Servo motor
EMMT-...-40-

Part number: 8171399

Data sheet

Feature	Value
Ambient temperature	-40 °C...40 °C
Note on ambient temperature	Up to 80°C with derating of -2.25% per degree Celsius
Max. installation height	4000 m
Note on max. installation height	As of 1,000 m: only with derating of -1.0% per 100 m
Storage temperature	-40 °C...70 °C
Relative air humidity	0 - 90%
Conforms to standard	IEC 60034
Temperature class as per EN 60034-1	F
Max. winding temperature	155 °C
Rating class as per EN 60034-1	S1
Temperature monitoring	Digital motor temperature transmission via EnDat® 2.2 Dig. motor temp. via BiSS-C
Motor type to EN 60034-7	IM B5 IM V1 IM V3
Mounting position	optional
Degree of protection	IP40 IP65
Note on degree of protection	IP40 for motor shaft without rotary shaft seal IP65 for motor shaft with rotary shaft seal
Concentricity, coaxiality, axial runout to DIN SPEC 42955	N
Balance quality	G 2.5
Detent torque	<1.0% of peak torque
Bearing lifetime under nominal conditions	20000 h
Featherkey shaft type	DIN 6885 A 3 x 3 x 12
Interface code, motor out	40P
Electrical connection 1, connection type	Hybrid plug
Electrical connection 1, connector system	M17x0.75 M23x1
Electrical connection 1, number of connections/cores	12
Pollution degree	2
Note on materials	RoHS-compliant

Feature	Value
Corrosion resistance class CRC	0 - No corrosion stress
LABS (PWIS) conformity	VDMA24364 zone III
Vibration resistance	Transport application test with severity level 2 to FN 942017-4 and EN 60068-2-6
Shock resistance	Shock test with severity level 2 to FN 942017-5 and EN 60068-2-27
Approval	RCM trademark German Technical Control Board (TÜV) c UL us - Recognized (OL)
CE mark (see declaration of conformity)	To EU EMC Directive To EU Low Voltage Directive In accordance with EU RoHS Directive
UKCA marking (see declaration of conformity)	To UK instructions for EMC To UK RoHS instructions To UK regulations for electrical equipment
Certificate issuing authority	TÜV 968/INS 464.00/24 UL E342973
Nominal operating voltage DC	48 V...325 V
Type of winding switch	Star inside
Number of pole pairs	5
Standstill torque	0.24 Nm...0.75 Nm
Nominal torque	0.21 Nm...0.69 Nm
Peak torque	0.83 Nm...2 Nm
Nominal rotary speed	3000 rpm...7000 rpm
Max. rotational speed	5760 rpm...15600 rpm
Angular acceleration	100000 rad/s²
Nominal power rating of motor	96 W...234 W
Continuous stall current	1.3 A...8.6 A
Nominal motor current	1 A...8.1 A
Peak current	5.4 A...20 A
Motor constant	0.055 Nm/A...0.33 Nm/A
Standstill torque constant	0.06 Nm/A...0.42 Nm/A
Voltage constant, phase-to-phase	3.6 mVmin...25.4 mVmin
Phase-phase winding resistance	0.41 Ohm...13.1 Ohm
Phase-phase winding inductance	0.57 mH...13.9 mH
Winding longitudinal inductivity Ld (phase)	0.22 mH...5.3 mH
Winding cross inductivity Lq (phase)	0.29 mH...6.9 mH
Electric time constant	0.82 ms...1.39 ms
Thermal time constant	4.6 min...21.4 min
Thermal resistance	1.05 K/W...1.58 K/W
Measuring flange	200 x 200 x 15 mm, steel
Total mass moment of inertia of output	0.039 kgcm²...0.138 kgcm²
Product weight	500 g...1200 g
Permissible axial shaft load	30 N
Permissible radial shaft load	150 N
Rotor position sensor	Absolute single-turn encoder Absolute multi-turn encoder
rotor position sensor, manufacturer designation	ECI 1119 EQI 1131 Festo iC-MHM KCD-BC33B-1617-JP4F-GRQ-009
rotor position sensor, absolute detectable revolutions	1 ...4096
Rotor position encoder interface	BiSS-C EnDat® 22
Rotor position sensor, encoder measuring principle	Magnetic Inductive
rotor position sensor, DC operating voltage	5 V
rotor position sensor, DC operating voltage range	3.6 V...14 V

Feature	Value
rotor position sensor, position values per revolution	65536 ...524288
Rotor position transducer resolution	16 bit...19 bit
Brake holding torque	0.45 Nm
Operating voltage DC for brake	24 V
Power consumption, brake	8.2 W
Number of emergency stops per hour	1
Mass moment of inertia of brake	0.0058 kgcm²
Switching cycles holding brake	10 million idle actuations (without friction work!)
Mean time to failure (MTTF), subcomponent	190 years, rotor position sensor