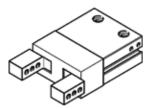
## Parallel gripper HGP-35-A-B Part number: 197551

Self-centering, can be used as internal and external gripper. Magnetic piston for proximity position sensing.



## **Data sheet**

Feature	Value
Size	35
Stroke per gripper jaw	12.5 mm
Max. replacement accuracy	0.2 mm
Repetition accuracy, gripper	<= 0.04 mm
Number of gripper fingers	2
Mode of operation	double-acting
Gripper function	Parallel
Design structure	Lever
Position detection	For proximity sensor
Total force at 6 bar, opening	750 N
Total force at 6 bar, closing	700 N
Working pressure	2 8 bar
Max. operating frequency of gripper	4 Hz
Min. opening time at 6 bar	77 ms
Min. closing time at 6 bar	77 ms
Operating medium	Filtered, unlubricated compressed air, 40 µm filtration
	Filtered, lubricated compressed air, 40 µm filtration
Corrosion resistance classification CRC	1
Ambient temperature	10 60 °C
Gripping force per gripper jaw at 6 bar, opening	375 N
Gripping force per gripper jaw at 6 bar, closing	350 N
Max. force on gripper jaw Fz dynamic	38 N
Max. force on gripper jaw Fz static	380 N
Max. torque at gripper Mx dynamic	2.5 Nm
Max. torque at gripper Mx static	25 Nm
Max. torque at gripper My dynamic	2.5 Nm
Max. torque at gripper My static	25 Nm
Max. torque at gripper Mz dynamic	2.5 Nm
Max. torque at gripper Mz static	25 Nm
Product weight	1,369 g
Mounting type	Optional
	with through hole
	with internal (female) thread
Pneumatic connection	G1/8
Materials note	Free of copper and PTFE
Materials information for cover cap	PA
Materials information, housing	Wrought Aluminum alloy
	Hard anodized
Materials information for gripper jaws	High alloy steel, non-corrosive



## FESTO