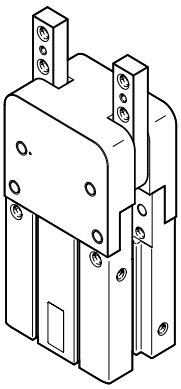
Radial grippers DHRC

Key features

At a glance



- Lateral gripper jaw support for high torque loads
- Gripper jaw centring options
- Maximum repetition accuracy
- Proximity switch for sensing the piston position at the end positions and position transmitter for sensing the piston position at any location
- Wide range of adaptation options on the drives
- Flexible application options: can be used as a double-acting and single-acting gripper

Position sensing

[A] Via proximity switch

The position sensing function uses proximity switches to sense any required positions.

Gripper function

[_] Double-acting

Open or close when pressurised with compressed air

[S] Single-acting, open

Open in unpressurised state. Closed when pressurised with compressed air

Gripping force backup

[NO] Opening

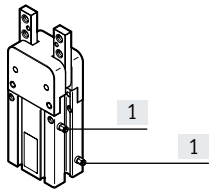
Opened by spring force when unpressurised

Note

Engineering software
Gripper selection
➔ www.festo.com

Key features

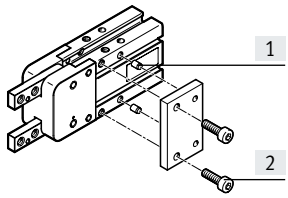
Supply ports

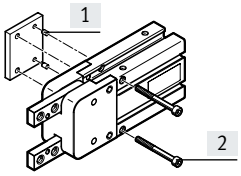


[1] Supply ports

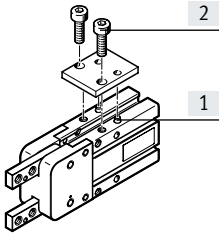
Mounting options

On the side



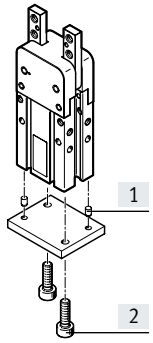


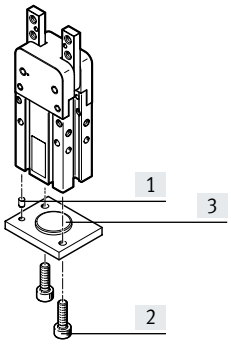
Vertical



[1] Centring sleeves
[2] Retaining screws

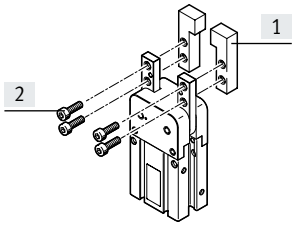
From underneath





[1] Centring sleeves
[2] Retaining screws
[3] Base

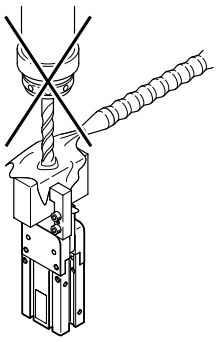
Mounting external gripper fingers



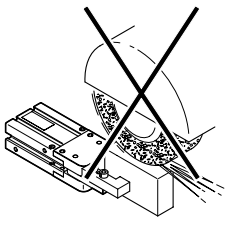
[1] External gripper fingers
[2] Retaining screws

Note

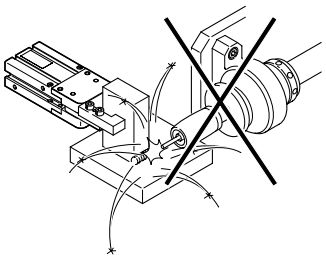
This gripper is not suitable for the following or similar applications:



- Machining
- Aggressive media



- Grinding dust

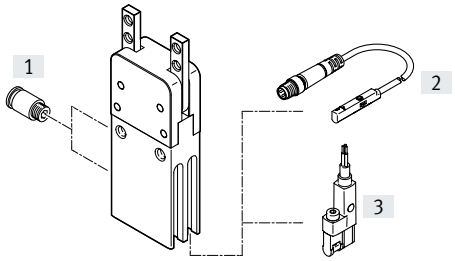


- Welding spatter

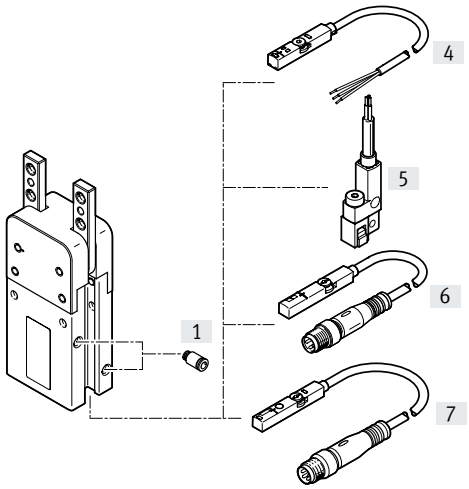
Peripherals overview

Peripherals overview

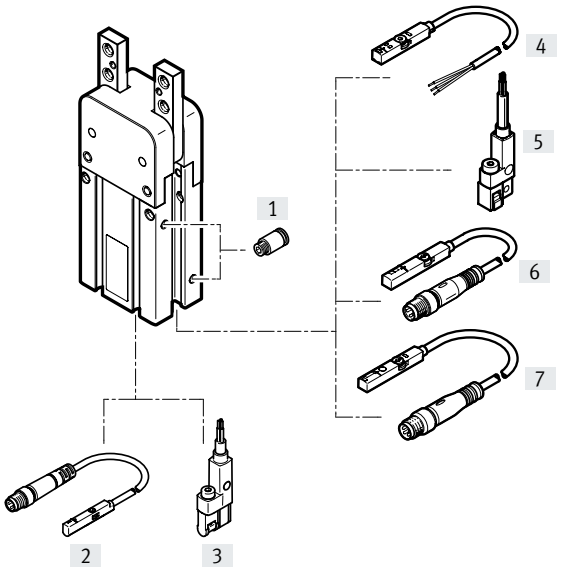
Size 6



Size 10



Size 16 ... 32



Accessories

	Type/order code	For size	Description	→ Page/Internet
[1]	Push-in fitting QS	6 ... 32	For connecting tubing with standard O.D.	qs
[2]	Proximity switch SMT-10M	6, 16 ... 32	For sensing the piston position at the end positions	21
[3]	Proximity switch SMT-10G	6, 16 ... 32	For sensing the piston position at the end positions	21
[4]	Proximity switch SMT-8M	10 ... 32	For sensing the piston position at the end positions	21
[5]	Proximity switch SMT-8G	10 ... 32	For sensing the piston position at the end positions	21
[6]	Position transmitter SMAT-8M	10 ... 32	For sensing the piston position at any location	22
[7]	Position transmitter SDAS-MHS	10 ... 32	For sensing the piston position at any location	22

Type codes

001	Series	
DHRC	Radial gripper	

002	Size [mm]	
6	6	
10	10	
16	16	
20	20	
25	25	
32	32	

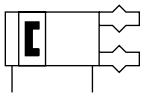
003	Position sensing	
A	For proximity sensor	

004	Gripper function	
	Double-acting	
S	Single-acting, open	

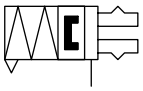
005	Gripping force backup	
	None	
NO	Opening	

Datasheet

Function
Double-acting
DHRC-...-A



Function – variants
Single-acting
Opening: DHRC-...-S-NO



Size
6 ... 32 mm

Opening angle
180°

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General technical data						
Size	6	10	16	20	25	32
Design	Connection direction on the side, force-guided motion sequence					
Mode of operation	Double-acting	Double-acting, single-acting, open				
Gripper function	Radial					
Number of gripper jaws	2					
Max. opening angle	180 deg					
Pneumatic connection	M3			M5		
Gripper repetition accuracy[1]	≤0.1 mm					
Rotational symmetry	≤0.2 mm					
Max. interchangeability	≤0.2 mm					
Max. operating frequency of gripper	≤3 Hz		≤2 Hz			
Position sensing	Via proximity switch					
Type of mounting	Optional: direct mounting via through-hole, direct mounting via thread	Optional: direct mounting via through-hole, direct mounting via thread, with through-hole and dowel pin, with female thread and dowel pin				
Mounting position	Any					

1) Under constant exposure to operating conditions, end-position drift occurs in the direction of movement of the gripper jaws, at 100 consecutive strokes

Operating and environmental conditions						
Size	6	10	16	20	25	32
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]					
Note on the operating/pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)					
Ambient temperature[1]	-10 ... 60 °C					
Corrosion resistance class CRC[2]	0 - no corrosion stress					

1) Note operating range of proximity switches
2) Corrosion resistance class CRC 0 to Festo standard FN 940070
No corrosion stress. Applies to small, visually unimportant standards-based parts such as threaded pins, circlips and clamping sleeves that are usually only available on the market in a phosphated or burnished version (and possibly oiled) as well as to ball bearings (for components < CRC 3) and plain bearings.

Datasheet

Operating pressure DHRC-...						
Size	6	10	16	20	25	32
Operating pressure	0.25 ... 0.8 MPa	0.1 ... 0.8 MPa				
Operating pressure	36.25 ... 116 psi	14.5 ... 116 psi				
Operating pressure	2.5 ... 8 bar	1 ... 8 bar				

Operating pressure DHRC-...-NO					
Size	10	16	20	25	32
Operating pressure	0.2 ... 0.8 MPa		0.15 ... 0.8 MPa		
Operating pressure	29 ... 116 psi		21.75 ... 116 psi		
Operating pressure	2 ... 8 bar		1.5 ... 8 bar		

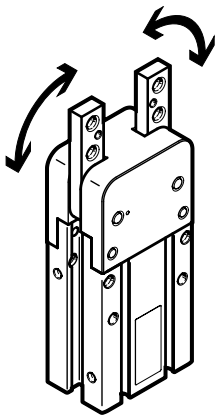
Weight DHRC-...						
Size	6	10	16	20	25	32
Product weight	24.5 g	54 g	111 g	218.4 g	438.5 g	716.5 g

Weight DHRC-...-NO					
Size	10	16	20	25	32
Product weight	59.5 g	112.5 g	220 g	440 g	720.5 g

Materials						
Size	6	10	16	20	25	32
Housing material	Anodised wrought aluminium alloy					
Gripper jaw material	High-alloy steel					
Cover cap material	Anodised wrought aluminium alloy					
Note on materials	Free of copper and PTFE, RoHS-compliant					

Datasheet

Opening and closing times



The indicated opening and closing times [ms] were measured at room temperature at an operating pressure of 6 bar with the gripper horizontally mounted and without additional gripper fingers (mean values shown).
The grippers must be throttled when handling heavier loads. Opening and closing times must then be adjusted accordingly.

Opening and closing times DHRC-...

Size	6	10	16	20	25	32
Min. opening time at 6 bar	10 ms	28 ms	37 ms	44 ms	90 ms	117 ms
Min. closing time at 6 bar	19 ms	43 ms	53 ms	57 ms	117 ms	129 ms

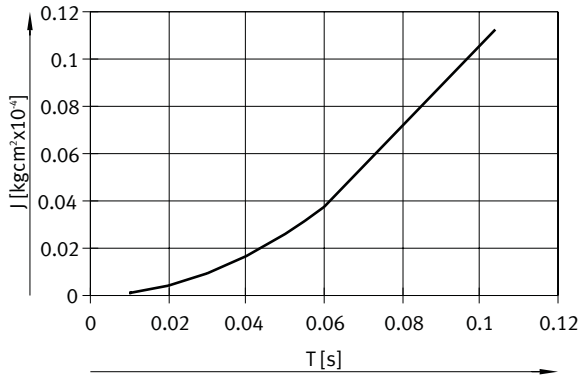
Opening and closing times DHRC-...-NO

Size	10	16	20	25	32
Min. opening time at 6 bar	53 ms	42 ms	73 ms	147 ms	229 ms
Min. closing time at 6 bar	26 ms	21 ms	32 ms	45 ms	65 ms

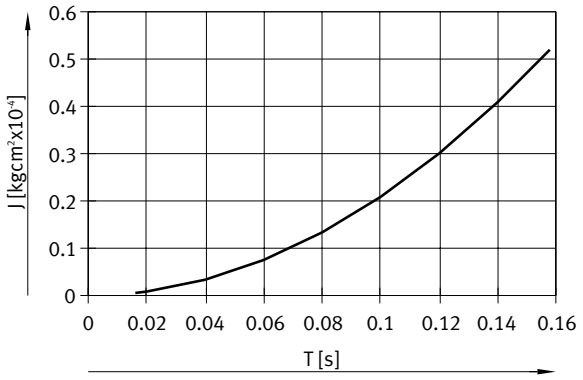
Datasheet

Opening and closing times t to be set at 6 bar as a function of mass moment of inertia of the gripper fingers

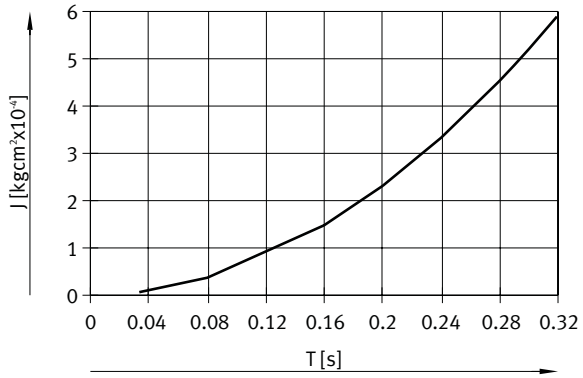
DHRC-6



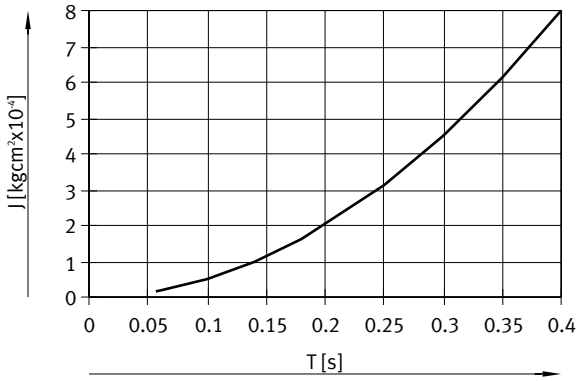
DHRC-10



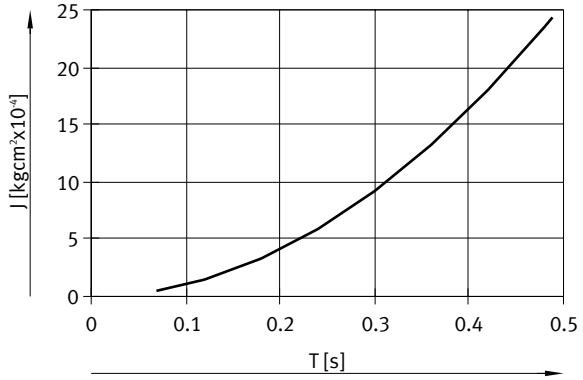
DHRC-16



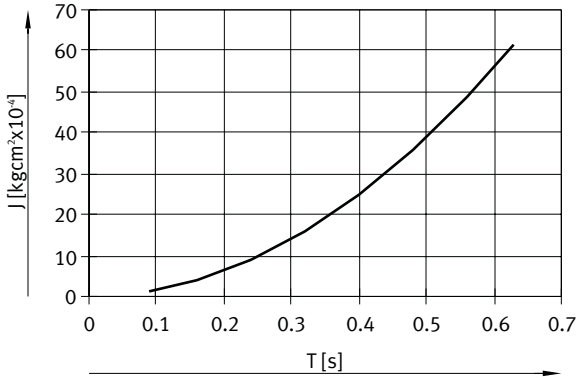
DHRC-20



DHRC-25

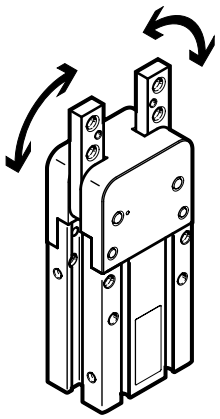


DHRC-32



Datasheet

Total gripping torque



The gripping torque is not constant across the opening angle ➔ page 15.

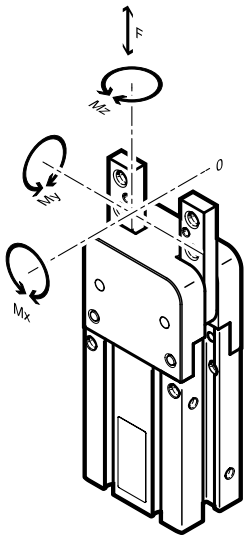
Total gripping torque DHRC-...

Size	6	10	16	20	25	32
Total gripping torque at 6 bar, opening	6.7 Ncm	25.3 Ncm	81.1 Ncm	166.2 Ncm	343.6 Ncm	725.6 Ncm
Total gripping torque at 6 bar, closing	4.8 Ncm	20.4 Ncm	66.8 Ncm	134.3 Ncm	277.5 Ncm	600.1 Ncm

Total gripping torque DHRC-...-NO

Size	10	16	20	25	32
Total gripping torque at 6 bar, closing	15.8 Ncm	50.3 Ncm	112 Ncm	239.5 Ncm	539.1 Ncm

Static characteristic load values at the gripper jaws



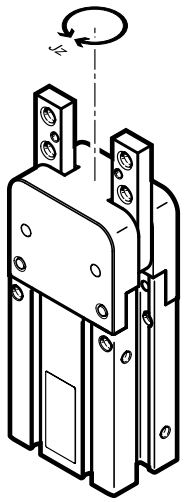
The indicated permissible forces and torques apply to a single gripper jaw. They include the lever arm, additional applied loads created by the workpiece or external gripper fingers and acceleration forces occurring during movement. The zero coordinate line (gripper jaw guide) must be taken into consideration when calculating torques.

Static characteristic load values at the gripper jaws

Size	6	10	16	20	25	32
Max. force on gripper jaw Fz, static	12 N	35 N	60 N	100 N	140 N	210 N
Maximum torque on gripper jaw Mx, static	0.3 Nm	0.5 Nm	2 Nm	4 Nm	7 Nm	12 Nm
Maximum torque on gripper jaw My, static	0.3 Nm	0.5 Nm	1 Nm	2 Nm	4 Nm	8 Nm
Maximum torque on gripper jaw Mz, static	0.3 Nm	0.5 Nm	2 Nm	4 Nm	7 Nm	12 Nm

Datasheet

Mass moments of inertia



Mass moment of inertia of the radial gripper in relation to the central axis, without external gripper fingers, with no load.

Mass moments of inertia DHRC-...

Size	6	10	16	20	25	32
Mass moment of inertia	0.01 kgcm2	0.04 kgcm2	0.132 kgcm2	0.292 kgcm2	1.311 kgcm2	3.105 kgcm2

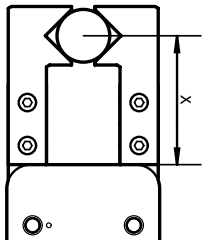
Mass moments of inertia DHRC-...-NO

Size	10	16	20	25	32
Mass moment of inertia	0.044 kgcm2	0.134 kgcm2	0.294 kgcm2	1.316 kgcm2	3.122 kgcm2

Datasheet

Gripping force F_{Gr} per gripper jaw as a function of the operating pressure and lever arm x

The gripping forces as a function of the operating pressure and lever arm can be determined from the following graphs.
The gripping torque is not constant across the opening angle
➔ page 15.



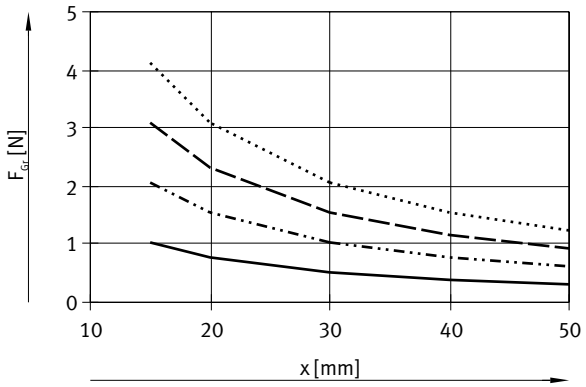
2 bar
4 bar
6 bar
8 bar

Note
Engineering software
Gripper selection
➔ www.festo.com

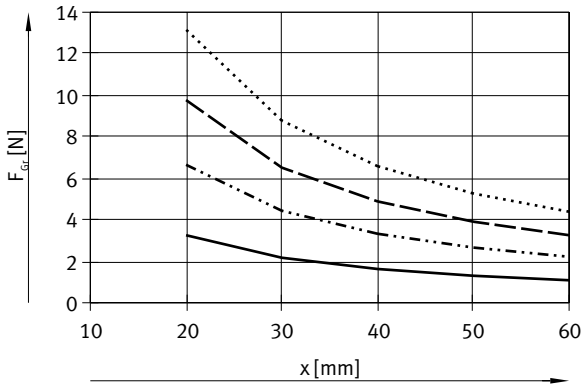
External gripping (closing)

Double-acting

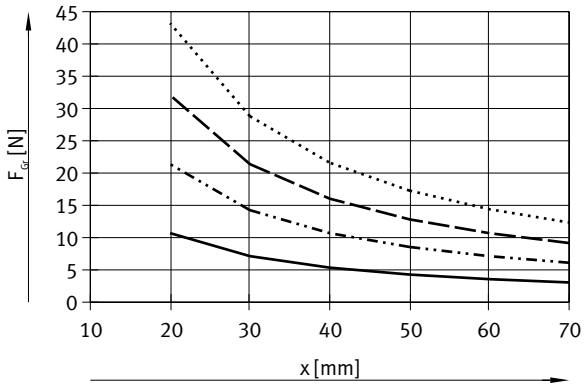
DHRC-6-A



DHRC-10-A

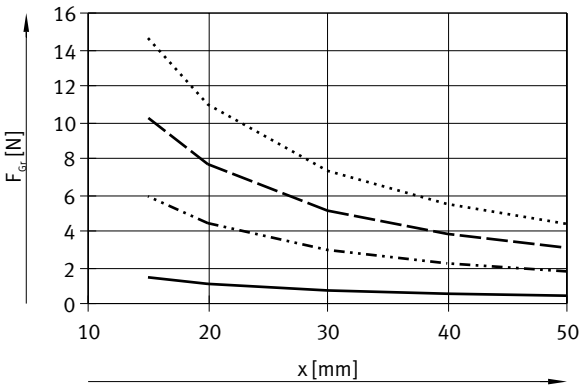


DHRC-16-A

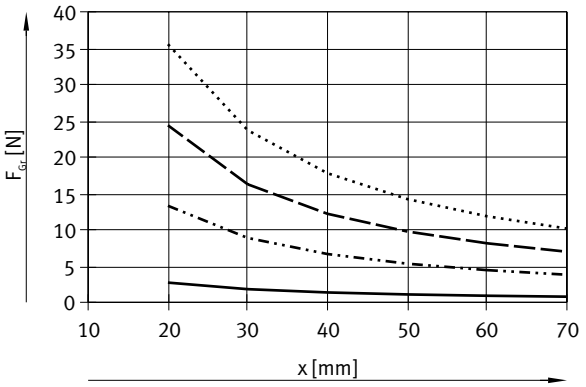


Single-acting

DHRC-10-A-S-NO



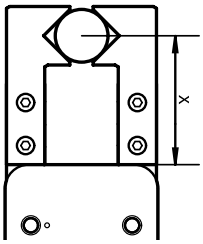
DHRC-16-A-S-NO



Datasheet

Gripping force F_{Gr} per gripper jaw as a function of the operating pressure and lever arm x

The gripping forces as a function of the operating pressure and lever arm can be determined from the following graphs.
The gripping torque is not constant across the opening angle
➔ page 15.



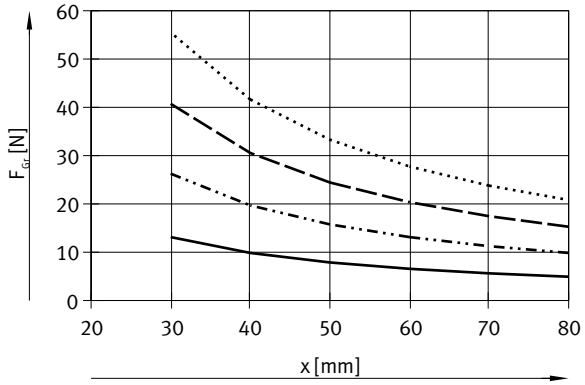
2 bar
4 bar
6 bar
8 bar

Note
Engineering software
Gripper selection
➔ www.festo.com

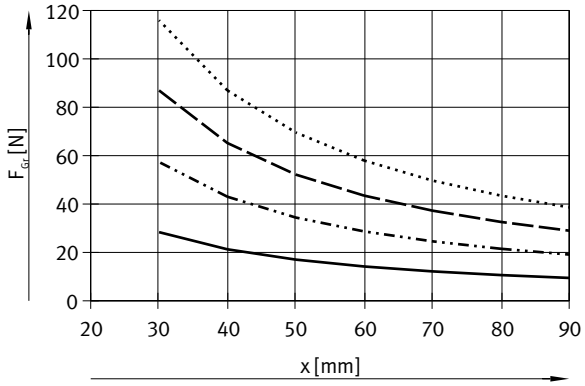
External gripping (closing)

Double-acting

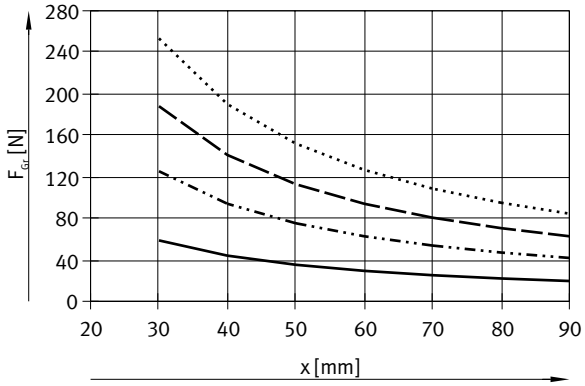
DHRC-20-A



DHRC-25-A

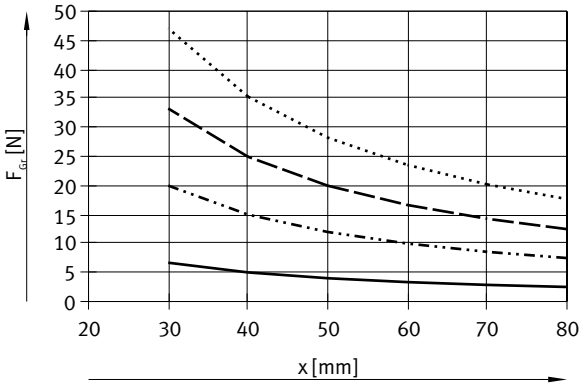


DHRC-32-A

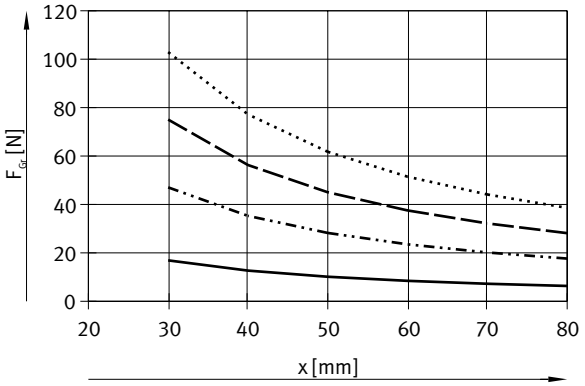


Single-acting

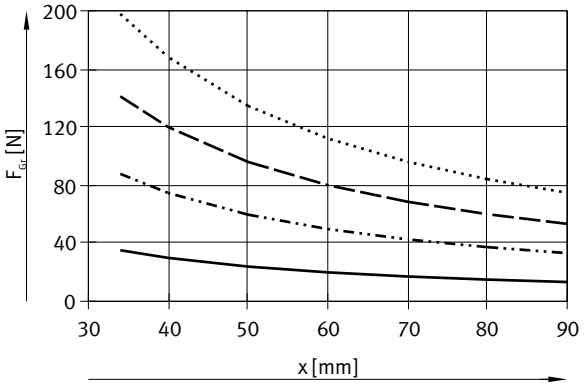
DHRC-20-A-S-NO



DHRC-25-A-S-NO



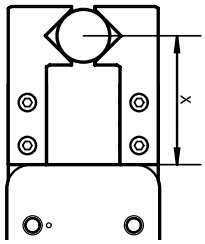
DHRC-32-A-S-NO



Datasheet

Gripping force F_{Gr} per gripper jaw as a function of the operating pressure and lever arm x

The gripping forces as a function of the operating pressure and lever arm can be determined from the following graphs.
The gripping torque is not constant across the opening angle
➔ page 15.

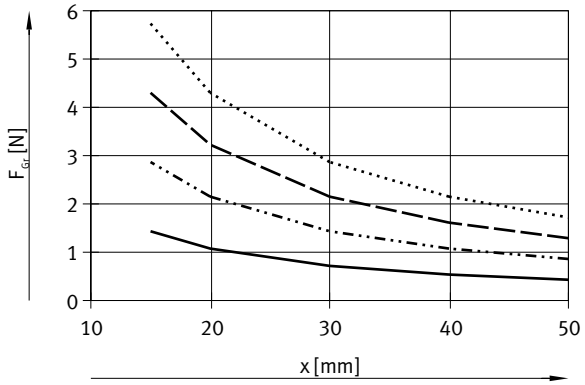


2 bar
4 bar
6 bar
8 bar

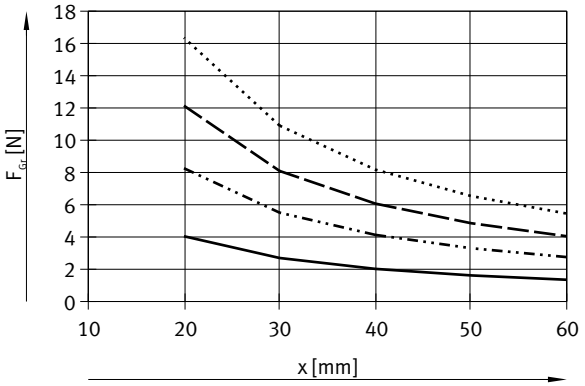
Note
Engineering software
Gripper selection
➔ www.festo.com

Internal gripping (opening)
Double-acting

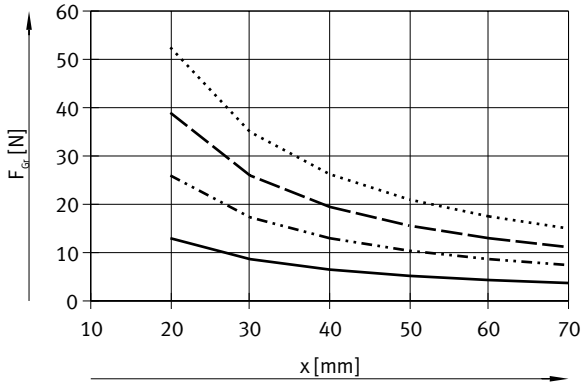
DHRC-6-A



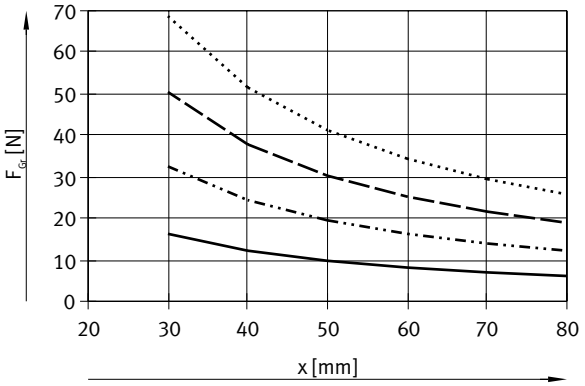
DHRC-10-A



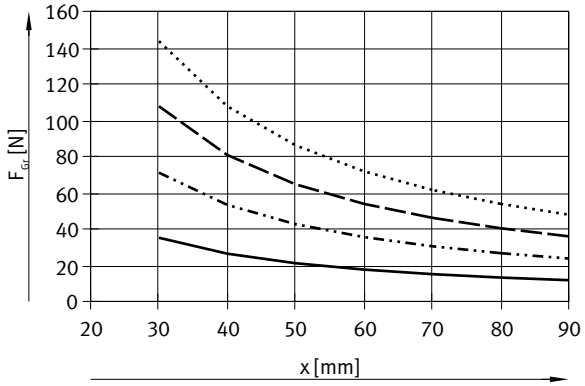
DHRC-16-A



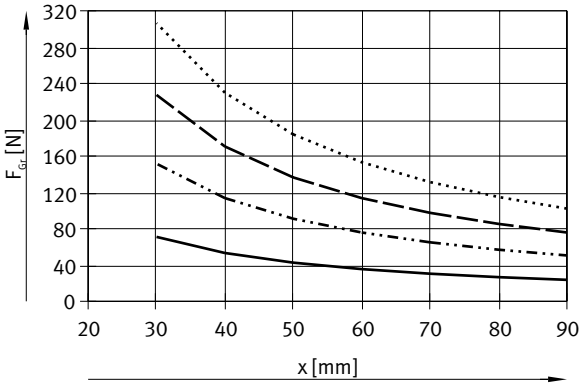
DHRC-20-A



DHRC-25-A



DHRC-32-A



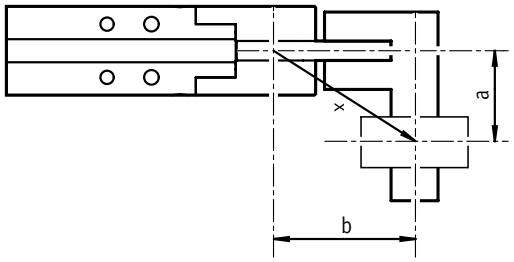
Datasheet

Gripping force F_{Gr} per gripper jaw at 6 bar as a function of lever arm x and eccentricity a and b

The following formula must be used to calculate the lever arm x with eccentric gripping:

$$x = \sqrt{a^2 + b^2}$$

The gripping force F_{Gr} can then be read from the graphs (➔ page 12/13/14) using the calculated value x.



Calculation example

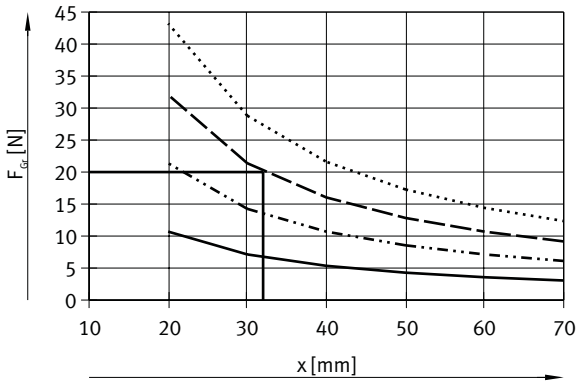
Assuming:
Distance a = 20 mm
Distance b = 25 mm
To be determined:
The gripping force at 6 bar,
with a DHRC-16-A,
used as an external gripper

Procedure:
Calculating the lever arm x

$$x = \sqrt{20^2 + 25^2}$$

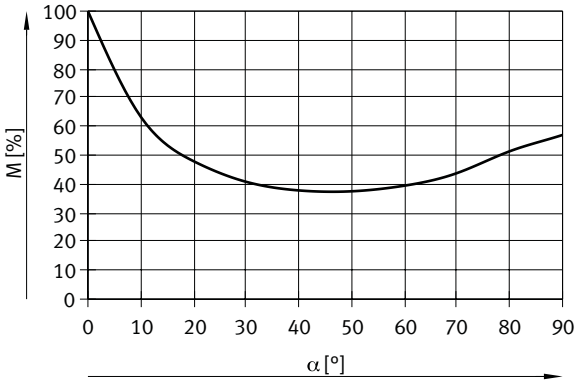
x = 32 mm

The graph (➔ page 12) gives a value for the gripping force of F_{Gr} = 20 N.



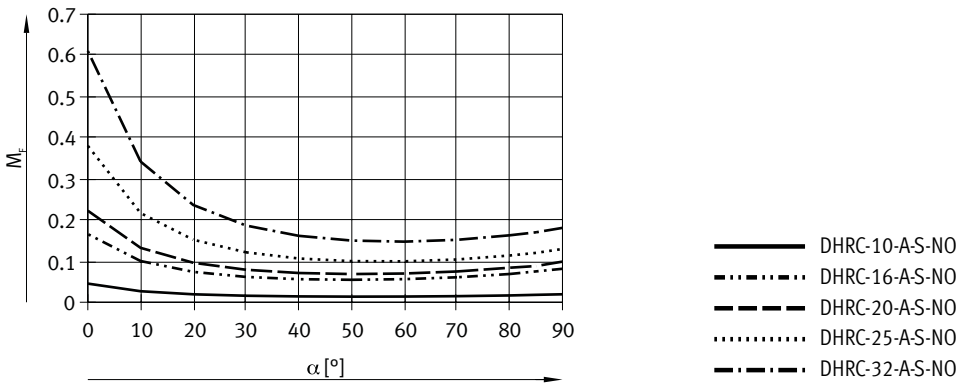
Torque curve M as a function of opening angle α

The drive principle of the gripper jaws means that the torque is not constant across the opening angle. The percentage of torque available in each case can be determined from the graph. Opening angle of 0° means: parallel gripper jaw position



Datasheet

Spring torque M_F as a function of opening angle α



Calculation of the actual gripping torques M_{Grges} for DHRC-...-S-NO as a function of the application

The radial gripper with integrated spring, DHRC-..-S.-NO (opening), can be used as follows:

- Single-acting gripper

To calculate the available gripping torque M_{Grges} (per gripper jaw), the data from the graphs for gripping force F_{Gr} (→ page 12/13/14),

$M_{Gr} = F_{Gr} * x * M$ [%]

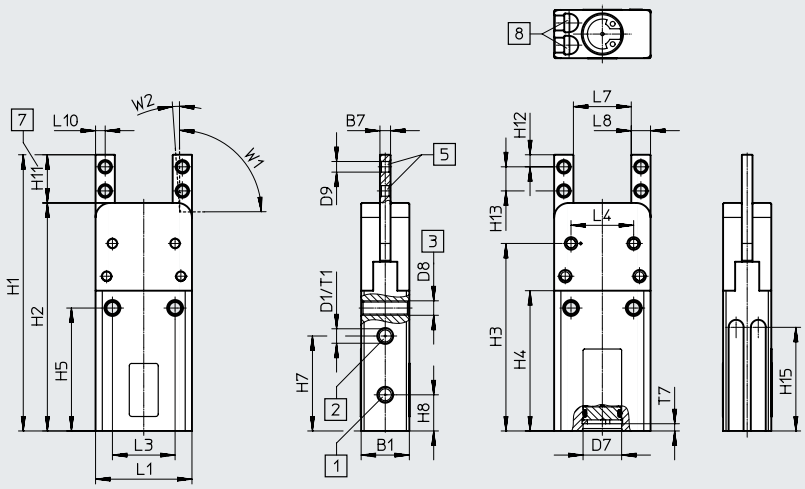
torque curve M (→ page 15) and
spring torque M_F (→ page 16) must be combined accordingly.

M_{Gr} Gripping torque
F_{Gr} Gripping force
x Lever arm
M Torque curve

Datasheet

Dimensions Download CAD data ➔ www.festo.com

DHRC-6



[1] Pneumatic connection, opening
[2] Pneumatic connection, closing
[3] Threaded hole for mounting the gripper
[5] Threaded hole for mounting the gripper fingers
[7] Area for mounting the gripper fingers
[8] C-slot for proximity switch

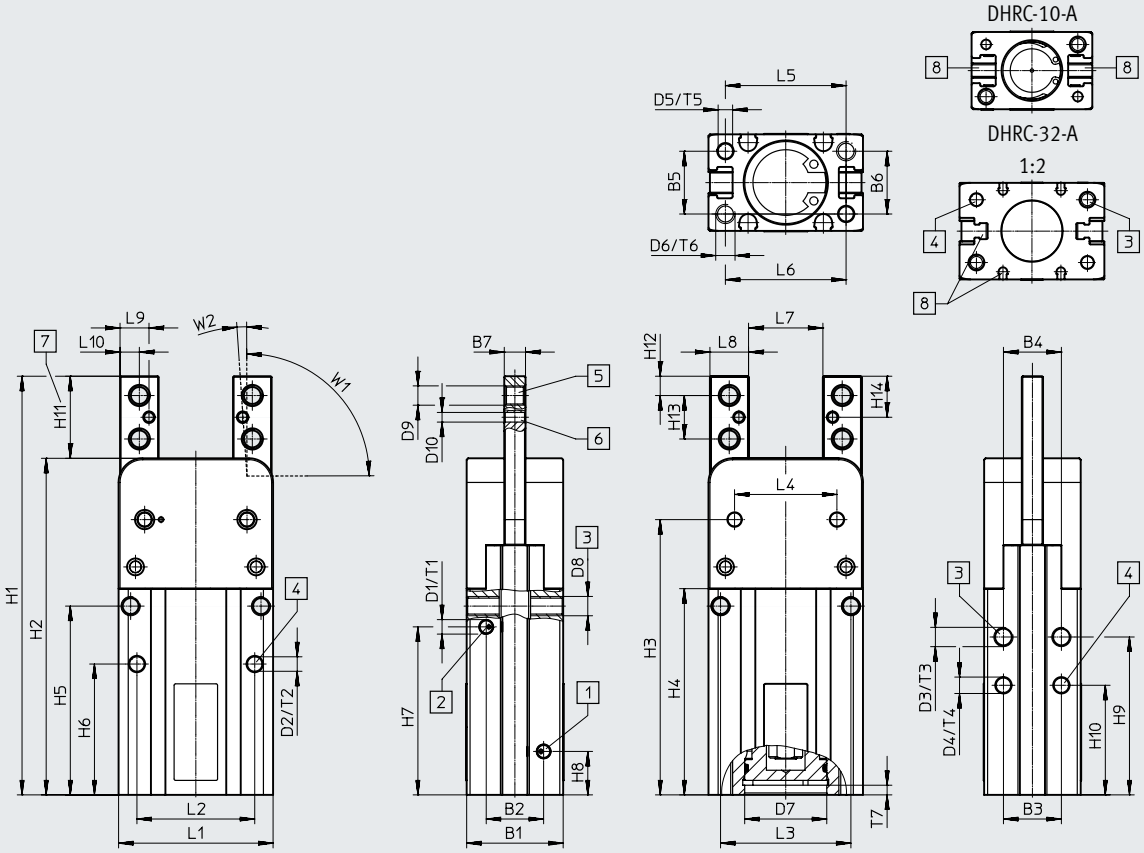
Size	B1	B7	D1	D7	D8	D9	H1	H2	H3	H4	H5	H7	H8	H11
		–0.01		ø										
[mm]	+0.3	–0.05		H8										–0.2
DHRC-6-A	10	2.2	M3	8	M3	$2.2^{+0.1}$	57.3	47.3	38.9	29.1	25.5	19.7	7.5	10

Size	H12	H13	H15	L1	L3	L4	L7	L8	L10	T1	T7	W1	W2
									+0.025				
[mm]	–0.2			+0.3			–0.4	–0.4	–0.225			±2°	+3°
DHRC-6-A	2.5	5	21.5	20	13	13	12	4	2	4.5	1.5	90°	2°

Datasheet

Dimensions Download CAD data ➔ www.festo.com

DHRC-10 ... 32



[1] Pneumatic connection, opening
[2] Pneumatic connection, closing
[3] Threaded hole for mounting the gripper
[4] Centring hole
[5] Threaded hole for mounting the gripper fingers
[7] Area for mounting the gripper fingers
[8] DHRC-10: T-slot for proximity switch
DHRC-16 ... 32: C-slot and T-slot for proximity switch

Datasheet

Size [mm]	B1 +0.3	B2	B3 ±0.02	B4	B5	B6 ±0.02	B7 –0.01 –0.05	D1	D2 ø H9	D3	D4 ø H9	D5 ø H9	D6	D7 ø H8	D8	D9	D10 ø +0.02
DHRC-10-A	16	10.8	10.8	10.8	10.8	10.8	3	M3	2	M3	2	2	M3	12	M3	$3.2^{+0.1}$	2
DHRC-10-A-S-NO																	
DHRC-16-A	20	11.9	12	12	13	13	4.4		3	M4	3	3	M4	17	M4	M4	
DHRC-16-A-S-NO																	
DHRC-20-A	26	15.6	16	14	16.6	17	5.6	M5	4	M5	4	4	M5	21	M5		
DHRC-20-A-S-NO																	
DHRC-25-A	33	20.4	21	21	20	20	6.6			M6			M6	26	M6	M5	3
DHRC-25-A-S-NO																	
DHRC-32-A	40	24	26	26	26	26	8.6		5		5	5		25		M6	
DHRC-32-A-S-NO																	

Size [mm]	H1	H2	H3	H4	H5	H6 +0.1	H7	H8	H9	H10 +0.1	H11 –0.2	H12 –0.2	H13	H14 –0.2	L1 +0.3	L2 ±0.02	L3
DHRC-10-A	69.2	53.6	43.8	–	27.5	17.5	21.5	7	22	14.4	15.6	3.5	8.6	7.8	25	18	18.6
DHRC-10-A-S-NO	75	59.4	49.6		33.3	23.3	27.3		27.8	20.2							
DHRC-16-A	86.7	69.7	57	42.7	39.1	27.1	34.8	9	32.7	22.7	17	4	9	8.5	32	24.4	27
DHRC-16-A-S-NO																	
DHRC-20-A	101.2	82.2	66.9	48.7	44.6	30.6	38.6	10.2	37.6	25.6	19	5		9.5	40	28.4	31.6
DHRC-20-A-S-NO																	
DHRC-25-A	122.6	99.6	79.9	58.1	53.4	38.4	46.4	10.5	45.4	33.4	23	5.5	12	11.5	50	37.2	37.4
DHRC-25-A-S-NO																	
DHRC-32-A	141.8	113.8	89.8	61.8	57.3	39.8	49.3	11	48.3	35.3	28	6	16	14	60	46	46
DHRC-32-A-S-NO																	

Size [mm]	L4	L5 ±0.02	L6	L7 –0.4	L8 –0.4	L9 +0.025 –0.225	L10 –0.2	T1	T2	T3	T4	T5	T6	T7	W1 ±2°	W2 +3°
DHRC-10-A	15.8	19	19	13	6	3	3	4	3	4	3	3	4	1.5	90°	2°
DHRC-10-A-S-NO																
DHRC-16-A	21.2	25	25	15.4	8	6	4	4.5		4.5			6	2		
DHRC-16-A-S-NO																
DHRC-20-A	26.8	31	30	22	9		4.5	6	4	8	4	4	10			
DHRC-20-A-S-NO																
DHRC-25-A	33	38	38	29.4	10	5	5	7.5		10			12			
DHRC-25-A-S-NO																
DHRC-32-A	39.8	46	46	34.4	12	6	6		5		5	5	13			
DHRC-32-A-S-NO																

NEW

Ordering data

Ordering data

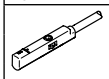
Size	Double-acting			Single-acting Opening	
[mm]	Part no.	Type		Part no.	Type
6	**8125285**	**DHRC-6-A**		**–**	
10	**8125472**	**DHRC-10-A**		**8133559**	**DHRC-10-A-S-NO**
16	**8128723**	**DHRC-16-A**		**8128721**	**DHRC-16-A-S-NO**
20	**8128697**	**DHRC-20-A**		**8128698**	**DHRC-20-A-S-NO**
25	**8128142**	**DHRC-25-A**		**8133557**	**DHRC-25-A-S-NO**
32	**8128107**	**DHRC-32-A**		**8133558**	**DHRC-32-A-S-NO**

Accessories

Proximity switches for size 6, 16 ... 32

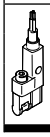
Ordering data – Proximity switch for C-slot, magneto-resistive

Datasheets → Internet: smt

	Type of mounting	Electrical connection, outlet direction of connection	Switching output	Cable length [m]	Part no.	Type
N/O						
	Inserted in the slot from above	Cable, 3-core, lengthwise	PNP	2.5	**551373**	**SMT-10M-PS-24V-E-2.5-L-OE**
		Plug M8x1, 3-pin, in-line		0.3	**551375**	**SMT-10M-PS-24V-E-0.3-L-M8D**
		Cable, 3-core, crosswise		2.5	**551374**	**SMT-10M-PS-24V-E-2.5-Q-OE**
		Plug M8x1, 3-pin, crosswise		0.3	**551376**	**SMT-10M-PS-24V-E-0.3-Q-M8D**

Ordering data – Proximity switch for C-slot, magneto-resistive

Datasheets → Internet: smt

	Type of mounting	Electrical connection, outlet direction of connection	Switching output	Cable length [m]	Part no.	Type
N/O						
	Inserted into the slot lengthwise	Cable, 3-core, crosswise	PNP	2.5	**547862**	**SMT-10G-PS-24V-E-2.5Q-OE**
		Plug M8x1, 3-pin, crosswise		0.3	**547863**	**SMT-10G-PS-24V-E-0.3Q-M8D**
		Cable, 3-core, crosswise	NPN	2.5	**8065030**	**SMT-10G-NS-24V-E-2.5Q-OE**
		Plug M8x1, 3-pin, crosswise		0.3	**8065029**	**SMT-10G-NS-24V-E-0.3Q-M8D**

Proximity switch for size 10 ... 32

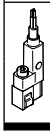
Ordering data – Proximity switch for T-slot, magneto-resistive

Datasheets → Internet: smt

	Type of mounting	Electrical connection outlet direction of connection	Switching output	Cable length [m]	Part no.	Type
N/O						
	Inserted in the slot from above, short design	Cable, 3-core, lengthwise	PNP	2.5	**574335**	**SMT-8M-A-PS-24V-E-2.5-OE**
		Plug M8x1, 3-pin, in-line		0.3	**574334**	**SMT-8M-A-PS-24V-E-0.3-M8D**
		Plug M12x1, 3-pin, in-line		0.3	**574337**	**SMT-8M-A-PS-24V-E-0.3-M12**
		Cable, 3-core, lengthwise	NPN	2.5	**574338**	**SMT-8M-A-NS-24V-E-2.5-OE**
		Plug M8x1, 3-pin, in-line		0.3	**574339**	**SMT-8M-A-NS-24V-E-0.3-M8D**
N/C						
	Inserted in the slot from above, short design	Cable, 3-core, lengthwise	PNP	7.5	**574340**	**SMT-8M-A-PO-24V-E-7.5-OE**

Ordering data – Proximity switch for T-slot, magneto-resistive

Datasheets → Internet: smt

	Type of mounting	Electrical connection, outlet direction of connection	Switching output	Cable length [m]	Part no.	Type
N/O						
	Inserted into the slot length-wise	Cable, 3-core, crosswise	PNP	2.5	**547859**	**SMT-8G-PS-24V-E-2.5Q-OE**
		Plug M8x1, 3-pin, crosswise		0.3	**547860**	**SMT-8G-PS-24V-E-0.3Q-M8D**
		Cable, 3-core, crosswise	NPN	2.5	**8065028**	**SMT-8G-NS-24V-E-2.5Q-OE**
		Plug M8x1, 3-pin, crosswise		0.3	**8065027**	**SMT-8G-NS-24V-E-0.3Q-M8D**

Ordering data – Connecting cables

Datasheets → Internet: nebu

	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-core	2.5	**541333**	**NEBU-M8G3-K-2.5-LE3**
			5	**541334**	**NEBU-M8G3-K-5-LE3**
	Straight socket, M12x1, 5-pin	Cable, open end, 3-core	2.5	**541363**	**NEBU-M12G5-K-2.5-LE3**
			5	**541364**	**NEBU-M12G5-K-5-LE3**
	Angled socket, M8x1, 3-pin	Cable, open end, 3-core	2.5	**541338**	**NEBU-M8W3-K-2.5-LE3**
			5	**541341**	**NEBU-M8W3-K-5-LE3**
	Angled socket, M12x1, 5-pin	Cable, open end, 3-core	2.5	**541367**	**NEBU-M12W5-K-2.5-LE3**
			5	**541370**	**NEBU-M12W5-K-5-LE3**

Accessories

Position transmitter for size 10 ... 32

The position transmitter continuously senses the position of the piston.
It has an analogue output with an output signal relative to the piston position.

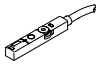
Ordering data – Position transmitter for T-slot

Datasheets → Internet: position transmitter

	Position measuring range	Analogue output [V]	[mA]	Type of mounting	Electrical connection	Cable length [m]	Part no.	Type
	0 ... 40	0 ... 10	–	Inserted in the slot from above	Plug M8x1, 4-pin, in-line	0.3	**553744**	**SMAT-8M-U-E-0.3-M8D**

Ordering data – Position transmitter for T-slot

Datasheets → Internet: sdas

	Description	Type of mounting	Electrical connection	Cable length [m]	Part no.	Type
	Choice of two operating modes: • two adjustable switching outputs • IO-Link®	Inserted in the slot from above	Plug M8x1, 4-pin, in-line	0.3	**8063974**	**SDAS-MHS-M40-1L-PNLK-PN-E-0.3-M8**
			Cable, open end	2.5	**8063975**	**SDAS-MHS-M40-1L-PNLK-PN-E-2.5-LE**

Ordering data – Connecting cables

Datasheets → Internet: nebu

	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type
	Straight socket, M8x1, 4-pin	Cable, open end, 4-core	2.5	**541342**	**NEBU-M8G4-K-2.5-LE4**
			5	**541343**	**NEBU-M8G4-K-5-LE4**
	Angled socket, M8x1, 4-pin	Cable, open end, 4-core	2.5	**541344**	**NEBU-M8W4-K-2.5-LE4**
			5	**541345**	**NEBU-M8W4-K-5-LE4**