End-position controllers CMFL





End-position controllers CMFL

Key features

At a glance

Properties

The end-position controller CMFL is used for force-controlled positioning of the short-stroke cylinder ADNE-LAS. The mode of operation therefore corresponds to that of a pneumatic cylinder, reproduced using a linear motor.

The drive technology used permits more dynamic movements compared with pneumatic cylinders; these movements additionally offer continuous monitoring including

The high dynamic response means that actuation is only possible via hardware inputs and outputs.

Range of applications

The following applications can be realised with the four predefined movement patterns:

- Ejecting "bad" parts from
- a continuous production process • Blocking movements
- Switching deflectors

- "motion complete". Everything from a single source
- Short-stroke cylinder ADNE-LAS
- End-position controller CMFL
- Motor cable NEBM
- Supply cable KPWR
- Control cable KES

The short-stroke cylinder ADNE-LAS and end-position controller CMFL form one unit. Only one cable is required between them.

CMFL → 3

Movement patterns

Short-stroke cylinder

→ Internet: adne

ADNE-LAS

Four movement patterns can be selected via inputs.

| 1. Advance | \longleftrightarrow |
|-----------------------------------|-----------------------|
| 2. Retract | ~~~~ • |
| 3. Advance and then retract again | |
| 4. Retract and then | |

advance again



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End-position controllers CMFL Technical data



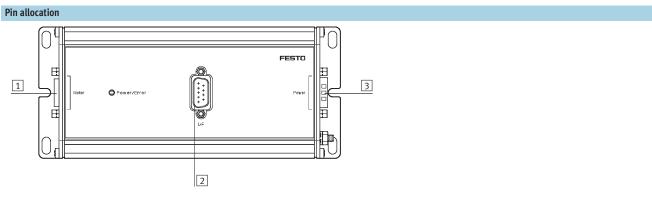
| General technical data | | | |
|----------------------------------|---------------------------------|--|--|
| Display | LED | | |
| Control elements | None | | |
| Interface | I/O interface | | |
| Number of digital logic inputs | 4 | | |
| Number of digital logic outputs | 2 | | |
| Controller operating mode | PWM MOSFET power end stage | | |
| Digital outputs, switching logic | PNP | | |
| Digital inputs, switching logic | Choice of PNP, NPN | | |
| Protective function | Software end-position detection | | |
| | Voltage failure detection | | |
| Type of mounting | Via mounting bracket | | |
| Product weight [g] | 470 | | |

| Electrical data | | |
|---------------------------------------|--------|------------------|
| Load supply | | |
| Nominal voltage (either) | [V DC] | 24 ±5% |
| | [V DC] | 48 ±5% |
| Nominal current | [A] | 3 |
| Peak current | [A] | 4.5 (at 24 V DC) |
| | [A] | 8 (at 48 V DC) |
| Logic supply | | |
| Nominal voltage | [V DC] | 24 ±10% |
| Nominal current | [A] | 0.1 |
| Peak current | [A] | 0.2 |
| Max. current of digital logic outputs | [mA] | 100 |

| Operating and environmental conditions | | | |
|---|---|--|--|
| Logic input | Galvanically isolated | | |
| Digital logic outputs | Galvanically isolated | | |
| Logic input specification | Based on IEC 61131-2 | | |
| Digital output design | To IEC 61131-2 | | |
| Protection class | IP65 | | |
| Vibration resistance | Based on DIN EN 60068-2-6 | | |
| Shock resistance | Based on DIN EN 60068-2-27 | | |
| CE mark (see declaration of conformity) ¹⁾ | To EU EMC Directive | | |
| Ambient temperature [°C] | 0 +40 | | |
| Storage temperature [°C] | -20 +60 | | |
| Relative air humidity [%] | 0 90 (non-condensing) | | |
| Note on materials | Contains PWIS (paint-wetting impairment substances) | | |
| | RoHS-compliant | | |
| Certification | C-Tick | | |

For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com → Support → User documentation. If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.

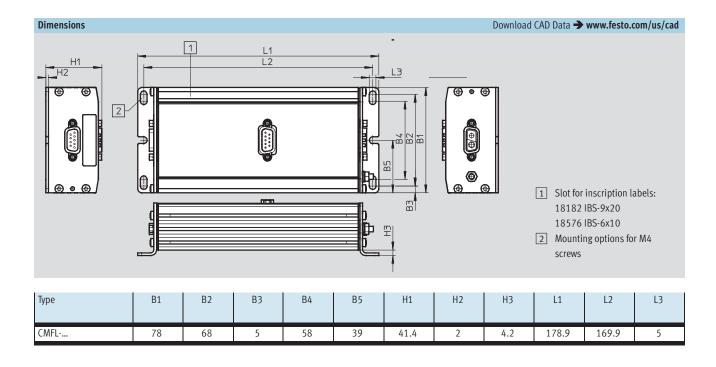
End-position controllers CMFL Technical data



| 1 Motor interface, 9-pin Sub-D socket | | |
|---------------------------------------|-------------------------|--|
| Pin | Function | |
| 1 | Centre pick-up | |
| 2 | Temperature sensor | |
| 3 | Serial data | |
| 4 | Motor – | |
| 5 | Motor + | |
| 6 | Clock | |
| 7 | Supply voltage | |
| 8 | Write protect | |
| 9 | Reference potential 0 V | |
| - | Cable screening | |

| 2 I/0 | 2 I/O interface, 9-pin Sub-D plug | | |
|-------|--|--|--|
| Pin | Function | | |
| 1 | Reference voltage | | |
| 2 | Enable | | |
| 3 | Control bit 2 | | |
| 4 | Start | | |
| 5 | Control bit 1 | | |
| 6 | Output supply voltage | | |
| 7 | Motion complete | | |
| 8 | Error | | |
| 9 | GND (connected internally with GND load) | | |
| - | Cable screening | | |

| 3 Pov | 3 Power supply, 2-pin Sub-D plug | | | |
|-------|----------------------------------|--|--|--|
| Pin | Function | | | |
| A1 | +48 VDC load | | | |
| A2 | GND load | | | |



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End-position controllers CMFL Technical data

| Ordering data | Ordering data | | | | | |
|------------------|--------------------|----------|------|--|--|--|
| Motor controller | Brief description | Part No. | Туре | | | |
| | With I/O interface | 567420 | CMFL | | | |

Accessories

| Ordering data – Cables | | | | | |
|------------------------|--|------------------|----------|------------------------|--|
| | Brief description | Cable length [m] | Part No. | Туре | |
| | Motor cable | 2.5 | 565369 | NEBM-S1G9-E-2.5-N-S1G9 | |
| | for connecting the motor and controller | 5 | 565370 | NEBM-S1G9-E-5-N-S1G9 | |
| | | 10 | 565371 | NEBM-S1G9-E-10-N-S1G9 | |
| | | | | | |
| | Supply cable | 2.5 | 537931 | KPWR-MC-1-SUB-9HC-2,5 | |
| | | 5 | 537932 | KPWR-MC-1-SUB-9HC-5 | |
| | | 10 | 537933 | KPWR-MC-1-SUB-9HC-10 | |
| | | | | | |
| | | | | | |
| | Control cable | 2.5 | 537923 | KES-MC-1-SUB-9-2,5 | |
| | for I/O interface, for connection to any PLC | 5 | 537924 | KES-MC-1-SUB-9-5 | |
| | controller | 10 | 537925 | KES-MC-1-SUB-9-10 | |
| | | | | | |

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