



Key features

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At a glance

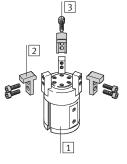
- Double-acting piston drive
- Self-centring
- Variable gripping action:
 External/internal gripping
- Versatility thanks to externally adaptable gripper fingers
- Wide range of options for mounting on drive units
- Maximum precision
- High holding force
- Sensor technology:
 Adaptable proximity sensors on the small grippers
 - Integral proximity sensors for medium and large grippers

- 🎍 - Note

Sizing software Gripper selection →www.festo.com

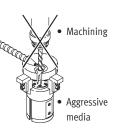
Mounting options for external gripper fingers (customer-specific)

- 1 Three-point gripper
- 2 External gripper fingers
- 3 Mounting screws



- Note

Grippers should always be used with exhaust air flow control. They are not suitable for the following, or for similar applications:

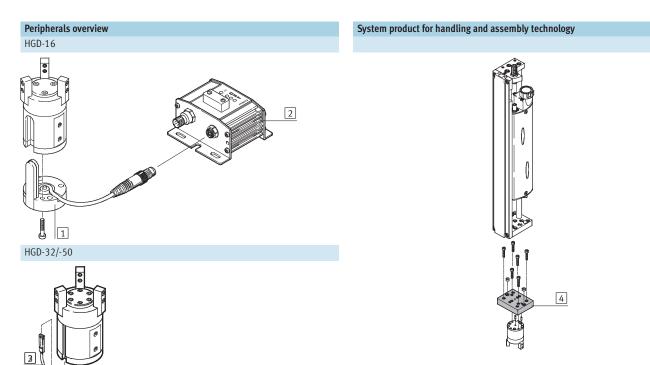


• Grinding dust



Three-point grippers HGD Peripherals overview and type codes

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Acces	sories		
	Туре	Brief description	→ Page/Internet
1	Position sensor SMH-S1	Adaptable and integratable sensor technology, for sensing the piston position	10
2	Evaluation unit SMH-AE1	For position sensor SMH-S1	10
3	Proximity sensor SME/SMT-8	For sensing the piston position	10
4	-	Drive/gripper connections	adapter kit

Type codes

		HGD —	16	 А
Туре				
HGD	Three-point gripper			
Size				
Position sen	sing			
А	For proximity sensing			

Function Double-acting

- **Ø** -Size 16 ... 50 mm

Stroke 5 ... 12 mm

- ≣ - www.festo.com	. 1	www.festo.com
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Wearing parts kits **→** 9



General techn	ical data							
Size			16	32	50			
Design			Lever mechanism					
Mode of operation			Double-acting	Double-acting				
Gripper function			3-point	3-point				
Number of gripper jaws			3	3				
Max. weight force per external gripper finger ¹⁾ [N]		0.08	0.3	0.75				
Stroke	per gripper jaw	[mm]	2.5	3.9	6			
	smallest gripping Ø $^{2)}$	[mm]	23	33.2	50			
	largest gripping Ø $^{2)}$	[mm]	28	41	62			
Pneumatic cor	inection		M3	M5	G1/8			
Repetition acc	uracy ³⁾	[mm]	≤ 0.04					
Max. interchar	Max. interchangeability [mm]		0.2					
Max. operating frequency [Hz]		4						
Position sensi	ng	For proximity sensing						
Type of mounti	ng		With female thread and loca	ting hole				

1) Valid for unthrottled operation

Without external gripper fingers
 Concentric to the central shaft

Operating and environmental conditions

Min. operating pressure [bar]	2
Max. operating pressure [bar]	8
Operating medium		Filtered compressed air, lubricated or unlubricated
Ambient temperature [[°C]	+5 +60
Corrosion resistance class CRC ¹⁾		2

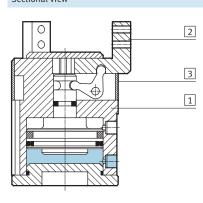
1) Corrosion resistance class 2 according to Festo standard 940 070

Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Weights [g]			
Size	16	32	50
HGD	110	300	985

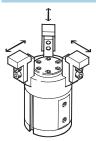
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Materials Sectional view



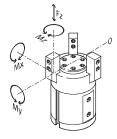
Three-point gripper Body Nickel-plated aluminium 1 High-alloy steel, nickel plated Gripper jaw 2 Cover cap Polyacetate 3 Note on materials Copper, PTFE and silicone-free Conforms to RoHS

Gripping force [N] at 6 bar



Size	16	32	50			
Gripping force per gripper jaw						
Opening	40	137	323			
Closing	30	120	293			
	·	·				
Total gripping force						
Opening	120	410	970			
Closing	90	360	880			

Characteristic load values at the gripper jaws



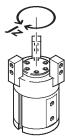
The indicated permissible forces and torques apply to a single gripper jaw. Static forces and torques relate to additional applied loads caused by

the workpiece or external gripper fingers, as well as forces which occur during handling. The zero co-ordinate line (gripper jaws point of rotation) must be taken into consideration for the calculation of torques.

Size		16	32	50
Max. permissible force F _Z	[N]	34	90	173
Max. permissible torque M _X	[Nm]	0.5	1.6	4.7
Max. permissible torque M _Y	[Nm]	0.8	2.8	8.1
Max. permissible torque M _Z	[Nm]	0.5	1.9	5.3

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Mass moment of inertia [kgm²x10⁻⁴]

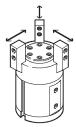


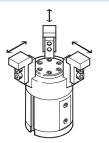
Mass moment of inertia [kgm²x10⁻⁴] for three-point grippers in relation to the central axis, without external gripper fingers, without load.

Size	16	32	50
HGD	0.14	0.79	6.10

Opening and closing times [ms] at 6 bar

With external gripper fingers Without external gripper fingers





The indicated opening and closing times [ms] have been measured at room temperature and 6 bar operating pressure without external gripper fingers.

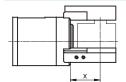
The grippers must be throttled for greater applied loads. Opening and closing times must then be adjusted accordingly.

Size		16	32	50
Without external gripper fir	igers			
HGD	Opening	5	10	10
	Closing	5	10	10
With external gripper finger	rs (as a function of weight forc	e)		
HGD	0.08 N	5	-	-
	0.11 N	10	-	-
	0.15 N	20	-	-
	0.30 N	50	-	-
	0.50 N	-	100	-
	0.75 N	-	200	-
	1.00 N	-	300	100
	1.50 N	-	-	200
	2.00 N	-	-	300

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Gripping force F per gripper as a function of operating pressure and the lever arm x

Gripping forces



Gripping torques can be determined with the following diagrams for the various sizes in relation to operating pressure and lever arm (distance from the zero co-ordinate line shown above to the pressure point at which the external fingers grip the workpiece).

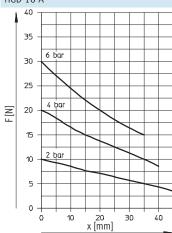
External gripping (closing)

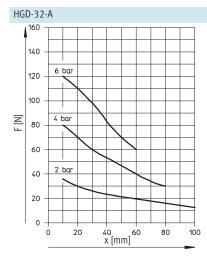


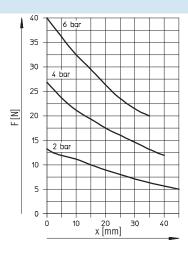


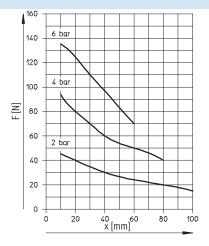
Internal gripping (opening)

HGD-16-A



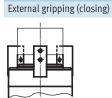




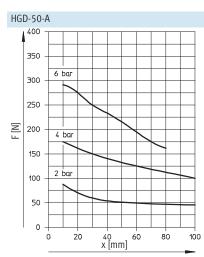


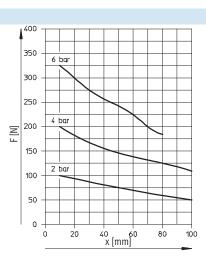
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Gripping force F per gripper as a function of operating pressure and the lever arm x

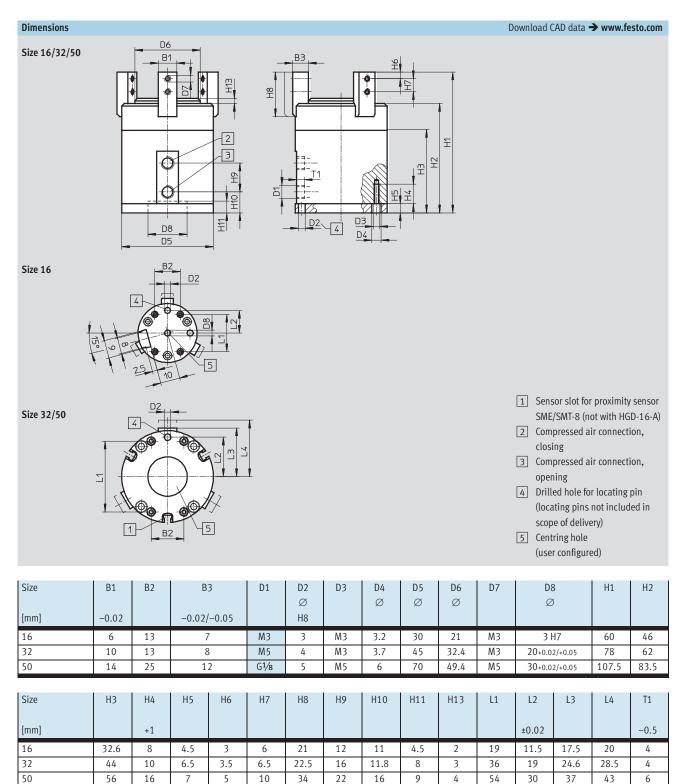


Internal gripping (opening)





Technical data



Ordering data		
Size	Double-ac	ting
[mm]	Part No.	Туре
16	174 819	HGD-16-A
32	161 837	HGD-32-A
50	161 838	HGD-50-A

Ordering data -	Ordering data – Wearing parts kits						
Size							
[mm]	Part No.	Туре					
16	378 535	HGD-16-A					
32	125 694	HGD-32-A					
50	125 695	HGD-50-A					

→ Internet: www.festo.com/catalog/...

Ordering data							
Туре	For size	Weight	Part No.	Туре	PU ¹⁾		
		[g]					
Position sensor SMH-S1 Technical data → Internet: smh-s1							
STR. C	16	30	175 713	SMH-S1-HGD16	1		
Evaluation unit SMH-AE1 Technical data → Internet: smh-ae							
1 de la companya de l	16	170	175 708	SMH-AE1-PS3-M12	1		
			175 709	SMH-AE1-NS3-M12			

1) Packaging unit quantity

Ordering data – Proximity sensors for T-slot, magneto-resistive						Technical data 🗲 Internet: sm
	Type of mounting	Switch	Electrical connection	Cable length	Part No.	Туре
		output		[m]		
N/O contact						
	Insertable in the slot from above, flush	PNP	Cable, 3-wire	2.5	543 867	SMT-8M-PS-24V-K-2,5-OE
2 B	with cylinder profile		Plug M8x1, 3-pin	0.3	543 866	SMT-8M-PS-24V-K-0,3-M8D
			Plug M12x1, 3-pin	0.3	543 869	SMT-8M-PS-24V-K-0,3-M12
		NPN	Cable, 3-wire	2.5	543 870	SMT-8M-NS-24V-K-2,5-0E
			Plug M8x1, 3-pin	0.3	543 871	SMT-8M-NS-24V-K-0,3-M8D
<i>A</i>	Insertable in the slot lengthwise, flush	PNP	Cable, 3-wire	2.5	175 436	SMT-8-PS-K-LED-24-B
	with the cylinder profile		Plug M8x1, 3-pin	0.3	175 484	SMT-8-PS-S-LED-24-B
N/C contact						
CT B I	Insertable in the slot from above, flush with cylinder profile	PNP	Cable, 3-wire	7.5	543 873	SMT-8M-PO-24V-K7,5-OE

Ordering data – Proximity sensors for T-slot, magnetic reed Technical data → Internet: s						
	Type of mounting	Switch	Electrical connection	Cable length	Part No.	Туре
		output		[m]		
N/O contact						
	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	2.5	150 855	SME-8-K-LED-24
	with the cylinder profile		Plug M8x1, 3-pin	0.3	150 857	SME-8-S-LED-24
N/C contact						
	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	7.5	160 251	SME-8-O-K-LED-24
	with the cylinder profile					

Ordering data	- Connecting cables	Technical data 🗲 Internet: nebu			
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 333	NEBU-M8G3-K-2.5-LE3
			5	541 334	NEBU-M8G3-K-5-LE3
	Straight socket, M12x1, 5-pin	Cable, open end, 3-wire	2.5	541 363	NEBU-M12G5-K-2.5-LE3
			5	541 364	NEBU-M12G5-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541 338	NEBU-M8W3-K-2.5-LE3
			5	541 341	NEBU-M8W3-K-5-LE3
	Angled socket, M12x1, 5-pin	Cable, open end, 3-wire	2.5	541 367	NEBU-M12W5-K-2.5-LE3
			5	541 370	NEBU-M12W5-K-5-LE3

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A Complete Suite of Automation Services

Our experienced engineers provide complete support at every stage of your development process, including: conceptualization, analysis, engineering, design, assembly, documentation, validation, and production.



Custom Automation Components Complete custom engineered solutions



Custom Control Cabinets Comprehensive engineering support and on-site services



Complete Systems Shipment, stocking and storage services

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