

Motor controller CMMP-AS-C20-11A-P3

Part number: 1366842

FESTO

For servo motors.



Data sheet

Feature	Value
Mains filter	Integrated
Safety function	Safe Torque off (STO)
Safety Integrity Level (SIL)	Safe torque off (STO)/SIL 2
Performance level (PL)	Safe torque off (STO)/category 3, performance level d
Display	Seven-segment display
Output frequency	0 ... 1,000 Hz
Output voltage range AC	0 - 560 V
Braking resistance	47 Ohm
Digital logic output characteristics	Electrically isolated Freely configurable to a given extent
Braking resistance pulse power	12 kVA
Max. current, digital logic outputs	100 mA
Max. peak current duration	2 s
Max. intermediate circuit voltage, DC	760 V
Nominal output current	20 A
Nominal operating voltage, AC	400 V
Nominal controller power	12,000 VA
Nominal DC voltage, logic power supply	24 V
Nominal current	20 A
Line frequency	50 ... 60 Hz
Parameters configuring interface	Parameters configuration and commissioning Control interface (PtP) RS232 (9600...115000 Bits/s)
Nominal operating voltage, phases	Three-phase
Peak power	25,000 VA
Effective peak current per phase	41.5 A
Current consumption, logic power supply without clamping brake	1 A
Permissible range, logic voltage	± 20 %
Permissible voltage fluctuation	+/- 10 %
Certificate issuing department	DGUV MFS 10027
CE symbol (see declaration of conformity)	according to EU-EMV guideline according to EU machines guideline according to EU low voltage guideline
Storage temperature	-25 ... 70 °C
Protection class	IP20
Ambient temperature	0 ... 50 °C
Authorization	C-Tick
Product weight	8,000 g
Number of analog monitor outputs	2
Number of analog set point inputs	3
Number of 24 V DC digital logic outputs	5
Number of digital logic inputs	10
Communications profile	DS301/DSP402 FHPP

Feature	Value
Process interface	I/O coupling For 255 positioning records
Logic input working range	8 ... 30 V
Monitor output working range	± 10 V
Set point input working range	± 10 V
Monitor output resolution	9 Bit
Encoder interface output, characteristics	Resolution 16384 ppr
Encoder interface input, characteristics	RS422 EnDat 2.2
Monitor output characteristics	Short circuit proof
Set point input characteristics	Differential inputs Can be configured for speed in RPM Can be configured for current
Logic input characteristics	Electrically isolated Freely configurable
Encoder interface output, function	Actual value feedback via encoder signals in speed control mode Set point specification for downstream slave drive unit
Encoder interface input, function	Encoder signal, speed set point in RPM In synchronous operation as specified speed in RPM for the slave drive unit Setpoint position value as encoder signal
Bus connection	Plug 9-pin Sub-D
Fieldbus coupling	CANopen DeviceNet Ethernet Profibus DP Sercos
Max. fieldbus transmission speed	1 Mbit/s
Mounting type	On subbase Tightened
Materials note	Conforms to RoHS