



Data sheet

Feature	Value	
Size	16	
Stroke per gripper jaws	10 mm	
Max. replacement accuracy	0.2 mm	
Max. angular gripper jaw backlash ax, ay	0.4 deg	
Max. gripper jaw backlash Sz	0.05 mm	
Rotationally symmetrical	0.2 mm	
Repetition accuracy, gripper	0.03 mm	
Number of gripper jaws	2	
Drive system	Electrical	
Mounting position	optional	
Gripper function	Parallel	
Design	Worm gear unit T-shape Rack and pinion Electric gripper	
Conforms to standard	IEC 61010-1	
Guide	Plain-bearing guide	
Position detection	Via proximity switch	
Type of motor	DC servo motor	
Operator controls	Latched switch	
Ready status indication	LED	
Max. cycle frequency	1.1 Hz	
Max. mass per external gripper finger	100 g	
Max. current consumption	1 A	
Nominal operating voltage DC	24 V	
Permissible voltage fluctuations	+/- 10 %	
Approval	RCM trademark	
KC mark	KC-EMV	
CE mark (see declaration of conformity)	To EU EMC Directive In accordance with EU RoHS Directive	
UKCA marking (see declaration of conformity)	To UK instructions for EMC To UK RoHS instructions	
Corrosion resistance class CRC	1 - Low corrosion stress	

Feature	Value
LABS (PWIS) conformity	VDMA24364-B2-L
Suitability for the production of Li-ion batteries	Metals with more than 5% by mass of copper are excluded from use. Exceptions are printed circuit boards, cables, electrical plug connectors and coils
Sound pressure level	70 dB(A)
Degree of protection	IP40
Ambient temperature	5 °C60 °C
Total gripping force	154 N
Mass moment of inertia	0.78 kgcm ²
Max. force on gripper jaw Fz static	200 N
Max. torque at gripper Mx static	7 Nm
Max. torque at gripper My static	4.4 Nm
Max. torque at gripper Mz static	7 Nm
Lubrication interval for guide components	2 MioCyc
Product weight	296 g
Electrical connection	5-pin Cable with plug M12x1
Type of mounting	Via female thread and centring sleeve Via through-hole and centring sleeve Either:
Note on materials	RoHS-compliant
Material housing	Anodised aluminium
Material gripper jaws	High-alloy stainless steel