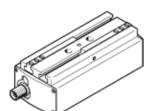
Parallel gripper HGPLE-14-60-3,1-DC-VCSC-G96 Part number: 2342435

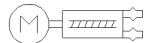
Product to be discontinued

with controllable gripper force and free, speed-controlled choice of the gripper positions.

Type to be discontinued. Available until 2020. See Support Portal for alternative products.







Data sheet

Feature	Value
Size	14
Stroke per gripper jaw	60 mm
Max. replacement accuracy	<= 0.2 mm
Max. angular gripper jaw backlash ax,ay	<= 0.2 deg
Max. gripper jaw backlash Sz	<= 0.05 mm
Controllable stroke range per gripper jaw	0 60 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	<= 0.05 mm
Number of gripper fingers	2
Assembly position	Any
Gripper function	Parallel
Design structure	Worm gear unit
	T-shaped
	Rack and pinion
	With integrated displacement encoder
Guide	Plain-bearing guide
Position detection	With integrated angular displacement encoder
Configuration support	FCT (Festo Configuration Tool)
Motor type	DC servo motor
Referencing	Fixed stop block positive
	Fixed stop block negative
Nominal operating voltage DC	24 V
CE symbol (see declaration of conformity)	according to EU-EMV guideline
Corrosion resistance classification CRC	2 - Moderate corrosion stress
Sound pressure level	<= 60 dB(A)
Protection class	IP40
Ambient temperature	10 40 °C
Mass moment of inertia	11.64 kgcm2
Max. force on gripper jaw Fz static	500 N
Max. torque at gripper Mx static	35 Nm
Max. torque at gripper My static	35 Nm
Max. torque at gripper Mz static	35 Nm
Lubrication interval for guide components	2 Mio SP
Max. ground per external gripper finger	150 g
Product weight	700 g
Electrical connection	Plug
	M12x1
	12-pin
Mounting type	Optional
	Internal thread and centering sleeve
	With through-hole and centering sleeve



Feature	Value
Materials note	Free of copper and PTFE
	Conforms to RoHS
Material housing	Aluminum
	Anodized
Material gripper jaws	Steel
	Hardened