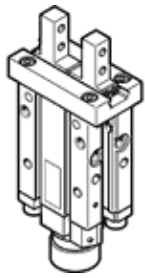


# Parallel gripper DHPC-20-A-NC-Z

Part number: 8116832

FESTO



## Data sheet

Feature	Value
Size	20
Stroke per gripper jaw	5 mm
Max. replacement accuracy	0.2 mm
Max. angular gripper jaw backlash ax,ay	0 deg
Max. gripper jaw backlash Sz	0 mm
Rotationally symmetrical	≤ 0.2 mm
Repetition accuracy, gripper	≤ 0.02 mm
Number of gripper fingers	2
Drive system	pneumatic
Assembly position	Any
Mode of operation	single-acting closed
Gripper function	Parallel
Gripper force back-up	On closing
Design structure	Connection via mounting spigot Lever Standard mounting of gripper fingers guided motion sequence
Guide	Ball guide
Position detection	For proximity sensor
Total gripping force at 0.6 MPa (6 bar, 87 psi), opening	170.9 N
Operating pressure MPa	0.25 ... 0.8 MPa
Working pressure	2.5 ... 8 bar
Operating pressure	36.25 ... 116 psi
Max. operating frequency of gripper	3 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	86 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	38 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further operation)
Corrosion resistance classification CRC	0 - No corrosion stress
PWIS conformity	VDMA24364-B2-L
Ambient temperature	-10 ... 60 °C
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) opening	85.5 N
Mass moment of inertia	0.574 kgcm <sup>2</sup>
Max. force on gripper jaw Fz static	73.5 N
Max. torque at gripper Mx static	0.66 Nm
Max. torque at gripper My static	1.33 Nm
Max. torque at gripper Mz static	0.66 Nm
Product weight	270 g
Mounting type	Direct mounting via through-holes Direct mounting via threads On mounting frame With through-hole and dowel pin With internal thread and dowel pin Optional
Pneumatic connection	M5
Materials note	Conforms to RoHS
Material housing	Anodised aluminium
Material gripper jaws	High alloy steel, non-corrosive