

Single-acting	Supplementary gripping force	Gripping force retention
• Gripping with spring force: $F_{\text{Gr}} = F_{\text{Spring}}$ • Gripping with pressure force: $F_{\text{Gr}} = F_{\text{Grip}} - F_{\text{Spring}}$	• Gripping with pressure and spring force: $F_{\text{Gr}} = F_{\text{Grip}} + F_{\text{Spring}}$	• Gripping with spring force: $F_{\text{Gr}} = F_{\text{Spring}}$

		Pressurised (in gripping action)	Unpressurised
HGP	Opening	$F_{\text{Gr}} = F_{\text{Grip}}$	$F_{\text{Gr}} = 0$
	Closing	$F_{\text{Gr}} = F_{\text{Grip}}$	$F_{\text{Gr}} = 0$
HGP-...-G1	Opening	$F_{\text{Gr}} = F_{\text{Grip}} + F_{\text{Spring}}$	$F_{\text{Gr}} = F_{\text{Spring}}$
	Closing	$F_{\text{Gr}} = F_{\text{Grip}} - F_{\text{Spring}}$	$F_{\text{Gr}} = 0$
HGP-...-G2	Opening	$F_{\text{Gr}} = F_{\text{Grip}} - F_{\text{Spring}}$	$F_{\text{Gr}} = 0$
	Closing	$F_{\text{Gr}} = F_{\text{Grip}} + F_{\text{Spring}}$	$F_{\text{Gr}} = F_{\text{Spring}}$

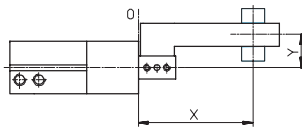
Parallel grippers HGP

Technical data

FESTO

Gripping force F_{Grip} per gripper jaw at 6 bar as a function of lever arm x and eccentricity y

External and internal gripping (closing and opening)



Gripping forces can be determined with the following diagrams for the various sizes at 6 bar in relation to

eccentric application of force (distance from the zero co-ordinate line shown opposite to the pressure point at

which the fingers grip the workpiece) and the maximum permissible off-centre point at which force is applied.

Calculation example

Given:

HGP-16-A-B

Lever arm $x = 20$ mm

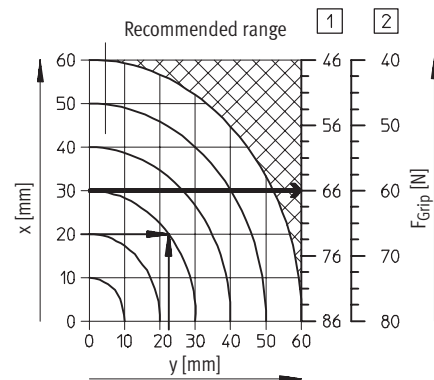
Eccentricity $y = 22$ mm

To be found:

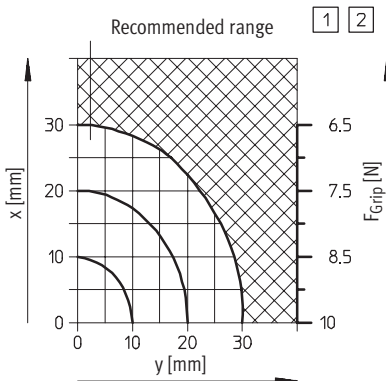
Gripping force at 6 bar

Procedure:

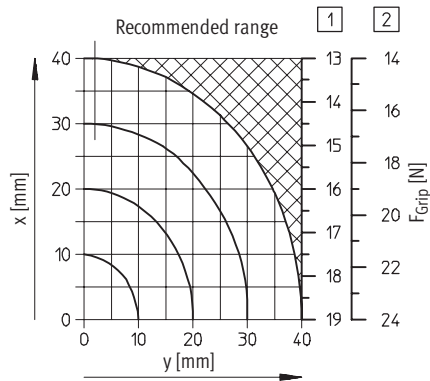
- Determine the intersection xy between lever arm x and eccentricity y in the graph for HGP-16-A-B
 - Draw an arc (with centre at origin) through intersection xy
 - Determine the intersection between the arc and the X axis
 - Read the gripping force
- Result:
Gripping force = approx. 66 N



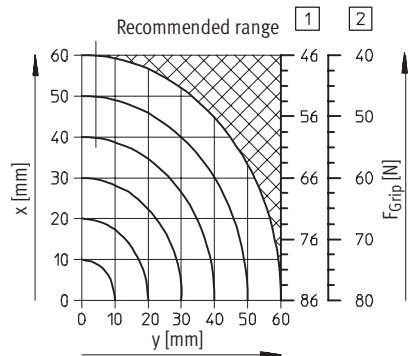
HGP-06-A



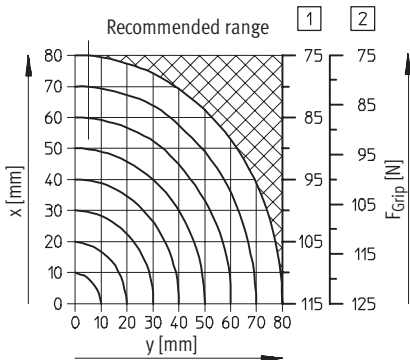
HGP-10-A-B



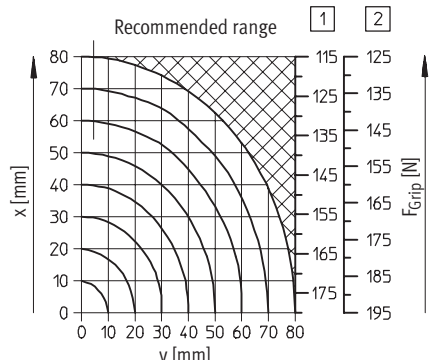
HGP-16-A-B



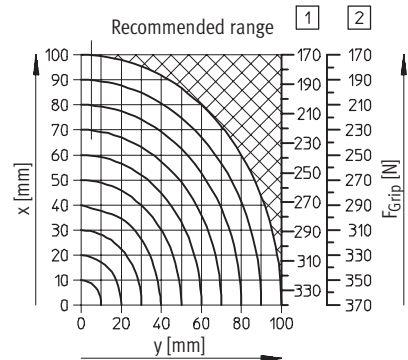
HGP-20-A



HGP-25-A-B



HGP-35-A-B



- 1 Closing
2 Opening

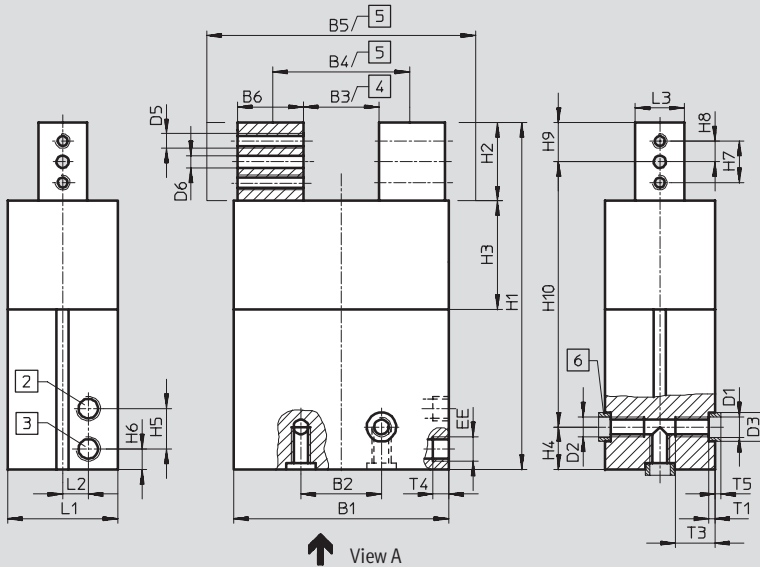
Parallel grippers HGP

Technical data

FESTO

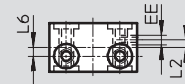
Dimensions

Download CAD data → www.festo.com/en/engineering

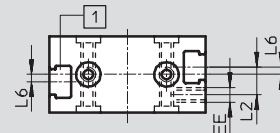


View A

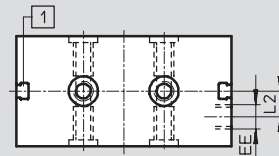
HGP-06-A



HGP-10-A-B

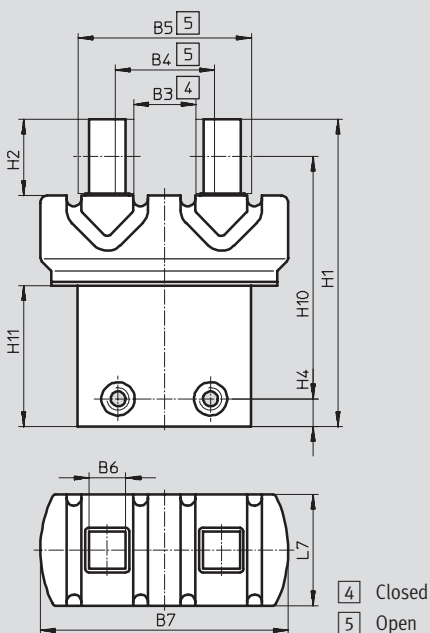


HGP-16 ... 32-A-B



- | | |
|--|--|
| 1 Sensor slot for proximity sensor SME/SMT-8 (not with HGP-06-A). Proximity sensors SME/SMT-10 can also be used in combination with the sensor strip HGP-SL-... (can be glued into place). | 2 Compressed air connection, opening |
| | 3 Compressed air connection, closing |
| | 4 Closed |
| | 5 Open |
| | 6 Centring sleeves ZBH (2 included in scope of delivery) |

With protective dust cap HGP-...-SSK



- | |
|----------|
| 4 Closed |
| 5 Open |

Parallel grippers HGP

Technical data

FESTO

Type	B1	B2 ¹⁾	B3	B4	B5	B6	B7	D1 Ø	D2	D3 Ø H8/h7	D5	D6 Ø H8	EE	H1	H2	H3	H4 ²⁾
		±0.1	±0.5	±0.5	±0.5	−0.03	±0.5										±0.1
HGP-06-A	18	11	6	10	21	5.5	–	3.2	M3	5	M2	1.5	M3	45.5	9.9	10.2	7.5
HGP-10-A-B	32	16	15.8	21.8	35.8	7	–	3.2	M3	5	M3	2	M3	66	15	16	7.5
HGP-16-A-B	47	25	17.8	27.8	53.8	13	–	5.3	M4	7	M4	3	M3	80	20	21.9	7.5
HGP-20-A-B	55.6	25	17.4	30.4	65.4	17.5	–	5.3	M4	7	M4	4	M5	101	24.9	26.1	7.5
HGP-25-A-B	68.2	29	21	36	80	22	–	6.4	M6	9	M5	4	G1/8	121	30	32.2	17.5
HGP-35-A-B	88	33	31	56	110	27	–	8.4	M8	12	M6	5	G1/8	142	31.9	44.8	17.5
With protective dust cap																	
HGP-16-A-B-SSK	47	25	16.4	26.4	46.4	10	67	5.3	M4	7	M4	3	M3	83	20.5	21.9	7.5
HGP-25-A-B-SSK	68.2	29	21	36	66	15	101	6.4	M6	9	M5	4	G1/8	126.8	31.5	32.2	17.5

Type	H5	H6	H7	H8	H9	H10	H11	L1	L2	L3	L6	L7	T1	T3	T4	T5
						±0.2				−0.03			+0.1	+1	+0.5	−0.3
HGP-06-A	7	4	5.8	2.9	5	33	–	10	1.5	5	1.8	–	1.2	–	3.5	1.2
HGP-10-A-B	7	4	8	4	7.5	51	–	15.5	4.2	7	1.5	–	1.2	6	3.5	1.2
HGP-16-A-B	7	4	11	5.5	10	62.5	–	22	5.7	10	–	–	1.6	7.5	3.5	1.4
HGP-20-A-B	10.5	11.5	14	7	12.5	81	–	30	9	12	–	–	1.6	8	6	1.4
HGP-25-A-B	16.5	8.3	16	8	15	88.5	–	37	10.5	15	–	–	2.1	15	6.5	1.9
HGP-35-A-B	16.5	8.5	17	8.5	16	108.5	–	45	10.5	20	–	–	2.6	16	6.5	2.4
With protective dust cap																
HGP-16-A-B-SSK	7	4	11	5.5	10	65.5	38.1	22	5.7	10	–	30	1.6	7.5	3.5	1.4
HGP-25-A-B-SSK	16.5	8.3	16	8	15	94.3	58.8	37	10.5	15	–	47	2.1	15	6.5	1.9

1) Tolerance for centring hole: ±0.02

2) Tolerance for centring hole: −0.05

-  - Note

Due to the distance H5 between the two air connections on types

HGP-06/-10/-16 which measures

7 mm, only the following tube fittings can be used

– QSM-M3-3

– QSML-M3-3

– QSMLL-M3-3

– CN-M3-PK-3

– LCN-M3-PK-3

➔ Volume 3

Parallel grippers HGP

Technical data

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Ordering data						
Size	Double-acting		Gripper retention force G1		Gripper retention force G2	
	Without compression spring		Open		Closed	
[mm]	Part No.	Type	Part No.	Type	Part No.	Type
6	174 815	HGP-06-A	–		–	
10	197 542	HGP-10-A-B	197 543	HGP-10-A-B-G1	197 544	HGP-10-A-B-G2
16	197 545	HGP-16-A-B	197 546	HGP-16-A-B-G1	197 547	HGP-16-A-B-G2
20	525 889	HGP-20-A-B	525 890	HGP-20-A-B-G1	525 891	HGP-20-A-B-G2
25	197 548	HGP-25-A-B	197 549	HGP-25-A-B-G1	197 550	HGP-25-A-B-G2
35	197 551	HGP-35-A-B	197 552	HGP-35-A-B-G1	197 553	HGP-35-A-B-G2
With protective dust cap						
16	539 636	HGP-16-A-B-SSK	–		–	
25	539 635	HGP-25-A-B-SSK	–		–	

Ordering data – Wearing parts kits		
Size		
[mm]	Part No.	Type
6	378 516	HGP-06-A
10	397 376	HGP-10
16	397 377	HGP-16
20	397 378	HGP-20
25	397 397	HGP-25
32	397 380	HGP-35

Parallel grippers HGP

Accessories

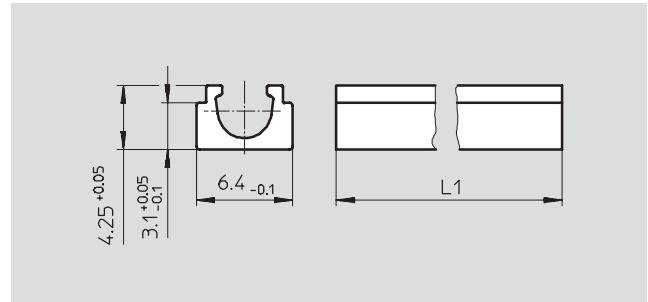
FESTO

Sensor rail HGP-SL

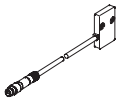
can be glued into place

Material:

Wrought aluminium alloy



Dimensions and ordering data				
For size [mm]	L1	Weight [g]	Part No.	Type
10	35	1.4	535 582	HGP-SL-10-10
16	38	1.5	535 583	HGP-SL-10-16
20	50	2.0	535 584	HGP-SL-10-20
25	58	2.3	535 585	HGP-SL-10-25
35	65	2.6	535 586	HGP-SL-10-35

Ordering data					
Type	For size	Weight [g]	Part No.	Type	PU ¹⁾
Position sensor SMH-S1 Technical data → 1 / 10.2-107					
	6	20	175 710	SMH-S1-HGP06	1
Evaluation unit SMH-AE1 Technical data → 1 / 10.2-110					
	6	170	175 708	SMH-AE1-PS3-M12	1
			175 709	SMH-AE1-NS3-M12	
Centring sleeve ZBH Technical data → 1 / 10.1-3					
	6, 10	1	189 652	ZBH-5	10
	16, 20		186 717	ZBH-7	
	25		150 927	ZBH-9	
	35		189 653	ZBH-12	

1) Packaging unit quantity

Parallel grippers HGP

Accessories

FESTO

Ordering data – Proximity sensors for T-slot, magneto-resistive								Technical data ➔ 1 / 10.2-13	
	Assembly	Switch output	Electrical connection			Cable length [m]	Part No.	Type	
			Cable	M8 plug	M12 plug				
N/O contact									
	Insertable from above	PNP	3-wire	–	–	2.5	525 898	SMT-8F-PS-24V-K2,5-OE	
		NPN					525 909	SMT-8F-NS-24V-K2,5-OE	
		–	2-wire	–	–	2.5	525 908	SMT-8F-ZS-24V-K2,5-OE	
		PNP	–	3-pin	–	0.3	525 899	SMT-8F-PS-24V-K0,3-M8D	
		NPN					525 910	SMT-8F-NS-24V-K0,3-M8D	
		PNP	–	–	3-pin	0.3	525 900	SMT-8F-PS-24V-K0,3-M12	
	Insertable from end, flush with the cylinder profile	PNP	3-wire	–	–	2.5	175 436	SMT-8-PS-K-LED-24-B	
			–	3-pin	–	0.3	175 484	SMT-8-PS-S-LED-24-B	
N/C contact									
	Insertable from above	PNP	3-wire	–	–	7.5	525 911	SMT-8F-PO-24V-K7,5-OE	

Ordering data – Proximity sensors for T-slot, magnetic reed						Technical data➔ 1 / 10.2-18	
	Assembly	Electrical connection		Cable length [m]	Part No.	Type	
		Cable	M8 plug				
N/O contact							
	Insertable from above	3-wire	–	2.5	525 895	SME-8F-DS-24V-K2,5-OE	
			–	5.0	525 897	SME-8F-DS-24V-K5,0-OE	
		2-wire	–	2.5	525 907	SME-8F-ZS-24V-K2,5-OE	
		–	3-pin	0.3	525 896	SME-8F-DS-24V-K0,3-M8D	
	Insertable from end, flush with the cylinder profile	3-wire	–	2.5	150 855	SME-8-K-LED-24	
		–	3-pin	0.3	150 857	SME-8-S-LED-24	
N/C contact							
	Insertable from end, flush with the cylinder profile	3-wire	–	7.5	160 251	SME-8-O-K-LED-24	

Ordering data – Plug sockets with cable							Technical data➔ 1 / 10.2-114	
	Assembly	Switch output		Connection	Cable length [m]	Part No.	Type	
		PNP	NPN					
Straight plug socket								
	M8 union nut			3-pin	2.5	159 420	SIM-M8-3GD-2,5-PU	
					5	159 421	SIM-M8-3GD-5-PU	
	M12 union nut			3-pin	2.5	159 428	SIM-M12-3GD-2,5-PU	
					5	159 429	SIM-M12-3GD-5-PU	
Angled plug socket								
	M8 union nut			3-pin	2.5	159 422	SIM-M8-3WD-2,5-PU	
					5	159 423	SIM-M8-3WD-5-PU	
	M12 union nut			3-pin	2.5	159 430	SIM-M12-3WD-2,5-PU	
					5	159 431	SIM-M12-3WD-5-PU	

Parallel grippers HGP

Accessories

FESTO

Ordering data – Proximity sensors for C-slot, magneto-resistive								Technical data➔ 1 / 10.2-57	
	Assembly	Switch output	Electrical connection		Cable length [m]	Connection direction	Part No.	Type	
			Cable	M8 plug					
N/O contact									
	Insertable from above	PNP	3-wire	–	2.5	In-line	525 915	SMT-10F-PS-24V-K2,5L-OE	
			–	3-pin	0.3	In-line	525 916	SMT-10F-PS-24V-K0,3L-M8D	
					Lateral	526 675	SMT-10F-PS-24V-K0,3Q-M8D		
	Insertable from end	PNP	–	3-pin	0.3	In-line	173 220	SMT-10-PS-SL-LED-24	
			3-wire	–	2.5		173 218	SMT-10-PS-KL-LED-24	

Ordering data – Proximity sensors for C-slot, magnetic reed							Technical data➔ 1 / 10.2-60	
	Assembly	Electrical connection		Cable length [m]	Connection direction	Part No.	Type	
		Cable	M8 plug					
N/O contact								
	Insertable from above	–	3-pin	0.3	In-line	525 914	SME-10F-DS-24V-K0,3L-M8D	
		3-wire	–	2.5	In-line	525 913	SME-10F-DS-24V-K2,5L-OE	
		2-wire				526 672	SME-10F-ZS-24V-K2,5L-OE	
	Insertable from end	–	3-pin	0.3	In-line	173 212	SME-10-SL-LED-24	
		3-wire	–	2.5		173 210	SME-10-KL-LED-24	

Ordering data – Plug sockets with cable						Technical data➔ 1 / 10.2-114	
	Assembly	Switch output		Connection	Cable length [m]	Part No.	Type
		PNP	NPN				
Straight plug socket							
	M8 union nut			3-pin	2.5	159 420	SIM-M8-3GD-2,5-PU
					5	159 421	SIM-M8-3GD-5-PU
Angled plug socket							
	M8 union nut			3-pin	2.5	159 422	SIM-M8-3WD-2,5-PU
					5	159 423	SIM-M8-3WD-5-PU

Handling units
Parallel grippers

7.5

