# Standards-based cylinders DDPC, with measured-value transducer DADE

# **FESTO**



# Key features

### Components for positioning and measuring using the standards-based cylinder DDPC



Measuring

With measured-value transducer DADE

Measured-value transducer DADE



Controller e.g. CECC



Operator unit e.g. CDPX



Positioning

With end-position controller SPC11 or controller module CPX-CMAX/-CMPX

Proportional directional control valve MPYE



End-position controller SPC11-INC



Proportional directional control valve VPWP



Sensor interface CASM



Controller module CPX-CMAX, CPX-CMPX

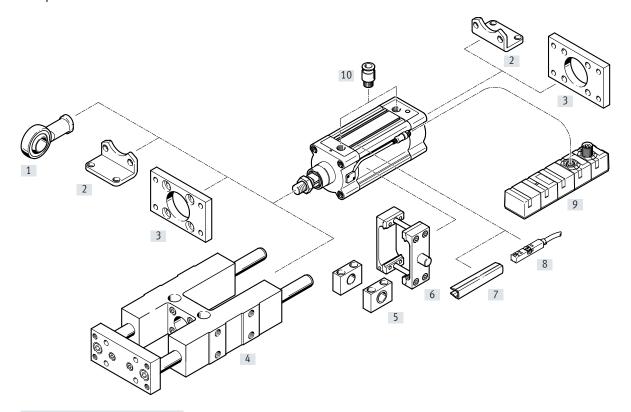


# Type codes

001	Series	
DDPC	Standards-based cylinder, integrated displacement encoder	
002	Protection against rotation	
D	With guide unit	
Q	With protection against rotation	
003	Piston diameter	
80	80	
100	100	
004	Stroke	
004	Stroke 10 2000	
 005		
	10 2000	

006	Piston rod type	
	At one end	
T	Through piston rod	
007	Cushioning	
P	Elastic cushioning rings/plates on both sides	
008	Position sensing	
Α	For proximity sensor	
009	Piston rod extension	
	None	
Е	1 500 mm	

# Peripherals overview



# - 🖣 - Note

If the drive DDPC is used without an end-position controller CPX-CMPX, SPC11 or axis controller CPX-CMAX, e.g. as a measuring cylinder, then the standard accessories for the drive DNC can be used.

# Peripherals overview

Acces	Accessories					
	Туре	Description	→ Page/Internet			
[1]	Rod eye SGS	With spherical bearing	ddpc			
[2]	Foot mounting HNC	For mounting the drive on the bearing and end caps	ddpc			
[3]	Flange mounting For mounting the drive on the bearing and end caps  FNC d					
[4]	Guide unit <sup>1)</sup> FENG-KF	For protecting against rotation at high torque loads	12			
[5]	Trunnion support LNZG	···				
[6]	Trunnion flange kit DAMT	For swivelling movements of the drive	ddpc			
[7]	Slot cover ABP-5-S	For protection against contamination	ddpc			
[8]	Proximity switch SME/SMT-8	For additional sensing of the piston position, can be ordered optionally, only in conjunction with the order code A in the drive's modular product system	ddpc			
[9]	Measured-value transducer DADE	Converts the sensor signal of the cylinder to a voltage signal of 0 10 V and/or a current signal of 4 20 mA	14			
[10]	Push-in fitting QS	For connecting tubing with standard O.D.	qs			

<sup>1)</sup> Guide unit FENG-KF must be attached to the piston rod so that backlash is eliminated

### Standards-based cylinders DDPC, with measured-value transducer DADE

### Data sheet





- **D** - Diameter 80 and 100 mm





General technical data	General technical data				
Piston Ø		80	100		
Based on standard		ISO 15552			
Design		Piston			
		Piston rod			
		Profile barrel			
Mode of operation		Double-acting			
Guide <sup>1)</sup>		Guide rod with yoke, with ball bearing guide			
Protection against rotation		Square piston rod			
Mounting position		Any			
Type of mounting		Via accessories			
Cushioning		Elastic cushioning rings/pads at both ends			
Position sensing		Integrated displacement encoder			
		Via proximity switch <sup>2)</sup>			
Measuring principle (displacement encoder)		Encoder, contactless and relative measurement			
Pneumatic connection		G3/8	G1/2		
Stroke					
DDPC	[mm]	10 1250			
DDPCD	[mm]	100 500			
Extended piston rod	[mm]	1 500			

- 1) Guide unit FENG-KF can be ordered via the modular product system (feature D) and is supplied attached. The maximum stroke is restricted.
- 2) Not included in the scope of delivery, can be ordered as an option

Operating and environmental conditions					
Operating pressure [bar] 4 12					
Operating pressure <sup>1)</sup>	[bar]	48			
Operating medium <sup>2)</sup>		Compressed air to ISO 8573-1:2010 [6:4:4]			
Note on the operating/pilot medium		Lubricated operation not possible			
		Pressure dew point 10°C below ambient/medium temperature			
Ambient temperature <sup>3)</sup>	[°C]	-20 +80			
Vibration resistance to DIN/IEC 68, Part 2-6		Severity level 2			
Continuous shock resistance to DIN/IEC 68, Par	rt 2 - 82	Severity level 2			
CE marking (see declaration of conformity) <sup>4)</sup>		To EU EMC Directive			
Corrosion resistance class CRC <sup>5)</sup>	Corrosion resistance class CRC <sup>5)</sup> 1				

- 1) Only applies to applications with end-position controller CPX-CMPX, SPC11 and axis controller CPX-CMAX
- $2) \qquad \text{The proportional directional control valve VPWP, MPYE used requires these characteristic values} \\$
- Note operating range of proximity switches
- 4) For information about the area of use, see the EC declaration of conformity: www.festo.com/sp → Certificates.
  - If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.
- 5) Corrosion resistance class CRC 1 to Festo standard FN 940070

Low corrosion stress. Dry indoor application or transport and storage protection. Also applies to parts behind covers, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

Forces [N] and impact energy [Nm]				
Piston Ø	80	100		
Theoretical force at 6 bar, advancing	3016	4712		
Theoretical force at 6 bar, retracting	2721	4418		
Impact energy at the end positions	1.8	2.5		

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Permissible impact velocity:

$$v = \sqrt{\frac{2 \cdot E}{m_1 + m_2}}$$

Permissible impact velocity Max. impact energy

 ${m_1}$  Moving mass (drive)  ${m_2}$  Moving payload

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Note

These specifications represent the maximum values that can be achieved. The maximum permissible impact energy must be observed.

Maximum permissible mass:

$$m_2 = \frac{2 \cdot E}{v^2} - m_1$$

Electrical data – Displacement encoder		
Output signal		Analogue
Linearity error		
Strokes up to 500 mm	[mm]	<±0.08
Strokes up to 1000 mm	[mm]	<±0.09
Strokes over 1000 mm	[mm]	<±0.11
Resolution <sup>1)</sup>	[%]	≤0.025
Repetition accuracy		
≤ 400	[mm]	±0.1
≤ 500	[mm]	±0.13
≤ 750	[mm]	±0.19
≤ 1200	[mm]	±0.3
≤ 1250	[mm]	±0.4
Max. speed of travel	[m/s]	1.5
Degree of protection		IP65
CE marking (see declaration of conformity) <sup>2)</sup>		To EU EMC Directive
Max. permitted magnetic interference field <sup>3)</sup>	[kA/m]	10
Electrical connection		Cable with 8-pin plug, round design, M12
Cable length	[m]	1.5

- 1) Always refers to max. stroke
- 2) For information about the area of use, see the EC declaration of conformity: www.festo.com/sp → Certificates.

  If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.
- 3) At a distance of 100 mm

### Pin allocation for the plug



Pin	Function	Colour
1	5 V	Black
2	GND	Brown
3	sin+	Red
4	sin-	Orange
5	cos-	Green
6	COS+	Yellow
7	Shielding	Shielding
8	n.c.	-

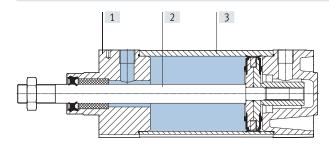
# $Standards\mbox{-}based\mbox{ cylinders DDPC, with measured-value transducer DADE}$

# Data sheet

Weight [g]		
Piston Ø	80	100
DDPC		
Basic weight with 0 mm stroke	3053	4330
Additional weight per 10 mm stroke	87	95
Moving mass with 0 mm stroke	804	994
Additional weight per 10 mm stroke	31	31
DDPCT – Through piston rod		
Basic weight with 0 mm stroke	3537	5019
Additional weight per 10 mm stroke	127	134
Moving mass with 0 mm stroke	1247	1467
Additional weight per 10 mm stroke	70	70
DDPC Additional weight with piston rod exte	ension	
Additional weight per 10 mm extension	31	31
DDPCC — Additional weight with clamping unit		
Additional weight	2046	2829
DDPCD – Additional weight with guide unit		
Basic weight with 0 mm stroke	10430	12990
Additional weight per 10 mm stroke	80	80

### Materials

Sectional view



Stand	tandards-based cylinder			
[1]	Cover	Wrought aluminium alloy		
[2]	Piston rod	High-alloy steel		
[3]	Cylinder barrel	Wrought aluminium alloy		
-	Seals	NBR, polyurethane		
	Note on materials	Free of copper and PTFE		
		RoHS-compliant		

### Torques and lateral forces

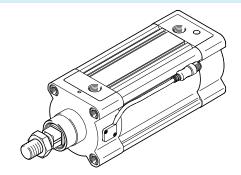
Max. torque for protection against rotation:

Dynamic ≤ 3 Nm Static ≤ 5 Nm

An external guide unit FENG-KF is recommended with higher torque loads. The guide unit is supplied attached.

The permissible static and dynamic characteristic load values with and without attached guide

→ Internet: feng



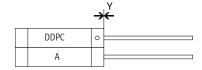
### **Mounting conditions**

When mounting a drive A with magnet (for position sensing) next to a standards-based cylinder DDPC, the following conditions must be observed:

- X Minimum distance between the drives
- Y Offset between the drives on the bearing can

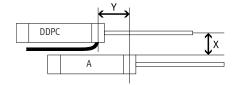
### Parallel assembly

The drives can be mounted directly next to one another if the offset Y = 0 mm.



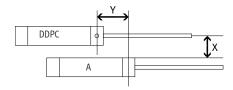
### Offset mounting, cable outlet between the drives

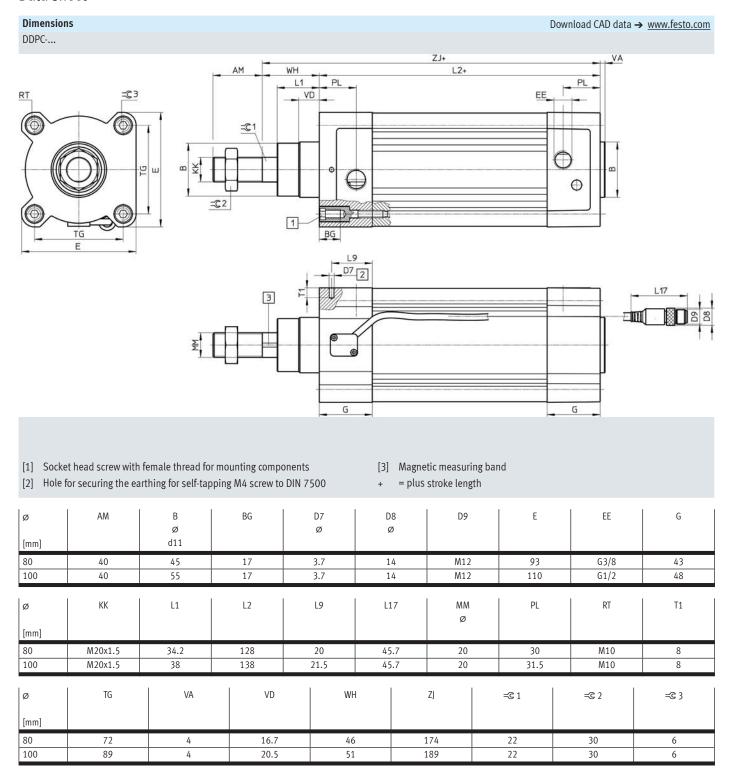
If the offset Y > 0 mm and the cable outlet is between the drives, a distance of X > 70 mm must be observed.



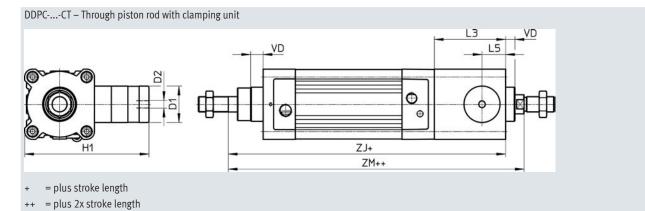
### Offset mounting, cable outlet upwards or downwards

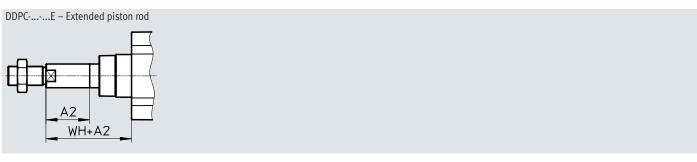
If the offset is Y > 0 mm and the cable outlet is up or down, a distance of X > 60 mm must be observed.





# Dimensions DDPC-...·T - Through piston rod ZJ+ ZM++ + = plus stroke length ++ = plus 2x stroke length





Ø	A2	D1	D2	H1	L3	L5
		Ø				
[mm]	max.	f9				
80	500	48	G1/8	165.5	95	31.5
100	500	48	G1/8	174	98	31

Ø	VD	WH	ZJ		ZM	
[mm]			DDPCT	DDPCCT	DDPCT	DDPCCT
80	16.7	46	174	269	222	317
100	20.5	51	189	287	240	338

### Dimensions Download CAD data → www.festo.com DDPC-...-D L1+ L12 3 L4 B2 L6 B1 \*90 1 8 0 0 보 모 12 모모 **B4** 0 $\oplus$ 2 3 L10 L11 L14 D2 L9 L2 L3+ Standards-based cylinder DDPC [1] Compensating coupling [3] Customers can drill additional mounting holes here as required + = plus stroke length Ø В1 В2 В3 В4 D1 D2 D3 D4 D6 Ø Ø Ø Ø -0.3 ±0.2 ±0.6 h6 [mm] 80 105 100 148 106 78 M10 18 11 25 100 130 120 172 131 78 M10 18 11 25 Ø Н1 H2 Н3 Н4 KK L1 L2 L3 L4 -0.5 ±0.2 ±0.2 +10 [mm] 80 189 180 130 130 M20x1.5 258 111 194 215 100 213 200 150 150 M20x1.5 263 116 138 220 Ø L5 L6 L9 L10 L11 L12 L13 L14 **=**© 1 [mm] ±0.2 72 80 40 128 32 20 21 11 20 27

100

40

128

32

27

20

24.5

89

11

20

# Ordering data – Modular product system

Ordering table							
Piston Ø		80	100	Conditions	Code	En	nter cod
Module no.		1677705	1691433				
Function		Standards-based cylinder with	n integrated displacement encoder		DDPC	DE	DPC
Protection against rotation		With protection against rotation	on		-Q	-Q	Į
Piston Ø	[mm]	80	100				
Stroke	[mm]	10 1250					
Guide unit		None					
		Attached			-D	1	
Clamping unit		None					
		Attached		[1]	-C		
Piston rod		At one end					
		Through piston rod			T		
Cushioning		Elastic cushioning rings/pads	at both ends		-P	-P	)
Position sensing		Via proximity switch			Α	А	
Piston rod extension		None					
	[mm]	1 500			E		

<sup>[1]</sup> C Only available with T

Measured-value transducer DADE-MVC-010 DADE-MVC-420 The measured-value transducer converts sensor signals of the standards-based cylinder DDPC into a voltage signal of 0 ... 10 V and/or a current signal of 4 ... 20 mA. These signals can be evaluated by a PLC with an appropriate signal input.



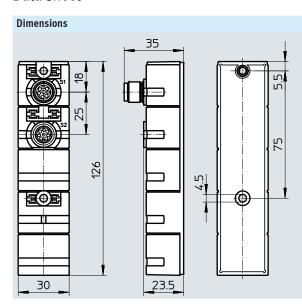
General technical data		
Type of mounting	With through-hole	
Mounting position	Any	
Short circuit current rating	Yes	
Reverse polarity protection	Yes	
Diagnostic function	Display via LED	

General electrical data			
Analogue output	[V]	0 10 (as per EN 61131-2)	
	[mA]	4 20 (as per EN 61131-2)	
Nominal operating voltage	[V DC]	24 ±25%	
Residual ripple	[%]	4 (at 50 Hz)	
Current consumption at nominal operating	[mA]	20 30	
voltage			
Switching logic at outputs		PNP	
Switching logic at inputs		PNP	
Debounce time at inputs	[ms]	3	
Linearity error FS		0.2%	

Operating and environmental conditions			
Ambient temperature	[°C]	0 55	
Degree of protection		IP65	
Relative humidity		95% non-condensing	
CE marking (see declaration of conformity)		To EU EMC Directive	
		To EU RoHS Directive	
KC marking		KC EMC	
Corrosion resistance class CRC <sup>1)</sup>		1	
Product weight	[g]	128	
Note on materials : Housing		Polybutylene terephthalate	

<sup>1)</sup> Corrosion resistance class CRC 1 to Festo standard FN 940070

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Download CAD data  $\rightarrow \underline{\text{www.festo.com}}$ 

### Pin allocation

PLC interface



4
3

Pin	Function	Cable colour
1	24 V	White
2	Analogue measurement signal	Brown
3	Reference output	Green
4	0 V measurement signal	Yellow
5	Reference input	Grey
6	Calibration input	Pink
7	Ready output	Blue
8	0 V power supply and inputs/outputs	Red

Measuring system i	nterf	ace
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Pin	Function
1	Ub
2	0 V
3	Signal sine +
4	Signal sine -
5	Signal cosine -
6	Signal cosine +
7	Screening / earth
8	-

		Description	Part no.	Туре
Measured-value transc	ducer		<u> </u>	
	With voltage signal	0 10 V	542117	DADE-MVC-010
	With current signal	4 20 mA	542118	DADE-MVC-420
				Data sheets → Internet: si
Accessories				CIM M42 OCD 2 DII
Accessories	Connecting cable	PLC connecting cable (length 2 m)	525616	SIM-M12-8GD-2-PU

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