End-position controllers CMFL





### **End-position controllers CMFL**

Key features

#### At a glance

Properties

The end-position controller CMFL is used for force-controlled positioning of the short-stroke cylinder ADNE-LAS. The mode of operation therefore corresponds to that of a pneumatic cylinder, reproduced using a linear motor.

The drive technology used permits more dynamic movements compared with pneumatic cylinders; these movements additionally offer continuous monitoring including

The high dynamic response means that actuation is only possible via hardware inputs and outputs.

#### Range of applications

The following applications can be realised with the four predefined movement patterns:

- Ejecting "bad" parts from
- a continuous production process • Blocking movements
- Switching deflectors

- "motion complete". Everything from a single source
- Short-stroke cylinder ADNE-LAS
- End-position controller CMFL
- Motor cable NEBM
- Supply cable KPWR
- Control cable KES

The short-stroke cylinder ADNE-LAS and end-position controller CMFL form one unit. Only one cable is required between them.

CMFL → 3

#### Movement patterns

Short-stroke cylinder

→ Internet: adne

ADNE-LAS

Four movement patterns can be selected via inputs.

1. Advance	$\longleftrightarrow$
2. Retract	<b>~~~~</b> •
3. Advance and then retract again	
4. Retract and then	

advance again



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# End-position controllers CMFL Technical data



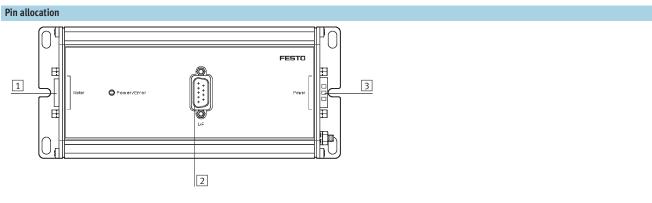
General technical data			
Display	LED		
Control elements	None		
Interface	I/O interface		
Number of digital logic inputs	4		
Number of digital logic outputs	2		
Controller operating mode	PWM MOSFET power end stage		
Digital outputs, switching logic	PNP		
Digital inputs, switching logic	Choice of PNP, NPN		
Protective function	Software end-position detection		
	Voltage failure detection		
Type of mounting	Via mounting bracket		
Product weight [g]	470		

Electrical data		
Load supply		
Nominal voltage (either)	[V DC]	24 ±5%
	[V DC]	48 ±5%
Nominal current	[A]	3
Peak current	[A]	4.5 (at 24 V DC)
	[A]	8 (at 48 V DC)
Logic supply		
Nominal voltage	[V DC]	24 ±10%
Nominal current	[A]	0.1
Peak current	[A]	0.2
Max. current of digital logic outputs	[mA]	100

Operating and environmental conditions			
Logic input	Galvanically isolated		
Digital logic outputs	Galvanically isolated		
Logic input specification	Based on IEC 61131-2		
Digital output design	To IEC 61131-2		
Protection class	IP65		
Vibration resistance	Based on DIN EN 60068-2-6		
Shock resistance	Based on DIN EN 60068-2-27		
CE mark (see declaration of conformity) <sup>1)</sup>	To EU EMC Directive		
Ambient temperature [°C]	0 +40		
Storage temperature [°C]	-20 +60		
Relative air humidity [%]	0 90 (non-condensing)		
Note on materials	Contains PWIS (paint-wetting impairment substances)		
	RoHS-compliant		
Certification	C-Tick		

For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com → Support → User documentation. If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.

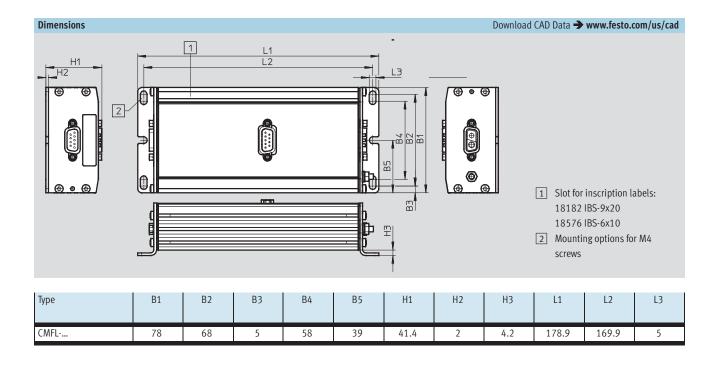
# End-position controllers CMFL Technical data



1 Motor interface, 9-pin Sub-D socket		
Pin	Function	
1	Centre pick-up	
2	Temperature sensor	
3	Serial data	
4	Motor –	
5	Motor +	
6	Clock	
7	Supply voltage	
8	Write protect	
9	Reference potential 0 V	
-	Cable screening	

2 I/0	2 I/O interface, 9-pin Sub-D plug		
Pin	Function		
1	Reference voltage		
2	Enable		
3	Control bit 2		
4	Start		
5	Control bit 1		
6	Output supply voltage		
7	Motion complete		
8	Error		
9	GND (connected internally with GND load)		
-	Cable screening		

3 Pov	3 Power supply, 2-pin Sub-D plug			
Pin	Function			
A1	+48 VDC load			
A2	GND load			



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# End-position controllers CMFL Technical data

Ordering data	Ordering data					
Motor controller	Brief description	Part No.	Туре			
	With I/O interface	567420	CMFL			

#### Accessories

Ordering data – Cables					
	Brief description	Cable length [m]	Part No.	Туре	
	Motor cable	2.5	565369	NEBM-S1G9-E-2.5-N-S1G9	
	for connecting the motor and controller	5	565370	NEBM-S1G9-E-5-N-S1G9	
		10	565371	NEBM-S1G9-E-10-N-S1G9	
	Supply cable	2.5	537931	KPWR-MC-1-SUB-9HC-2,5	
		5	537932	KPWR-MC-1-SUB-9HC-5	
		10	537933	KPWR-MC-1-SUB-9HC-10	
	Control cable	2.5	537923	KES-MC-1-SUB-9-2,5	
	for I/O interface, for connection to any PLC	5	537924	KES-MC-1-SUB-9-5	
	controller	10	537925	KES-MC-1-SUB-9-10	

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**Pneumatics** Pneumatic linear and rotary actuators, valves, and air supply



PLCs and I/O Devices PLC's, operator interfaces, sensors and I/O devices

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