Radial gripper DHRC-10-A-S-NO Part number: 8133559





Data sheet

| Feature | Value |
|--|--|
| Size | 10 |
| Max. replacement accuracy | 0.2 mm |
| Max. opening angle | 180 deg |
| Rotationally symmetrical | 0.2 mm |
| Repetition accuracy, gripper | 0.1 mm |
| Number of gripper jaws | 2 |
| Drive system | Pneumatic |
| Mounting position | optional |
| Mode of operation | Single-acting Open |
| Gripper function | Radial |
| Gripper force back-up | During opening |
| Design | Connection direction at side Force pilot operated motion sequence |
| Position detection | Via proximity switch |
| Operating pressure | 0.2 MPa0.8 MPa 2 bar8 bar 29 psi116 psi |
| Max. operating frequency of gripper | 3 Hz |
| Min. opening time at 0.6 MPa (6 bar, 87 psi) | 53 ms |
| Min. closing time at 0.6 MPa (6 bar, 87 psi) | 26 ms |
| Operating medium | Compressed air to ISO 8573-1:2010 [7:4:4] |
| Note on operating and pilot medium | Lubricated operation possible (in which case lubricated operation will always be required) |
| Corrosion resistance class CRC | 0 - No corrosion stress |
| LABS (PWIS) conformity | VDMA24364-B2-L |
| Ambient temperature | -10 °C60 °C |
| Total gripper torque, closing, 0.6 MPa (6 bar, 87 psi) | 15.8 Ncm |
| Mass moment of inertia | 0.044 kgcm² |
| Max. force on gripper jaw Fz static | 35 N |
| Max. torque at gripper Mx static | 0.5 Nm |
| Max. torque at gripper My static | 0.5 Nm |
| Max. torque at gripper Mz static | 0.5 Nm |

| Feature | Value |
|-----------------------|--|
| Product weight | 59.5 g |
| Type of mounting | Direct mounting via through-hole Direct mounting via thread Via through-hole and dowel pin Via female thread and dowel pin Either: |
| Pneumatic connection | M3 |
| Note on materials | RoHS-compliant |
| Material cover cap | Wrought aluminium alloy, anodised |
| Material housing | Anodised wrought aluminium alloy |
| Material gripper jaws | High-alloy steel |