Parallel gripper DHPC-...-6-A-Part number: 8116728

FESTO



Data sheet

| Feature | Value |
|--|---|
| Size | 6 |
| Stroke per gripper jaws | 2 mm |
| Max. replacement accuracy | 0.2 mm |
| Max. angular gripper jaw backlash ax, ay | 0 deg |
| Max. gripper jaw backlash Sz | 0 mm |
| Rotationally symmetrical | 0.2 mm |
| Repetition accuracy, gripper | 0.02 mm |
| Number of gripper jaws | 2 |
| Drive system | Pneumatic |
| Mounting position | optional |
| Mode of operation | Double-acting Single-acting Closed Open |
| Gripper function | Parallel |
| Gripper force back-up | None |
| Design | Connection via mounting spigot Connection direction at side Connection direction downwards Flat mounting method for gripper fingers Lever Side mounting method for gripper fingers Standard mounting method for gripper fingers Force pilot operated motion sequence |
| Guide | Ball guide |
| Position detection | Via proximity switch |
| Variants | Metals with copper, zinc or nickel by mass as main constituent are excluded from use. Exceptions are nickel in steel, chemically nickel- plated surfaces, printed circuit boards, cables, electrical plug connectors and coils. |
| Operating pressure | 0.15 MPa0.8 MPa 1.5 bar8 bar 21.75 psi116 psi |
| Max. operating frequency of gripper | 3 Hz |
| Min. opening time at 0.6 MPa (6 bar, 87 psi) | 8 ms19 ms |
| Min. closing time at 0.6 MPa (6 bar, 87 psi) | 8 ms19 ms |

| Feature | Value |
|---|--|
| Operating medium | Compressed air to ISO 8573-1:2010 [7:4:4] |
| Note on operating and pilot medium | Lubricated operation possible (in which case lubricated operation will always be required) |
| Corrosion resistance class CRC | 0 - No corrosion stress |
| LABS (PWIS) conformity | VDMA24364-B2-L |
| Suitability for the production of Li-ion batteries | Product corresponds to the internal product definition from Festo for use in battery production:Metals with more than 1% by mass of copper, zinc or nickel are excluded from use.The exceptions are nickel in steel, chemically nickel-plated surfaces, printed circuit boards, cables, electrical plug connectors and coils |
| Ambient temperature | -10 °C60 °C |
| Total gripping force, opening, 0.6MPa (6bar, 87 psi) | 10.4 N14.6 N |
| Total gripping force, closing, 0.6MPa (6bar, 87 psi) | 7.8 N11 N |
| Gripper force per gripper jaw, opening, 0.6 MPa (6 bar, 87 psi) | 5.2 N7.3 N |
| Gripper force per gripper jaw, closing, 0.6 MPa (6 bar, 87 psi) | 3.9 N5.5 N |
| Mass moment of inertia | 0.011 kgcm ² 0.013 kgcm ² |
| Max. force on gripper jaw Fz static | 22 N |
| Max. torque at gripper Mx static | 0.24 Nm |
| Max. torque at gripper My static | 0.11 Nm |
| Max. torque at gripper Mz static | 0.11 Nm |
| Product weight | 25 g31 g |
| Type of mounting | Direct mounting via through-hole Direct mounting via thread On mounting frame Either: |
| Pneumatic connection | M3 M5 |
| Note on materials | RoHS-compliant |
| Material housing | Anodised aluminium |
| Material gripper jaws | High-alloy stainless steel |