

# Three-point gripper HGDD-35-A

Part number: 1163037

FESTO



## Data sheet

Feature	Value
Size	35
Stroke per gripper jaw	4 mm
Max. replacement accuracy	$\leq 0.2$ mm
Max. angular gripper jaw backlash ax,ay	$\leq 0.1$ deg
Max. gripper jaw backlash Sz	$\leq 0.05$ mm
Rotationally symmetrical	$\leq 0.2$ mm
Repetition accuracy, gripper	$\leq 0.03$ mm
Number of gripper fingers	3
Assembly position	Any
Mode of operation	double-acting
Gripper function	3-point
Design structure	Inclined plane guided motion sequence
Position detection	For proximity sensor
Total gripping force at 0.6 MPa (6 bar, 87 psi), opening	366 N
Total gripping force at 0.6 MPa (6 bar, 87 psi), closing	336 N
Working pressure	3 ... 8 bar
Working pressure, sealing air	0 ... 0.5 bar
Max. operating frequency of gripper	$\leq 4$ Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	44 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	52 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further operation)
Corrosion resistance classification CRC	2 - Moderate corrosion stress
PWIS conformity	VDMA24364-B2-L
Protection class	IP65
Ambient temperature	5 ... 60 °C
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) opening	122 N
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) closing	112 N
Mass moment of inertia	1.01 kgcm <sup>2</sup>
Max. force on gripper jaw Fz static	300 N
Max. torque at gripper Mx static	12 Nm
Max. torque at gripper My static	8 Nm
Max. torque at gripper Mz static	8 Nm
Lubrication interval for guide components	5 Mio SP
Max. mass per external gripper finger	57 g
Product weight	309 g
Mounting type	With through-hole and dowel pin With internal thread and dowel pin Optional
Pneumatic connection, sealing air	M3
Pneumatic connection	M5
Materials note	Conforms to RoHS
Material cover cap	High alloy steel, non-corrosive
Material housing	Smooth-anodised wrought aluminium alloy
Material gripper jaws	Steel, hardened