



Key features

#### Hardware

- The motor controller SFC-LAC serves as a positioning controller and closed loop position controller
- Available with or without control panel
- Thanks to IP54 protection, the motor controller can be mounted close to the drive

#### Parameter assignment via:

- Control panel:
- suitable for simple position sequences • FCT (Festo Configuration Tool)
- configuration package:
- with RS 232 interface
- Windows-based PC user interface, Festo Configuration Tool
- Easy actuation via:
  - I/O interface - Profibus
  - CANopen, "Interpolated position mode" included
  - DeviceNet



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DeviceNet.

### For controlling

# linear module HME

# FHPP – Festo Handling and Positioning Profile

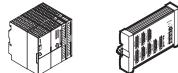
# Optimised data profile

Festo has developed an optimised data profile, the "Festo Handling and Positioning Profile (FHPP)", that is tailored to the target applications for handling and positioning tasks.

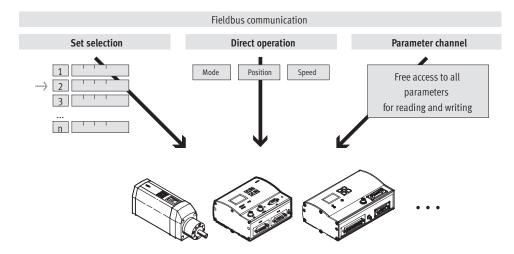
The FHPP data profile permits the actuation of Festo motor controllers, using a fieldbus interface, via standardised control and status bytes. The following are defined, among others:

- Operating modes

- I/O data structure
- Parameter objects
- Sequence control







PROFIBUS<sup>®</sup>, DeviceNet<sup>®</sup>, CANopen<sup>®</sup> is a registered trademark of its respective trademark holder in certain countries.

# - Type discontinued Available up until 2011

# Motor controllers SFC-LAC

Key features

# FCT software – Festo Configuration Tool

### Software platform for electric drives from Festo

- All drives in a system can be managed and archived in a common project
- Project and data management for all supported device types
- Simple to use thanks to graphically-supported parameter entry
- Universal mode of operation for all drives

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• Working offline at your desk or online at the machine

#### Mechanical reference positions and limit positions

- Red. 14 +++ 140 8
- Reference positions can be either edited or taught in
- Flexible adaptation to installation conditions
- Settings are displayed clearly

## Position set table



- 31 position sets ensure flexibility in positioning
- Absolute or relative positioning values can be used
- The following parameters can be set flexibly for each application:
  - Position
- Speed
- Acceleration
- Braking ramps
- Complete function test

# Type discontinued Available up until 2011

# Motor controllers SFC-LAC

Type codes

		SFC	 – LAC	- VD	- 10	— E	— H2	- I0
Туре								
SFC	Motor controller							
Motor type	e							
LAC	Linear direct drive			I				
Voltage								
VD	Voltage, 48 V				1			
Nominal of	current							
10	Nominal current, 10 A					1		
Encoder								
E	Encoder							
Control pa	anel							
HO	Without control panel							-
H2	Built-in control panel							
Control in	iterface							
10	I/O interface							
PB	Profibus interface							
CO	CANopen interface							
DN	DeviceNet interface							

# - Type discontinued Available up until 2011

# Motor controllers SFC-LAC

Technical data

Fieldbus interfaces



CANOpea

Device<u>Net</u>



General technical data						
Туре		SFC10	SFCPB	SFCCO	SFCDN	
Operating mode		Adaptive status controller				
Position sensor		Encoder				
Encoder input		CAN bus				
Display (optional)		Interface with full-text disp	lay via graphic LCD display (:	128 x 64 pixels)		
Control elements (optional)		4 keys				
Interface		I/O interface for 31	Profibus DP	CANopen	DeviceNet	
		position sets and homing				
Number of digital logic inputs		8	-			
Number of digital logic outputs		4	-			
Bus terminating resistor		-	Not integrated in the device			
Communication profile		-	DP-V0/V1 / FHPP	DS301 / FHPP	FHPP	
			Step7 functional modules	DS301, DSP402	Device type 0C <sub>h</sub>	
Max. fieldbus baud rate	[Mbit/s]	-	12	1	0.5	
Mains filter		Integrated				
Type of mounting		H-rail, wall or surface bracket				
Product weight	[g]	1,200				

# Electrical data

General		
Rated output	[VA]	480
Parameterisation interface		RS232; 38,400 baud
Max. intermediate circuit voltage	[V DC]	48
Peak power	[VA]	960
Peak current per phase, effective	[A]	15
Load supply		
Nominal voltage	[V DC]	48 +5/-10%
Nominal current	[A]	10
Peak current	[A]	20
Leste comple		
Logic supply		
Nominal voltage	[V DC]	24 ±10%
Nominal current	[A]	0.5
Peak current	[A]	0.8
Max. current per output	[A]	0.5
(digital logic outputs)		

# Type discontinued Available up until 2011

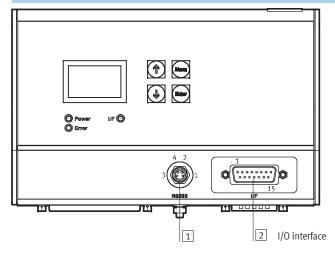
# Motor controllers SFC-LAC

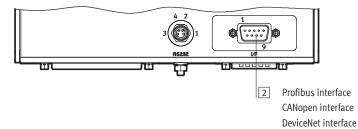
Technical data

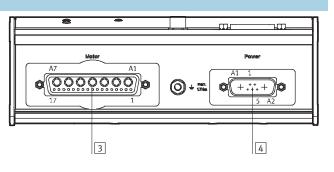
# FESTO

Derating and environmental conditions						
Туре	SFCIO	SFCPB	SFCCO	SFCDN		
Digital logic outputs	Electrically isolated	-	-	-		
Logic inputs	Electrically isolated	-	-	-		
Logic input specification	IEC 61131	-	-	-		
Mains filter	Integrated					
Protection class	IP54					
Vibration resistance	To DIN EN 60068-2-6					
Shock resistance	To DIN EN 60068-2-27	To DIN EN 60068-2-27				
Protective function	I <sup>2</sup> t monitoring					
	Current monitoring	Current monitoring				
	Voltage failure detection					
	Lag error monitoring					
	Software end position detection					
	Temperature monitoring					
CE mark (see declaration of conformity)	In accordance with EU EMC directive					
Ambient temperature [°C]	0 +40					
Relative air humidity [%]	0 95 (non-condensing)					
Certification	C-Tick	C-Tick				

#### Pin allocation







# - - Type discontinued Available up until 2011

# Motor controllers SFC-LAC

Technical data

1 RS2	1 RS232 interface, 4-pin M8 socket			
Pin	Function			
1	0 V			
2	Transmitted data (TxD)			
3	Received data (RxD)			
4	-			

2 I/O	?] I/O interface, 15-pin Sub-D plug				
Pin	Function				
1	24 V (supply for output)				
2	Position set coding, bit 1				
3	Position set coding, bit 2				
4	Position set coding, bit 3				
5	Position set coding, bit 4				
6	Position set coding, bit 5				
7	Stop bit				
8	0 V				
9	Enable bit				
10	Start bit				
11	MC				
12	Ready				
13	Acknowledge				
14	Error				
15	0 V				

2 <b>Pro</b>	2 Profibus interface, 9-pin Sub-D socket			
Pin	Function			
1	-			
2	-			
3	RxD/TxD-P			
4	CNTR-P			
5	DGND			
6	VP			
7	-			
8	RxD/TxD-N			
9	-			

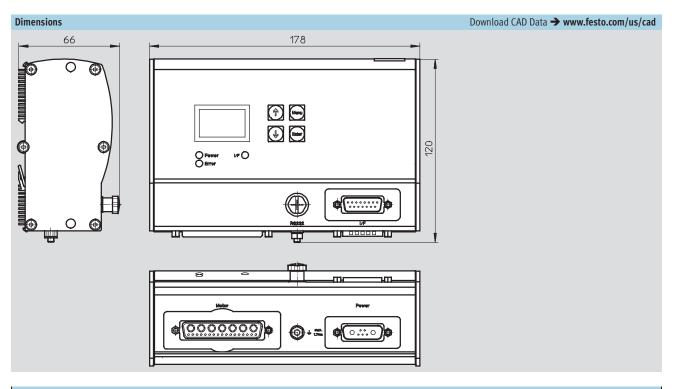
2 CAI	2 CANopen interface, 9-pin Sub-D plug				
Pin	Function				
1	-				
2	CAN_L				
3	CAN_GND				
4	-				
5	CAN_SHLD				
6	CAN_V-				
7	CAN_H				
8	-				
9	CAN_V+				

#### 2 DeviceNet interface, 9-pin Sub-D plug Pin Function 1 CAN\_L 2 CAN\_GND 3 4 CAN\_SHLD 5 6 CAN\_V-7 CAN\_H 8 \_ 9 CAN\_V+

3 Mo	3 Motor interface, 24-pin plug connector				
Pin	Function				
A1	String 1+				
A2	String 1-				
A3	String 2+				
A4	0 V				
A5	String 2-				
A6	String 3+				
A7	String 3-				
1	24 V				
2	-				
3	-				
4	CAN-H line				
5	CAN-L line				
6	CAN ground				
7	-				
8	-				
9	-				
10	-				
11	-				
12	-				
13	-				
14	-				
15	-				
16	0 V				
17	-				

4 Po	4 Power supply, 7-pin plug				
Pin	Function				
A1	48 V (load)				
A2	0 V (load)				
1	24 V (logic)				
2	0 V (logic)				
3	-				
4	PE				
5	-				

Technical data



Ordering data		
Motor controller	Brief description	Part No. Type
	With I/O interface	
	Without control panel	540 038 SFC-LAC-VD-10-E-H0-IO
	With control panel	540 039 SFC-LAC-VD-10-E-H2-I0
	With Profibus interface	
	Without control panel	540 631 SFC-LAC-VD-10-E-H0-PB
	With control panel	540 632 SFC-LAC-VD-10-E-H2-PB
	With CANopen interface	
	Without control panel	540 633 SFC-LAC-VD-10-E-H0-CO
	With control panel	540 634 SFC-LAC-VD-10-E-H2-CO
	With DeviceNet interface	
	Without control panel	552 346 SFC-LAC-VD-10-E-H0-DN
	With control panel	552 347 SFC-LAC-VD-10-E-H2-DN

# • **Type discontinued** Available up until 2011

# Motor controllers SFC-LAC

Accessories

Ordering data – Cables						
	Brief description	Cable length [m]	Part No.	Туре		
	Supply cable,	2.5	538 914	KPWR-MC-1-SUB-15HC-2,5		
and all	for connecting load and logic supply	5	538 915	KPWR-MC-1-SUB-15HC-5		
THE REAL PROPERTY OF		10	538 916	KPWR-MC-1-SUB-15HC-10		
	Motor cable,	2.5	539 489	KMTR-LAC-S50HC-S50HC-2,5		
No Start	for connecting motor and controller	5	539 490	KMTR-LAC-S50HC-S50HC-5		
		10	539 491	KMTR-LAC-S50HC-S50HC-10		
	Control cable,	2.5	538 919	KES-MC-1-SUB-15-2,5		
No Bear	for I/O interface to any controller	5	538 920	KES-MC-1-SUB-15-5		
		10	538 921	KES-MC-1-SUB-15-10		
	Programming cable,	2.5	537 926	KDI-MC-M8-SUB-9-2,5		
	for parameterisation and commissioning via RS232 interface using					
THE THE PARTY OF T	FCT software					

Ordering data – Pl			
	Brief description	Part No.	Туре
Plug for Profibus			
_0	– 9-pin Sub-D connection	532 216	FBS-SUB-9-GS-DP-B
<u>op</u>	<ul> <li>Bus terminating resistor integrated</li> </ul>		
	- Position of DIL switch can be read externally		
	– IP65		
	· ·	•	
Bus connection ad	apter for Profibus	-	
o o o	<ul> <li>9-pin Sub-D plug to 5-pin round plug/socket M12</li> </ul>	533 118	FBA-2-M12-5POL-RK
	<ul> <li>Bus terminating resistor must be connected externally</li> </ul>		
Plug for CANopen a			
	– 9-pin Sub-D connection	532 219	FBS-SUB-9-BU-2x5POL-B
	<ul> <li>Bus terminating resistor integrated</li> </ul>		
	<ul> <li>Position of DIL switch can be read externally</li> </ul>		
	- IP65		
Bus connection ad	apter for CANopen and DeviceNet		
	- 9-pin Sub-D plug to 5-pin round plug/socket M12	525 632	FBA-2-M12-5POL
	- Bus terminating resistor must be connected externally		
Ţ.			
1 Star	– 9-pin Sub-D plug to 5-pin strip	525 634	FBA-1-SL-5POL
and a second	- Bus terminating resistor must be connected externally		
ŭ/			
	<ul> <li>5-pin terminal strip for connecting the fieldbus cable to the bus connection adapter</li> </ul>	525 635	FBSD-KL-2x5POL
	FBA-1-SL-5POL		
A. 50000			
¥			

Accessories

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Ordering data – Central support				
	Brief description	Part No. Type		
Central support				
	For mounting the controller	160 909 MUP-8/12		

## Ordering data – Power supply units

	Brief description		Nominal output voltage	Nominal output current	Part No.	Туре
		Ŭ	[V DC]	[A]		
<u>Allan</u>	Power supply for motor	100 240	48	5	542 403	SVG-1/230VAC-48VDC-5A
	controller	100 240	48	10	542 404	SVG-1/230VAC-48VDC-10A
		400 500	48	20	542 405	SVG-3/400VAC-48VDC-20A

Ordering data – Documentation and software				
	Brief description	Part No.	Туре	
Co.	<ul> <li>Operating package contains:</li> <li>CD-ROM</li> <li>with user documentation for SFC-LAC, in the languages de, en, es, fr, it, sv</li> <li>with FCT (Festo Configuration Tool) configuration software, in the languages de, en</li> <li>Brief description</li> <li>This operating package is included in the scope of delivery.</li> </ul>	542 004	P.BP-SFC-LAC	

## Ordering data – Documentation<sup>1)</sup>

Ordering data – Documentation 17					
	Language	Part No. Type	Part No. Type		
		For I/O interface	For Profibus interface		
	DE	540 547 P.BE-SFC-LAC-IO-DE	540 649 P.BE-SFC-LAC-PB-DE		
	EN	540 548 P.BE-SFC-LAC-IO-EN	540 650 P.BE-SFC-LAC-PB-EN		
	ES	540 549 P.BE-SFC-LAC-IO-ES	540 651 P.BE-SFC-LAC-PB-ES		
	FR	540 550 P.BE-SFC-LAC-IO-FR	540 652 P.BE-SFC-LAC-PB-FR		
	IT	540 551 P.BE-SFC-LAC-IO-IT	540 653 P.BE-SFC-LAC-PB-IT		
	SV	540 552 P.BE-SFC-LAC-IO-SV	540 654 P.BE-SFC-LAC-PB-SV		
		For CANopen interface	For DeviceNet interface		
	DE	540 655 P.BE-SFC-LAC-CO-DE	555 886 P.BE-SFC-LAC-DN-DE		
	EN	540 656 P.BE-SFC-LAC-CO-EN	555 887 P.BE-SFC-LAC-DN-EN		
	ES	540 657 P.BE-SFC-LAC-CO-ES	555 888 P.BE-SFC-LAC-DN-ES		
	FR	540 658 P.BE-SFC-LAC-CO-FR	555 889 P.BE-SFC-LAC-DN-FR		
	IT	540 659 P.BE-SFC-LAC-CO-IT	555 890 P.BE-SFC-LAC-DN-IT		
	SV	540 660 P.BE-SFC-LAC-CO-SV	555 891 P.BE-SFC-LAC-DN-SV		

1) User documentation in paper form is not included in the scope of delivery

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#### **A Complete Suite of Automation Services**

Our experienced engineers provide complete support at every stage of your development process, including: conceptualization, analysis, engineering, design, assembly, documentation, validation, and production.



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**Pneumatics** Pneumatic linear and rotary actuators, valves, and air supply



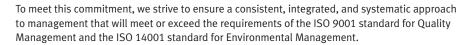
PLCs and I/O Devices PLC's, operator interfaces, sensors and I/O devices

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