

Angle grippers HGW

FESTO



Angle grippers HGW

Key features

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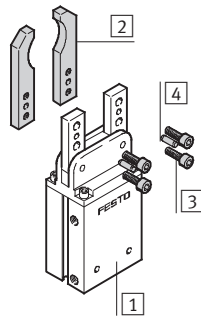
At a glance


- Double-acting piston drive
- Self-centring
- Variable gripping action:
 - External/internal gripping
- Versatility thanks to externally adaptable gripper fingers
- Wide range of options for mounting on drive units
- Constant gripping torque over the entire angle range
- 40° opening angle
- Internal fixed flow control
- Sensor technology:
 - Adaptable proximity sensors on the small grippers
 - Integral proximity sensors for medium and large grippers

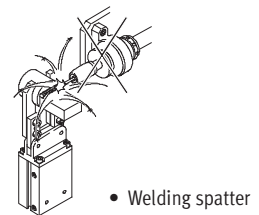
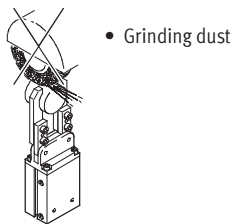
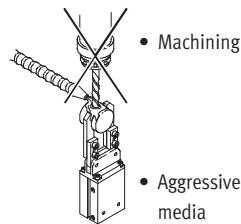
-  - Note
Sizing software
Gripper selection
➔ www.festo.com

Mounting options for external gripper fingers (customer-specific)

- 1 Angle gripper
- 2 External gripper fingers
- 3 Mounting screws
- 4 Centring pins



-  - Note
Grippers should always be used with exhaust air flow control. They are not suitable for the following, or for similar applications:

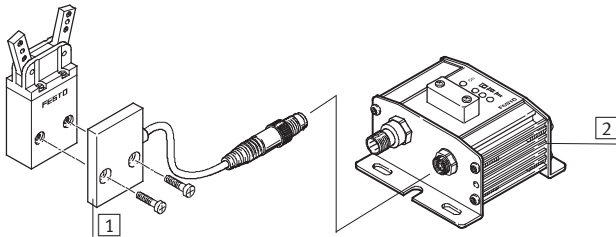


Angle grippers HGW

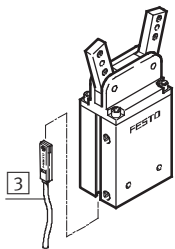
Peripherals overview and type codes

Peripherals overview

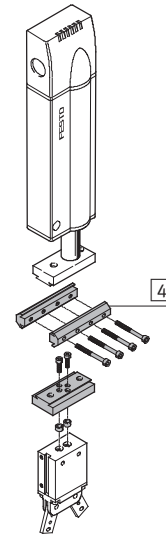
HGW-10



HGW-16 ... 40



System product for handling and assembly technology



| Accessories | | | |
|-------------|----------------------------|---|-----------------|
| Type | | Brief description | → Page/Internet |
| 1 | Position sensor SMH-S1 | Adaptable and integratable sensor technology, for sensing the piston position | 11 |
| 2 | Evaluation unit SMH-AE1 | For position sensor SMH-S1 | 11 |
| 3 | Proximity sensor SME/SMT-8 | For sensing the piston position | 11 |
| 4 | - | Drive/gripper connections | adapter kit |

Type codes

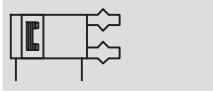
| | | | | | |
|-------------------------|-----------------------|---|----|---|---|
| HGW | | - | 16 | - | A |
| Type | | | | | |
| HGW | Angle gripper | | | | |
| Size | | | | | |
| Position sensing | | | | | |
| A | For proximity sensing | | | | |

Angle grippers HGW

Technical data

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Function
Double-acting



[www.festo.com/en/
Spare_parts_service](http://www.festo.com/en/Spare_parts_service)

Wearing parts kits
→ 10



Size
10 ... 40 mm

| General technical data | | 10 | 16 | 25 | 32 | 40 |
|-----------------------------------|------|--------------------------------------|----|----|-----------------|----|
| Design | | Lever mechanism | | | | |
| Mode of operation | | Double-acting | | | | |
| Gripper function | | Angle | | | | |
| Number of gripper jaws | | 2 | | | | |
| Opening angle | [°] | 40 | | | | |
| Pneumatic connection | | M3 | | M5 | G $\frac{1}{8}$ | |
| Repetition accuracy ¹⁾ | [mm] | ≤ 0.04 | | | | |
| Max. interchangeability | [mm] | 0.2 | | | | |
| Max. operating frequency | [Hz] | 4 | | | | |
| Position sensing | | For proximity sensing | | | | |
| Type of mounting | | With female thread and centring hole | | | | |

1) End position drift under constant conditions of use with 100 consecutive strokes in the direction of movement of the gripper jaws

| Operating and environmental conditions | | |
|--|-------|---|
| Min. operating pressure | [bar] | 2 |
| Max. operating pressure | [bar] | 8 |
| Operating medium | | Filtered compressed air, lubricated or unlubricated |
| Ambient temperature | [°C] | +5 ... +60 |
| Corrosion resistance class CRC ¹⁾ | | 2 |

1) Corrosion resistance class 2 according to Festo standard 940 070
Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

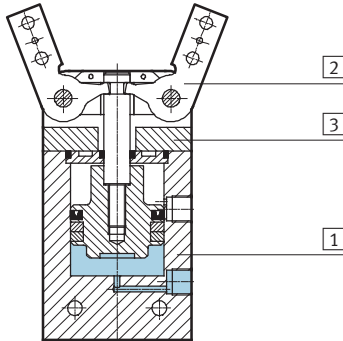
| Weights [g] | | 10 | 16 | 25 | 32 | 40 |
|-------------|--|----|-----|-----|-----|-----|
| HGW | | 39 | 100 | 250 | 420 | 720 |

Angle grippers HGW

Technical data

Materials

Sectional view

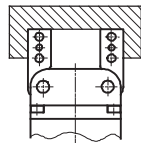
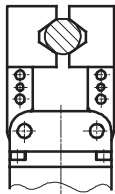


| Angle gripper | | |
|---------------|-------------------|--|
| 1 | Body | Hard anodised aluminium |
| 2 | Gripper jaw | Nickel-plated tool steel |
| 3 | Cover cap | Polyacetate |
| - | Note on materials | Copper, PTFE and silicone-free Conforms to RoHS |

Total gripping torque [Ncm] at 6 bar, with external gripper fingers

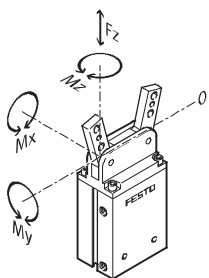
External gripping

Internal gripping



| Size | 10 | 16 | 25 | 32 | 40 |
|-----------------------|----|-----|-----|-----|-----|
| Total gripping torque | | | | | |
| Opening | 25 | 120 | 360 | 680 | 965 |
| Closing | 22 | 106 | 320 | 600 | 880 |

Characteristic load values at the gripper jaws



The indicated permissible forces and torques apply to a single gripper jaw. Static forces and torques relate to additional applied loads caused by

the workpiece or external gripper fingers, as well as forces which occur during handling. The zero co-ordinate

line (gripper jaws point of rotation) must be taken into consideration for the calculation of torques.

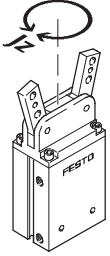
| Size | 10 | 16 | 25 | 32 | 40 | |
|-------------------------------|------|-----|-----|-----|-----|-----|
| Max. permissible force F_z | [N] | 16 | 31 | 54 | 74 | 124 |
| Max. permissible torque M_x | [Nm] | 0.3 | 0.9 | 1.7 | 3 | 5.7 |
| Max. permissible torque M_y | [Nm] | 0.1 | 0.3 | 0.6 | 1 | 2.2 |
| Max. permissible torque M_z | [Nm] | 0.2 | 0.5 | 1.1 | 1.8 | 3.6 |

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Mass moment of inertia [$\text{kgm}^2 \times 10^{-4}$]



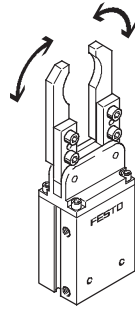
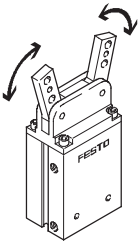
Mass moment of inertia [$\text{kgm}^2 \times 10^{-4}$] for angle grippers in relation to the central axis, without external gripper fingers, without load.

| Size | 10 | 16 | 25 | 32 | 40 |
|------|------|------|------|------|------|
| HGW | 0.03 | 0.13 | 0.60 | 1.48 | 3.54 |

Opening and closing times [ms] at 6 bar

Without external gripper fingers

With external gripper fingers



The indicated opening and closing times [ms] have been measured at room temperature and 6 bar operating pressure without external gripper fingers.

The grippers must be throttled for greater applied loads. Opening and closing times must then be adjusted accordingly.

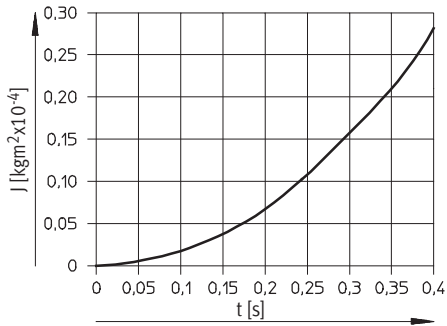
| Size | 10 | 16 | 25 | 32 | 40 | |
|-----------------------------------|---------|----|----|----|----|----|
| Without external gripper fingers | | | | | | |
| HGW | Opening | 5 | 25 | 50 | 50 | 60 |
| | Closing | 5 | 30 | 40 | 40 | 50 |
| With external gripper fingers → 7 | | | | | | |

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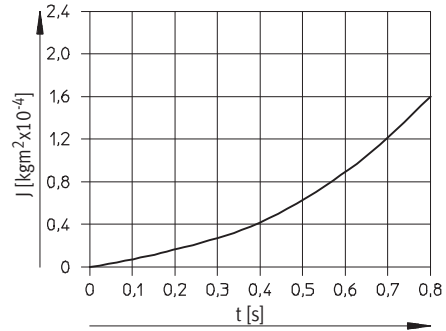
Technical data

Opening and closing times t as a function of gripper finger mass moment of inertia J

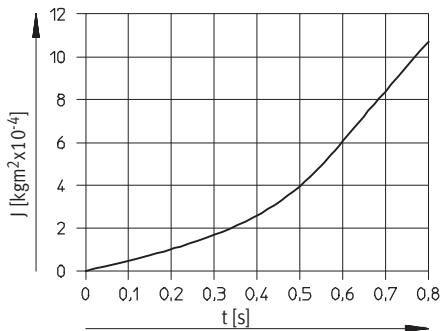
HGW-10-A



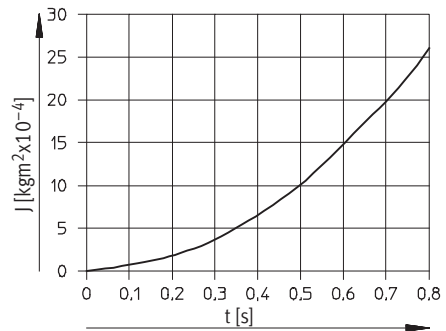
HGW-16-A



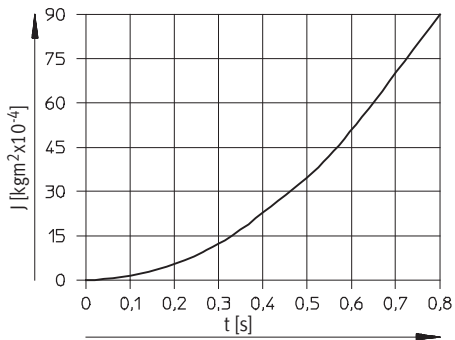
HGW-25-A



HGW-32-A



HGW-40-A



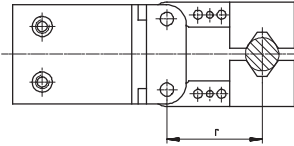
Angle grippers HGW

Technical data

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Gripping force F per gripper as a function of operating pressure and the lever arm r

Gripping forces

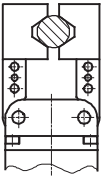


Gripping forces can be determined with the following diagrams for the various sizes in relation to operating

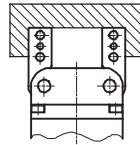
pressure and lever arm (distance from the zero co-ordinate line shown oppo-

site to the pressure point at which the external fingers grip the workpiece).

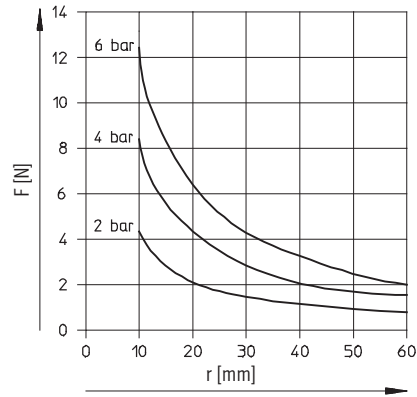
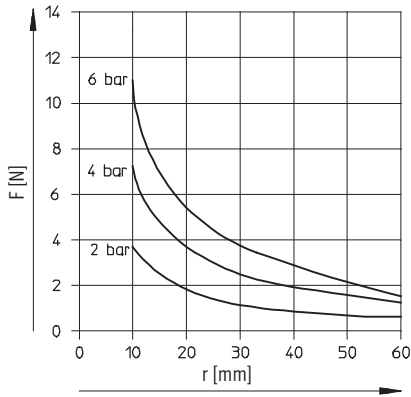
External gripping (closing)



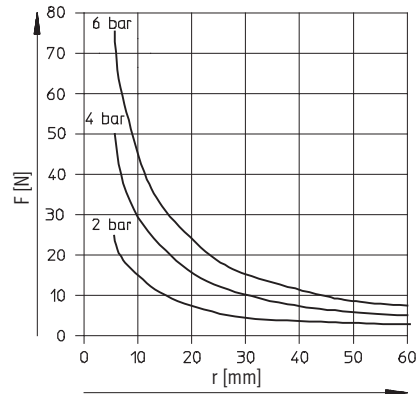
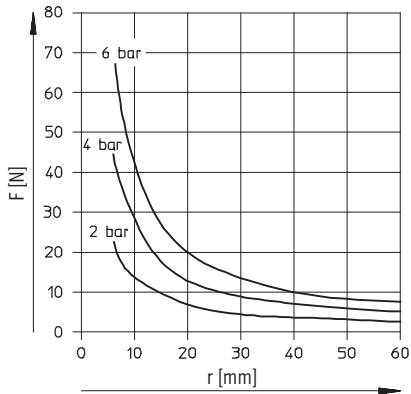
Internal gripping (opening)



HGW-10-A



HGW-16-A



Angle grippers HGW

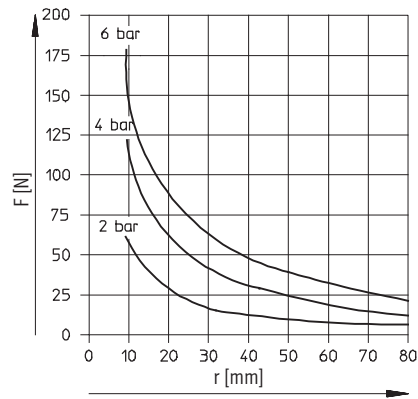
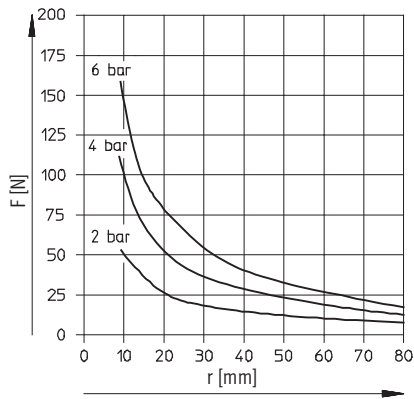
Technical data

Gripping force F per gripper as a function of operating pressure and the lever arm r

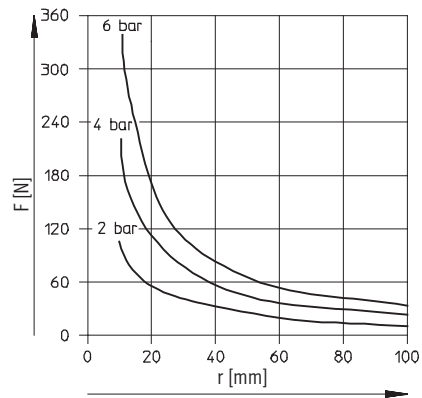
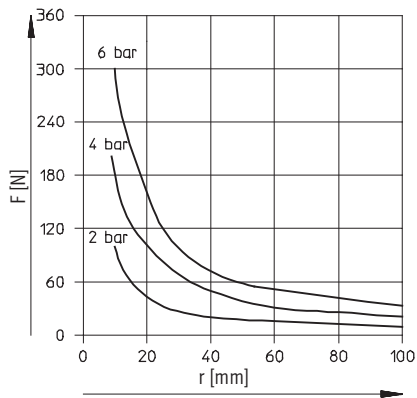
External gripping (closing)

Internal gripping (opening)

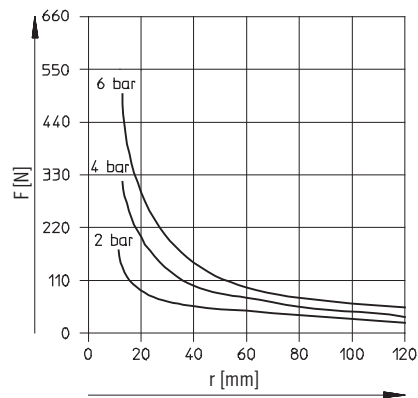
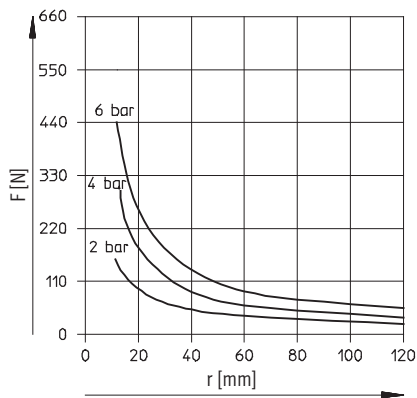
HGW-25-A



HGW-32A



HGW-40A



Angle grippers HGW

Technical data

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Dimensions

Download CAD data → www.festo.com/en/engineering

View A
HGW-10
HGW-16 ... 40

1 Sensor slot for proximity sensor SME/SMT-8 (not with HGW-10-A)
2 Compressed air connection, closing
3 Compressed air connection, opening
4 Centring sleeves ZBH (2 included in scope of delivery)

| Size | B1 | B2 | B3 | B4 | B5 | D2 | D3 | D4 | D5 | D6 | EE | H1 | H2 | H3 | H4 | H5 |
|------|------|-------|-------|------|-------------|----|------------|-----------|---------|-----|-----------------|------|------|------|-------|----|
| [mm] | | ±0.02 | ±0.02 | | -0.02/-0.05 | | ∅ H8/h7 | ∅ +0.1 | ∅ H8 | ∅ | | | | | | |
| 10 | 24 | 15 | 17 | 9.75 | 5.5 | M3 | 5 | 2.5 | 2 | 2.2 | M3 | 56.3 | 34.5 | 16 | 8.8 | 7 |
| 16 | 33.4 | 16 | 24 | 13 | 8 | M3 | 5 | 2.5 | 2.5 | 3.2 | M3 | 81 | 53.2 | 23 | 12.25 | 9 |
| 25 | 44 | 25 | 32 | 18 | 10 | M4 | 7 | 3.3 | 3 | 3.2 | M5 | 100 | 63.5 | 24.7 | 14.3 | 11 |
| 32 | 51 | 29 | 37 | 20.5 | 12 | M6 | 9 | 5.1 | 3 | 4.3 | G $\frac{1}{8}$ | 116 | 73 | 25 | 20 | 13 |
| 40 | 59 | 33 | 42 | 23.5 | 15 | M8 | 12 | 6.4 | 4 | 5.3 | G $\frac{1}{8}$ | 129 | 79.5 | 47 | 8 | 14 |

| Size | H6 | H7 | H8 | H9 | H10 | H11 | L1 | L2 | L3 | L4 | L6 | T1 | T2 | T3 | T4 | T5 |
|------|-----|------|-------|------|------|-------|------|------|-------|----|-------|------|------|----|------|-----|
| [mm] | | | ±0.05 | | | -0.05 | | | -0.02 | | ±0.02 | +0.1 | | +1 | +0.5 | |
| 10 | 3.5 | 5.75 | 10.75 | 44.8 | 27.5 | 12.3 | 14 | 2 | 3 | 7 | 2 | 1.2 | 12.3 | - | 3.5 | 1.2 |
| 16 | 4.5 | 7.5 | 13.7 | 65.5 | 52.3 | 7.5 | 19 | 5.5 | 4 | 10 | - | 1.2 | 7 | 7 | 4.5 | 1.2 |
| 25 | 5.5 | 8.8 | 18.7 | 80.7 | 65 | 7.5 | 29.5 | 8.75 | 5 | 14 | - | 1.6 | 7 | 8 | 6.5 | 1.4 |
| 32 | 6.5 | 11 | 22 | 92.5 | 72 | 11 | 38 | 9.5 | 6 | 17 | - | 2.1 | 10 | 15 | 6.5 | 1.9 |
| 40 | 7 | 12 | 25.5 | 103 | 74 | 17.5 | 49 | 11 | 8 | 21 | - | 2.6 | 15 | 16 | 6.5 | 2.4 |

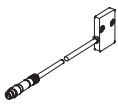


| Ordering data | | |
|---------------|---------------|----------|
| Size | Double-acting | |
| [mm] | Part No. | Type |
| 10 | 174 818 | HGW-10-A |
| 16 | 161 833 | HGW-16-A |
| 25 | 161 834 | HGW-25-A |
| 32 | 161 835 | HGW-32-A |
| 40 | 161 836 | HGW-40-A |

| Ordering data – Wearing parts kits | | |
|------------------------------------|----------|----------|
| Size | | |
| [mm] | Part No. | Type |
| 10 | 378 527 | HGW-10-A |
| 16 | 125 680 | HGW-16-A |
| 25 | 125 681 | HGW-25-A |
| 32 | 125 682 | HGW-32-A |
| 40 | 125 683 | HGW-40-A |

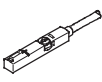


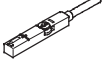
Angle grippers HGW

Accessories

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| Ordering data | | | | | |
|---|----------|------------|-----------------------------------|-----------------|------------------|
| Type | For size | Weight [g] | Part No. | Type | PU ¹⁾ |
| Position sensor SMH-S1 | | | Technical data → Internet: smh-s1 | | |
|  | 10 | 20 | 175 711 | SMH-S1-HGW10 | 1 |
| Evaluation unit SMH-AE1 | | | Technical data → Internet: smh-ae | | |
|  | 10 | 170 | 175 708 | SMH-AE1-PS3-M12 | 1 |
| | | | 175 709 | SMH-AE1-NS3-M12 | |
| Centring sleeve ZBH | | | Technical data → Internet: zbh | | |
|  | 10, 16 | 1 | 189 652 | ZBH-5 | 10 |
| | 25 | | 186 717 | ZBH-7 | |
| | 32 | | 150 927 | ZBH-9 | |
| | 40 | | 189 653 | ZBH-12 | |

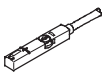


1) Packaging unit quantity



| Ordering data – Proximity sensors for T-slot, magneto-resistive | | | | | |
|---|--|-----------------------|-------------------|----------|---------------------------------|
| Type of mounting | Switch output | Electrical connection | Cable length [m] | Part No. | Type |
| N/O contact | | | | | |
|  | Insertable in the slot from above, flush with cylinder profile | PNP | Cable, 3-wire | 2.5 | 543 867 SMT-8M-PS-24V-K-2,5-OE |
| | | | Plug M8x1, 3-pin | 0.3 | 543 866 SMT-8M-PS-24V-K-0,3-M8D |
| | | | Plug M12x1, 3-pin | 0.3 | 543 869 SMT-8M-PS-24V-K-0,3-M12 |
|  | Insertable in the slot lengthwise, flush with the cylinder profile | NPN | Cable, 3-wire | 2.5 | 543 870 SMT-8M-NS-24V-K-2,5-OE |
| | | | Plug M8x1, 3-pin | 0.3 | 543 871 SMT-8M-NS-24V-K-0,3-M8D |
|  | Insertable in the slot lengthwise, flush with the cylinder profile | PNP | Cable, 3-wire | 2.5 | 175 436 SMT-8-PS-K-LED-24-B |
| | | | Plug M8x1, 3-pin | 0.3 | 175 484 SMT-8-PS-S-LED-24-B |
| N/C contact | | | | | |
|  | Insertable in the slot from above, flush with cylinder profile | PNP | Cable, 3-wire | 7.5 | 543 873 SMT-8M-PO-24V-K7,5-OE |

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Accessories

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| Ordering data – Proximity sensors for T-slot, magnetic reed | | | | | Technical data → Internet: sme | |
|---|--|---------------|-----------------------|------------------|--------------------------------|--------------------------------|
| | Type of mounting | Switch output | Electrical connection | Cable length [m] | Part No. | Type |
| N/O contact | | | | | | |
|  | Insertable in the slot from above, flush with cylinder profile | Contacting | Cable, 3-wire | 2.5 | 543 862 | SME-8M-DS-24V-K-2,5-OE |
| | | | | 5.0 | 543 863 | SME-8M-DS-24V-K-5,0-OE |
| | | | Cable, 3-wire | 2.5 | 543 872 | SME-8M-ZS-24V-K-2,5-OE |
| | | | Plug M8x1, 3-pin | 0.3 | 543 861 | SME-8M-DS-24V-K-0,3-M8D |
|  | Insertable in the slot lengthwise, flush with the cylinder profile | Contacting | Cable, 3-wire | 2.5 | 150 855 | SME-8-K-LED-24 |
| | | | Plug M8x1, 3-pin | 0.3 | 150 857 | SME-8-S-LED-24 |
| N/C contact | | | | | | |
|  | Insertable in the slot lengthwise, flush with the cylinder profile | Contacting | Cable, 3-wire | 7.5 | 160 251 | SME-8-O-K-LED-24 |

| Ordering data – Connecting cables | | | | Technical data → Internet: nebu | |
|---|-------------------------------|------------------------------|------------------|---------------------------------|-----------------------------|
| | Electrical connection, left | Electrical connection, right | Cable length [m] | Part No. | Type |
|  | Straight socket, M8x1, 3-pin | Cable, open end, 3-wire | 2.5 | 541 333 | NEBU-M8G3-K-2.5-LE3 |
| | | | 5 | 541 334 | NEBU-M8G3-K-5-LE3 |
| | Straight socket, M12x1, 5-pin | Cable, open end, 3-wire | 2.5 | 541 363 | NEBU-M12G5-K-2.5-LE3 |
| | | | 5 | 541 364 | NEBU-M12G5-K-5-LE3 |
|  | Angled socket, M8x1, 3-pin | Cable, open end, 3-wire | 2.5 | 541 338 | NEBU-M8W3-K-2.5-LE3 |
| | | | 5 | 541 341 | NEBU-M8W3-K-5-LE3 |
| | Angled socket, M12x1, 5-pin | Cable, open end, 3-wire | 2.5 | 541 367 | NEBU-M12W5-K-2.5-LE3 |
| | | | 5 | 541 370 | NEBU-M12W5-K-5-LE3 |

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Our experienced engineers provide complete support at every stage of your development process, including: conceptualization, analysis, engineering, design, assembly, documentation, validation, and production.



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Complete custom engineered solutions



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Pneumatic linear and rotary actuators, valves, and air supply



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Festo is a leading global manufacturer of pneumatic and electromechanical systems, components and controls for industrial automation, with more than 12,000 employees in 56 national headquarters serving more than 180 countries. For more than 80 years, Festo has continuously elevated the state of manufacturing with innovations and optimized motion control solutions that deliver higher performing, more profitable automated manufacturing and processing equipment. Our dedication to the advancement of automation extends beyond technology to the education and development of current and future automation and robotics designers with simulation tools, teaching programs, and on-site services.

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