Radial gripper DHRC

Characteristics

At a glance Link dhrc

- Lateral gripper jaw support for high torque loads
- Gripper jaw centring options
- Max. repetition accuracy
- Proximity switch for sensing the piston position in the end positions and position transmitter for sensing the piston position at any point
- Wide range of adaptation options on the drives
- Flexible application options: can be used as a double- and single-acting gripper

These grippers are not designed for the following or similar application examples:
- Machining
- Aggressive media
- Grinding dust
- Welding spatter

Engineering tools Link engineering tools

Save time with engineering tools: Smart engineering for the optimal solution. Our goal is to increase your productivity. Our engineering tools play an integral part in achieving this goal. They help you size your system correctly, tap into unimagined productivity reserves and generate additional productivity along the entire value chain. In every phase of your project, from the initial contact to the modernisation of your machine, you will come across a number of different tools that will be of use to you.

Gripper selection:
- This tool helps you to select the right grippers by simply entering the exact parameters for your application

Diagrams Link dhrc

The diagrams shown in this document are also available online. These can be used to display precise values.

Position sensing

[A]	For proximity sensor

By using proximity switches, any position can be detected.

Gripper function

[_]	Double-acting

Opening or closing by applying compressed air

[S]	Single-acting, open

Open when depressurised. Closed when pressurised with compressed air

Gripping force backup

[NO]	Opening

Opened by spring force in depressurised state

Type code

001	Series	
DHRC	Radial gripper	

002	Size [mm]	
6	6	
10	10	
16	16	
20	20	
25	25	
32	32	

003	Position sensing	
A	For proximity sensor	

004	Gripper function	
	Double-acting	
S	Single-acting, open	

005	Gripping force backup	
	None	
NO	Opening	

Datasheet

General technical data

Size	6	10	16	20	25	32
Design	Connection direction at side Force pilot operated motion sequence					
Mode of operation	Double-acting	Double-acting Single-acting Open				
Gripper function	Radial					
Number of gripper jaws	2					
Max. opening angle	180 deg					
Pneumatic connection	M3			M5		
Repetition accuracy, gripper [1]	≤0.1 mm					
Rotationally symmetrical	–	≤0.2 mm				
Max. replacement accuracy	≤0.2 mm					
Max. operating frequency of gripper	≤3 Hz		≤2 Hz			
Position detection	Via proximity switch					
Type of mounting	Either: Direct mounting via through-hole Direct mounting via thread	Either: Direct mounting via through-hole Direct mounting via thread Via through-hole and dowel pin Via female thread and dowel pin				
Mounting position	optional					

1) Under constant exposure to operating conditions, end-position drift occurs in the direction of movement of the gripper jaws, at 100 consecutive strokes

Operating and environmental conditions

Size	6	10	16	20	25	32
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]					
Note on operating and pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)					
Ambient temperature [1]	-10 ... 60°C					
Corrosion resistance class CRC [2]	0 - No corrosion stress					

1) Note the operating range of the proximity switches

2) More information www.festo.com/x/topic/crc

Operating pressure – DHRC-...

Size	6	10	16	20	25	32
Operating pressure	0.25 ... 0.8 MPa	0.1 ... 0.8 MPa				
Operating pressure	36.25 ... 116 psi	14.5 ... 116 psi				
Operating pressure	2.5 ... 8 bar	1 ... 8 bar				

Operating pressure – DHRC-...-NO

Size	10	16	20	25	32
Operating pressure	0.2 ... 0.8 MPa		0.15 ... 0.8 MPa		
Operating pressure	29 ... 116 psi		21.75 ... 116 psi		
Operating pressure	2 ... 8 bar		1.5 ... 8 bar		

Weight – DHRC-...

Size	6	10	16	20	25	32
Product weight	24.5 g	54 g	111 g	218.4 g	438.5 g	716.5 g

Weight – DHRC-...-NO

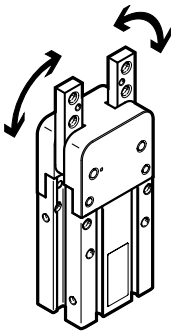
Size	10	16	20	25	32
Product weight	59.5 g	112.5 g	220 g	440 g	720.5 g

Datasheet

Materials

Size	6	10	16	20	25	32
Material housing	Anodised wrought aluminium alloy					
Material gripper jaws	High-alloy steel					
Material cover cap	Wrought aluminium alloy, anodised					
Note on materials	RoHS-compliant					
LABS (PWIS) conformity	VDMA24364-B2-L					
Suitability for the production of Li-ion batteries	Suitable for battery production with reduced Cu/Zn/Ni values (F1a)					

Total gripping torque



The gripping torque is not constant across the opening angle.

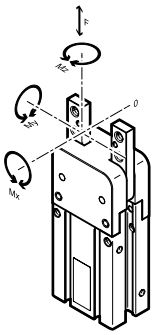
Total gripping torque – DHRC-...

Size	6	10	16	20	25	32
Total gripping torque at 0.6 MPa (6 bar, 87 psi), opening	6.7 Ncm	25.3 Ncm	81.1 Ncm	166.2 Ncm	343.6 Ncm	725.6 Ncm
Total gripper torque, closing, 0.6 MPa (6 bar, 87 psi)	4.8 Ncm	20.4 Ncm	66.8 Ncm	134.3 Ncm	277.5 Ncm	600.1 Ncm

Total gripping torque – DHRC-...-NO

Size	10	16	20	25	32
Total gripper torque, closing, 0.6 MPa (6 bar, 87 psi)	15.8 Ncm	50.3 Ncm	112 Ncm	239.5 Ncm	539.1 Ncm

Characteristic load values at the gripper jaws



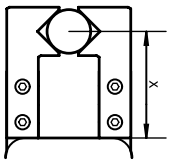
The indicated permissible forces and torques apply to a single gripper jaw. They include the lever arm, additional applied loads created by the workpiece or external gripper fingers and acceleration forces occurring during movement. The zero coordinate line (gripper jaw guide) must be taken into account when calculating torques.

Datasheet

Characteristic load values at the gripper jaws

Size	6	10	16	20	25	32
Max. force on gripper jaw Fz static	12 N	35 N	60 N	100 N	140 N	210 N
Max. torque at gripper Mx static	0.3 Nm	0.5 Nm	2 Nm	4 Nm	7 Nm	12 Nm
Max. torque at gripper My static	0.3 Nm	0.5 Nm	1 Nm	2 Nm	4 Nm	8 Nm
Max. torque at gripper Mz static	0.3 Nm	0.5 Nm	2 Nm	4 Nm	7 Nm	12 Nm

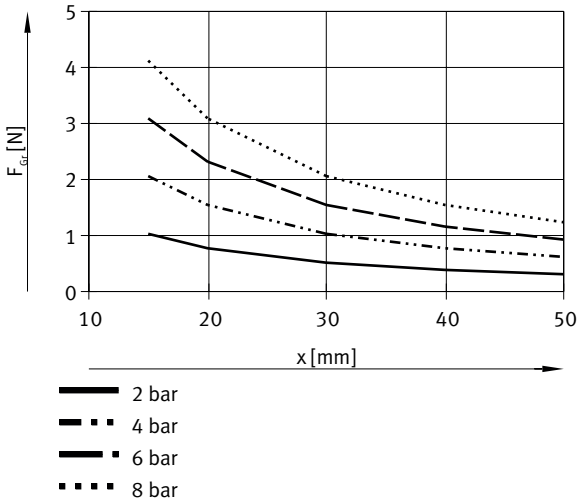
Gripping force F per gripper jaw as a function of operating pressure and lever arm x



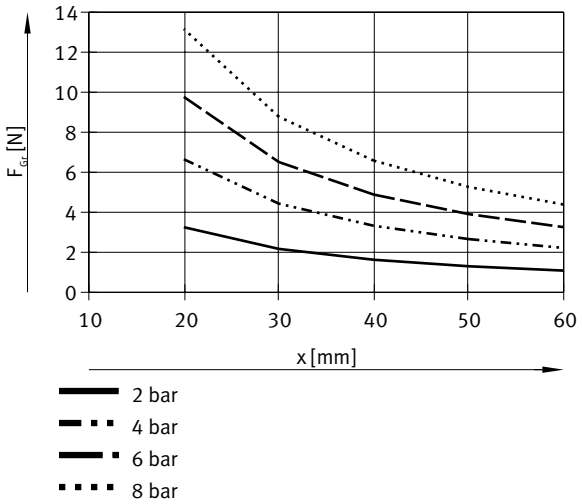
The gripping forces as a function of operating pressure and lever arm can be determined from the following graphs.
The gripping torque is not constant across the opening angle.

Sizing software for gripper selection → https://www.festo.com/x/topic/eng

Gripping force F per gripper jaw as a function of operating pressure and lever arm x – External gripping (closing), double-acting – DHRC-6-A

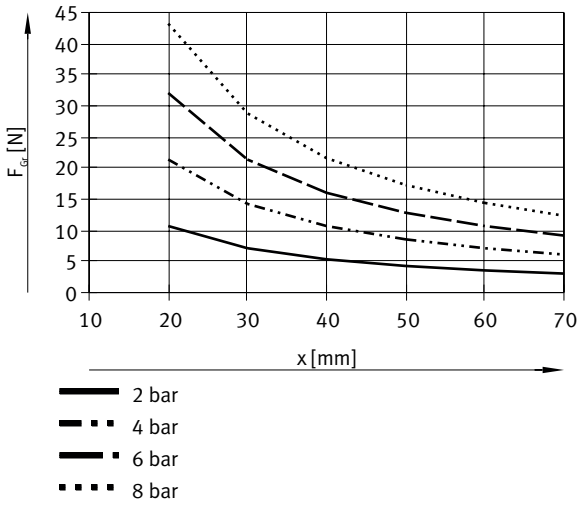


Gripping force F per gripper jaw as a function of operating pressure and lever arm x – External gripping (closing), double-acting – DHRC-10-A

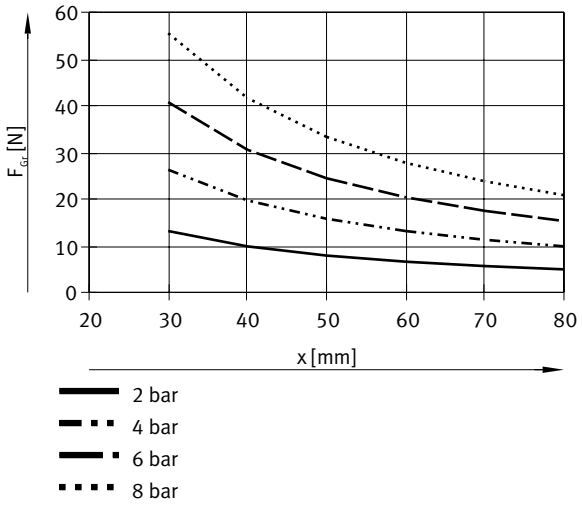


Datasheet

Gripping force F per gripper jaw as a function of operating pressure and lever arm x – External gripping (closing), double-acting – DHRC-16-A

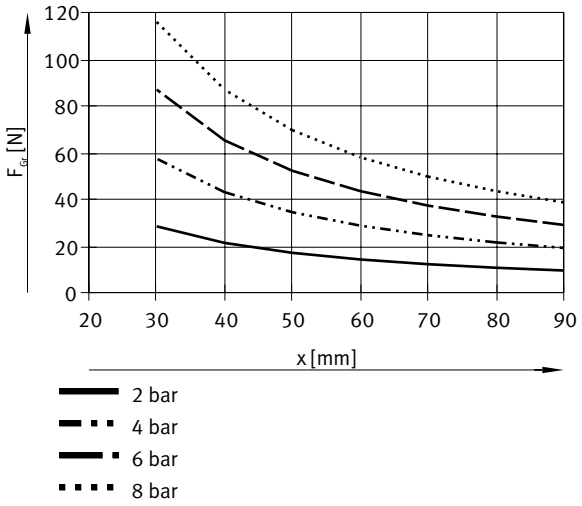


Gripping force F per gripper jaw as a function of operating pressure and lever arm x – External gripping (closing), double-acting – DHRC-20-A

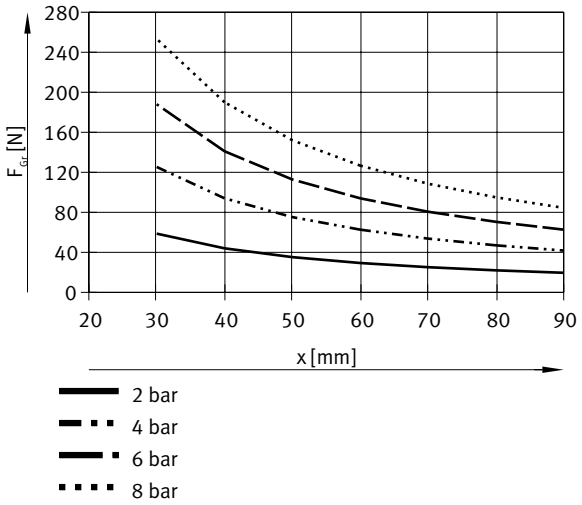


Datasheet

Gripping force F per gripper jaw as a function of operating pressure and lever arm x – External gripping (closing), double-acting – DHRC-25-A

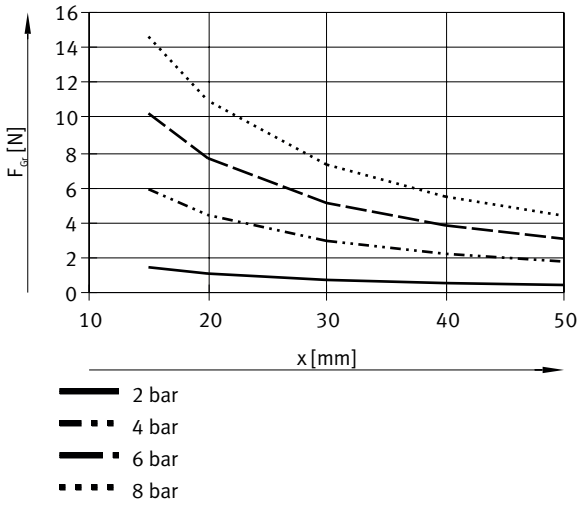


Gripping force F per gripper jaw as a function of operating pressure and lever arm x – External gripping (closing), double-acting – DHRC-32-A

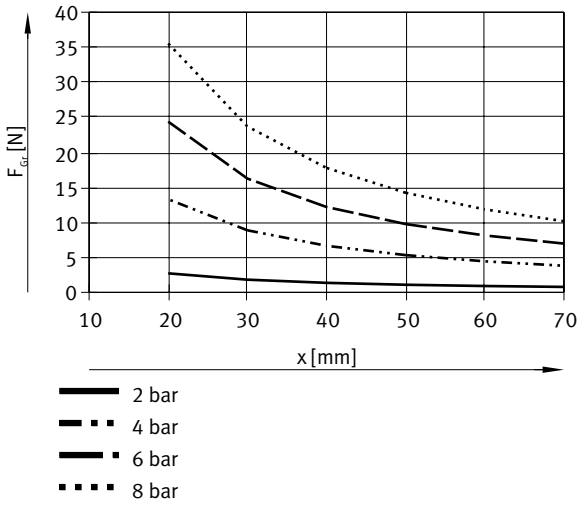


Datasheet

Gripping force F per gripper jaw as a function of operating pressure and lever arm x – External gripping (closing), single-acting – DHRC-10-A-S-NO

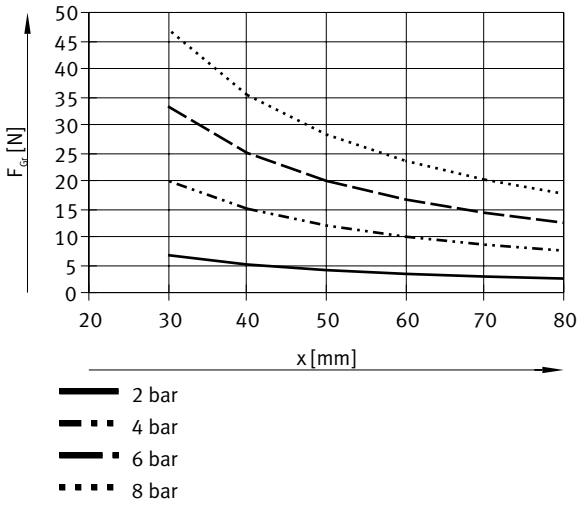


Gripping force F per gripper jaw as a function of operating pressure and lever arm x – External gripping (closing), single-acting – DHRC-16-A-S-NO

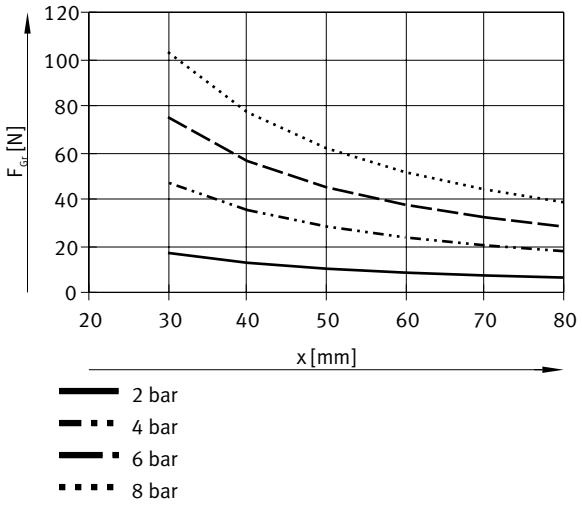


Datasheet

Gripping force F per gripper jaw as a function of operating pressure and lever arm x – External gripping (closing), single-acting – DHRC-20-A-S-NO

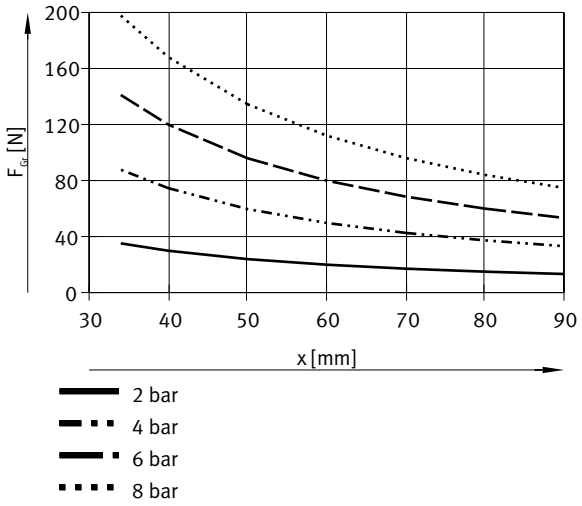


Gripping force F per gripper jaw as a function of operating pressure and lever arm x – External gripping (closing), single-acting – DHRC-25-A-S-NO

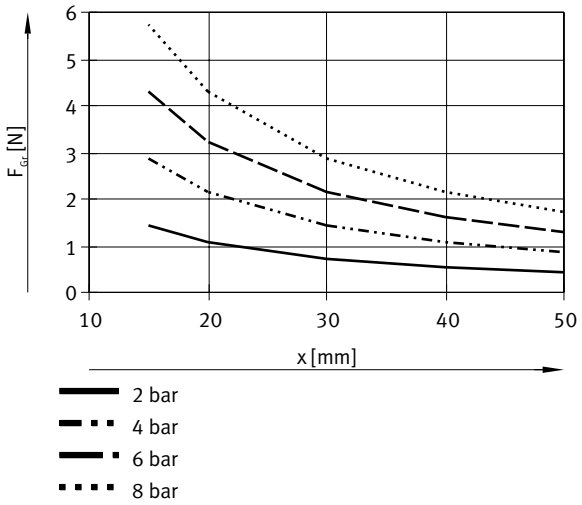


Datasheet

Gripping force F per gripper jaw as a function of operating pressure and lever arm x – External gripping (closing), single-acting – DHRC-32-A-S-NO

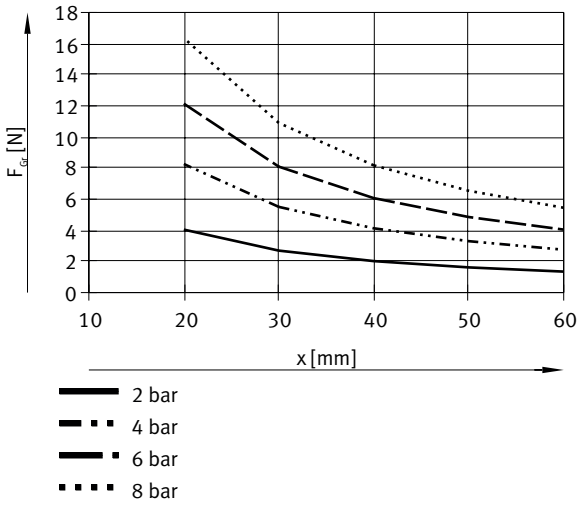


Gripping force F per gripper jaw as a function of operating pressure and lever arm x – Internal gripping (opening), double-acting – DHRC-6-A

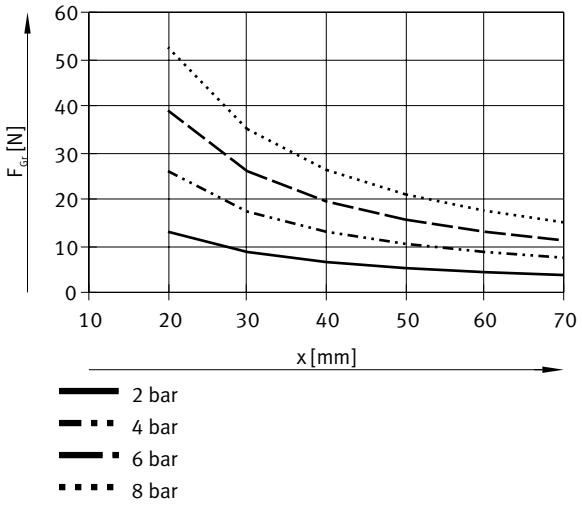


Datasheet

Gripping force F per gripper jaw as a function of operating pressure and lever arm x – Internal gripping (opening), double-acting – DHRC-10-A

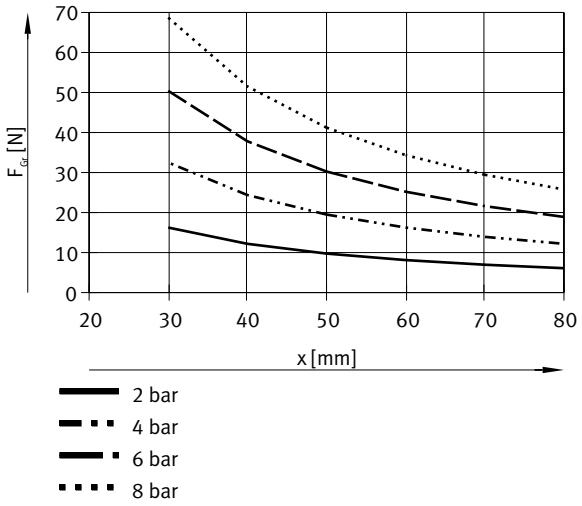


Gripping force F per gripper jaw as a function of operating pressure and lever arm x – Internal gripping (opening), double-acting – DHRC-16-A

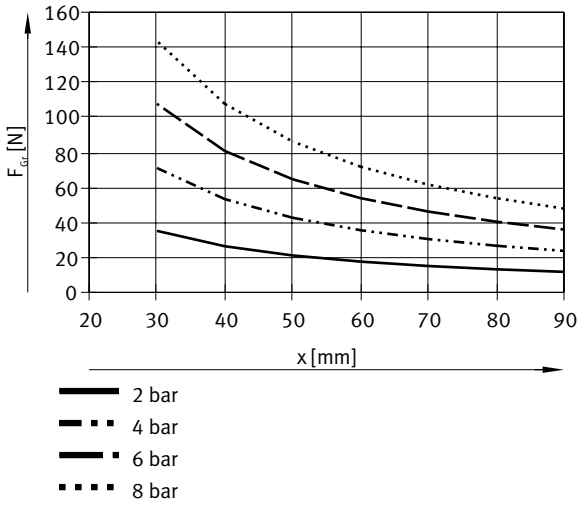


Datasheet

Gripping force F per gripper jaw as a function of operating pressure and lever arm x – Internal gripping (opening), double-acting – DHRC-20-A

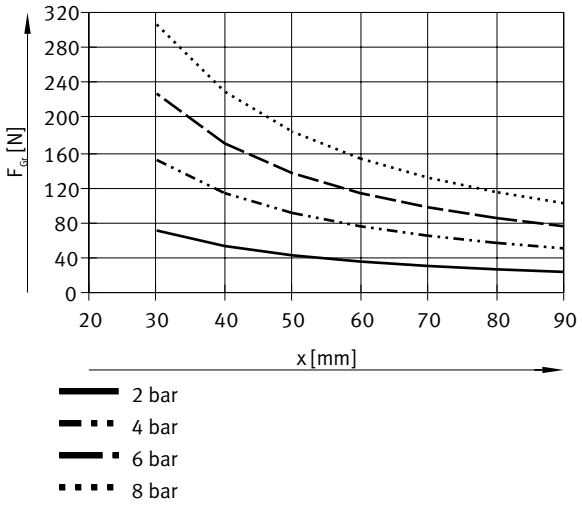


Gripping force F per gripper jaw as a function of operating pressure and lever arm x – Internal gripping (opening), double-acting – DHRC-25-A

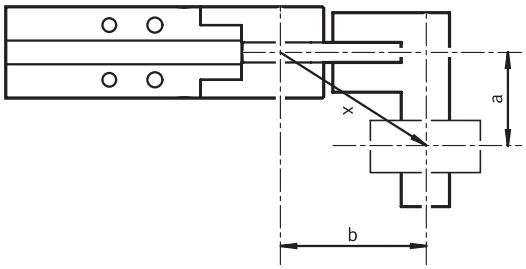


Datasheet

Gripping force F per gripper jaw as a function of operating pressure and lever arm x – Internal gripping (opening), double-acting – DHRC-32-A



Gripping force F per gripper jaw at 0.6 MPa (6 bar, 87 psi) as a function of lever arm x and eccentricity a and b



Gripping force F per gripper jaw at 0.6 MPa (6 bar, 87 psi) as a function of lever arm x and eccentricity a and b

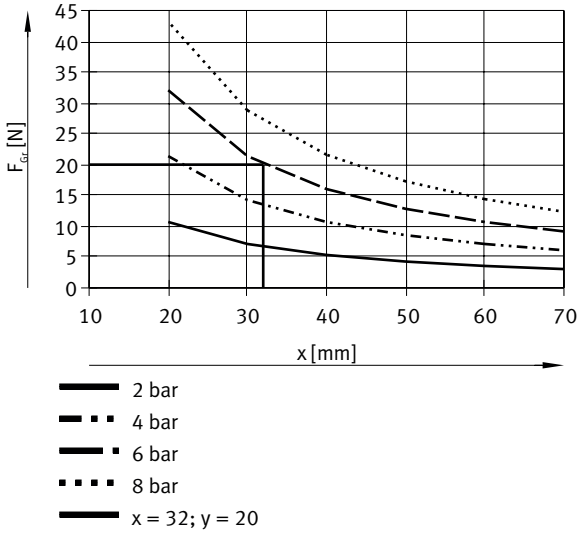
$x = \sqrt{a^2 + b^2} = \sqrt{20^2 + 25^2} = 32$ mm

The formula (on the left) must be used to calculate the lever arm x with eccentric gripping.
The gripping force F can then be read from the graphs using the calculated value x.

Calculation example:
Assuming:
Distance a = 20 mm
Distance b = 25 mm
To be determined:
The gripping force at 6 bar, with a DHRC-16-A, used as an external gripper.

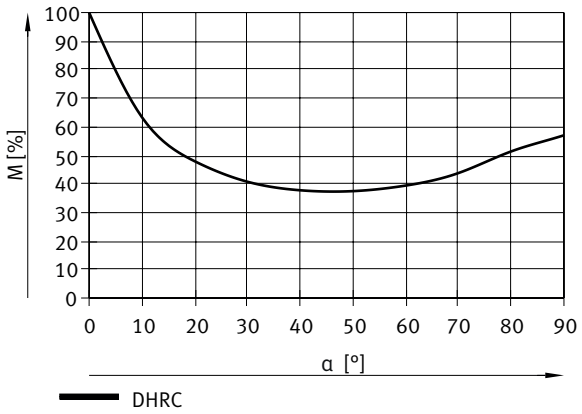
Datasheet

Gripping force F per gripper jaw at 0.6 MPa (6 bar, 87 psi) as a function of lever arm x and eccentricity a and b



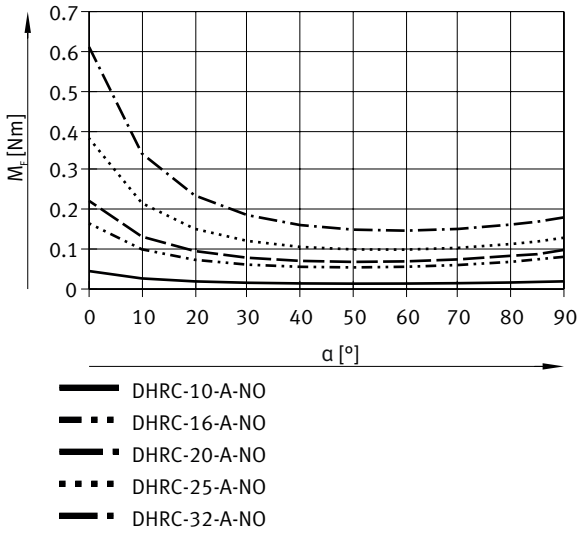
The graph gives a value of F = 20 N for the gripping force.

Torque curve M as a function of opening angle



The drive principle of the gripper jaws means that the torque is not constant across the opening angle. The percentage available in each case can be calculated in the graph.
Opening angle of 0° means: parallel gripper jaw position.

Spring moment M as a function of the opening angle



Calculation of the actual gripping torques M for DHRC-...-S-NO as a function of the application:

The gripper with integrated spring, DHRC-..-S.-NO (opening), can be used as a single-acting gripper.

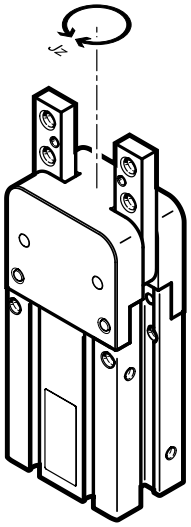
To calculate the available gripping torque MGrtotal (per gripper jaw), the data from the graphs for the gripping force FGr, the torque curve M and the spring torque MF must be combined accordingly.

MGr = FGr * x * M [%]

MGr = Gripping torque
FGr = Gripping force
x = Lever arm
M = Torque curve

Datasheet

Mass moments of inertia



Mass moment of inertia of the gripper in relation to the central axis, without external gripper fingers, with no load.

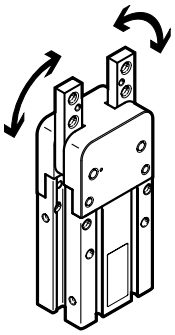
Mass moments of inertia – DHRC-...

Size	6	10	16	20	25	32
Mass moment of inertia	0.01 kgcm2	0.04 kgcm2	0.132 kgcm2	0.292 kgcm2	1.311 kgcm2	3.105 kgcm2

Mass moments of inertia – DHRC-...-NO

Size	10	16	20	25	32
Mass moment of inertia	0.044 kgcm2	0.134 kgcm2	0.294 kgcm2	1.316 kgcm2	3.122 kgcm2

Opening and closing times



The indicated opening and closing times [ms] were measured at room temperature at an operating pressure of 0.6 MPa (6 bar, 87 psi) with a horizontally mounted gripper and without additional gripper fingers (mean values shown).
The grippers must be throttled for larger applied loads. Opening and closing times must then be adjusted accordingly.

Opening and closing times – DHRC-...

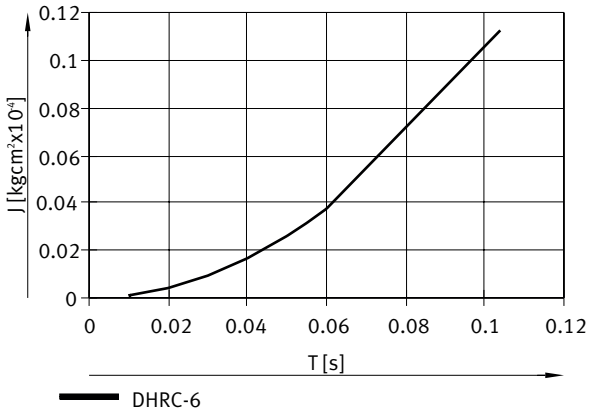
Size	6	10	16	20	25	32
Min. opening time at 0.6 MPa (6 bar, 87 psi)	10 ms	28 ms	37 ms	44 ms	90 ms	117 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	19 ms	43 ms	53 ms	57 ms	117 ms	129 ms

Opening and closing times – DHRC-...-NO

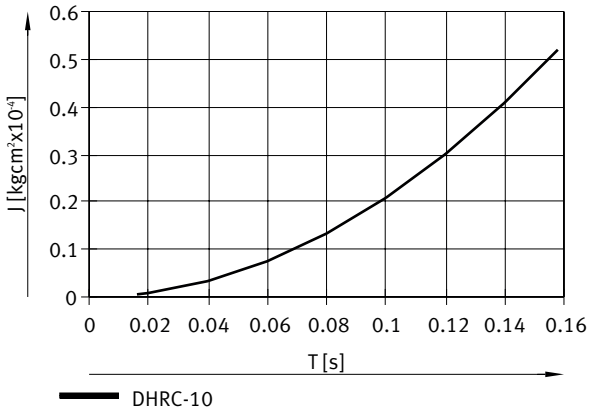
Size	10	16	20	25	32
Min. opening time at 0.6 MPa (6 bar, 87 psi)	53 ms	42 ms	73 ms	147 ms	229 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	26 ms	21 ms	32 ms	45 ms	65 ms

Datasheet

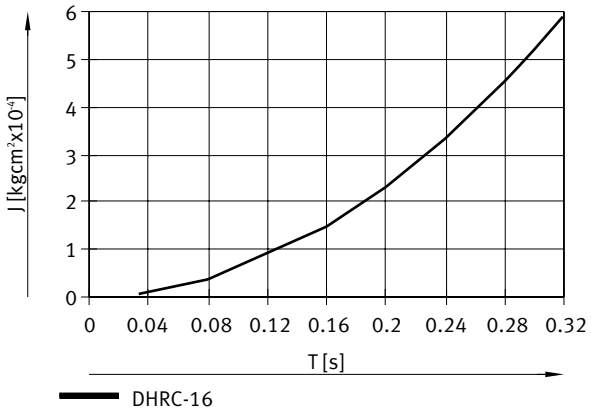
Opening and closing times T to be set at 0.6 MPa (6 bar, 87 psi) as a function of mass moment of inertia of the gripper fingers – DHRC-6



Opening and closing times T to be set at 0.6 MPa (6 bar, 87 psi) as a function of mass moment of inertia of the gripper fingers – DHRC-10

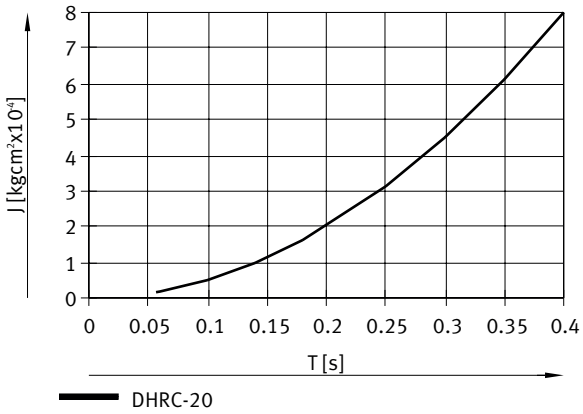


Opening and closing times T to be set at 0.6 MPa (6 bar, 87 psi) as a function of mass moment of inertia of the gripper fingers – DHRC-16

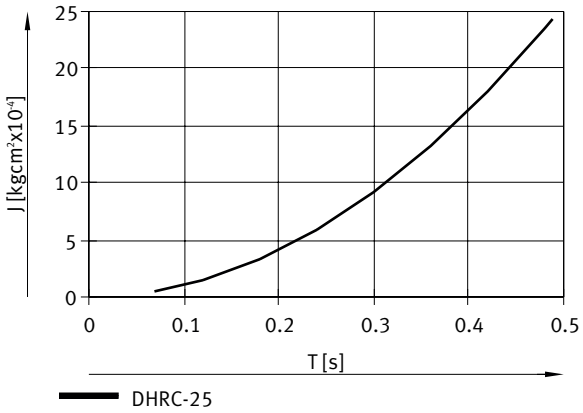


Datasheet

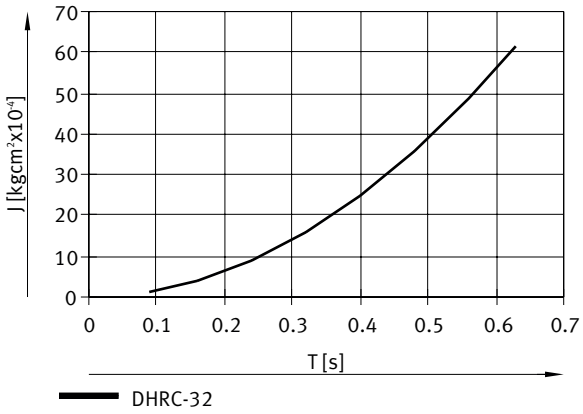
Opening and closing times T to be set at 0.6 MPa (6 bar, 87 psi) as a function of mass moment of inertia of the gripper fingers – DHRC-20



Opening and closing times T to be set at 0.6 MPa (6 bar, 87 psi) as a function of mass moment of inertia of the gripper fingers – DHRC-25

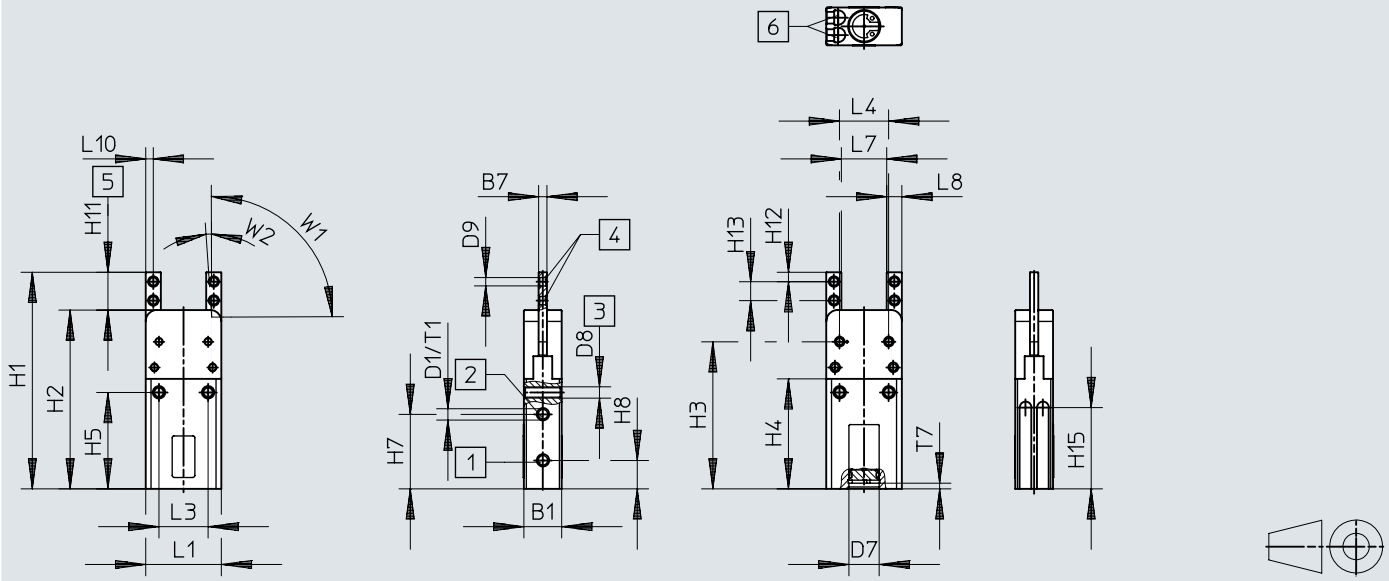


Opening and closing times T to be set at 0.6 MPa (6 bar, 87 psi) as a function of mass moment of inertia of the gripper fingers – DHRC-32



Dimensions

Dimensions – DHRC-6 Download CAD data www.festo.com



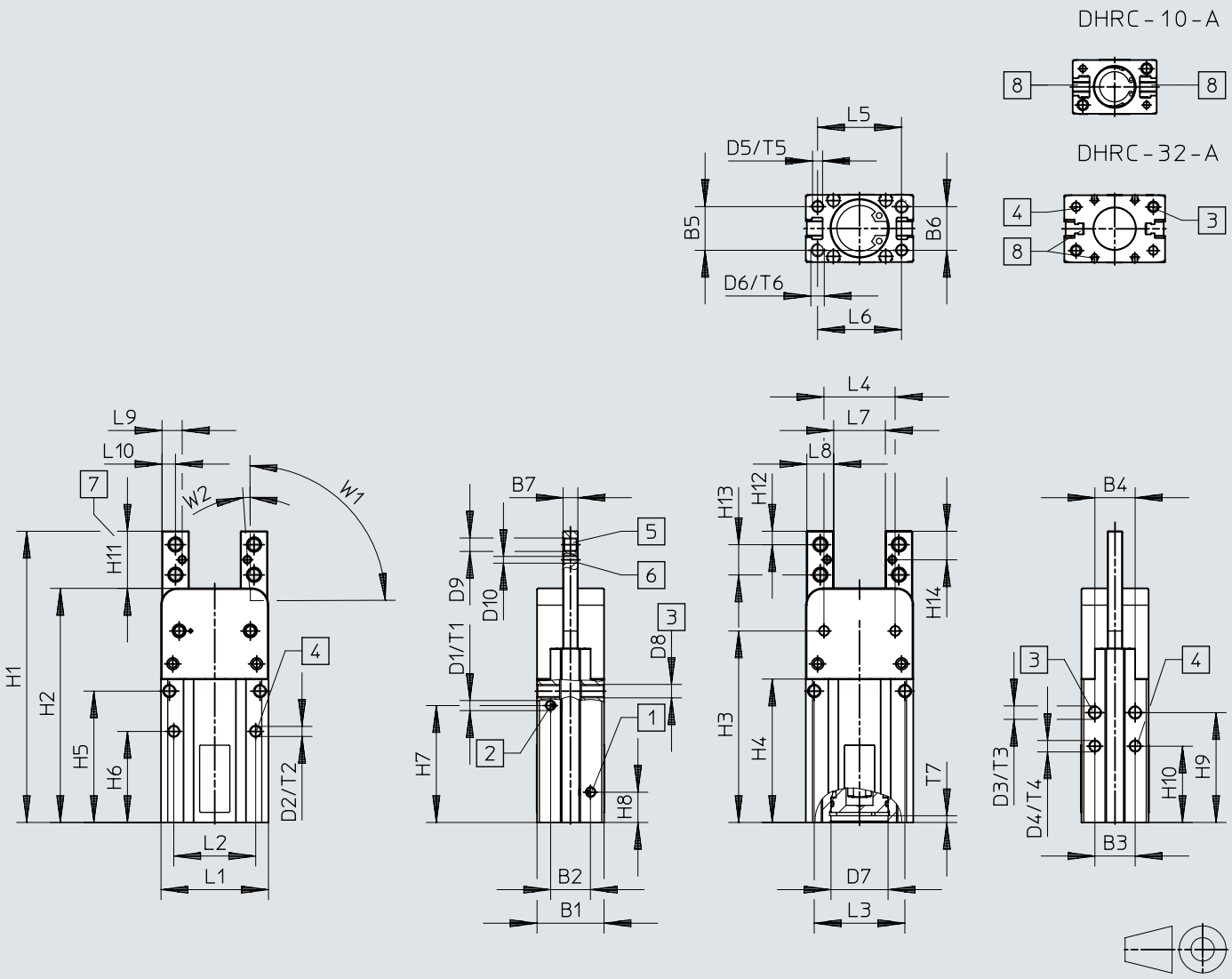
[1] Open pneumatic connection
[2] Close pneumatic connection
[3] Threaded hole for mounting the gripper
[4] Threaded hole for mounting gripper fingers
[5] Area for mounting gripper fingers
[6] C-slot for proximity switch

	B1 +0,3	B7 –0,01 –0,05	D1	D7 ø H8	D8	D9	H1	H2	H3	H4	H5	H7	H8	H11 –0,2
DHRC-6-A	10	2,2	M3	8	M3	$2,2^{+0,1}$	57,3	47,3	38,9	29,1	25,5	19,7	7,5	10

	H12 –0,2	H13	H15	L1 +0,3	L3	L4	L7 –0,4	L8 –0,4	L10 +0,025 –0,225	T1	T7	W1 ±2°	W2 +3°
DHRC-6-A	2,5	5	21,5	20	13	13	12	4	2	4,5	1,5	90°	2°

Dimensions

Dimensions – DHRC-10 ... 32 Download CAD data www.festo.com



[1] Open pneumatic connection
[2] Close pneumatic connection
[3] Threaded hole for mounting the gripper
[4] Centring holes
[5] Threaded hole for mounting gripper fingers
[6] Area for mounting gripper fingers
[7] DHRC-10: T-slot for proximity switches, DHRC-16 ... 32: Round slot and T-slot for proximity switches

Dimensions

	B1 +0,3	B2	B3 ±0,02	B4	B5	B6 ±0,02	B7 −0,01 −0,05	D1	D2 ø H9	D3	D4 ø H9	D5 ø H9	D6	D7 ø H8	D8	D9	D10 ø +0,02
DHRC-10-A	16	10,8	10,8	10,8	10,8	10,8	3	M3	2	M3	2	2	M3	12	M3	$3,2^{+0,1}$	2
DHRC-10-A-S-NO																	
DHRC-16-A	20	11,9	12	12	13	13	4,4		3	M4	3	3	M4	17	M4	M4	
DHRC-16-A-S-NO																	
DHRC-20-A	26	15,6	16	14	16,6	17	5,6	M5	4	M5	4	4	M5	21	M5		
DHRC-20-A-S-NO																	
DHRC-25-A	33	20,4	21	21	20	20	6,6			M6			M6	26	M6	M5	3
DHRC-25-A-S-NO																	
DHRC-32-A	40	24	26	26	26	26	8,6		5		5	5		25		M6	
DHRC-32-A-S-NO																	

	H1	H2	H3	H4	H5	H6 +0,1	H7	H8	H9	H10 +0,1	H11 −0,2	H12 −0,2	H13	H14 −0,2	L1 +0,3	L2 ±0,02	L3
DHRC-10-A	69,2	53,6	43,8	–	27,5	17,5	21,5	7	22	14,4	15,6	3,5	8,6	7,8	25	18	18,6
DHRC-10-A-S-NO	75	59,4	49,6		33,3	23,3	27,3		27,8	20,2							
DHRC-16-A	86,7	69,7	57	42,7	39,1	27,1	34,8	9	32,7	22,7	17	4	9	8,5	32	24,4	27
DHRC-16-A-S-NO																	
DHRC-20-A	101,2	82,2	66,9	48,7	44,6	30,6	38,6	10,2	37,6	25,6	19	5		9,5	40	28,4	31,6
DHRC-20-A-S-NO																	
DHRC-25-A	122,6	99,6	79,9	58,1	53,4	38,4	46,4	10,5	45,4	33,4	23	5,5	12	11,5	50	37,2	37,4
DHRC-25-A-S-NO																	
DHRC-32-A	141,8	113,8	89,8	61,8	57,3	39,8	49,3	11	48,3	35,3	28	6	16	14	60	46	46
DHRC-32-A-S-NO																	

	L4	L5 ±0,02	L6	L7 −0,4	L8 −0,4	L9 +0,025 −0,225	L10 −0,2	T1	T2	T3	T4	T5	T6	T7	W1 ±2°	W2 +3°
DHRC-10-A	15,8	19	19	13	6	3	3	4	3	4	3	3	4	1,5	90°	2°
DHRC-10-A-S-NO																
DHRC-16-A	21,2	25	25	15,4	8	6	4	4,5		4,5			6	2		
DHRC-16-A-S-NO																
DHRC-20-A	26,8	31	30	22	9		4,5	6	4	8	4	4	10			
DHRC-20-A-S-NO																
DHRC-25-A	33	38	38	29,4	10	5	5	7,5		10			12			
DHRC-25-A-S-NO																
DHRC-32-A	39,8	46	46	34,4	12	6	6		5		5	5	13			
DHRC-32-A-S-NO																

Ordering data

DHRC-6-...

	Size	Mode of operation	Product weight	Part no.	Type
	6	Double-acting	24.5 g	**8125285**	**DHRC-6-A**

DHRC-10-...

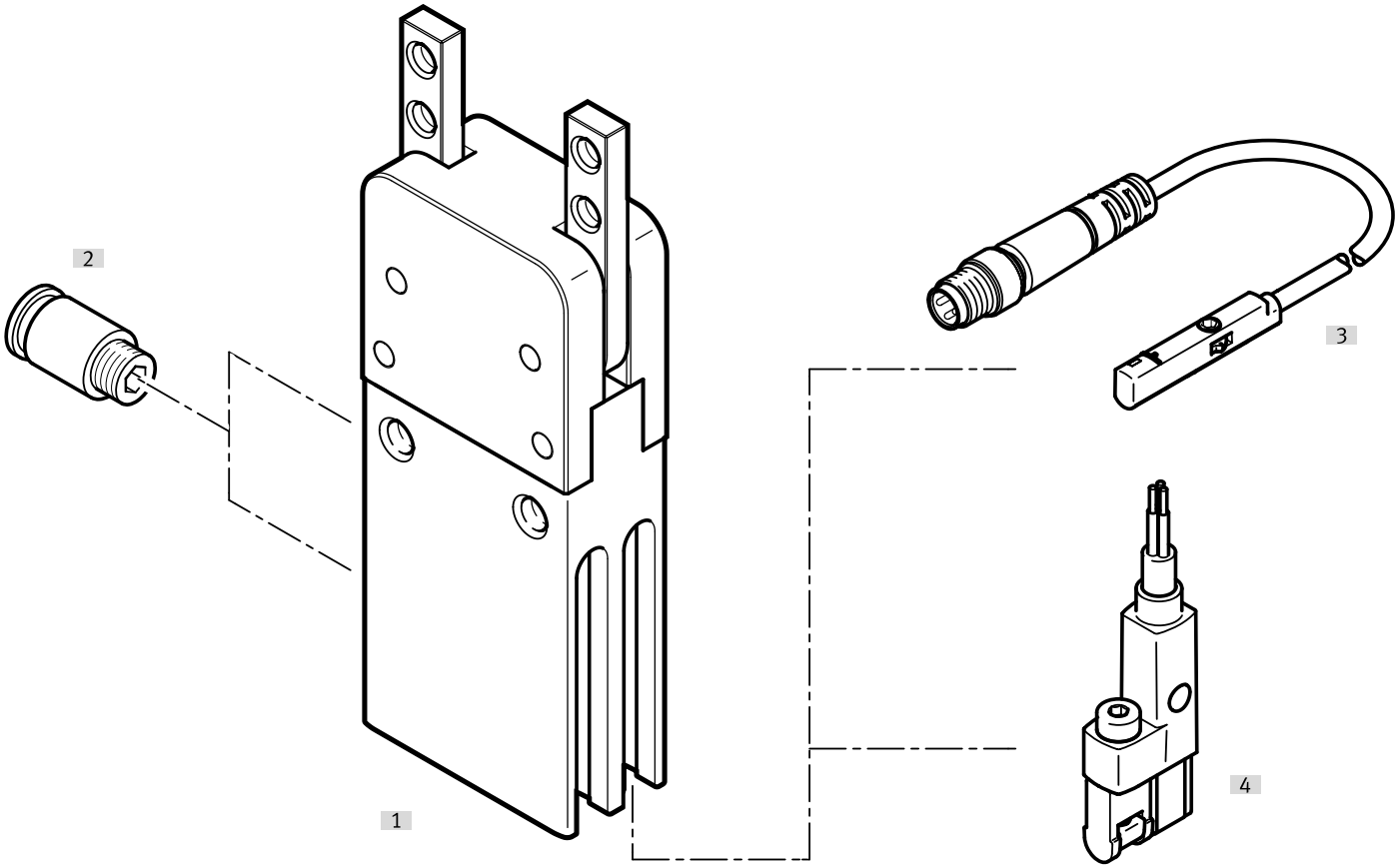
	Size	Mode of operation	Product weight	Part no.	Type
	10	Double-acting	54 g	**8125472**	**DHRC-10-A**
		Single-acting Open	59.5 g	**8133559**	**DHRC-10-A-S-NO**

DHRC-16 ... 32-...

	Size	Mode of operation	Product weight	Part no.	Type
	16	Double-acting	111 g	**8128723**	**DHRC-16-A**
		Single-acting Open	112.5 g	**8128721**	**DHRC-16-A-S-NO**
	20	Double-acting	218.4 g	**8128697**	**DHRC-20-A**
		Single-acting Open	220 g	**8128698**	**DHRC-20-A-S-NO**
	25	Double-acting	438.5 g	**8128142**	**DHRC-25-A**
		Single-acting Open	440 g	**8133557**	**DHRC-25-A-S-NO**
	32	Double-acting	716.5 g	**8128107**	**DHRC-32-A**
		Single-acting Open	720.5 g	**8133558**	**DHRC-32-A-S-NO**

Peripherals

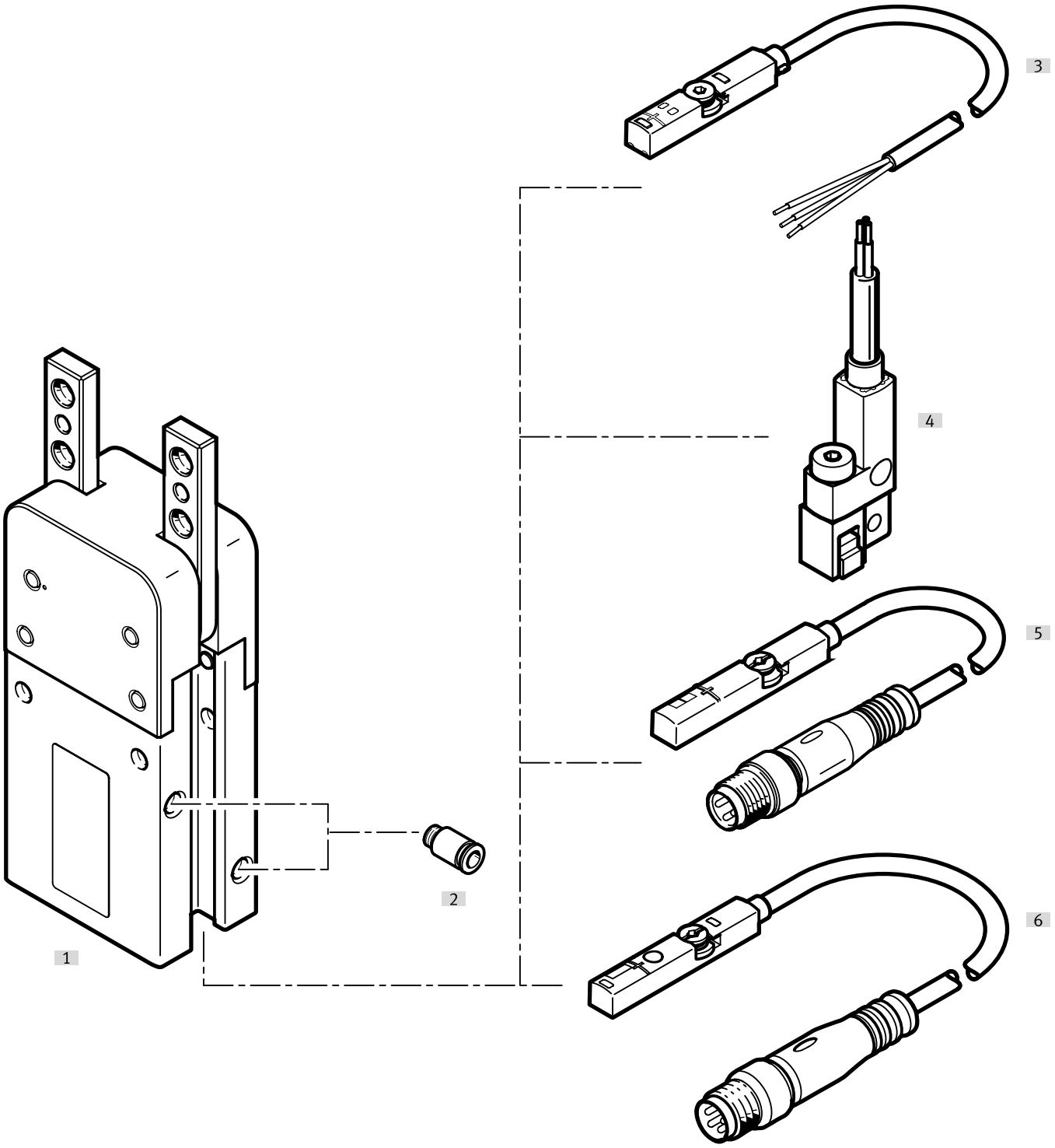
Size 6



Accessories			→ Link
	Type/order code	Description	
[1]	Radial grippers DHRC	Double-acting	dhrc
[2]	Push-in fitting QS	For connecting tubing with standard O.D	qs
[3]	Proximity switch SMT-10M	For sensing the piston position in the end positions	26
[4]	Proximity switch SMT-10G	For sensing the piston position in the end positions	26

Peripherals

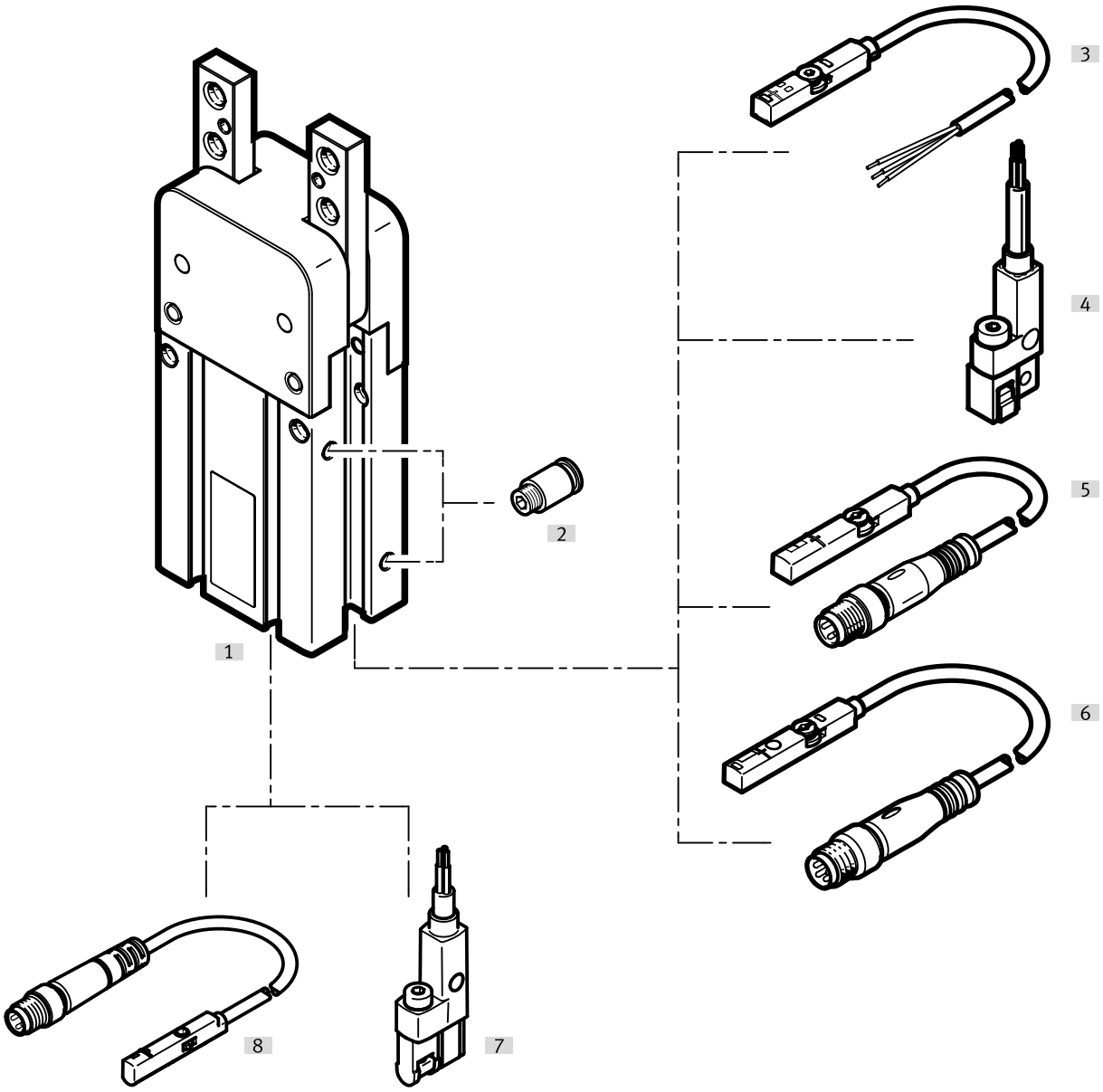
Size 10



Accessories			→ Link
	Type/order code	Description	
[1]	Radial grippers DHRC	Double-acting or single-acting	dhrc
[2]	Push-in fitting QS	For connecting tubing with standard O.D	qs
[3]	Proximity switch SMT-8M	For sensing the piston position in the end positions	26
[4]	Proximity switch SMT-8G	For sensing the piston position in the end positions	26
[5]	Position transmitter SMAT-8M	For sensing the piston position at any point	27
[6]	Position transmitter SDAS-MHS	For sensing the piston position at any point	27

Peripherals

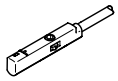
Size 16 ... 32



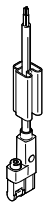
Accessories			→ Link
	Type/order code	Description	
[1]	Radial grippers DHRC	Double-acting or single-acting	dhrc
[2]	Push-in fitting QS	For connecting tubing with standard O.D	qs
[3]	Proximity switch SMT-8M	For sensing the piston position in the end positions	26
[4]	Proximity switch SMT-8G	For sensing the piston position in the end positions	26
[5]	Position transmitter SMAT-8M	For sensing the piston position at any point	27
[6]	Position transmitter SDAS-MHS	For sensing the piston position at any point	27
[7]	Proximity switch SMT-10G	For sensing the piston position in the end positions	26
[8]	Proximity switch SMT-10M	For sensing the piston position in the end positions	26

Accessories

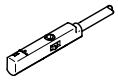
Proximity switch SMT-10M for round slot, magneto-resistive – for sizes 6, 16 ... 32 Link smt

	Type of mounting	Switching output	Electrical connection	Cable length	Part no.	Type
	Screw-clamped, Insertable in the slot from above	3-wire PNP N/O contact	Open end	2.5 m	551374	SMT-10M-PS-24V-E-2,5-Q-OE
					551373	SMT-10M-PS-24V-E-2,5-L-OE
			Plug M8, A-coded	0.3 m	551375	SMT-10M-PS-24V-E-0,3-L-M8D
					551376	SMT-10M-PS-24V-E-0,3-Q-M8D

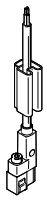
Proximity switch SMT-10G for round slot, magneto-resistive – for sizes 6, 16 ... 32 Link smt

	Type of mounting	Switching output	Electrical connection	Cable length	Part no.	Type
	Clamped in C-slot, Insertable in the slot lengthwise	3-wire NPN N/O contact	Open end	2.5 m	8065030	SMT-10G-NS-24V-E-2,5Q-OE
			Plug M8, A-coded	0.3 m	8065029	SMT-10G-NS-24V-E-0,3Q-M8D
		3-wire PNP N/O contact	Open end	2.5 m	547862	SMT-10G-PS-24V-E-2,5Q-OE
			Plug M8, A-coded	0.3 m	547863	SMT-10G-PS-24V-E-0,3Q-M8D

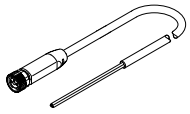
Proximity switch SMT-8M for T-slot, magneto-resistive – for sizes 10 ... 32 Link smt

	Type of mounting	Switching output	Electrical connection	Cable length	Part no.	Type
	Screw-clamped, Insertable in the slot from above	3-wire NPN N/O contact	Open end	2.5 m	574338	SMT-8M-A-NS-24V-E-2,5-OE
			Plug M8, A-coded	0.3 m	574339	SMT-8M-A-NS-24V-E-0,3-M8D
		3-wire PNP N/C contact	Open end	7.5 m	574340	SMT-8M-A-PO-24V-E-7,5-OE
		3-wire PNP N/O contact		2.5 m	574335	SMT-8M-A-PS-24V-E-2,5-OE
			Plug M8, A-coded	0.3 m	574334	SMT-8M-A-PS-24V-E-0,3-M8D
			Plug M12, A-coded		574337	SMT-8M-A-PS-24V-E-0,3-M12

Proximity switch SMT-8G for T-slot, magneto-resistive – for sizes 10 ... 32 Link smt

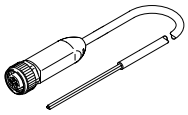
	Type of mounting	Switching output	Electrical connection	Cable length	Part no.	Type
	Clamped in T-slot, Insertable in the slot lengthwise	3-wire NPN N/O contact	Open end	2.5 m	8065028	SMT-8G-NS-24V-E-2,5Q-OE
			Plug M8, A-coded	0.3 m	8065027	SMT-8G-NS-24V-E-0,3Q-M8D
		3-wire PNP N/O contact	Open end	2.5 m	547859	SMT-8G-PS-24V-E-2,5Q-OE
			Plug M8, A-coded	0.3 m	547860	SMT-8G-PS-24V-E-0,3Q-M8D

Connecting cables NEBA, straight, M8 connection

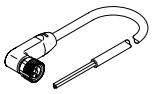
	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M8x1, A-coded, to EN 61076-2-104	Open end	3	2.5 m	8078223	NEBA-M8G3-U-2.5-N-LE3
				5 m	8078224	NEBA-M8G3-U-5-N-LE3

Accessories

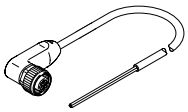
Connecting cables NEBA, straight, M12 connection

	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M12x1, A-coded to EN 61076-2-101	Open end	3	2.5 m	**8078236**	**NEBA-M12G5-U-2.5-N-LE3**
				5 m	**8078237**	**NEBA-M12G5-U-5-N-LE3**

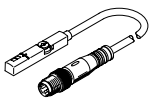
Connecting cables NEBA, angled, M8 connection

	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M8x1, A-coded, to EN 61076-2-104	Open end	3	2.5 m	**8078230**	**NEBA-M8W3-U-2.5-N-LE3**
				5 m	**8078231**	**NEBA-M8W3-U-5-N-LE3**

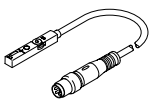
Connecting cables NEBA, angled, M12 connection

	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M12x1, A-coded to EN 61076-2-101	Open end	3	2.5 m	**8078245**	**NEBA-M12W5-U-2.5-N-LE3**
				5 m	**8078246**	**NEBA-M12W5-U-5-N-LE3**

Position transmitter SMAT-8M for T-slot, plug M8, A-coded – for size 10 ... 32 Link smat

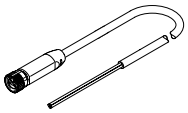
	Sensing range	Analogue output	Electrical connection 1, number of connections/ cores	Cable length	Part no.	Type
	52 mm	0 - 10 V	4	0.3 m	**553744**	**SMAT-8M-U-E-0,3-M8D**

Position transmitter SDAS for T-slot, M8 plug, A-coded – for size 10 ... 32 Link sdas

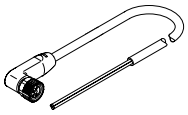
	Description	Sensing range	Electrical connection 1, number of connections/ cores	Cable length	Part no.	Type
	Operating modes: two adjustable switching outputs; IO-Link®	52 mm	4	0.3 m	**8063974**	**SDAS-MHS-M40-1L-PNLK-PN-E-0.3-M8**
				2.5 m	**8063975**	**SDAS-MHS-M40-1L-PNLK-PN-E-2.5-LE**

Accessories

Connecting cables NEBA, straight

	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M8x1, A-coded, to EN 61076-2-104	Open end	4	2.5 m	**8078227**	**NEBA-M8G4-U-2.5-N-LE4**
				5 m	**8078228**	**NEBA-M8G4-U-5-N-LE4**

Connecting cables NEBA, angled

	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M8x1, A-coded, to EN 61076-2-104	Open end	4	2.5 m	**8078233**	**NEBA-M8W4-U-2.5-N-LE4**
				5 m	**8078234**	**NEBA-M8W4-U-5-N-LE4**