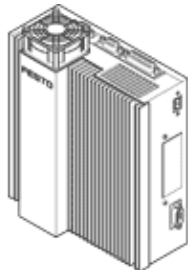


Motor controller SEC-AC-508/P01

Part number: 193847

FESTO

for servomotors, including documentation, software and plug set.
4000 VA for 400 V AC 3-phase mains connection.



Data sheet

Feature	Value
Mains filter	Integrated
Braking resistance	150 Ohm
Digital logic output characteristics	Electrically isolated Freely configurable to a given extent
Setpoint input impedance	20 kOhm
Braking resistance pulse power	3.2 kVA
Max. current, digital logic outputs	100 mA
Max. peak current duration	2 s
Max. intermediate circuit voltage, DC	680 V
Nominal operating voltage, AC	400 V
Nominal controller power	4,000 VA
Nominal DC voltage, logic power supply	24 V
Nominal current	8 A
Effective nominal current per phase	8 A
Line frequency	50 ... 60 Hz
Parameters configuring interface	RS232 (9600...57600 Bits/s) Parameters configuration and commissioning Control interface (PtP)
Nominal operating voltage, phases	Three-phase
Peak power	9,000 VA
Effective peak current per phase	16 A
Current consumption, logic power supply without clamping brake	0.45 A
Permissible range, logic voltage	± 20 %
Permissible voltage fluctuation	-15 % / +20 %
CE symbol (see declaration of conformity)	according to EU-EMV guideline
Storage temperature	-25 ... 60 °C
Protection class	IP20
Ambient temperature	0 ... 50 °C
Authorization	c UL us - Listed (OL)
Product weight	2,700 g
Number of analog monitor outputs	2
Number of analog set point inputs	2
Number of 24 V DC digital logic outputs	5
Number of digital logic inputs	10
Process interface	I/O coupling For 16 sets of travel commands
Logic input working range	12 ... 30 V
Monitor output working range	± 10 V
Setpoint input working range	± 10 V
Monitor output resolution	8 Bit
Encoder interface output, characteristics	Resolution: 1024 ppr
Encoder interface input, characteristics	3-phase encoding signals Resolution: 1024 ppr

Feature	Value
	RS422
Monitor output characteristics	Short-circuit proof
Setpoint input characteristics	Differential inputs Can be configured for speed in RPM Can be configured for current
Logic input characteristics	Electrically isolated Freely configurable
Encoder interface output, function	Actual value feedback via encoder signals in speed control mode Set point specification for downstream slave drive unit
Encoder interface input, function	Encoder signal, speed set point in RPM In synchronous operation as specified speed in RPM for the slave drive unit
Fieldbus coupling	No